

# A quasilinearization method for elliptic problems with a nonlinear boundary condition

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## Abstract

We study a nonlinear elliptic second order problem with a nonlinear boundary condition. Assuming the existence of an ordered couple of a supersolution and a subsolution, we develop a quasilinearization method in order to construct an iterative scheme that converges to a solution. Furthermore, under an extra assumption we prove that the convergence is quadratic.

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## 1. Introduction

In this work, we study the following nonlinear elliptic boundary problem:

$$\begin{cases} \Delta u = f(x, u) & \text{in } \Omega \\ \frac{\partial u}{\partial \eta} = g(x, u) & \text{on } \partial\Omega. \end{cases} \quad (1.1)$$

Here  $\Omega$  is a bounded smooth domain of  $\mathbb{R}^n$ , and  $f : \overline{\Omega} \times \mathbb{R} \rightarrow \mathbb{R}$ ,  $g : \partial\Omega \times \mathbb{R} \rightarrow \mathbb{R}$  are continuous and twice continuously differentiable with respect to  $u$ .

Nonlinear boundary conditions of this kind appear for example when one considers the problem of finding extremals for the best constant in the Sobolev trace inequality (see e.g. [5])

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and [11]). On the other hand, for  $n = 1$ , the problem can be regarded as a mathematical model for the axial deformation of a nonlinear elastic beam, with two nonlinear elastic springs acting at the extremities according to the law  $u'(0) = -g(u(0))$ ,  $u'(T) = g(u(T))$ , and the total force exerted by the nonlinear spring undergoing the displacement  $u$  given by  $f(t, u)$  [6,14].

The aim of this paper is to develop a quasilinearization technique for problem (1.1) assuming the existence of an ordered couple of a subsolution and a supersolution. More precisely, we construct an iterative scheme that converges to a solution. Furthermore, under an extra assumption we prove that the convergence is quadratic.

The method of supersolutions and subsolutions (definitions will be given in Section 2 below) is one of the most extensively used tools in nonlinear analysis, both for ODE and PDE problems. There exists a vast literature on this subject; see e.g. [4] for a survey. In particular, for elliptic problems with nonlinear boundary conditions such as (1.1), this method has been applied to obtain existence results for example in [7,12].

The quasilinearization method has been developed by Bellman and Kalaba [3], and generalized by Lakshmikantham [9,10]. It has been applied to different nonlinear problems in the presence of an ordered couple of a subsolution and a supersolution. In a recent work [8] it has been successfully applied for a second order ODE Neumann problem for the case in which the supersolution  $\beta$  and the subsolution  $\alpha$  present the reversed order, namely  $\beta \leq \alpha$ .

Our main results read as follows.

**Theorem 1.1.** *Let  $\alpha, \beta \in H^1(\Omega) \cap C(\overline{\Omega})$  be respectively a subsolution and a supersolution of (1.1) such that  $\alpha \leq \beta$ . Furthermore, assume that*

$$\frac{\partial^2 f}{\partial u^2}(x, u) \leq 0$$

*for  $x \in \overline{\Omega}$  and  $\alpha(x) \leq u \leq \beta(x)$ , and*

$$\frac{\partial^2 g}{\partial u^2}(x, u) \geq 0$$

*for  $x \in \partial\Omega$  and  $\alpha(x) \leq u \leq \beta(x)$ . Then the sequence defined below by (3.1) and (3.2) converges in  $H^1(\Omega) \cap C(\overline{\Omega})$  to a solution of (1.1).*

The proof relies on an associated maximum principle and the unique solvability of the associated linear Robin problem.

Moreover, under a monotonicity condition on  $f$  and  $g$ , we prove the quadratic convergence of the method.

**Theorem 1.2.** *Under the hypotheses of the previous theorem, assume furthermore that*

$$\frac{\partial f}{\partial u}(x, u) > 0$$

*for  $x \in \overline{\Omega}$  and  $\alpha(x) \leq u \leq \beta(x)$ , and*

$$\frac{\partial g}{\partial u}(x, u) < 0$$

*for  $x \in \partial\Omega$  and  $\alpha(x) \leq u \leq \beta(x)$ . Then the convergence of the sequence defined by (3.1) and (3.2) is quadratic for the  $C(\overline{\Omega})$ -norm.*

**Remark 1.1.** An analogous result may be obtained by a similar argument under the following non-local boundary condition:

$$u = c \quad \text{on } \partial\Omega, \quad \int_{\partial\Omega} \frac{\partial u}{\partial \eta} = h(c)$$

where  $c$  is a constant with unknown value (see e.g. [2]).

