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Non-Riemannian geometry, Born–Infeld models and trace free gravitational equations



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ABSTRACT

Non-Riemannian generalization of the standard Born-Infeld (BI) Lagrangian is introduced and analyzed from a theory of gravitation with dynamical torsion field. The field equations derived from the proposed action lead to a trace free gravitational equation (non-Riemannian analog to the trace free equation (TFE) from Finkelstein et al., 2001; Ellis et al., 2011; Ellis, 2014) and the field equations for the torsion respectively. In this theoretical context, the fundamental constants arise all from the same geometry through geometrical invariant quantities (as from the curvature R). New results involving generation of primordial magnetic fields and the link with leptogenesis and baryogenesis are presented and possible explanations given. The physically admissible matter fields can be introduced in the model via the torsion vector h_{μ} . Such fields include some dark matter candidates such as axion, right neutrinos and Majorana and moreover, physical observables as vorticity can be included in the same way. From a new wormhole solution in a cosmological spacetime with torsion we also show that the primordial cosmic magnetic fields can originate from h_{μ} with the axion field (that is contained in h_{μ}) the responsible to control the dynamics and stability of the cosmic magnetic field but not the magnetogenesis itself. As we pointed out before (Cirilo-Lombardo, 2017), the analysis of Grand Unified Theories (GUT) in the context of this model indicates that the group manifold candidates are based in SO(10), SU(5) or some exceptional groups as *E*(6), *E*(7), etc.

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1. Introduction

The idea to construct a complete geometrization of the physics is very old. The drawback of the Einstein GR (General Relativity) equations is the RHS: $R_{\alpha\beta} - \frac{g_{\alpha\beta}}{2}R = \kappa T_{\alpha\beta}$ with the symmetric tensor (non-geometrical) $\kappa T_{\alpha\beta}$ that introduces *heuristically* the energy-momentum distribution. Similar drawbacks are contained by the unimodular gravity. It is well known that the unimodular gravity is obtained from Einstein-Hilbert action in which the *unimodular condition*: $\sqrt{-\det g_{\mu\nu}} = 1$ is also imposed from the very beginning (Finkelstein et al., 2001; Ellis et al., 2011; Ellis, 2014). The resulting field equations correspond to the *traceless* Einstein equations and can be shown that they are equivalent to the full Einstein equations with the cosmological constant term Λ , where Λ enters as an integration constant and the equivalence between unimodular gravity and general relativity is given by the arbitrary value of lamda. On the other hand the idea that the cosmological term arises as an integration constant is one of the motivations for the study of the unimodular gravity, for recent study, see Barrau and Linsefors, Barcelo et al., Carballo-Rubio, Firouzjaee and Ellis (2014, 2014, 2015, 2015) and Ellis and Mavromatos (2013) in the context of supergravity. The fact that the determinant of the metric is fixed has clearly profound consequences on the structure of given theory. First of all, it reduces the full group of diffeomorphisms to invariance under the group of unimodular general coordinate transformations which are transformations that leave the determinant of the metric unchanged.

Similar thing happens in the non-Riemannian case, as pointed out in Cirilo-Lombardo (2010, 2011a, 2011b, 2007, 2013), where the corresponding affine geometrical structure induces naturally the following constraint: $\frac{K}{g} = constant$. This natural constraint impose a condition (ratio) between both basic tensors through their determinants: the metric determinant *g* and the fundamental one *K* (in the sense of a nonsymmetric theory that contains the antisymmetric structures), independently of the precise functional form of *K* or *g*. In this work our starting point will be precisely the last one, where a *metric affine structure* in the space-time man-

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ifold (as described in Section 2) will be considered. We will also show that trace free gravitational equations can be naturally obtained when the Lagrangian function (geometrical action) is taken as a measure involving a particular combination of the fundamental tensors of the geometry:

$$\sqrt{\left|\det f\left(\mathsf{g}_{\mu\nu},f_{\mu\nu},\mathsf{R}_{\mu\nu}\right)\right|}$$

with the (0, 2) tensors $g_{\mu\nu}$, $f_{\mu\nu}$, $R_{\mu\nu}$: the symmetric metric, the antisymmetric one (that acts as potential of the torsion field) and the generalized Ricci tensor (proper of the non-Riemannian geometry). The three tensors are related with a Clifford structure of the tangent space (for details see Cirilo-Lombardo, 2015) where the explicit choice for $f(g_{\mu\nu}, f_{\mu\nu}, R_{\mu\nu})$ is given in Section 3. This type of Lagrangians, because are non-Riemannian generalizations of the well known Nambu–Goto and Born–Infeld (BI) ones, can be physically and geometrically analyzed. Due the pure geometrical structure of the theory, induced energy momentum tensors and fundamental constants (actually functions) *emerge* naturally. Consequently, this fact allows the physical realization of the Mach principle that is briefly treated in Section 8 after the (trace free) dynamic equations in Section 4 are obtained.

In Section 5 the trace free gravitational equations and the meaning of the cosmological term as integration constant are discussed from the physical point of view, meanwhile in Section 6 the constancy of G (Newton constant) is similarly discussed. The important role played by the dual of the torsion field as geometrical energy-momentum tensor is given in Section 7. Some physical consequences of the model, as the geometrical origin of the $\alpha \Omega$ -dynamo, is presented in Section 9 that it is very important because establish the link between the mathematical structure of the model of the first part of the article and the physics of the early universe and the particle physics of the second half of this work. In Section 10 the direct relation between the torsion with axion electrodynamics and Chern-Simons (CS) theory is discussed considering the geometrical structure of the dual vector of the torsion field. In Section 11 an explanation about the magnetogenesis in FRW scenario, the structure of the GUT where the SM is derived and the role of the axion in the dynamics of the cosmic magnetic field is presented. Finally some concluding remarks are given in Section 11.

2. Basis of the metrical-affine geometry

The starting point is a hypercomplex construction of the (metric compatible) spacetime manifold (Cirilo-Lombardo, 2015; McInnes, 1984)

$$M, g_{\mu\nu} \equiv e_{\mu} \cdot e_{\nu} \tag{1}$$

where for each point $p \in M$ there exists a local affine space A. The connection over A, $\widetilde{\Gamma}$, define a generalized affine connection Γ on M, specified by (∇, K) , where K is an invertible (1, 1) tensor over M. We will demand for the connection to be compatible and rectilinear, that is

$$\nabla K = KT, \qquad \nabla g = 0 \tag{2}$$

where *T* is the torsion, and *g* the space-time metric (used to raise and lower the indices and determining the geodesics), that is preserved under parallel transport. This generalized compatibility condition ensures that the generalized affine connection Γ maps autoparallels of Γ on *M* into straight lines over the affine space *A* (locally). The first equation above is equal to the condition determining the connection in terms of the fundamental field in the *UFT* non-symmetric. Hence, *K* can be identified with the fundamental tensor in the non-symmetric fundamental theory.

This fact gives us the possibility to restrict the connection to a (anti-)Hermitian theory.

The covariant derivative of a vector with respect to the generalized affine connection is given by

$$A^{\mu}{}_{;\nu} \equiv A^{\mu}{}_{,\nu} + \Gamma^{\mu}{}_{\alpha\nu}A^{\alpha} \tag{3}$$

$$A_{\mu;\nu} \equiv A_{\mu} ,_{\nu} - \Gamma^{\alpha}_{\ \mu\nu} A_{\alpha} \tag{4}$$

The generalized compatibility condition (2) determines the 64 components of the connection by the 64 equations

$$K^{\mu}_{\nu;\alpha} = K^{\mu}_{\rho} T^{\rho}_{\ \nu\alpha} \quad \text{where} \quad T^{\rho}_{\ \nu\alpha} \equiv 2\Gamma^{\rho}_{\ [\alpha\nu]} \tag{5}$$

Notice that by contracting indices ν and α in the first equation above, an additional condition over this hypothetical fundamental (nonsymmetric) tensor *K* is obtained

$$K_{\mu\alpha}^{\alpha} = 0$$

that, geometrically speaking, reads

 $d^*K=0.$

This is a current-free condition over the tensor *K*. Notice that the metric is used here to down the indices (metric compatible space-time) and consequently we can work also with $K_{\alpha\nu} = g_{\alpha\beta}K_{\nu}^{\beta}$.

The metric is uniquely determined by the metricity condition, which puts 40 restrictions on the derivatives of the metric

$$g_{\mu\nu,\rho} = 2\Gamma_{(\mu\nu)\rho} \tag{6}$$

The space–time curvature tensor, that is defined in the usual way, has two possible contractions: the Ricci tensor $R^{\lambda}_{\mu\lambda\nu} = R_{\mu\nu}$, and the second contraction $R^{\lambda}_{\lambda\mu\nu} = 2\Gamma^{\lambda}_{\lambda[\nu,\mu]}$, which is identically zero due to the metricity condition (2).

In order to find a symmetry of the torsion tensor, let us denote the inverse of K by \hat{K} . Therefore, \hat{K} is uniquely specified by condition $\hat{K}^{\alpha\rho} K_{\alpha\sigma} = K^{\alpha\rho} \hat{K}_{\alpha\sigma} = \delta^{\rho}_{\sigma}$.

As it was pointed out in Cirilo-Lombardo (2010, 2011a, 2011b, 2007, 2013), inserting explicitly the torsion tensor as the antisymmetric part of the connection in (5), and multiplying by $\frac{1}{2}\hat{K}^{\alpha\nu}$, results, after straightforward computations, in

$$\left(Ln\sqrt{-K}\right), \mu - \Gamma^{\nu}_{(\mu\nu)} = 0 \tag{7}$$

where $K = \det (K_{\mu\rho})$. Notice that from expression (7) we arrive at the relation between the determinants *K* and *g*:

$$\frac{\kappa}{g} = \text{constant}$$

(strictly a constant scalar function of the coordinates). Now we can write

$$\Gamma^{\nu}_{\ \alpha\nu,\beta} - \Gamma^{\nu}_{\ \beta\nu,\alpha} = \Gamma^{\nu}_{\ \nu\beta,\alpha} - \Gamma^{\nu}_{\ \nu\alpha,\beta} \,, \tag{8}$$

as the first term of (7) is the derivative of a scalar. Then, the torsion tensor has the symmetry

$$T^{\nu}_{\nu[\beta,\alpha]} = T^{\nu}_{\nu[\alpha,\beta]} = 0 \tag{9}$$

This implies that the trace of the torsion tensor, defined as $T^{\nu}_{\ \nu\alpha}$, is the gradient of a scalar field

$$T_{\alpha} = \nabla_{\alpha}\phi \tag{10}$$

In McInnes (1984) an interesting geometrical analysis is presented of non-symmetric field structures. There, expressions precisely as (1) and (2) ensure that the basic non-symmetric field structures (*i.e. K*) take on a definite geometrical meaning when interpreted in terms of affine geometry. Notice that the tensor K carries the 2-form (bivector) that will be associated with the fundamental antisymmetric form in the next sections. Such antisymmetric form is introduced from the tangent space via the generalization of the Ambrose–Singer theorem by exponentiation.

3. Geometrical Lagrangians: the generalized Born-Infeld action

Let us start with the geometrical Lagrangian introduced in Cirilo-Lombardo (2010, 2011a, 2011b, 2007, 2013)

$$\mathcal{L}_{g} = \sqrt{\det\left[\lambda\left(g_{\alpha\beta} + F_{\alpha\beta}\right) + R_{\alpha\beta}\right]} \tag{11}$$

it can be rewritten as

$$\mathcal{L}_{g} = \sqrt{\det\left(G_{\alpha\beta} + \mathcal{F}_{\alpha\beta}\right)} \tag{12}$$

with the following redefinitions

$$G_{\alpha\beta} = \lambda g_{\alpha\beta} + R_{(\alpha\beta)}$$
 and $\mathcal{F}_{\alpha\beta} = \lambda F_{\alpha\beta} + R_{[\alpha\beta]}$ (13)

where a totally antisymmetric torsion tensor $T^{\alpha}_{\gamma\beta} = \varepsilon^{\alpha}_{\gamma\beta\delta}h^{\delta}$ is assumed (h^{δ} its dual vector field). Notice that the antisymmetric tensor $F_{\alpha\beta}$, that takes the role of the electromagnetic field, is proportional to the dual of the potential for the (totally antisymmetric) torsion field (Cirilo-Lombardo, 2010, 2011a, 2011b, 2007, 2013). A brief review on the origin of this type of Lagrangians in the context of unified theories in reductive geometries is in Appendix A. Consequently the generalized Ricci tensor splits into a symmetric and antisymmetric part, namely:

$$R_{\mu\nu} = \overbrace{\mathring{R}_{\mu\nu} - T_{\mu\rho}}^{R_{(\mu\nu)}} T_{\alpha\nu}^{\ \rho} + \overbrace{\nabla_{\alpha}T_{\mu\nu}}^{R_{[\mu\nu]}}$$

where $\tilde{R}_{\mu\nu}$ is the general relativistic Ricci tensor constructed with the Christoffel connection. The expansion of the determinant leads to the Born–Infeld generalization in the usual form:

$$\mathcal{L}_{g} = \sqrt{|G|} \sqrt{1 + \frac{1}{2} \mathcal{F}_{\mu\nu} \mathcal{F}^{\mu\nu} - \frac{1}{16} \left(\mathcal{F}_{\mu\nu} \widetilde{\mathcal{F}}^{\mu\nu} \right)^{2}}$$
(14)

$$=\Lambda^{2}\sqrt{|g|}\sqrt{1+\frac{1}{2}\Lambda_{1}^{2}F_{\mu\nu}F^{\mu\nu}-\frac{1}{16b^{4}}\left(\Lambda_{2}^{2}F_{\mu\nu}\widetilde{F}^{\mu\nu}\right)^{2}}$$
(15)

where

$$\Lambda = \lambda + \frac{g_{\alpha\beta} R^{(\alpha\beta)}}{4} \tag{16}$$

$$\Lambda_1^2 = \lambda^2 \left(1 + \frac{2}{\lambda} \frac{F_{\mu\nu} R^{[\mu\nu]}}{F_{\mu\nu} F^{\mu\nu}} + \frac{1}{\lambda^2} \frac{R_{[\mu\nu]} R^{[\mu\nu]}}{F_{\mu\nu} F^{\mu\nu}} \right)$$
(17)

$$\Lambda_2^2 = \lambda^2 \left(1 + \frac{2}{\lambda} \frac{F_{\mu\nu} \widetilde{R}^{[\mu\nu]}}{F_{\mu\nu} \widetilde{F}^{\mu\nu}} + \frac{1}{\lambda^2} \frac{R_{[\mu\nu]} \widetilde{R}^{[\mu\nu]}}{F_{\mu\nu} \widetilde{F}^{\mu\nu}} \right)$$
(18)