**Remark 1.2.** Our proof of Theorem 1.1 cannot be extended to  $f = f(x, u, \nabla u)$ , although the existence of solutions can be proved by fixed point arguments (see e.g. [7,12]).

This paper is organized as follows.

In Section 2 we give some preliminary results and definitions. In Section 3, we describe the method of quasilinearization. More precisely, we define iteratively a nondecreasing sequence of subsolutions that converges to a solution of the problem.

Finally, in Section 4 we prove the quadratic convergence of the scheme under a monotonicity condition on  $f$  and  $g$ .

## 2. Definitions and preliminary results

We shall make use of the following maximum principle associated with our problem:

**Lemma 2.1.** *Let  $\lambda > 0$ ,  $\mu > 0$  and assume that  $u \in H^2(\Omega)$  satisfies*

$$\begin{cases} \Delta u - \lambda u \geq 0 & \text{in } \Omega \\ \frac{\partial u}{\partial \eta} + \mu u \leq 0 & \text{on } \partial\Omega. \end{cases}$$

*Then  $u \leq 0$ .*

**Proof.** We multiply by  $u^+ := \max\{u, 0\}$ , and integrate by parts:

$$0 \leq \int_{\Omega} (\Delta u - \lambda u) u^+ = - \int_{\Omega^+} |\nabla u|^2 - \lambda \int_{\Omega^+} u^2 + \int_{\partial\Omega} u^+ \frac{\partial u}{\partial \eta}$$

where  $\Omega^+ = \{x \in \Omega : u(x) > 0\}$ . Moreover, as  $\frac{\partial u}{\partial \eta} \leq -\mu u$  on  $\partial\Omega$ , then

$$\int_{\partial\Omega} u^+ \frac{\partial u}{\partial \eta} \leq -\mu \int_{\Omega} u^+ u \leq 0.$$

Hence, we conclude that  $u^+ = 0$ , and the proof is complete.  $\square$

We shall need the following basic existence and uniqueness result for the Robin problem:

**Lemma 2.2.** *Let  $\varphi \in L^2(\Omega)$  and  $\psi \in L^2(\partial\Omega)$ . Then, for any  $\lambda, \mu > 0$  the Robin problem:*

$$\begin{cases} \Delta u - \lambda u = \varphi & \text{in } \Omega \\ \frac{\partial u}{\partial \eta} + \mu u = \psi & \text{on } \partial\Omega \end{cases}$$

*admits a unique solution  $u \in H^2(\Omega)$ .*

**Proof.** In order to show existence, we consider the functional  $J : H^1(\Omega) \rightarrow \mathbb{R}$  given by

$$J(u) = \int_{\Omega} \left[ \frac{|\nabla u|^2}{2} + \lambda \frac{u^2}{2} - \varphi u \right] + \int_{\partial\Omega} \left[ \mu \frac{u^2}{2} - \psi u \right].$$

It is easy to see that  $J$  is coercive and weakly lower semicontinuous; hence it achieves a minimum  $u \in H^1(\Omega)$  (see e.g. [13], section 1.1), which is a weak solution. As  $\|\Delta u\|_{L^2} = \|\lambda u + \varphi\|_{L^2} < \infty$ , we conclude that  $u \in H^2(\Omega)$ . Uniqueness follows from the maximum principle.  $\square$

**Lemma 2.3.** *Let  $\lambda, \mu > 0$ ,  $\varphi \in L^\infty(\Omega)$  and  $\psi \in L^\infty(\partial\Omega)$ . Then there exists a constant  $C$  such that if  $u$  is a weak solution of*

$$\begin{cases} \Delta u - \lambda u = \varphi & \text{in } \Omega \\ \frac{\partial u}{\partial \eta} + \mu u = \psi & \text{on } \partial\Omega \end{cases}$$

then

$$\|u\|_{L^\infty(\Omega)} \leq C [\|\varphi\|_{L^\infty(\Omega)} + \|\psi\|_{L^\infty(\partial\Omega)}].$$

**Proof.** Multiplying the equation by  $u$  and integrating, it follows that

$$\|\varphi\|_{L^2} \|u\|_{L^2} \geq - \int_{\Omega} \varphi u = \|\nabla u\|_{L^2}^2 + \lambda \|u\|_{L^2}^2 - \int_{\partial\Omega} u \frac{\partial u}{\partial \eta}.$$

Hence

$$\|\nabla u\|_{L^2}^2 + \lambda \|u\|_{L^2}^2 \leq \|\varphi\|_{L^2} \|u\|_{L^2} + \int_{\partial\Omega} u \psi - \mu \int_{\partial\Omega} u^2.$$

From the trace imbedding  $H^1(\Omega) \hookrightarrow L^2(\partial\Omega)$  (see e.g. [1], Theorem 5.22) it follows that

$$\|u\|_{H^1(\Omega)} \leq c [\|\varphi\|_{L^2(\Omega)} + \|\psi\|_{L^2(\partial\Omega)}]$$

for some constant  $c$ .

Note that if  $n = 1$ , the result follows trivially. For  $n > 1$ , fix any  $p > n$ . As  $W^{1,p}(\Omega) \hookrightarrow L^\infty(\Omega) \hookrightarrow L^p(\Omega)$ , it suffices to show that

$$\|u\|_{W^{1,p}(\Omega)} \leq c [\|\varphi\|_{L^p(\Omega)} + \|\psi\|_{L^p(\partial\Omega)}]$$

for some constant  $c$ . By contradiction, suppose that there exists a sequence  $\{u_k\}_{k \in \mathbb{N}}$  such that  $\|u_k\|_{W^{1,p}(\Omega)} = 1$  and

$$\|\Delta u_k - \lambda u_k\|_{L^p(\Omega)} + \left\| \frac{\partial u_k}{\partial \eta} + \mu u_k \right\|_{L^p(\partial\Omega)} \rightarrow 0.$$

As  $W^{m,p}(\Omega) \hookrightarrow H^m(\Omega)$ , we get from the previous computations that  $\|u_k\|_{H^1(\Omega)} \rightarrow 0$ , and as  $\Delta u_k - \lambda u_k \rightarrow 0$  for the  $L^2$ -norm it follows that  $\|u_k\|_{H^2(\Omega)} \rightarrow 0$ .

Then  $\|u_k\|_{W^{1,2^*}(\Omega)} \rightarrow 0$ , and repeating the previous argument we deduce that  $\|u_k\|_{W^{2,2^*}(\Omega)} \rightarrow 0$ . If  $2^* \geq n$ , then  $W^{2,2^*}(\Omega) \hookrightarrow W^{1,p}(\Omega)$  and  $\|u_k\|_{W^{1,p}(\Omega)} \rightarrow 0$ , a contradiction. Otherwise, repeating the argument a certain number of times we obtain that  $\|u_k\|_{W^{2,q}(\Omega)} \rightarrow 0$  for some  $q \geq n$ , and the proof follows.  $\square$

Next, we recall the definition of the concept of supersolution and subsolution. We say that  $\alpha \in H^1(\Omega) \cap C(\overline{\Omega})$  is a subsolution of problem (1.1) if it satisfies

$$\begin{cases} \Delta\alpha \geq f(x, \alpha) & \text{in } \Omega \\ \frac{\partial\alpha}{\partial\eta} \leq g(x, \alpha) & \text{on } \partial\Omega. \end{cases}$$

In the same way,  $\beta \in H^1(\Omega) \cap C(\overline{\Omega})$  is a supersolution if it satisfies

$$\begin{cases} \Delta\beta \leq f(x, \beta) & \text{in } \Omega \\ \frac{\partial\beta}{\partial\eta} \geq g(x, \beta) & \text{on } \partial\Omega. \end{cases}$$

### 3. The quasilinearization method

In this section we define the quasilinearization method and give a proof of Theorem 1.1.

Assume that  $\alpha$  and  $\beta$  are respectively a subsolution and a supersolution of (1.1) with  $\alpha \leq \beta$ , and fix  $\lambda, \mu > 0$  such that

$$\begin{aligned} \lambda &> \max_{x \in \overline{\Omega}, \alpha(x) \leq u \leq \beta(x)} \frac{\partial f}{\partial u}(x, u) \\ \mu &> - \min_{x \in \partial\Omega, \alpha(x) \leq u \leq \beta(x)} \frac{\partial g}{\partial u}(x, u). \end{aligned}$$