Although the action is exact and have the correct limit, the analysis can be simplest and substantially improved using the following action

$$\mathcal{L}_{gs} = \sqrt{\det\left[\lambda g_{\alpha\beta}\left(1 + \frac{R_s}{4\lambda}\right) + \lambda F_{\alpha\beta}\left(1 + \frac{R_A}{\lambda}\right)\right]}$$
(19)

$$R_{s} \equiv g^{\alpha\beta} R_{(\alpha\beta)}; \qquad R_{A} \equiv f^{\alpha\beta} R_{[\alpha\beta]}$$
(20)

(with $f^{\alpha\beta} \equiv \frac{\partial \ln(\det F_{\mu\nu})}{\partial F_{\alpha\beta}}$, det $F_{\mu\nu} = 2F_{\mu\nu}\widetilde{F}^{\mu\nu}$) that contains all necessary information and is more suitable to manage. If the induced structure from the tangent space $T_p(M)$ (via Ambrose–Singer theorem) is intrinsically related to a (super)manifold structure, we have seen that there exists a transformation (Weyl, 1952; Cirilo-Lombardo, 2015) $U_A^B(P) = \delta_A^B + \mathcal{R}_{A\mu\nu}^B dx^{\mu} \wedge dx^{\nu} \rightarrow \delta_A^B + \omega^k (\mathcal{T}_k)_A^B$ (with A, B.... generally a multi-index) having the same form as the blocks inside of the square root proposed Lagrangian (19): e.g. $\lambda g_{\alpha\beta} \left(1 + \frac{R_s}{4\lambda}\right) \sim$ where the Poisson structure is evident

(as the dual of the Lie algebra of the group manifold) in our case leading the identification between the group structure of the tangent space with the space-time curvature as $\mathcal{R}^B_{A\mu\nu}dx^{\mu} \wedge dx^{\nu} \equiv \omega^k (\mathcal{T}_k)^B_A$.

4. Field equations

The geometry of the space-time manifold is to be determined by the Noether symmetries

$$\frac{\delta L_G}{\delta g^{\mu\nu}} = 0, \quad \frac{\delta L_G}{\delta f^{\mu\nu}} = 0 \tag{21}$$

where the functional (Hamiltonian) derivatives in the sense of Palatini (in this case with respect to the potentials), are understood. The choice "measure-like" form for the geometrical Lagrangian L_G (reminiscent of a nonlinear sigma model), as is evident, satisfy the following principles:

i) the principle of the natural extension of the Lagrangian density as square root of the fundamental line element containing also $F_{\mu\nu}$;

ii) the symmetry principle between $g_{\mu\nu}$ and $F_{\mu\nu}$ (e.g. $g_{\mu\nu}$ and $F_{\mu\nu}$ should enter into L_G symmetrically);

iii) the principle that the spinor symmetry, namely

$$\nabla_{\mu}g_{\lambda\nu} = 0, \tag{22}$$

$$\nabla_{\mu}\sigma_{\lambda\nu} = 0 \tag{23}$$

with

$$\mathbf{g}_{\lambda\nu} = \gamma_{\lambda} \cdot \gamma_{\nu},\tag{24}$$

$$\sigma_{\lambda\nu} = \gamma_{\lambda} \wedge \gamma_{\nu} \sim *F_{\lambda\nu} \tag{25}$$

should be derivable from L_G (21).

The last principle is key because it states that the spinor invariance of the fundamental space-time structure should be derivable from the dynamic symmetries given by (21). The fact that the L_G satisfies the 3 principles shows also that it has the simpler form (Xin, 1996).

Notice that the action density proposed by Einstein (2014) in his nonsymmetric field theory satisfies i) and ii) but not iii).

Remark 1. Due the totally antisymmetric character of the torsion field it is completely determined by the fundamental (structural 2-form) antisymmetric tensor, and consequently the variations must acquire the form given by expression (21): metric and torsion have each one their respective potentials that are in coincidence with the fundamental structure of the geometry.

4.1.
$$\delta_g L_G$$

The starting point for the metrical variational procedure is in the same way as in the standard Born–Infeld theory: from the following factorization of the geometrical Lagrangian:

$$\mathcal{L} = \sqrt{|g|} \sqrt{\det(\alpha\lambda)} \sqrt{1 + \frac{1}{2b^2} F_{\mu\nu} F^{\mu\nu} - \frac{1}{16b^4} \left(F_{\mu\nu} \widetilde{F}^{\mu\nu}\right)^2} \equiv \sqrt{|g|} \sqrt{\det(\alpha\lambda)} \mathbb{R}$$
(26)

where

$$b = \frac{\alpha}{\beta} = \frac{1 + (R_S/4\lambda)}{1 + (R_A/4\lambda)},\tag{27}$$

$$R_S = g^{\alpha\beta} R_{\alpha\beta}, \tag{28}$$

$$R_A = f^{\alpha\beta} R_{\alpha\beta},\tag{29}$$

(31)

and λ an arbitrary constant we perform the variational metric procedure with the following result (details see Appendix B)

$$\delta_g \mathcal{L} = 0 \Rightarrow \tag{30}$$

$$\begin{aligned} &= \frac{R_s}{2\mathbb{R}^2 \alpha^2} \left[F_{\alpha\lambda} F_{\beta}^{\lambda} - F_{\mu\nu} F^{\mu\nu} \frac{R_{(\alpha\beta)}}{R_s} \right] + \\ &+ \frac{R_s}{4\mathbb{R}^2 \alpha^2 b^2} \left[F_{\mu\nu} \widetilde{F}^{\mu\nu} \left(\frac{F_{\eta\rho} \widetilde{F}^{\eta\rho}}{8} g_{\alpha\beta} - F_{\alpha\lambda} \widetilde{F}_{\beta}^{\lambda} \right) \right. \\ &+ \frac{F_{\eta\rho} \widetilde{F}^{\eta\rho}}{2} \frac{R_{(\alpha\beta)}}{R_s} \right] + \\ &+ 2\lambda \left[g_{\alpha\beta} + \frac{1}{\mathbb{R}^2 \alpha^2} \left(F_{\alpha\lambda} F_{\beta}^{\lambda} \right. \\ &+ \frac{F_{\mu\nu} \widetilde{F}^{\mu\nu}}{2b^2} \left(\frac{F_{\eta\rho} \widetilde{F}^{\eta\rho}}{8} g_{\alpha\beta} - F_{\alpha\lambda} \widetilde{F}_{\beta}^{\lambda} \right) \right) \right]. \end{aligned}$$

Remark 2. Notice that:

1) The eq. (31) is trace-free type, consequently the trace of the third term of the above equation (that is the cosmological one) is equal to zero. This happens trivially if $\lambda = 0$ or $4\mathbb{R}^2\alpha^2 =$ $-\left(F_{\alpha\lambda}F^{\alpha\lambda}-\frac{(F_{\mu\nu}\widetilde{F}^{\mu\nu})^2}{4b^2}\right)$. In terms of the Maxwell Lagrangian we have $(\mathbb{R}\alpha)^2 = \left(L_{Maxwell} + \frac{(F_{\mu\nu}\tilde{F}^{\mu\nu})^2}{16b^2}\right) \equiv \mathcal{W}(I_S, I_P, b)$ that allow us to simplify the eq. (31) once more as follows

$$\begin{split} R_{(\alpha\beta)} &- \frac{g_{\alpha\beta}}{4} R_{s} \\ &= \frac{R_{s}}{2W} \bigg[F_{\alpha\lambda} F_{\beta}^{\lambda} - F_{\mu\nu} F^{\mu\nu} \frac{R_{(\alpha\beta)}}{R_{s}} \bigg] + \\ &+ \frac{R_{s}}{4Wb^{2}} \bigg[F_{\mu\nu} \widetilde{F}^{\mu\nu} \left(\frac{F_{\eta\rho} \widetilde{F}^{\eta\rho}}{8} g_{\alpha\beta} - F_{\alpha\lambda} \widetilde{F}_{\beta}^{\lambda} \right) \\ &+ \frac{F_{\eta\rho} \widetilde{F}^{\eta\rho}}{2} \frac{R_{(\alpha\beta)}}{R_{s}} \bigg] + \\ &+ 2\lambda \bigg[g_{\alpha\beta} + \frac{1}{W} \left(F_{\alpha\lambda} F_{\beta}^{\lambda} \\ &+ \frac{F_{\mu\nu} \widetilde{F}^{\mu\nu}}{2b^{2}} \left(\frac{F_{\eta\rho} \widetilde{F}^{\eta\rho}}{8} g_{\alpha\beta} - F_{\alpha\lambda} \widetilde{F}_{\beta}^{\lambda} \right) \bigg) \bigg], \end{split}$$

2) *b* takes the place of limiting parameter (maximum value) for the electromagnetic field strength.

3) b is not a constant in general, in sharp contrast with the Born-Infeld or string theory cases.

4) Because *b* is the ratio $\frac{\alpha}{\beta} = \frac{1+(R_S/4\lambda)}{1+(R_A/\lambda4)}$ involving both curvature scalars from the contractions of the generalized Ricci tensor: it is preponderant when the symmetrical contraction of $R_{\alpha\beta}$ is greater than the skew one.

5) The fact pointed out in ii), namely that the curvature scalar plays the role as some limiting parameter of the field strength, was conjectured by Mansouri (1976) in the context of gravity theory over group manifold (generally with symmetry breaking). In such a case, this limit was established after the explicit integration of the internal group-valuated variables that is not our case here.

6) In similar form that the Eddington conjecture: $R_{(\alpha\beta)} \propto g_{\alpha\beta}$, we have a condition over the ratios as follows:

$$\frac{R_{(\alpha\beta)}}{R_s} \propto \frac{g_{\alpha\beta}}{D}$$
(32)

that seems to be universal.

7) The equations are the simplest ones when $b^{-2} = 0$ ($\beta = 0$), taking the exact "quasilinear" form

$$R_{(\alpha\beta)} - \frac{g_{\alpha\beta}}{4}R_{s} = \underbrace{\frac{R_{s}}{2\alpha^{2}} \left[F_{\alpha\lambda}F_{\beta}^{\lambda} - F_{\mu\nu}F^{\mu\nu}\frac{R_{(\alpha\beta)}}{R_{s}}\right]}_{\text{Maxwell-like}} + 2\lambda \underbrace{\left[g_{\alpha\beta} + \frac{1}{\mathcal{W}}F_{\alpha\lambda}F_{\beta}^{\lambda}\right]}_{\widetilde{g}_{eff}},$$
(33)

this particular case (e.g. projective invariant) will be used through this work. Notice that when $b^{-2} = 0$ ($\beta = 0$) all terms into the gravitational equation (31) involving the pseudoscalar invariant, namely $F_{\mu\nu}\tilde{F}^{\mu\nu}$ or $F_{\alpha\lambda}\tilde{F}^{\lambda}_{\beta}$, vanishes. Consequently we arrive to the simplest expression (33) that will be used in Section 11 for example.

4.2. $\delta_f L_G$

Let us to take as starting point the geometrical Lagrangian (19)

$$\mathcal{L}_{gs} = \sqrt{\det\left[\lambda g_{\alpha\beta}\left(1 + \frac{R_s}{4\lambda}\right) + \lambda F_{\alpha\beta}\left(1 + \frac{R_A}{4\lambda}\right)\right]} \tag{34}$$

$$=\sqrt{|g|}\lambda^{2}\alpha^{2}\left(\sqrt{1+\frac{1}{2}}\mathcal{F}_{\mu\nu}\mathcal{F}^{\mu\nu}-\frac{1}{16}\left(\mathcal{F}_{\mu\nu}\widetilde{\mathcal{F}}^{\mu\nu}\right)^{2}\right)$$
(35)

then, having into account that: $R_A = f^{\mu\nu}R_{\mu\nu}$ and $\frac{\partial \ln(\det F_{\mu\nu})}{\partial F_{\alpha\beta}} =$ $f^{\alpha\beta}$ (due that b that contains R_A must be also included in the variation) we obtain

$$\frac{\delta L_G}{\delta F_{\sigma\omega}} = 0 \to \left(\frac{\sqrt{|\mathbf{g}|\lambda\beta}}{2\mathbb{R}b}\right) \left[\mathbb{F}^{\sigma\omega}\beta - \frac{\mathbb{F}}{4\lambda}R_{[\mu\nu]}\chi^{\mu\nu\sigma\omega}\right] = 0 \quad (36)$$

where:

$$\mathbb{F} \equiv \left[F_{\mu\nu}F^{\mu\nu} - \frac{1}{4}b^{-2} \left(F_{\mu\nu}\widetilde{F}^{\mu\nu}\right)^2 \right],$$
$$\mathbb{F}^{\sigma\alpha} \equiv \left[F^{\sigma\alpha} - \frac{1}{4}b^{-2} \left(F_{\mu\nu}\widetilde{F}^{\mu\nu}\right)\widetilde{F}^{\sigma\alpha} \right]$$

and

$$\chi^{\mu\nu\sigma\omega} \equiv f^{\mu\omega} f^{\sigma\nu} - f^{\mu\sigma} f^{\omega\nu}$$

Notice that the quantity $b = \alpha / \beta$ (concretely β) was also varied in the above expression given the second term in (36).

Contracting (36) with $F_{\alpha\beta}$, a condition over the curvature and the electromagnetic field invariants is obtained as

$$\left(\frac{\sqrt{|g|}\lambda\beta}{\mathbb{R}b}\right)\mathbb{F}\left[\beta-\frac{R_A}{2\lambda}\right]=0$$

This condition is satisfied for $R_A = -4\lambda$ is the exact projective invariant case (that correspond with $\beta = 0$), and for $R_A = 2\lambda$.

Remark 3. The variational equation (36) is a dynamic equation for the torsion field in complete analogy with the eqs. (31) for the curvature.

5. Emergent trace free gravitational equations: the meaning of Λ

Starting from the trace free equation (31) that is not assumed but arises from the model, the task (Ellis, 2014) is to rewrite it as

л

$$\underbrace{\overset{\circ}{R}_{\alpha\beta} - \frac{g_{\alpha\beta}}{2}\overset{\circ}{R}}_{\equiv G_{\alpha\beta}} = \underbrace{6\left(-h_{\alpha}h_{\beta} + \frac{g_{\alpha\beta}}{2}h_{\gamma}h^{\gamma}\right)}_{\equiv T^{h}_{\alpha\beta}} + \frac{g_{\alpha\beta}}{2}R_{s} + T^{F}_{\alpha\beta} + 2\lambda\rho_{\alpha\beta}$$
(37)

where

$$\rho_{\alpha\beta} \equiv g_{\alpha\beta} + \frac{1}{\mathcal{W}} \left(F_{\alpha\lambda} F_{\beta}^{\lambda} + \frac{F_{\mu\nu} \widetilde{F}^{\mu\nu}}{2b^2} \left(\frac{F_{\eta\rho} \widetilde{F}^{\eta\rho}}{8} g_{\alpha\beta} - F_{\alpha\lambda} \widetilde{F}_{\beta}^{\lambda} \right) \right)$$
(38)

$$T_{\alpha\beta}^{F} \equiv \frac{R_{s}}{2W} \left\{ \left(F_{\alpha\lambda}F_{\beta}^{\lambda} - F_{\mu\nu}F^{\mu\nu}\frac{R_{(\alpha\beta)}}{R_{s}} \right) + \frac{1}{2b^{2}} \left[F_{\mu\nu}\widetilde{F}^{\mu\nu}\left(\frac{F_{\eta\rho}\widetilde{F}^{\eta\rho}}{8}g_{\alpha\beta} - F_{\alpha\lambda}\widetilde{F}_{\beta}^{\lambda}\right) + \frac{\left(F_{\eta\rho}\widetilde{F}^{\eta\rho}\right)^{2}}{2}\frac{R_{(\alpha\beta)}}{R_{s}} \right] \right\}$$
(39)

the LHS of (37) is the Einstein tensor. The "GR" divergence ∇ of $G_{\alpha\beta}$ is zero because is a geometrical identity and in an analog manner $\nabla^{\alpha} \left(T^{h}_{\alpha\beta} + T^{F}_{\alpha\beta}\right) = 0$ because both tensors have the same symmetry that the corresponding GR energy momentum tensors of a vector field and electromagnetic field respectively:

$$\overset{\circ}{\nabla}^{\alpha}G_{\alpha\beta} = \overset{\circ}{\nabla}^{\alpha}\left(T^{h}_{\alpha\beta} + T^{F}_{\alpha\beta}\right) = 0$$

consequently the remaining part must be a covariantly constant tensor that we *assume* proportional to $g_{\alpha\beta}$:

$$\nabla^{\alpha} \left(\frac{g_{\alpha\beta}}{2} R_{s} + 2\lambda \rho_{\alpha\beta} \right) = 0$$

$$\Rightarrow \left(\frac{g_{\alpha\beta}}{2} R_{s} + 2\lambda \rho_{\alpha\beta} \right) = \Lambda g_{\alpha\beta} \to R_{s} = 2\Lambda$$
(40)

Coming back to the original trace free expressions we have the expected formula

$$\underbrace{\overset{\circ}{R}_{\alpha\beta} - \frac{g_{\alpha\beta}}{2}\overset{\circ}{R}}_{\equiv G_{\alpha\beta}} = \underbrace{6\left(-h_{\alpha}h_{\beta} + \frac{g_{\alpha\beta}}{2}h_{\gamma}h^{\gamma}\right)}_{\equiv T^{h}_{\alpha\beta}} + T^{F}_{\alpha\beta} + \Lambda g_{\alpha\beta} \qquad (41)$$

Remark 4. Tracing the first expression in (40) we have $R_s = 2\Lambda = \overset{\circ}{R} + 6h_{\mu}h^{\mu}$ linking the value of the curvature and the norm of the torsion vector field. Consequently, if the dual of the torsion field have the role of the energy–matter carrier, the meaning of lambda as the vacuum energy is immediately established.

Remark 5. Notice that the LHS in expression (40) instead to be proportional to the metric tensor it can be proportional to the square of a Killing–Yano tensor.

6. On the constancy of G

At this level, no assertion can state with respect to *G* or even with respect to *c*. The link with the general relativistic case is given by the identification of electromagnetic energy–momentum tensor with the term analogous $T_{\alpha\beta}^F$ in our metric variational equations:

$$\frac{8\pi G}{c^4} \left(F_{\alpha\lambda} F_{\beta}^{\lambda} - F_{\mu\nu} F^{\mu\nu} \frac{g_{\alpha\beta}}{4} \right) \rightarrow \frac{R_s}{2W} \left(F_{\alpha\lambda} F_{\beta}^{\lambda} - F_{\mu\nu} F^{\mu\nu} \frac{R_{(\alpha\beta)}}{R_s} \right)$$

Consequently we have:

$$\kappa = \frac{8\pi G}{c^4} \to \frac{R_s}{2\mathbb{R}^2 \alpha^2} \quad \text{and}$$
$$\frac{g_{\alpha\beta}}{4} = \frac{R_{(\alpha\beta)}}{R_s}$$

The above expression indicates that the ratio must remains constant due the Noether symmetries and conservation laws of the field equations. Notice that (as in the case of *b*) there exists a limit for all the physical fields coming from the *geometrical invariants quantities*.

7. The vector h_{μ} and the energy–matter interpretation

One of the characteristics that more attract the attention in unified field theoretical models is the possibility to introduce the energy and matter through its geometrical structure. In our case the torsion field takes the role of RHS of the standard GR gravity equation by mean its dual, namely h_{μ} .

Consequently, in order to explain the physical role of h_{μ} , we know (due the Hodge–de Rham decomposition [Appendix C]) that it can be decomposed as:

$$h_{\alpha} = \nabla_{\alpha} \Omega + \varepsilon_{\alpha}^{\beta\gamma\delta} \nabla_{\beta} A_{\gamma\delta} + \gamma_1 \varepsilon_{\alpha}^{\beta\gamma\delta} M_{\beta\gamma\delta} + \gamma_2 \overbrace{P_{\alpha}}^{\text{polar vector}}$$
(42)

where γ_1 and γ_2 can be phenomenologically related to physical constants (e.g.: $\gamma_1 = \frac{8\pi}{c}\sqrt{G}$ is a physical constant related to the Blackett formula, Blackett, 1947). The arguments in favor of this type of theories and from the decomposition (42) can be resumed as follows:

i) the existence of an angular momentum Helmholtz theorem (Helmholtz, 1858, 1867): the theorem in analysis is exactly as in E_3 but, in the four dimensional case M_4 there exists an additional *axial vector*;

ii) the concept of *chirality* is achieved in the model by the existence of polar and axial vectors in expression (42).

iii) if Ω , $A_{\gamma\delta}$ are the wave tensors and $\varepsilon_{\alpha}^{\beta\gamma\delta}M_{\beta\gamma\delta}$, P_{α} the particle vectors (vector and axial part respectively), the concept of an inertial-wave vector is introduced in the equation (42).

Consequently, from the (36) with $\beta = 0$ for the torsion namely: $\nabla_{\alpha} T^{\alpha\beta\gamma} = -\lambda F^{\beta\gamma}$ and coming back to (42) we obtain the following important equation

$$\overset{\circ}{\Box}A_{\gamma\delta} - \gamma \left[\nabla_{\alpha}M^{\alpha}_{\ \gamma\delta} + \left(\nabla_{\gamma}P_{\delta} - \nabla_{\delta}P_{\gamma} \right) \right] = -\lambda F_{\gamma\delta}$$
(43)

Let us consider, in particular, the case when $\lambda F_{\gamma\delta} \rightarrow 0$:

$$\overset{\circ}{\Box}A_{\gamma\delta} = \gamma \left[\nabla_{\alpha} M^{\alpha}_{\ \gamma\delta} + \left(\nabla_{\gamma} P_{\delta} - \nabla_{\delta} P_{\gamma} \right) \right]$$
(44)

We can immediately see that, if $M^{\alpha}_{\gamma\delta}$ is identified with the intrinsic spin angular momentum of the ponderable matter, P_{δ} is its lineal momentum vector and $A_{\gamma\delta}$ is the gravitational radiation tensor, then eq. (44) states that the sum of the intrinsic spin angular momentum and the orbital angular momentum of ponderable matter is conserved if the gravitational radiation is absent., if $M^{\alpha}_{\gamma\delta}$ is identified with the intrinsic spin angular momentum of the ponderable matter, P_{δ} is its lineal momentum vector and $A_{\gamma\delta}$ is the gravitational radiation tensor, then eq. (44) states that the sum of the intrinsic spin angular momentum and the orbital angular momentum of ponderable matter is conserved if the gravitational radiation is absent.

7.1. Killing–Yano systems and the vector h_{μ}

Without enter in many details (these will be treated somewhere) the antisymmetric tensor $A_{\gamma\delta}$ in the h_{β} composition is related with the Killing (Carter, 1968) and Killing–Yano (Yano, 1952) systems. Consequently we can introduce two types of couplings into the $A_{\gamma\delta}$ divergence: it correspond with the generalized current interpretation that also has h_{μ} .

$$A_{\gamma\delta} \equiv A_{[\gamma;\delta]} \tag{45}$$

such that

i) Defining

$$\overset{\circ}{\nabla}_{\rho} A_{[\gamma;\delta]} = \frac{4\pi}{3} \left(j_{[\gamma} g_{\delta]\rho} \right)$$
(46)

then, in this case we can identify $A_{\gamma\delta} = 2F_{\gamma\delta}$ because $F_{\gamma;\delta}^{\delta} = 4j_{\gamma}$ and $A_{[\gamma\delta;\rho]} = F_{[\gamma\delta;\rho]} = 0$.