We define recursively a sequence  $\{u_n\}$  in the following way. Set  $u_0 = \alpha$ , and assuming that  $u_n$  is known, define  $u_{n+1}$  as a solution to the following quasilinear Robin problem:

$$\Delta u_{n+1} - \lambda u_{n+1} = f(x, u_n) + \frac{\partial f}{\partial u}(x, u_n)[P_n(x, u_{n+1}) - u_n] - \lambda P_n(x, u_{n+1}) \quad (3.1)$$

in the domain  $\Omega$ , with the boundary condition

$$\frac{\partial u_{n+1}}{\partial\eta} + \mu u_{n+1} = g(x, u_n) + \frac{\partial g}{\partial u}(x, u_n)[P_n(x, u_{n+1}) - u_n] + \mu P_n(x, u_{n+1}) \quad (3.2)$$

on  $\partial\Omega$ , where

$$P_n(x, u) = \begin{cases} u_n(x) & \text{if } u < u_n(x) \\ u & \text{if } u_n(x) \leq u \leq \beta(x) \\ \beta(x) & \text{if } u > \beta(x). \end{cases}$$

We shall see in the proof of Theorem 1.1 that  $u_n \leq \beta$  and consequently that  $P_n$  is well defined. On the other hand, as  $u_n(x) \leq P_n(x, u) \leq \beta(x)$ , a straightforward application of the Schauder Theorem shows that (3.1) and (3.2) admits at least one solution and therefore  $u_{n+1}$  is well defined.

Furthermore, from the fact that  $\alpha \leq u_n \leq \beta$  it will follow that the sequence defined by (3.1) and (3.2) is indeed a Newton scheme (see (3.3) below). However, it is not possible to apply the Newton method directly since the linearized problem (3.3) might fail to have a unique solution.

**Proof of Theorem 1.1.** We will prove by induction that  $u_n$  is a subsolution, and that  $\alpha \leq u_n \leq u_{n+1} \leq \beta$ .

First, observe that

$$\Delta u_{n+1} - \lambda u_{n+1} = f(x, u_n) + \left[ \frac{\partial f}{\partial u}(x, u_n) - \lambda \right] [P_n(x, u_{n+1}) - u_n] - \lambda u_n.$$

From our choice of  $\lambda$ ,  $\frac{\partial f}{\partial u}(x, u_n) - \lambda \leq 0$ , and by the inductive hypothesis  $\Delta u_n \geq f(x, u_n)$ . As  $P_n(x, u_{n+1}) - u_n \geq 0$ , it follows that

$$\Delta u_{n+1} - \lambda u_{n+1} \leq \Delta u_n - \lambda u_n.$$

In a similar way, using the fact that  $\frac{\partial u_n}{\partial \eta} + \mu u_n \leq g(x, u_n)$ , we conclude that

$$\begin{aligned} \frac{\partial u_{n+1}}{\partial \eta} + \mu u_{n+1} &= g(x, u_n) + \left[ \frac{\partial g}{\partial u}(x, u_n) + \mu \right] [P_n(x, u_{n+1}) - u_n] + \mu u_n \\ &\geq \frac{\partial u_n}{\partial \eta} + \mu u_n. \end{aligned}$$

From the maximum principle, it follows that  $u_{n+1} \geq u_n$ .

In order to show that  $u_{n+1} \leq \beta$ , we use a Taylor expansion:

$$f(x, v) = f(x, u_n) + \frac{\partial f}{\partial u}(x, u_n)(v - u_n) + \frac{1}{2} \frac{\partial^2 f}{\partial u^2}(x, \xi)(v - u_n)^2$$

for some  $\xi$  between  $u_n(x)$  and  $v$ .

Choosing  $v = P_n(x, u_{n+1})$ , as  $\frac{\partial^2 f}{\partial u^2}(x, \xi) \leq 0$  we deduce that

$$f(x, P_n(x, u_{n+1})) \leq f(x, u_n) + \frac{\partial f}{\partial u}(x, u_n)(P_n(x, u_{n+1}) - u_n).$$

Hence, from the definition of  $u_{n+1}$ ,

$$\Delta u_{n+1} - \lambda u_{n+1} \geq f(x, P_n(x, u_{n+1})) - \lambda P_n(x, u_{n+1}).$$

Moreover, from the choice of  $\lambda$ , the mapping  $u \mapsto f(x, u) - \lambda u$  is nonincreasing and, therefore,

$$\Delta u_{n+1} - \lambda u_{n+1} \geq f(x, \beta) - \lambda \beta \geq \Delta \beta - \lambda \beta.$$

In a similar way,

$$\begin{aligned} \frac{\partial u_{n+1}}{\partial \eta} + \mu u_{n+1} &\leq g(x, P_n(x, u_{n+1})) + \mu P_n(x, u_{n+1}) \\ &\leq g(x, \beta) + \mu \beta \leq \frac{\partial \beta}{\partial \eta} + \mu \beta. \end{aligned}$$

By the maximum principle, we conclude that  $u_{n+1} \leq \beta$ .