In this case the contribution of $A_{\gamma\delta}$ to h_{β} is null.

ii) Let us consider now a fully antisymmetric coupling as

$$A_{[\gamma;\delta];\rho} = \frac{4\pi}{3} j_{[\gamma} F_{\delta]\rho}$$
(47)

having into account the vorticity vector also

$$\omega_{\mu} \equiv u^{\lambda} \varepsilon_{\lambda \mu \nu \rho} \nabla^{\nu} u^{\rho} \tag{48}$$

and considering a plasma with electrons, protons etc.

$$j^{\gamma} \sim A^{\gamma} + q_s n_s u_s^{\gamma} \tag{49}$$

where A_{μ} is the vector potential and q_s is the particle charge, n_s is the number density (in the rest frame) and the four-velocity of species *s* is u_s^{γ} . In this case h_{α} takes the form

$$h_{\alpha} = \nabla_{\alpha} \Omega + \varepsilon_{\alpha}^{\beta\gamma\delta} \nabla_{\beta} A_{\gamma\delta} + \gamma_1 \varepsilon_{\alpha}^{\beta\gamma\delta} M_{\beta\gamma\delta} + \gamma_2 P_{\alpha} \to$$
(50)

$$h_{\alpha} = \nabla_{\alpha} \Omega + \varepsilon_{\alpha}^{\gamma \delta \rho} \frac{4\mu}{3} j_{[\gamma} F_{\delta]\rho} - \gamma_1 u^{\lambda} \varepsilon_{\lambda \alpha \nu \rho} \nabla^{\nu} u^{\rho} + \gamma_2 P_{\alpha}$$
(51)

$$h_{\alpha} = \nabla_{\alpha} \Omega + \varepsilon_{\alpha}^{\gamma \delta \rho} \frac{4\pi}{3} [A + q_s n_s u_s]_{[\gamma} F_{\delta]\rho}$$
(52)

 $-\gamma_1 u^{\lambda} \varepsilon_{\lambda\alpha\nu\rho} \nabla^{\nu} u^{\rho} + \gamma_2 P_{\alpha}$ Consequently in 3 + 1 decomposition we have (overbar correspond to spacial 3-dim. vectors)

$$h_0 = \nabla_0 \Omega + \frac{4\pi}{3} \overline{j} \cdot \overline{B} + \gamma_1 \overline{u} \cdot \left(\overline{\nabla} \times \overline{u}\right) + \gamma_2 P_0$$
(53)

$$h_{0} = \nabla_{0}\Omega + \frac{4\pi}{3} \left[\overline{A} \cdot \left(\overline{\nabla} \times \overline{A} \right) + q_{s} n_{s} \overline{u}_{s} \cdot \overline{B} \right]$$

$$+ \gamma_{1} \overline{u} \cdot \left(\overline{\nabla} \times \overline{u} \right) + \gamma_{2} P_{0}$$
(54)

and

$$h_{i} = \nabla_{i}\Omega + \frac{4\pi}{3} \left[-\left(\overline{j} \times \overline{E}\right)_{i} + j_{0}\overline{B}_{i} \right]$$

$$+ \gamma_{1} \left[u_{0} \left(\overline{\nabla} \times \overline{u} \right) + \left(\overline{u} \times \overline{\nabla} u_{0} \right) + \left(\overline{u} \times \overline{u} \right) \right]_{i} + \gamma_{2}P_{i}$$

$$h_{i} = \nabla_{i}\Omega + \frac{4\pi}{3} \left[-\left(\left(\overline{A} + q_{s}n_{s}\overline{u}_{s} \right) \times \overline{E} \right)_{i} + \left(\Phi + q_{s}n_{s}u_{0s} \right) \overline{B}_{i} \right]$$

$$+ \gamma_{1} \left[u_{0} \left(\overline{\nabla} \times \overline{u} \right) + \left(\overline{u} \times \overline{\nabla} u_{0} \right) + \left(\overline{u} \times \overline{u} \right) \right]_{i} + \gamma_{2}P_{i}$$

$$H_{i} = V_{i} \left[u_{0} \left(\overline{\nabla} \times \overline{u} \right) + \left(\overline{u} \times \overline{\nabla} u_{0} \right) + \left(\overline{u} \times \overline{u} \right) \right]_{i} + \gamma_{2}P_{i}$$

$$H_{i} = V_{i} \left[u_{0} \left(\overline{\nabla} \times \overline{u} \right) + \left(\overline{u} \times \overline{\nabla} u_{0} \right) + \left(\overline{u} \times \overline{u} \right) \right]_{i} + \gamma_{2}P_{i}$$

$$H_{i} = V_{i} \left[u_{0} \left(\overline{\nabla} \times \overline{u} \right) + \left(\overline{u} \times \overline{\nabla} u_{0} \right) + \left(\overline{u} \times \overline{u} \right) \right]_{i} + \gamma_{2}P_{i}$$

Notice that in h_0 we can recognize the magnetic and vortical helicities

$$h_0 = \nabla_0 \Omega + \frac{4\pi}{3} \left[h_M + q_s n_s \overline{u}_s \cdot \overline{B} \right] + \gamma_1 h_V + \gamma_2 P_0 \tag{57}$$

The above expression will be very important in the next sections, in particular to discuss magnetogenesis and particle generation. Notice the important fact that the symmetry of the vorticity can be associated to a 2-form bivector in the context of the notoph field (Ogievetsky and Polubarinov, 1965; Ogievetsky and Polubarinov, 1967; Kalb and Ramond, 1974) theory.

8. Physical consequences

In this section we will make contact with the physical consequences of the model. Firstly we introduce the 3 + 1 splitting for axisymmetric spacetimes that is useful from the physical viewpoint for the analysis of the electrodynamic equations with high degree of nonlinearity, as in our case. Secondly we take the 3 + 1field equations in the in the linear limit where the induction equations (dynamo) are obtained, showing explicitly the important role of the torsion field as the generator of a purely geometric α -term. Thirdly, we derive the geometrical analog of the Lorentz force and the elimination of the electric field from the induction equations. Also, the origin of the seed magnetic field via the geometrical α -term generated by the torsion vector is worked out.

8.1. Electrodynamic structure in 3 + 1

The starting point will be the line element in 3 + 1 splitting (Thorne and Macdonald, 1982; Macdonald and Thorne, 1982) (Appendix D): the 4-dimensional space-time is split into 3-dimensional space and 1-dimensional time to form a foliation of 3-dimensional spacelike hypersurfaces. The metric of the space-time is consequently, given by $ds^2 = -\alpha^2 dt^2 + \gamma_{ij} (dx^i + \beta^i dt) (dx^j + \beta^j dt)$ where γ_{ij} is the metric of the 3-dimensional hypersurface, α is the lapse function, and β^i is the shift function (see Appendix D for details). For any nonlinear Lagrangian, in sharp contrast with the Einstein–Maxwell case, the field equations $d * \mathbb{F} = *\mathbb{J}$ and the Bianchi-geometrical condition dF = 0 (where we have defined the Hodge dual * and $\mathbb{F} = \frac{\partial \mathcal{L}}{\partial F}$) are expressed by the vector fields

$$E, B, \mathbb{E} = \frac{\partial \mathcal{L}}{\partial E}, \mathbb{B} = \frac{\partial \mathcal{L}}{\partial B}$$
(58)

that live into the slice. In our case given by the geometrical Lagrangian \mathcal{L}_g (not be confused with the Lie derivative \mathcal{L}_β !)

$$\nabla \cdot \mathbb{E} = -h \cdot \mathbb{B} + 4\pi \rho_e \tag{59}$$

$$\nabla \cdot B = 0 \tag{60}$$

$$\nabla \times (\alpha E) = -(\partial_t - \mathcal{L}_\beta)B$$

$$= -\partial_0 B + (\beta \cdot \nabla) B - (B \cdot \nabla) \beta \qquad (61)$$

$$\nabla \times (\alpha \mathbb{B}) + h_0 \mathbb{B} - \overline{h} \times \mathbb{E} = -(\partial_t - \mathcal{L}_\beta) \mathbb{E} + 4\pi \alpha j$$
$$= \partial_0 \mathbb{E} - (\beta \cdot \nabla) \mathbb{E} + (\mathbb{E} \cdot \nabla) \beta + 4\pi \alpha j$$
(62)

where h^{μ} is the torsion vector. Notice that, here and the subsequent sections, the overbar indicates 3-dimensional space vectors.

8.2. Dynamo effect and geometrical origin of $\alpha \Omega$ term

In the case of weak field approximation and $(F^{01} \rightarrow E^i, F^{jk} \rightarrow B^i)$ the electromagnetic Maxwell-type equations in 3 + 1 take the form

$$\nabla_{\nu}F^{\nu\mu} = T^{\mu\nu\rho}F_{\nu\rho} = \varepsilon^{\mu\nu\rho}\delta h^{\delta}F_{\nu\rho} \qquad (d^*F = J)$$
(63)

$$\nabla \cdot E = -h \cdot B \tag{64}$$

$$\partial_t \overline{E} - \overline{\nabla} \times \overline{B} = h^0 \overline{B} - \overline{h} \times \overline{E}$$
(65)

and

(66)

(67)

$$\nabla_{\nu}^{*}F^{\nu\mu} = 0 \qquad (dF = 0)$$

$$\overline{\nabla} \cdot \overline{B} = 0$$

$$\partial_t \overline{B} = -\overline{\nabla} \times \overline{E} \tag{68}$$

Putting all together, the set of equations is

$$\overline{\nabla} \cdot \overline{E} + \overline{h} \cdot \overline{B} = \rho_{ext} \tag{69}$$

$$\partial_t E - \nabla \times B = h^0 B - h \times E - \sigma_{ext} \left[E + \overline{\nu} \times B \right]$$
(70)

$$\nabla \cdot B = 0 \tag{71}$$

$$\partial_t \overline{B} = -\overline{\nabla} \times \overline{E} \tag{72}$$

where we have introduced external charge density and current. Following the standard procedure we take the rotational to the second equation above obtaining straightforwardly the modified dynamo equation

$$\overline{\nabla} \times \partial_t \overline{E} + \overline{\nabla}^2 \overline{B} = \overline{\nabla} \times \left(h^0 \overline{B}\right) + \left(\overline{h} \cdot \overline{B} - \rho_{ext}\right) \overline{h} + \left(\overline{\nabla} \cdot \overline{h}\right) \overline{E} - \sigma_{ext} \left[\partial_t \overline{B} + \left(\overline{\nabla} \cdot \overline{\nu}\right) \overline{B}\right]$$
(73)

where the standard identities of the vector calculus plus the first, the third and the fourth equations above have been introduced. Notice that in the case of the standard approximation and (in the spirit of this research) without any external or additional ingredients, we have

$$\overline{\nabla}^2 \overline{B} = h^0 \left(\overline{\nabla} \times \overline{B} \right) + \left(\overline{h} \cdot \overline{B} \right) \overline{h} + \left(\overline{\nabla} \cdot \overline{h} \right) \overline{E}$$
(74)

Here we can see that there exist and α -term with a pure geometrical origin (and not only a turbulent one) that is given by h^0 (the zero component of the dual of the torsion tensor).

8.3. The generalized Lorentz force

An important point in any theory beyond relativity is the concept of force. As is known, general relativity has deficiencies at this point. Now we are going to show that it is possible to derive from our proposal the Lorentz force as follows. From expression (32) the geometrical induced current is recognized

$$\partial_t \overline{E} - \overline{\nabla} \times \overline{B} = h^0 \overline{B} - \overline{h} \times \overline{E} \equiv \overline{J}$$
(75)

$$\overline{J} \times \overline{B} = \left(h^0 \overline{B} - \overline{h} \times \overline{E} - \overline{j}_{ext}\right) \times \overline{B}$$
(76)

$$= -\left[\left(\overline{h} \cdot \overline{B}\right)\overline{E} - \left(\overline{E} \cdot \overline{B}\right)\overline{h}\right] - \overline{j}_{ext} \times \overline{B}$$
(77)

we assume j_{ext} proportional to the velocity and other contributions. Consequently, reordering terms from above, a geometrically induced Lorentz-like force arises

$$\left(\overline{J} + \overline{j}_{ext}\right) \times \overline{B} = -\left[\underbrace{\left(\overline{h} \cdot \overline{B}\right)}_{\rho_{geom}} \overline{E} - \left(\overline{E} \cdot \overline{B}\right) \overline{h}\right] \to \quad (78)$$

 $\underbrace{\left(\overline{h} \cdot \overline{B}\right)}_{\rho_{geom}} \overline{E} + \underbrace{\left(\overline{J} + \overline{j}_{ext}\right)}_{j_{gen}} \times \overline{B} = \left(\overline{E} \cdot \overline{B}\right) \overline{h} \to \text{Lorentz induced force}$

being the responsible of the induced force, the torsion vector itself. Notice, from the above equation, the following issues:

1) The external currents are identified with \overline{J}

2) We can eliminate the electric field in standard form

$$\overline{E} = \frac{(\overline{E} \cdot \overline{B})\overline{h} - \overline{j}_{gen} \times \overline{B}}{(\overline{h} \cdot \overline{B})}$$
(80)

being the above expression very important in order to replace the electric field into the dynamo equation, introducing naturally the external current in the model.

8.4. Generalized current and α -term

In previous paragraph we have derived a geometrical induced Lorentz force where the link between the physical world and the proposed geometrical model is through a generalized current j_{gen} . An important fact of that expression is that it is possible to eliminate the electric field (and insert it into the equation of induction) as follows.

From the formula of the induction, namely

$$\overline{\nabla}^2 \overline{B} + \overline{\nabla} \times \left(-h^0 \overline{B} + \overline{h} \times \overline{E} \right) = 0$$

$$\underbrace{\mathcal{E}_{Geom}}$$
(81)

and using the eq. (49) to eliminate the electric field as function of the torsion, the generalized current and the magnetic field respectively:

$$\overline{h} \times \overline{E} = \frac{-\overline{h} \times \left(\overline{j}_{gen} \times \overline{B}\right)}{\left(\overline{h} \cdot \overline{B}\right)} = -\frac{\left(\overline{h} \cdot \overline{B}\right)\overline{j}_{gen} - \left(\overline{h} \cdot \overline{j}_{gen}\right)\overline{B}}{\left(\overline{h} \cdot \overline{B}\right)}$$
(82)
$$\overline{h} \times \overline{E} = -\overline{j}_{gen} + \frac{\left(\overline{h} \cdot \overline{j}_{gen}\right)}{\left(\overline{h} \cdot \overline{B}\right)}\overline{B} = \left|\overline{j}_{gen}\right| \left(-n_{\overline{j}_{gen}} + \frac{\cos\alpha}{\cos\beta}n_{B}\right)$$
(83)

being α the angle between the vector torsion \overline{h} and the generalized current \overline{j}_{gen} and β the angle between \overline{h} and the magnetic field \overline{B} . Above, n_B and $n_{\overline{j}_{gen}}$ are unitary vectors in the direction of \overline{B} and \overline{j}_{gen} respectively. Notice the important fact that the RHS of (68) is independent of the torsion and the magnetic field. Consequently we obtain

$$\overline{\nabla}^{2}\overline{B} + \overline{\nabla} \times \left[-\overline{j}_{gen} + \left(\frac{\left(\overline{h} \cdot \overline{j}_{gen}\right)}{\left(\overline{h} \cdot \overline{B}\right)} - h^{0} \right) \overline{B} \right] = 0$$

$$\underbrace{ \mathcal{E}_{Geom}}$$
(84)

We introduce the explicitly the physical scenario via the generalized current \overline{j}_{gen}

$$-\overline{j}_{gen} \sim \sigma_{ext} \left[\overline{E} + \overline{\nu} \times \overline{B} \right] + \left(\frac{c}{e} \frac{\overline{\nabla}p}{n_e} \right)$$
(85)

then

$$\overline{\nabla}^{2}\overline{B} + \overline{\nabla} \times \left[\sigma_{ext}\left[\overline{E} + \overline{\nu} \times \overline{B}\right] + \left(\frac{c}{e}\frac{\overline{\nabla}p}{n_{e}}\right) + \left(\frac{(\overline{h} \cdot \overline{j}_{gen})}{(\overline{h} \cdot \overline{B})} - h^{0}\right)\overline{B}\right] = 0$$

$$\mathcal{E}_{Geom}$$
(86)

 $\overline{\nabla}^2 \overline{B}$

(79)

$$\underbrace{+\sigma_{ext}\left[\left(-\partial_{t}\overline{B}\right)+\overline{\nabla}\times\left(\overline{\nu}\times\overline{B}\right)\right]+\overline{\nabla}\times\left(\frac{c}{e}\frac{\overline{\nabla}p}{n_{e}}\right)+\overline{\nabla}\times\left(\frac{\left(\overline{h}\cdot\overline{j}_{gen}\right)}{\left(\overline{h}\cdot\overline{B}\right)}-h^{0}\right)\overline{B}}_{\mathcal{E}_{Geom}}$$
=0

(87)

finally the expected geometrically induced expression is obtained:

$$\partial_t \overline{B} = \eta \overline{\nabla}^2 \overline{B} + \overline{\nabla} \times \left(\overline{\nu} \times \overline{B}\right) + \eta \overline{\nabla} \times \left[\left(\frac{c}{e} \, \overline{\nabla} p \over n_e \right) + \alpha \overline{B} \right] = \partial_t \overline{B}$$
(88)

$$\rightarrow \eta \underbrace{\overline{\nabla}^2 \overline{B}}_{\text{diffusive}} + \underbrace{\overline{\nabla} \times (\overline{\nu} \times \overline{B})}_{\text{advective}} + \eta \underbrace{\overline{\nabla} \times (\alpha \overline{B})}_{\alpha \text{-term}} + \underbrace{\frac{c}{e} \frac{\overline{\nabla} p \times \overline{\nabla} n_e}{n_e^2}}_{\text{Biermann battery}}$$
(89)

$$= -\partial_t \overline{B}$$

where $\eta \equiv \frac{1}{\sigma_{ext}}$ as usual and the geometric α :

$$\alpha \equiv \left(\frac{\left(\overline{h} \cdot \overline{j}_{gen}\right)}{\left(\overline{h} \cdot \overline{B}\right)} - h^{0}\right)$$

$$= \left(\frac{\cos \alpha \left|\overline{j}_{gen}\right|}{\cos \beta \left|\overline{B}\right|} - h^{0}\right)$$
(90)

8.5. Seed magnetic field

Notice from the last expression that $\alpha \overline{B}$ is explicitly

$$\alpha \overline{B} = \frac{\cos \alpha \left| \overline{j}_{gen} \right|}{\cos \beta} n_B - h^0 \overline{B} \tag{91}$$

or (via elimination of the unitary vector)

$$\alpha \left| \overline{B} \right| = \frac{\cos \alpha \left| \overline{j}_{gen} \right|}{\cos \beta} - h^0 \left| \overline{B} \right|$$
(92)

we see *clearly* the first term in RHS independent of the intensity of the magnetic field. Considering only the terms of interest without the diffusive and advective term in the induction equation (only time-dependence for the magnetic field is preserved) namely

$$\eta \overline{\nabla \times (\alpha \overline{B})} = -\partial_t \overline{B}$$
(93)

$$\eta \overline{\nabla} \left(\frac{\cos \alpha \left| \overline{j}_{gen} \right|}{\cos \beta} \right) = -\partial_t \left| \overline{B} \right| \tag{94}$$

we see that the currents given by the fields (related to the geometry via h_{α}) originate the magnetic field.

If we consider all the currents of the fields of theory (fermions, bosons, etc.) the seed would be precisely these field currents. The other missing point is to derive the fluid (hydrodynamic) equations (which as is known does not have a definite Lagrangian formulation) from the same unified formulation. Notice that there are, under special conditions, analogous formulas for vorticity ω than for the magnetic field *B*. This would mean that the 2-form of vorticity must also be included in the fundamental antisymmetric tensor, together with the electromagnetic field.

8.6. Comparison with the mean field formalism

Now we compare the obtained equations with respect to the mean field formalism (Rädler and Rheinhardt, 2007; Cirilo-Lombardo, 2017). Starting from expressions (69)–(72) as before, we have:

$$\eta \overline{\nabla}^2 \overline{B} + \overline{\nabla} \times \left(\overline{\nu} \times \overline{B}\right) - \partial_t \overline{B} + \eta \overline{\nabla} \times \left(-h^0 \overline{B} + \overline{h} \times \overline{E}\right)_{\mathcal{E}_{Geom}} = 0 \qquad (95)$$

 \mathcal{E}_{Geom} takes the place of electromotive force due the torsion field with full analogy as $\mathcal{E} = \langle u \times b \rangle$ is the mean electromotive force due to fluctuations. Also as in the mean field case that there are the splitting

$$\mathcal{E} = \mathcal{E}^{\langle 0 \rangle} + \mathcal{E}^{\langle B \rangle} \tag{96}$$

with $\mathcal{E}^{\langle 0 \rangle}$ independent of $\langle \overline{B} \rangle$ and $\mathcal{E}^{\langle \overline{B} \rangle}$ linear and homogeneous in \overline{B} , we have in the torsion case the following correspondence

$$\begin{array}{c} -h^0 \overline{B} \longleftrightarrow \mathcal{E}^{\langle \overline{B} \rangle} \\ \overline{h} \times \overline{E} \longleftrightarrow \mathcal{E}^{\langle 0 \rangle} \end{array}$$

geometrical \longleftrightarrow turbulent

Consequently, the problems of mean-field dynamo theory that are concerned with the generation of a mean EMF by turbulence, have in this model a pure geometric counterpart. In the past years, attention has shifted from kinematic calculations, akin to those familiar from quasilinear theory for plasmas, to self-consistent theories which account for the effects of small scale magnetic fields (including their back-reaction on the dynamics) and for the constraints imposed by the topological conservation laws, such as that for magnetic helicity. Here the torsion vector generalize (as we can see from above set of equations) the concept of helicity. The consequence of this role of the dual torsion field is that the traditionally invoked mean-field dynamo mechanism (i.e. the so-called alpha effect) may be severely quenched or increased at modest fields and magnetic Reynolds numbers, and that spatial transport of this generalized magnetic helicity is crucial to mitigating this quench. Thus, the dynamo problem is seen in our model as one of generalized helicity transport, and so may be tackled like other problems in turbulent transport. A key element in this approach is to understand the evolution of the torsion vector field besides of the turbulence energy and the generalized helicity profiles in spacetime. This forces us to confront the problem of spreading of strong MHD turbulence, and a spatial variant or analogue of the selective decay problem with the dynamics of the torsion field.

9. Torsion, axion electrodynamics vs. Chern Simons theory

Let us review briefly the electromagnetic sector of the theory QCD based in a gauge symmetry $SU(3) \times U(1)$

$$L_{QCD/QED} = +\sum \overline{\psi}_{f} \left[\gamma^{\mu} \left(\partial_{\mu} - ig_{f}t^{\alpha}A^{\alpha}_{\mu} - iq_{f}A_{\mu} \right) - m_{f} \right] \psi_{f}$$

$$- \frac{G^{\alpha}_{\mu\nu}G^{\alpha\mu\nu}}{G^{\alpha\mu\nu}} - \frac{F_{\mu\nu}F^{\mu\nu}}{G^{\alpha\mu\nu}} - \frac{g^{2}\theta G^{\alpha}_{\mu\nu}\widetilde{G}^{\alpha\mu\nu}}{G^{\alpha\mu\nu}} - \frac{g^{2}\theta F_{\mu\nu}\widetilde{F}^{\mu\nu}}{G^{\alpha\mu\nu}} + \frac{g^{2}\theta F^{\mu\nu}}{G^{\alpha\mu\nu}} + \frac{g^{2}\theta F^{\mu\nu}}{G^{\mu\nu}} + \frac{g^{2}$$

As is well know, electromagnetic fields will couple to the electromagnetic currents, namely: $J_{\mu} = \sum_{f} q_{f} \overline{\psi}_{f} \gamma_{\mu} \psi_{f}$ consequently,

there appear term will induce through the quark loop the coupling of $F_{\mu\nu}\tilde{F}^{\mu\nu}$ (the anomaly) to the QCD topological charge. The effective Lagrangian can be written as

$$L_{MCS} = -\frac{F_{\mu\nu}F^{\mu\nu}}{4} - A_{\mu}J^{\mu} - \frac{c}{4}\theta F_{\mu\nu}\widetilde{F}^{\mu\nu}$$
(98)

where a pseudo-scalar field $\theta = \theta(\bar{x}, t)$ (playing the role of the axion field) is introduced and $c = \sum_{f} \frac{(q_{f}e)^{2}}{2\pi^{2}}$. This is the Chern-Simons Lagrangian where, if θ is constant, the last term is a total divergence: $F_{\mu\nu}\tilde{F}^{\mu\nu} = \partial_{\mu}J_{CS}^{\mu}$. The question appear if θ is not a constant $\theta F_{\mu\nu}\tilde{F}^{\mu\nu} = \theta\partial_{\mu}J_{CS}^{\mu} = \partial_{\mu}(\theta J_{CS}^{\mu}) - J_{CS}^{\mu}\partial_{\mu}\theta$.

Now we can see from the previous section that if, from the general decomposition of the four dimensional dual of the torsion field via the Hodge de Rham theorem we retain b_{α} as gradient of

a pseudoscalar (e.g.: axion) these equations coincide in form with the respective equation for MCS theory. Precisely because under this condition $h_{\alpha} = \nabla_{\alpha} \theta$, in flat space (curvature = 0 but torsion \neq 0) the equations become the same as in Kharzeev (2010) namely

$$\overline{\nabla} \cdot \overline{E} - c\overline{P} \cdot \overline{B} = \rho_{ext} \tag{99}$$

$$\partial_t \overline{E} - \overline{\nabla} \times \overline{B} = -c\theta \overline{B} + c\overline{P} \times \overline{E} - \sigma_{ext} \left[\overline{E} + \overline{\nu} \times \overline{B} \right]$$
(100)

$$\cdot B = 0 \tag{101}$$

$$\partial_t B = -\nabla \times E \tag{102}$$

provided:

$$h^0 \to -c\theta$$
 (103)

$$\overline{h} \to -c\overline{P} \tag{104}$$

where from QCD the constant *c* is determined as $c = \frac{e^2}{2\pi}$ and the $\partial_{\mu}\theta = \left(\dot{\theta}, \overline{P}\right)$ in the Kharzeev (2010) notation. The main difference is that while in the case of photons in axion ED was given by Wilzcek (1987) the Lagrangian where that above equations are derived is

$$L_{MCS} = -\frac{F_{\mu\nu}F^{\mu\nu}}{4} - A_{\mu}J^{\mu} + \frac{c}{4}P_{\mu}J^{\mu}_{CS}, \qquad J^{\mu}_{CS} \equiv \varepsilon^{\mu\sigma\rho\nu}A_{\sigma}F_{\rho\nu}$$
(105)

in our case is the dual of the torsion field (that we take as the gradient of a pseudoscalar) responsible of the particular structure of the set of equations.