Next we observe that, as it has been already proved that  $\alpha \leq u_{n+1} \leq \beta$ , the definition of  $u_{n+1}$  reduces to a Newton iteration:

$$\begin{cases} \Delta u_{n+1} = f(x, u_n) + \frac{\partial f}{\partial u}(x, u_n)[u_{n+1} - u_n] & \text{in } \Omega \\ \frac{\partial u_{n+1}}{\partial \eta} = g(x, u_n) + \frac{\partial g}{\partial u}(x, u_n)[u_{n+1} - u_n] & \text{on } \partial \Omega. \end{cases} \quad (3.3)$$

Moreover, using the Taylor expansion as before we obtain

$$\Delta u_{n+1} = f(x, u_{n+1}) - \frac{1}{2} \frac{\partial^2 f}{\partial u^2}(x, \xi)(u_{n+1} - u_n)^2 \geq f(x, u_{n+1}) \quad \text{in } \Omega,$$

and similarly

$$\frac{\partial u_{n+1}}{\partial \eta} \leq g(x, u_{n+1}) \quad \text{on } \partial \Omega.$$

Hence,  $u_{n+1}$  is a subsolution of the problem.

As  $\{u_n\}$  is monotone nondecreasing, it converges pointwise to some function  $u$ , with  $\alpha(x) \leq u(x) \leq \beta(x)$ . Moreover, from the proof of [Lemma 2.3](#)

$$\begin{aligned} \|u_{n+1}\|_{H^1(\Omega)} &\leq C_1 \left\| f(x, u_n) + \frac{\partial f}{\partial u}(x, u_n)[u_{n+1} - u_n] - \lambda u_n \right\|_{L^2(\Omega)} \\ &\quad + C_2 \left\| g(x, u_n) + \frac{\partial g}{\partial u}(x, u_n)[u_{n+1} - u_n] + \mu u_n \right\|_{L^2(\partial \Omega)}. \end{aligned}$$

Hence, as  $\alpha \leq u_n \leq \beta$ , it follows that  $\{u_n\}$  is bounded in  $H^1(\Omega)$ , and from [\(3.3\)](#) we deduce that it is bounded in  $H^2(\Omega)$ . Moreover, by the compactness of the imbedding  $H^2(\Omega) \hookrightarrow H^1(\Omega)$  there exists a subsequence  $u_{n_k}$  such that  $u_{n_k} \rightarrow u$  in  $H^1(\Omega)$ . For any test function  $\varphi \in H_0^1(\Omega)$ ,

$$-\int_{\Omega} \nabla u_{n_k} \nabla \varphi = \int_{\Omega} \left[ f(x, u_{n_k-1}) + \frac{\partial f}{\partial u}(x, u_{n_k-1})(u_{n_k} - u_{n_k-1}) \right] \varphi.$$

By dominated convergence, we conclude that  $-\int_{\Omega} \nabla u \nabla \varphi = \int_{\Omega} f(x, u) \varphi$ , and hence  $u$  is a weak solution of

$$\Delta u = f(x, u).$$

Therefore  $u \in H^2(\Omega)$ . Then, if we consider again a test function  $\varphi \in H^1(\Omega)$ ,

$$\begin{aligned} &-\int_{\Omega} \nabla u_{n_k} \nabla \varphi + \int_{\partial \Omega} \left[ g(x, u_{n_k-1}) + \frac{\partial g}{\partial u}(x, u_{n_k-1})(u_{n_k} - u_{n_k-1}) \right] \varphi \\ &= \int_{\Omega} \left[ f(x, u_{n_k-1}) + \frac{\partial f}{\partial u}(x, u_{n_k-1})(u_{n_k} - u_{n_k-1}) \right] \varphi. \end{aligned}$$

By dominated convergence,

$$-\int_{\Omega} \nabla u \nabla \varphi + \int_{\partial \Omega} g(x, u) \varphi = \int_{\Omega} f(x, u) \varphi.$$

Using the divergence theorem and the fact that the range of the trace operator  $H^1(\Omega) \hookrightarrow L^2(\partial \Omega)$  is  $H^{1/2}(\partial \Omega)$  (see e.g. [\[1\]](#), 7.56), which is dense in  $L^2(\partial \Omega)$ , we conclude that  $\frac{\partial u}{\partial \eta} = g(x, u)$  on  $\partial \Omega$ .  $\square$

#### 4. Quadratic convergence

In this section we give a proof of [Theorem 1.2](#).