10. Magnetic helicity generation and cosmic torsion field

Here we consider the projective invariant case: $\beta = 0$ ($R_A = -4\lambda$) where the gravitational and field equations are considerably simplified because $\mathbb{R} = 1$ and $b^{-1} = 0$. Scalar curvature R and the torsion 2-form field $T^a_{\mu\nu}$ with a *SU* (2)-Yang–Mills structure are defined in terms of the affine connection $\Gamma^{\lambda}_{\mu\nu}$ and the *SU*(2) valuated (structural torsion potential) f^a_{μ} by

$$R = g^{\mu\nu} R_{\mu\nu} \qquad R_{\mu\nu} = R^{\lambda}_{\mu\lambda\nu}$$

$$R^{\lambda}_{\mu\lambda\nu} = \partial_{\nu} \Gamma^{\lambda}_{\mu\rho} - \partial_{\rho} \Gamma^{\lambda}_{\mu\nu} + \dots$$

$$T^{a}_{\mu\nu} = \partial_{\mu} f^{a}_{\nu} - \partial_{\nu} f^{a}_{\mu} + \varepsilon^{a}_{bc} f^{b}_{\mu} f^{c}_{\nu}$$
(106)

G and Λ are the geometrically induced Newton gravitational constant (as we have been discussed before) and the integration cosmological constant, respectively. From the last equation for the totally antisymmetric Torsion 2-form, the potential f^a_{μ} define the affine connection $\Gamma^{\lambda}_{\mu\nu}$. Similarly to the case of Einstein-Yang–Mills systems, for our new *UFT* model it can be interpreted as a prototype of gauge theories interacting with gravity (*e.g.* QCD, GUTs, etc.). We stress here the important fact that all the fundamental constants are really geometrically induced as required by the Mach principle. After varying the action, we obtain the gravitational equation (41), namely

$$\overset{\circ}{R}_{\alpha\beta} - \frac{g_{\alpha\beta}}{2} \overset{\circ}{R} = 6 \left(-h_{\alpha}h_{\beta} + \frac{g_{\alpha\beta}}{2}h_{\gamma}h^{\gamma} \right)$$

$$+ \kappa_{geom} \left[F_{\alpha\lambda}F_{\beta}^{\lambda} - F_{\mu\nu}F^{\mu\nu}\frac{g_{\alpha\beta}}{4} \right] + \Lambda g_{\alpha\beta}$$

$$(107)$$

with the "gravitational constant" geometrically induced as

$$\kappa_g \equiv \frac{R_s}{2W} = \left. \frac{8\pi G}{c^4} \right|_{today} \tag{108}$$

and the field equation for the torsion 2-form in differential form

$$d^*T^a + \frac{1}{2}\varepsilon^{abc} \left(f_b \wedge^* T_c - T_b \wedge f_c \right) = -\lambda^* f^a$$
(109)

Notice that (108) κ_g and Λ are not independent, but related by $R_s = 2\Lambda$. In this case $\beta = 0$ we have the simplest expression:

$$\kappa_g \equiv \frac{R_s}{2\left(1 + \frac{R_s}{4\lambda}\right)^2} = \frac{\Lambda}{\left(1 + \frac{2\Lambda}{4\lambda}\right)^2}$$

in consequence, generalizing the conjecture of Markov (1984), if Λ is proportional to the energy, κ goes as Λ if $|\Lambda| \leq 1$, and as Λ^{-1} in other case.

We are going to seek for a classical solution of (107) and (109) with the following ansatz for the metric and gauge connection

$$ds^{2} = d\tau^{2} + a^{2}(\tau) \sigma^{i} \otimes \sigma^{i} \equiv d\tau^{2} + e^{i} \otimes e^{i}.$$
(110)

Here τ is the Euclidean time and the dreibein is defined by $e^i \equiv a(\tau)\sigma^i$. The gauge connection is

$$f^a \equiv f^a_\mu dx^\mu = f\sigma^a, \tag{111}$$

for a, b, c = 1, 2, 3, and for a, b, c = 0 we have

$$f^0 \equiv f^0_\mu dx^\mu = s\sigma^0. \tag{112}$$

This choice for the potential torsion is accordingly to the symmetries involved in the problem.

The σ^i 1-form satisfies the SU(2) Maurer–Cartan structure equation

$$d\sigma^a + \varepsilon^a_{\ bc} \sigma^b \wedge \sigma^c = 0 \tag{113}$$

Notice that in the ansatz the frame and SU(2) (isospin-like) indices are identified (as for the case with the non-abelian-Born-Infeld (NBI) Lagrangian of Cirilo-Lombardo, 2005) The torsion 2-form

$$T^{\gamma} = \frac{1}{2} T^{\gamma}_{\ \mu\nu} dx^{\mu} \wedge dx^{\nu}$$
(114)

becomes

$$T^{a} = df^{a} + \frac{1}{2} \varepsilon^{a}_{bc} f^{b} \wedge f^{c}$$

$$= \left(-f + \frac{1}{2} f^{2}\right) \varepsilon^{a}_{bc} \sigma^{b} \wedge \sigma^{c}$$
(115)

$$d^{*}T^{a} + \frac{1}{2}\varepsilon^{abc} \left(f_{b} \wedge^{*}T_{c} - T_{b} \wedge f_{c}\right) = -2\lambda^{*}f^{a}$$

$$(-2f + f^{2})(1 - f)d\tau \wedge e^{b} \wedge e^{c} = -2\lambda d\tau \wedge e^{b} \wedge e^{c}$$
(116)

$$^{*}T^{a} \equiv h(-2f + f^{2})d\tau \wedge \frac{e^{a}}{a^{2}}$$
(117)

$${}^*f^a = -f\frac{d\tau \wedge e^b \wedge e^c}{a^3} \tag{118}$$

Note that to be complete in our description of the possible physical scenarios, we include f^0 as an U(1) component of the torsion potential (although does not belong to the space SU(2)/U(1)). Having all the above issues into account, the expression for the torsion is analogous to the non-abelian 2-form strength field of Cirilo-Lombardo (2005).

Inserting T^a from (115) into the dynamic equation (109) we obtain

$$(-2f + f^2)(1 - f)d\tau \wedge e^b \wedge e^c = -\lambda d\tau \wedge e^b \wedge e^c,$$
(119)

and from expression (119) we have an algebraic cubic equation for f

$$(-2f + f2)(1 - f) + \lambda = 0$$
(120)



Fig. 1. Wormhole solution $\{a \text{ vs. } t\}$ for f = 2.35 and $K = \pi < 1$.

We can see that, in contrast with our previous work with a dualistic theory (Cirilo-Lombardo, 2005) where the NBI energymomentum tensor of Born–Infeld was considered, there exist three non-trivial solutions for f, depending on the cosmological constant λ . In this preliminary analysis of the problem, only the values of f that make the quantity $\left(-f + \frac{1}{2}f^2\right) \in \mathbb{R}$. Consequently for $\lambda = 2$ we find f = 2.35 then

$$T_{bc}^{a} = \frac{2}{5} \frac{\varepsilon_{bc}^{a}}{a^{2}}; \qquad T_{0c}^{a} = 0$$
(121)

That is, only spatial torsion field is non-vanishing while cosmic time torsion field vanishes (an analogous feature with magnetic and electric Yang–Mills can be seen in the solution of Giddings and Strominger and in Cirilo-Lombardo, 2005). Substituting the expression for the torsion 2-form $(121)^1$ into the symmetric part of the variational equation we reduce the gravitational equations to an ordinary differential equation for the scale factor *a*,

$$3\left[\left(\frac{\dot{a}}{a}\right)^2 - \frac{1}{a^2}\right] - \Lambda = \frac{3\kappa_g}{4a^2}\left(f^2 + s^2\right) + \frac{3}{2a^4}f^2\left(f - 2\right)^2$$
(122)

that in the case for the computed value for $f \sim 2.35$ with s = 10 and $\Lambda \lesssim 1$ the scale factor is described in Fig. 1 and the scale factor goes as:

$$a(\tau) = \Lambda^{-1/2} \times \sqrt{\left(1 - \frac{12\kappa_g^2 \Lambda}{\alpha}\right)^{1/2} \sinh\left(\sqrt{\Lambda/3} \left(\tau - \tau_0\right)\right) - 1 + \kappa_g \left(f^2 + s^2\right)/4}$$
(123)

where we define the geometrically induced fine structure function $\alpha \equiv \kappa_g \left(f^2 + s^2\right)/4$.

10.1. Primordial symmetries of standard model and torsion field

In Alvarez-Castillo et al. (2017) the cross section for neutrino helicity spin flip obtained from this type of f(R; T) model of gravitation with dynamic torsion field introduced by us in Cirilo-Lombardo (2013), was phenomenologically analyzed using the relation with the axion decay constant f_a (Peccei–Quinn parameter) due the energy dependence of the cross section. Consequently, the link with the phenomenological energy/mass window was found from the astrophysical and high energy viewpoints. The important point is that, in relation with the torsion vector interaction Lagrangian, the f_a parameter gives an estimate of the torsion field strength that can variate with time within cosmological scenarios as the described above, potentially capable of modifying the overall leptogenesis picture, the magnetogenesis, the baryogenesis and also to obtain some indication about the primordial (super) symmetry of the early universe.

In FRW scenario given here we saw that the torsion through its dual vector, namely:

$$h^0 = \frac{2}{5} \frac{\delta_a^0 C_\tau}{a^2} d\tau \wedge e^a \tag{124}$$

goes as $\sim a^{-2}$ with C_{τ} a covariantly constant vector field (e.g.: $\overset{\circ}{\nabla}C_{\tau} = 0$) that we take of the form $C_{\tau} \sim (\overset{\cdot}{\theta} + q_{\tau})$ (due the Hodge-de Rham decomposition of h_{μ} , expression (42)) where θ is a pseudoscalar field playing the obvious role of axion and q_{τ} : vector field linking h^0 with the magnetic field via the equation of motion for the torsion. Consequently, the torsion dual vector h^i has the maximum value when the radius of the universe is a_{\min} , e.g. $a_{\min} = a(\tau_0)$ increases to the maximum value the spin-flip neutrino cross section and, for instance, the quantity of right neutrinos compensating consequently the actual (e.g. $a_{today} = a(\tau)$) asymmetry of the electroweak sector of the SM (see the behavior of a in Fig. 1). This fact indicates that the original symmetry group contains naturally $SU_R(2) \times SU_L(2) \times U(1)$ typically inside GUT's structurally based generally in SO(10), SU(5) or some exceptional groups as E(6), E(7), etc.

Also it is interesting to note that from the FRW line element written in terms of the cosmic time the Hubble flow electromagnetic fields $E_{\mu} \equiv (0, E_i) = a^{-2} (0, \partial_{\tau} A_i)$ and $B_{\mu} \equiv (0, B_i) = a^{-2} (0, \varepsilon_{ijk} \partial_i A_k)$

$$\overline{\nabla} \cdot \overline{E} + \left(\frac{\alpha}{f} \overline{\nabla}\theta + \overline{\Pi}\right) \cdot \left(a^2 \overline{B}\right) = 0$$
(125)

$$\partial_{\tau} \left(a^2 \overline{E} \right) - \overline{\nabla} \times \left(a^2 \overline{B} \right) = \left(\frac{\alpha}{f} \partial_{\tau} \theta + \Pi_0 \right) \left(a^2 \overline{B} \right)$$
(126)

$$-\left(\overline{f}\nabla\theta + \Pi\right) \times E$$

$$\overline{\nabla} \cdot \overline{B} = 0 \tag{127}$$

$$\partial_t B = -\nabla \times E$$
 (128)

where $\Pi_{\mu} \equiv f_{\mu} \left(u_{\mu}, \gamma^5 b_{\mu}, eA_{\mu}.... \right)$ is a vector function of physical entities as potential vector, vorticity, angular velocity, axial vector etc. as described by expression (42). In principle we can suppose that it is zero (low back reaction, Kolb and Turner, 1994) then

$$\overline{h} = \frac{\alpha}{f} \overline{\nabla}\theta, \qquad h^0 = \frac{\alpha}{f} \partial_\tau \theta \tag{129}$$

being $\left[\partial_{\tau}^2 - \overline{\nabla}^2 - \frac{\alpha}{f} \partial_{\tau} \theta \overline{\nabla} \times\right] (a^2 \overline{B}) = 0$ the second order equation for the magnetic field that shows the chiral character of the plasma particles.

10.2. Magnetogenesis and cosmic helicity

Now we pass to see which role plays the torsion field in the magnetic field generation in a FRW cosmology. Taking as the starting point the (hyper) electrodynamic equations (Joyce and Shaposhnikov, 1997) and introducing a Fourier mode decomposition $\overline{B}(\overline{x}) = \int d^3 \overline{k} \overline{B}(\overline{k}) e^{-i\overline{k}\cdot\overline{x}}$ with $\overline{B}(\overline{k}) = h_i \overline{e}_i$ where $i = 1, 2, \ \overline{e}_i^2 = 1, \ \overline{e}_i \cdot \overline{k} = \overline{e}_1 \cdot \overline{e}_2 = 0$ the torsion-modified dynamical equations for the expanding FRW become

¹ In the tetrad: $\overset{\circ}{R}_{00} = -3\frac{\ddot{a}}{a}, \overset{\circ}{R}_{ab} = -\left[\frac{\ddot{a}}{a} + 2\left(\frac{\dot{a}}{a}\right)^2 - \frac{2}{a^2}\right].$

$$\frac{\overline{z}}{\overline{z}} + \left[\left(2\dot{a} + \frac{k^2}{\sigma} \right) + \frac{ah^0 |k|}{\sigma} \right] \overline{z} = 0$$
(130)

$$\dot{z} + \left[\left(2\dot{a} + \frac{k^2}{\sigma} \right) - \frac{ah^0 |k|}{\sigma} \right] z = 0$$
(131)

where the magnetic field is written in terms of complex variable $z(\overline{z})$ as

$$z = h_1 + ih_2 \tag{132}$$

$$\overline{z} = h_1 - ih_2 \tag{133}$$

from equation (117) we see that the solution for *z* namely:

$$z = z_0 e^{-\left(2a + \frac{k^2}{\sigma}\tau\right) + \int \frac{a\hbar^0 |\mathbf{k}|}{\sigma} d\tau}$$
(134)

contains the instable mode in the sense of Joyce and Shaposhnikov (1997) $\frac{k}{\sigma}\tau < \int \frac{ah^0}{\sigma}d\tau$. Consequently a defined polarization of the magnetic field appear and from the dynamical equation for the torsion field: $\nabla_{[\mu}h_{\nu]} = -\lambda \widetilde{F}_{\mu\nu}$ that in this case we have

$$\nabla_{[i} h_{\tau]} = \nabla_{i} \left(a^{-2} q_{\tau} \right) = -\lambda B_{i} \tag{135}$$

that implies a relation between the vector part of the h^0 (namely q_{τ}) with the vector potential A^k of the magnetic field as follows:

$$\nabla_i q_\tau \approx -\lambda \varepsilon_{ijk} \nabla^j A^k \tag{136}$$

Consequently, the primordial magnetic field (or seed) would be connected in a self-consistent way with the torsion field by means of the dual vector h_0 . It (h_μ) in turn, would be connected phenomenologically with the physical fields (matter) of theory through Hodge–de Rham decomposition expression (42). We note from expression (120) that the pseudo-scalar (axion) controls the stability, growth and dynamo effect but not the generation of the magnetic field (primordial or seed) as is clear from expression (122) where the (pseudo-)vector part of h_0 contributes directly to the generation of the magnetic field as clearly given by eq. (121).

10.3. Magnetogenesis and cosmic helicity II

In the case to include the *complete alpha term* given by equations (92) and in the same analytical conditions (e.g.: Fourier decomposition) from the previous paragraph, the torsion-modified dynamic equations for the expanding FRW become

$$\frac{\overline{z}}{\overline{z}} + \left[\left(2\dot{a} + \frac{k^2}{\sigma} \right) + \frac{a |k|}{\sigma} \left(h^0 - \frac{\cos \alpha \left| \overline{j}_{gen} \right|}{\cos \beta \left| \overline{z} \right|} \right) \right] \overline{z} = 0$$
(137)

$$\dot{z} + \left[\left(2\dot{a} + \frac{k^2}{\sigma} \right) - \frac{a \left| k \right|}{\sigma} \left(h^0 - \frac{\cos \alpha \left| \overline{j}_{gen} \right|}{\cos \beta \left| z \right|} \right) \right] z = 0$$
(138)

where in this case the magnetic field is written (by convenience) in terms of complex variable $z(\overline{z})$ as

$$z = |z| e^{i\rho} \rightarrow \dot{z} = \left(\dot{|z|} + i\dot{\rho} |z| \right) e^{i\rho}$$
(139)

$$\overline{z} = \left|\overline{z}\right| e^{-i\rho} \to \overline{\overline{z}} = \left(\left|\overline{z}\right| - i\rho \left|\overline{z}\right|\right) e^{-i\rho} \tag{140}$$

From equation (124) we see that the solution for *z* namely:

$$z = z_0 \exp\left[-\left(2a + \frac{k^2}{\sigma}\tau\right) + \int \frac{a\,|k|}{\sigma} \left(h^0 - \frac{\cos\alpha\,\left|\overline{j}_{gen}\right|}{\cos\beta\,|z_0|}\right)d\tau\right]$$
(141)

with $z_0 = |z_0| e^{i\rho_0}$ ($|z_0| = const$)

contains the instable mode in the sense of Joyce and Shaposhnikov (1997) for example (117) $\frac{k}{\sigma}\tau < \int \frac{a}{\sigma} \left(h^0 - \frac{\cos\alpha|\overline{j}_{gen}|}{\cos\beta|z|}\right) d\tau$. But now there are not a definite polarization for the magnetic field, but now all depends on the difference:

$$\int \frac{a}{\sigma} \left(h^0 - \frac{\cos \alpha \left| \overline{j}_{gen} \right|}{\cos \beta \left| z_0 \right|} \right) d\tau$$

ı.

Replacing explicitly h_{α} from the decomposition (42) we can see in a clear form, the interplay between the physical entities, as the vortical and magnetic helicities for example:

$$\left(\nabla_{0}\Omega + \frac{4\pi}{3}\left[h_{M} + q_{s}n_{s}\overline{u}_{s}\cdot\overline{B}\right] + \gamma_{1}h_{V} + \gamma_{2}P_{0}\right) - \frac{\cos\alpha\left|\overline{j}_{gen}\right|}{\cos\beta\left|z_{0}\right|}$$

Now considering in $|\overline{j}_{gen}|$ the fermionic current $\sum_{f} q_{f} \overline{\psi}_{f} \gamma_{\mu} \psi_{f}$, Ω as the axion a, $|z_{0}| = \frac{\cos \beta}{\cos \alpha}$ and putting $\gamma_{2} = 0$ we have an interesting expression:

$$\nabla_0 a + \frac{4\pi}{3} \left[h_M + q_s n_s \overline{u}_s \cdot \overline{B} \right] + \gamma_1 h_V = \left| \sum_f q_f \overline{\psi}_f \gamma_\mu \psi_f \right|$$

The above expression it is very important because establishes the desired connection between helicities, magnetic field and fermionic fields and axion. We can order it as

$$\nabla_0 a - \left| \sum_f q_f \overline{\psi}_f \gamma_\mu \psi_f \right| = - \left[\frac{4\pi}{3} \left(h_M + q_s n_s \overline{u}_s \cdot \overline{B} \right) + \gamma_1 h_V \right]$$

We now clearly see the link between the axion and the fermionic fields (the dynamics of the interacting fields and the involved currents) in the LHS and the macroscopic physical observables in the RHS giving an indication of the origin of leptogenesis and baryogenesis in the context of this non-Riemannian gravitational model.

10.4. Dark matter, energy condition and UFT model

As is well know, in a wormhole solution energy conditions are always violated in the standard general relativity. In the context of general relativity, this fact is closely related to the necessity to introduce exotic matter through the energy momentum tensor. Physically speaking, the observations of Type Ia Supernova (SNIa), together with the cosmic microwave background radiation (CMB)[and the larger scale structure, suggest that the present universe is in accelerating expansion, which needs something as dark energy with a negative equation of state (e.g. phantom field, non-canonical dynamical terms, etc.). The simplest standard model introduces the cosmological constant term Λ , which has a constant effective equation of state w = -1, and drive the acceleration of the universe assuming the effective energy of the Λ term occupies $\sim 73\%$ of the total energy (assuming also \sim 23% dark matter, \sim 4% baryon matter and \sim 10–5% radiation) constituting the Λ CDM model. This simple model satisfies more or less all the cosmological observations but is still a phenomenological one. Also the model suffers 2 important drawbacks: the 'fine-tunning' (Jain et al., 2015) and the 'coincidence' (Velten et al., 2014) problems. In consequence other

candidates as the dark energy (especially the dynamical models) are required. Beyond the general relativity, there are proposals in the literature where wormoholes of different kinds (Bronnikov and Galiakhmetov, 2015) and other solutions with torsion were performed. For example, the Einstein–Cartan model ECM is the simplest version of the Poincare gauge theory of gravity (PGTG), in which the torsion is not dynamic because the gravitational action is proportional to the curvature scalar of Riemann–Cartan space–time (the ECT is a degenerate gauge theory in this particular aspect): wormholes were treated for example in Bronnikov and Galiakhmetov (2015).

The proposed model presented in this paper is purely geometric: no energy-momentum tensor (EMT) is introduced. As have been seen, an effective TEM (e.g.: eqs. (39)–(41)) is obtained when, from the general gravitational equations, the standard Einstein tensor is isolated. In our case, the effective TEM of the wormhole solution is diagonal (in the corresponding coordinates) with the isotropic typical structure $\approx \mathbb{R} \otimes SU$ (2). Consequently, we can proceed analyzing this effective TEM (geometrical) by mean the standard energy conditions expressions (Hawking and Ellis, 1973), namely:

i) WEC (weak energy condition)

$$T_{\mu\nu}\big|_{eff}\,\zeta^{\mu}\zeta^{\nu}\geqq 0$$

 $(\zeta^{\nu}: \text{any timelike vector}) \Rightarrow \rho \ge 0, \rho + p_k \ge 0, (k = 1, 2, 3)$

guarantees that the energy density as measured by any local observer is nonnegative.

ii) DEC (dominant energy condition)

 $T_{00}|_{eff} \geq |T_{ik}|_{eff}$

$$(\zeta^{\nu}: \text{ any timelike vector}) \Rightarrow \rho \ge 0, \rho + p_k \ge 0, (i, k = 1, 2, 3)$$

includes *WEC* and requires each principal pressure never exceeds the energy density which guarantees that the speed of sound cannot exceed the light velocity *c*.

iii) SEC (strong energy condition)

requires
$$\rightarrow \rho + \sum p_k \geq 0$$

and defines the sign of the acceleration due to gravity. In our case, the wormhole solution presented in Fig. 1, *the condition iii) is ful-filled jointly with conditions i) and ii).* As we have made mention above, in Bronnikov and Galiakhmetov (2015) wormhole solutions with nondynamical torsion were constructed in the context of the standard Einstein–Cartan model (ECM) fulfilling the energy conditions also. The fundamental differences between the model in Bronnikov and Galiakhmetov (2015) and here are:

• In the case of Bronnikov and Galiakhmetov (2015) the energy conditions are fulfilled only for particular values (local conditions or windows) of the parameters in the introduced equation.

• In our case there are not free parameters but geometrically induced functions mutually related. Consequently, there are no parameters that can be freely chosen but geometrically induced and mutually related functions, so that the freedom to choose them independently is restricted: e.g. once one of them is fixed, the others are automatically related to each other by means of expressions of a dynamic character (like the analogue of field b) or by means of the constraint given by Λ , etc. (see Sections 5 and 6). This important fact, which will be treated in a particular way in another work (Cirilo-Lombardo, in preparation), would give an indication that the solutions could have an overall character in our model.

11. Discussion and perspectives

In this paper we have introduced a simple geometric Lagrangian in the context of a unified theory based on affine geometry. From the functional action proposed, that is as square root or measure, the dynamic equations were derived: an equation analogous to trace free Einstein equations *TFE* and a dynamic equation for the torsion (which was taken totally antisymmetric). Although the aim of this paper was to introduce and to analyze the model from the viewpoint of previous research, we bring some new results and possible explanations about the generation of primordial magnetic fields and the link with the leptogenesis and baryogenesis. The physically admissible analysis of the torsion vector h_{μ} , from the point of view of the symmetries, has allowed us to see how matter fields can be introduced in the model. These fields include some dark matter candidates such as axion, right neutrinos and Majorana. Also the vorticity can be included in the same way and, as the torsion vector is connected to the magnetic field, both vorticity and magnetic field can be treated with equal footing. The other point is that from the wormhole solution in a cosmological spacetime with torsion we show that primordial cosmic magnetic fields can be originated by the dual torsion field h_{μ} being the axion field contained in h_{μ} , the responsible to control the dynamics and stability of the cosmic magnetic field, but is not responsible of the magnetogenesis itself. Also the energy conditions in the wormhole solution are fulfilled. The last important point to highlight is that the dynamic torsion field h_{μ} acts as mechanism of the reduction of an original (early, primordial) GUT (Grand Unified Theory) symmetry of the universe containing \sim SU(3) ×SU(2)_R ×SU(2)_L ×U(1) to $SU(3) \times SU(2)_L \times U(1)$ today. Consequently, the GUT candidates are SO(10), SU(5) or some exceptional groups as E(6), E(7) for example.