**Proof of Theorem 1.2.** Let us define the error  $\mathcal{E}_n = u - u_n$ . Using the Taylor expansion around  $u_n$ , it follows from [\(3.3\)](#) that

$$\begin{cases} \Delta \mathcal{E}_{n+1} = f(x, u) - f(x, u_{n+1}) + \frac{1}{2} \frac{\partial^2 f}{\partial u^2}(x, \xi)[u_{n+1} - u_n]^2 & \text{in } \Omega \\ \frac{\partial \mathcal{E}_{n+1}}{\partial \eta} = g(x, u) - g(x, u_{n+1}) + \frac{1}{2} \frac{\partial^2 g}{\partial u^2}(x, \theta)[u_{n+1} - u_n]^2 & \text{on } \partial \Omega \end{cases} \quad (4.1)$$

for some  $\xi = \xi(x) \in [u_n(x), u_{n+1}(x)]$  for  $x \in \overline{\Omega}$ , and  $\theta = \theta(x) \in [u_n(x), u_{n+1}(x)]$  for  $x \in \partial\Omega$ . Set

$$\lambda = \min_{x \in \overline{\Omega}, \alpha(x) \leq u \leq \beta(x)} \frac{\partial f}{\partial u}(x, u) > 0,$$

$$\mu = - \max_{x \in \partial\Omega, \alpha(x) \leq u \leq \beta(x)} \frac{\partial g}{\partial u}(x, u) > 0.$$

As  $\mathcal{E}_{n+1} \geq 0$ , it follows that

$$f(x, u) - f(x, u_{n+1}) \geq \lambda \mathcal{E}_{n+1}$$

and

$$g(x, u) - g(x, u_{n+1}) \leq -\mu \mathcal{E}_{n+1}.$$

Thus, we may define  $\phi$  as the unique solution of the linear Robin problem

$$\begin{cases} \Delta\phi - \lambda\phi = \frac{1}{2} \frac{\partial^2 f}{\partial u^2}(x, \xi) \mathcal{E}_n^2 & \text{in } \Omega \\ \frac{\partial\phi}{\partial\eta} + \mu\phi = \frac{1}{2} \frac{\partial^2 g}{\partial u^2}(x, \theta) \mathcal{E}_n^2 & \text{on } \partial\Omega. \end{cases}$$

Using the fact that  $0 \leq u_{n+1} - u_n \leq \mathcal{E}_n$  and that  $\frac{\partial^2 f}{\partial u^2}(x, \xi) \leq 0 \leq \frac{\partial^2 g}{\partial u^2}(x, \theta)$  we conclude

$$\begin{aligned} \Delta\mathcal{E}_{n+1} - \lambda\mathcal{E}_{n+1} &\geq \Delta\phi - \lambda\phi & \text{in } \Omega, \\ \frac{\partial\mathcal{E}_{n+1}}{\partial\eta} + \mu\mathcal{E}_{n+1} &\leq \frac{\partial\phi}{\partial\eta} + \mu\phi & \text{on } \partial\Omega. \end{aligned}$$

By the maximum principle,  $\mathcal{E}_{n+1} \leq \phi$ , and from Lemma 2.3 we deduce that

$$\|\phi\|_{L^\infty(\Omega)} \leq c \left\{ \left\| \frac{\partial^2 f}{\partial u^2}(x, \xi) \mathcal{E}_n^2 \right\|_{L^\infty(\Omega)} + \left\| \frac{\partial^2 g}{\partial u^2}(x, \theta) \mathcal{E}_n^2 \right\|_{L^\infty(\partial\Omega)} \right\}.$$

Hence,

$$0 \leq \mathcal{E}_{n+1} \leq c \|\mathcal{E}_n\|_{L^\infty(\Omega)}^2$$

for some constant  $c$  independent of  $n$ , and the proof is complete.  $\square$

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