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Appendix A

We must to remind that the model where the interaction arises is based on a pure affine geometrical construction where the geometrical Lagrangian of the theory contains dynamically the generalized curvature $\mathcal{R} = \det(\mathcal{R}^a_{\ \mu})$, namely

$$L_g = \sqrt{det \mathcal{R}^a_{\ \mu} \mathcal{R}_{a\nu}} = \sqrt{det G_{\mu\nu}}$$

characterizing a higher dimensional group manifold e.g.: SU(2, 2). Then, after the breaking of the symmetry, typically from the conformal to the Lorentz group e.g.: $SU(2, 2) \rightarrow SO(1, 3)$, the generalized curvature becomes to

$$\mathcal{R}^{a}_{\ \mu} = \lambda \left(e^{a}_{\ \mu} + f^{a}_{\ \mu} \right) + R^{a}_{\ \mu} \qquad \left(M^{a}_{\ \mu} \equiv e^{a\nu} M_{\nu\mu} \right)$$

taking the original Lagrangian L_g the following form: $L_g \rightarrow \sqrt{Det \left[\lambda^2 \left(g_{\mu\nu} + f^a_{\mu} f_{a\nu}\right) + 2\lambda R_{(\mu\nu)} + 2\lambda f^a_{\mu} R_{[a\nu]} + R^a_{\mu} R_{a\nu}\right]}$, reminiscent of a nonlinear sigma model or M-brane. Notice that f^a_{μ} , in a sharp contrast with the tetrad field e^a_{μ} , carries the symmetry $e_{a\mu} f^a_{\nu} = f_{\mu\nu} = -f_{\nu\mu}$. see (Velten et al., 2014; Hawking and Ellis, 1973; Cirilo-Lombardo, 2010, 2011a, 2011b, 2007) for more mathematical and geometrical details of the theory.

Consequently the generalized Ricci tensor splits into a symmetric and antisymmetric part, namely:

$$R_{\mu\nu} = \overbrace{\overset{R_{(\mu\nu)}}{\overset{\alpha}{R_{\mu\nu}} - T_{\mu\rho}^{\ \alpha}T_{\alpha\nu}}^{R_{(\mu\nu)}} + \overbrace{\overset{\alpha}{\nabla}_{\alpha}T_{\mu\nu}}^{R_{[\mu\nu]}}$$

where $\overset{\circ}{R}_{\mu\nu}$ is the general relativistic Ricci tensor constructed with the Christoffel connection, $T_{\mu\rho}{}^{\alpha}T_{\alpha\nu}{}^{\rho}$ is the quadratic term in the torsion field and the antisymmetric last part $\overset{\circ}{\nabla}_{\alpha}T_{\mu\nu}{}^{\alpha}$ is the divergence of the totally antisymmetric torsion field that introduce its dynamics in the theory. From a theoretical point of view our theory containing a dynamical totally antisymmetric torsion field is comparable to that of Kalb-Ramond in string or superstring theory (Green et al., 1987) but in our case all: energy, matter and interactions are geometrically induced.

Notice that ${}^*f_{\mu
u}$ in L_g must be proportional to the physical electromagnetic field, namely $jF_{\mu\nu}$ where the parameter j homogenizes the units such that the combination $g_{\mu\nu} + jF_{\mu\nu}$ has the correct sense. We will not go into details but the great advantage of the model is that it is purely geometric without energymomentum tensor added by hand.

Appendix **B**

On the g-variation: from

$$\mathcal{L} = \sqrt{|g|} \sqrt{\det(\alpha\lambda)} \sqrt{1 + \frac{1}{2b^2} F_{\mu\nu} F^{\mu\nu} - \frac{1}{16b^4} \left(F_{\mu\nu} \widetilde{F}^{\mu\nu}\right)^2}$$
$$\equiv \sqrt{|g|} \sqrt{\det(\alpha\lambda)} \mathbb{R}$$
(B.1)

where

$$b = \frac{\alpha}{\beta} = \frac{1 + (R_S/4\lambda)}{1 + (R_A/4\lambda)},\tag{B.2}$$

$$R_S = g^{\alpha\beta} R_{\alpha\beta}, \tag{B.3}$$

$$R_A = f^{\alpha\beta} R_{\alpha\beta}, \tag{B.4}$$

and λ arbitrary constant. Knowing that, in the metrical case we have as usual procedure:

$$\delta_{g}\mathcal{L} = \left[\delta\left(\sqrt{|g|}\sqrt{\det\left(\alpha\lambda\right)}\right)\mathbb{R} + \sqrt{|g|}\sqrt{\det\left(\alpha\lambda\right)}\delta\mathbb{R}\right]$$
(B.5)

$$\delta\left(F_{\mu\nu}F^{\mu\nu}\right) = 2F_{\mu\lambda}F_{\nu}^{\lambda}\delta g^{\mu\nu} \tag{B.6}$$

$$\delta\left(\widetilde{F}_{\mu\nu}F^{\mu\nu}\right) = \left(-\frac{1}{2}\widetilde{F}_{\eta\rho}F^{\eta\rho}g_{\mu\nu} + 4\widetilde{F}_{\mu\rho}F_{\nu}^{\rho}\right)\delta g^{\mu\nu} \tag{B.7}$$

then

$$\begin{split} \left[2R_{(\alpha\beta)} - \frac{g_{\alpha\beta}}{2}R_{s}\right] \mathbb{R} & (B.8) \\ &= \frac{R_{s}}{\mathbb{R}\alpha^{2}} \left[F_{\alpha\lambda}F_{\beta}^{\lambda} + \frac{1}{2b^{2}}F_{\mu\nu}\widetilde{F}^{\mu\nu}\left(\frac{F_{\eta\rho}\widetilde{F}^{\eta\rho}}{8}g_{\alpha\beta} - F_{\alpha\lambda}\widetilde{F}_{\beta}^{\lambda}\right)\right] \\ &- F_{\mu\nu}F^{\mu\nu}R_{(\alpha\beta)} + \frac{R_{(\alpha\beta)}}{\mathbb{R}\alpha^{2}} \left[\frac{(F_{\eta\rho}\widetilde{F}^{\eta\rho})^{2}}{4\mathbb{R}^{2}b^{2}} - F_{\mu\nu}F^{\mu\nu}\right] \\ &+ 4\lambda \left[g_{\alpha\beta} + \frac{1}{\mathbb{R}^{2}\alpha^{2}}\left(F_{\alpha\lambda}F_{\beta}^{\lambda} + \frac{F_{\mu\nu}\widetilde{F}^{\mu\nu}}{2b^{2}}\left(\frac{F_{\eta\rho}\widetilde{F}^{\eta\rho}}{8}g_{\alpha\beta} - F_{\alpha\lambda}\widetilde{F}_{\beta}^{\lambda}\right)\right)\right], \end{split}$$

$$R_{(\alpha\beta)} - \frac{g_{\alpha\beta}}{4} R_{s}$$

$$= \frac{R_{s}}{2\mathbb{R}^{2}\alpha^{2}} \left[F_{\alpha\lambda}F_{\beta}^{\lambda} - F_{\mu\nu}F^{\mu\nu}\frac{R_{(\alpha\beta)}}{R_{s}} \right] +$$
(B.9)

$$+ \frac{R_{s}}{4\mathbb{R}^{2}\alpha^{2}b^{2}} \left[F_{\mu\nu}\widetilde{F}^{\mu\nu} \left(\frac{F_{\eta\rho}\widetilde{F}^{\eta\rho}}{8} g_{\alpha\beta} - F_{\alpha\lambda}\widetilde{F}_{\beta}^{\lambda} \right) \right. \\ \left. + \frac{F_{\eta\rho}\widetilde{F}^{\eta\rho}}{2} \frac{R_{(\alpha\beta)}}{R_{s}} \right] + \\ \left. + 2\lambda \left[g_{\alpha\beta} + \frac{1}{\mathbb{R}^{2}\alpha^{2}} \left(F_{\alpha\lambda}F_{\beta}^{\lambda} \right) \right. \\ \left. + \frac{F_{\mu\nu}\widetilde{F}^{\mu\nu}}{2b^{2}} \left(\frac{F_{\eta\rho}\widetilde{F}^{\eta\rho}}{8} g_{\alpha\beta} - F_{\alpha\lambda}\widetilde{F}_{\beta}^{\lambda} \right) \right) \right].$$

Appendix C

Some remarks on the general Hodge-de Rham decomposition of $h = h_{\alpha} dx^{\alpha}$

Theorem 6. if $h = h_{\alpha} dx^{\alpha} \notin F'(M)$ is a 1-form on *M*, then there exist a zero-form Ω , a 2-form $\alpha = A_{[\mu\nu]}dx^{\mu} \wedge dx^{\nu}$ and an harmonic 1-form $q = q_{\alpha} dx^{\alpha}$ on M that

$$h = d\Omega + \delta\alpha + q \to h_{\alpha} = \nabla_{\alpha}\Omega + \varepsilon_{\alpha}^{\beta\gamma\delta}\nabla_{\beta}A_{\gamma\delta} + q_{\alpha}$$
(C.1)

Notice that even if is not harmonic, and assuming that q_{α} is a polar vector, an axial vector can be added such that the above expression takes the form

$$h_{\alpha} = \nabla_{\alpha} \Omega + \varepsilon_{\alpha}^{\beta \gamma \delta} \nabla_{\beta} A_{\gamma \delta} + \varepsilon_{\alpha}^{\beta \gamma \delta} M_{\beta \gamma \delta} + q_{\alpha}$$
(C.2)

where $M_{\beta\gamma\delta}$ is a completely antisymmetric tensor (of such a man-

ner that $\varepsilon_{\alpha}^{\beta\gamma\delta}M_{\beta\gamma\delta} \equiv \gamma^5 b_{\alpha}$ is an axial vector). Consequently, we know that in unified theories where we are not able to deal with energy-momentum tensor, the fields and they interactions are effectively restricted due the same geometrical framework: the spacetime itself. This fact permits us to rewrite (14) considering the physical quantities of interest:

$$h_{\alpha} = \nabla_{\alpha} \Omega + \varepsilon_{\alpha}^{\beta \gamma \delta} \nabla_{\beta} A_{\gamma \delta} + \gamma^5 b_{\alpha} + (P_{\alpha} - eA_{\alpha}).$$

Appendix D

D.1. Electrodynamical equations in 3 + 1

The starting point will be the line element in 3 + 1 splitting (Thorne and Macdonald, 1982; Macdonald and Thorne, 1982): the 4-dimensional spacetime is split into 3-dimensional space and 1-dimensional time to form a foliation of 3-dimensional spacelike hypersurfaces. The metric of the spacetime is consequently, given by

$$ds^{2} = -\alpha^{2}dt^{2} + \gamma_{ij}\left(dx^{i} + \beta^{i}dt\right)\left(dx^{j} + \beta^{j}dt\right)$$

where γ_{ii} is the metric of the 3-dimensional hypersurface, α is the lapse function, and β^i is the shift function. At every spacetime point, a fiducial observer (FIDO) is introduced in such a way that his corresponding world-line is perpendicular to the hypersurface where he is stationary.

His FIDO 4-vector velocity is then given by

$$U^{\mu} = \frac{1}{\alpha} \left(1, -\beta^{i} \right), U_{\mu} = (-\alpha, 0, 0, 0)$$

one deals with the physical quantities defined on the 3-dimensional hypersurface as measured by the FIDO. For example, the electric field and the magnetic field are defined with the help of the U^{μ} respectively, by

$$E^{\mu} = F^{\mu\nu}U_{\nu}$$
$$B^{\mu} = -\frac{1}{2\sqrt{-g}}\varepsilon^{\mu\nu\rho\sigma}U_{\nu}F_{\mu\nu}$$

notice that the zero components are null: $E^0 = B^0 = 0$. Also, the 4-current J^{μ} can be similarly decomposed as

$$J^{\mu} = \rho_e U^{\mu} + j^{\mu}$$

where we defined

$$\rho_e = -J^{\mu}U_{\mu}$$
$$j^{\mu} = J^{\mu} + J^{\nu}U_{\nu}U^{\mu}$$

then $j^0 = 0$. So that *j*, *E* and *B* can be treated as 3-vectors in spacelike hypersurfaces. In terms of these 3-vectors the Maxwell eqs. can be written as

$$\nabla \cdot E = 4\pi \rho_e$$
$$\nabla \cdot B = 0$$

$$\nabla \times (\alpha E) = -(\partial_t - \mathcal{L}_\beta)B$$

= $-\partial_0 B + (\beta \cdot \nabla) B - (B \cdot \nabla) \beta$
$$\nabla \times (\alpha B) = -(\partial_t - \mathcal{L}_\beta)E + 4\pi \alpha j$$

= $\partial_0 E - (\beta \cdot \nabla) E + (E \cdot \nabla) \beta + 4\pi \alpha j$

The derivatives in these equations are covariant derivatives with respect to the metric of the absolute space γ_{ij} being \mathcal{L}_{β} the Lie derivative operator geometrically defined as: $\mathcal{L}_{\beta}V = d(i_{\beta} \cdot V)$ with V a vector field.

ZAMOs observers

$$U = \frac{1}{\alpha} \left(\partial_t - \beta^i e_i \right)$$

in the Boyer–Lindquist coordinates we have e_r, e_{θ} and $e_{\varphi} = \frac{1}{\sqrt{g_{\varphi\varphi}}} \partial_{\varphi}$. The plasma 4-velocity (medium) u can be expressed as $u = \gamma (U + \overline{v})$ where \overline{v} is the plasma 3-velocity with respect to the ZAMOs.

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