# Lipschitz regularity of almost minimizers in a Bernoulli problem with non-standard growth 

by<br>João Vitor da Silva,* Analía Silva ${ }^{\dagger}$<br>\&<br>Hernán Vivas ${ }^{\ddagger}$

November 27, 2023


#### Abstract

In this work we establish the optimal Lipschitz regularity for non-negative almost minimizers of the one-phase Bernoulli-type functional $$
\mathcal{J}_{\mathrm{G}}(u, \Omega):=\int_{\Omega}\left(\mathrm{G}(|\nabla u|)+\chi_{\{u>0\}}\right) d x
$$ where $\Omega \subset \mathbb{R}^{n}$ is a bounded domain and $\mathrm{G}:[0, \infty) \rightarrow[0, \infty)$ is a Young function with $\mathrm{G}^{\prime}=$ $g$ satisfying the Lieberman's classical conditions. Moreover, of independent mathematical interest, we also address a Höder regularity characterization via Campanato-type estimates in the context of Orlicz modulars, which is new for such a class of non-standard growth functionals.


Keywords: Almost minimizers, Lipschitz regularity, Orlicz spaces
MSC 2020: 35B65, 35J70, 35J87, 46E30.

## 1 Introduction and main result

In this manuscript we deal with one-phase problems driven by the G-energy functionals, with G a suitable function with non-polynomial growth. Specifically, we study nonnegative almost minimizers for one-phase Bernoulli-type functional as follows

$$
\mathcal{J}_{\mathrm{G}}(u, \Omega):=\int_{\Omega}\left(\mathrm{G}(|\nabla u|)+\chi_{\{u>0\}}\right) d x
$$

where $\Omega \subset \mathbb{R}^{n}$ is a bounded Lipschitz domain and $\mathrm{G}:[0, \infty) \rightarrow[0, \infty)$ is a Young function with $\mathrm{G}^{\prime}=g$ satisfying
(1.1) $\delta \leq \frac{t g^{\prime}(t)}{g(t)} \leq g_{0} \quad$ for some constants $\quad 1<\delta \leq g_{0}<\infty \quad$ (Lieberman's condition).

[^0]In our research, almost minimizers mean that we will consider functions $0 \leq u \in W^{1, \mathrm{G}}(\Omega)$ such that for some $\beta>0$ and constant $\kappa \geq 0$ it holds that

$$
\begin{equation*}
\mathcal{J}_{\mathrm{G}}\left(u, B_{r}(x)\right) \leq\left(1+\kappa r^{\beta}\right) \mathcal{J}_{\mathrm{G}}\left(v, B_{r}(x)\right) \tag{1.2}
\end{equation*}
$$

for any ball $B_{r}(x)$ such that $\overline{B_{r}(x)} \subset \Omega$ and any $v \in W^{1, \mathrm{G}}\left(B_{r}(x)\right)$ such that $v=u$ on $\partial B_{r}(x)$ in the sense of traces (see Definition 2.7 and Subsection 2.2 for more details).

Particularly, in this framework, we address optimal local Lipschitz regularity for such class of almost minimizers, where the corresponding estimate depends only on universal parameters

$$
\|\nabla u\|_{L^{\infty}\left(\Omega^{\prime}\right)} \leq \mathrm{C}\left(\delta, g_{0}, \Omega^{\prime}, \beta, \kappa\right) \mathrm{G}^{-1}\left(1+\int_{\Omega} \mathrm{G}(|\nabla u|) d x\right) \quad \text { for any } \quad \Omega^{\prime} \subset \subset \Omega
$$

We must highlight that the functional $\mathcal{J}_{\mathrm{G}}$ is a natural generalization of the classical one-phase (Bernoulli type) $p$-energy functional, which corresponds to the choice of $\mathrm{G}(t)=\frac{1}{p} t^{p}$ (for each $p \in(1, \infty)$ fixed). We will denote by $\mathcal{J}_{p}$ such functional.

Additionally, in the current literature, see e.g. [36, almost minimizers have been interpreted as a sort of minimizers of "perturbed functionals". For instance, one can consider the functional with regional structure (which is quite similar to certain functionals arising in phase transitions for nonlinear nonlocal models - see [17])

$$
\begin{equation*}
\hat{\mathcal{J}}_{\mathrm{G}}(u, \Omega)=\mathcal{J}_{\mathrm{G}}(u, \Omega)+\frac{1}{2} \iint_{\Omega \times \Omega} \Phi(y, z) \Psi(u(y)-u(z)) d y d z, \tag{1.3}
\end{equation*}
$$

where $\Phi(y, z)=\rho(y) \rho(z)$ with $\rho(x)=\Theta(u(x))$, and $\Theta: \mathbb{R} \rightarrow[0,1]$ fulfils $\Theta \equiv 0$ for $x \leq 0$. Moreover, the potential $\Psi: \mathbb{R} \rightarrow[0,1]$ satisfies $\Psi \equiv 0$ for $x \in(-\infty, 0]$

Now, if we define the $\Psi_{u}$-convolution as

$$
\left(\Phi * \Psi_{u}\right)(y, z):=\iint_{\Omega \times \Omega} \Phi(y, z) \Psi(u(y)-u(z)) d y d z
$$

then (1.3) turns out to be

$$
\hat{\mathcal{J}}_{\mathrm{G}}(u, \Omega)=\mathcal{J}_{\mathrm{G}}(u, \Omega)+\frac{1}{2} \Phi(y, z) * \Psi_{u}(y, z) .
$$

Then, we verify that

$$
\mathcal{J}_{\mathrm{G}}(u, \Omega) \leq \hat{\mathcal{J}}_{\mathrm{G}}(u, \Omega)
$$

On the other hand, it is easy to see

$$
\hat{\mathcal{J}}_{\mathrm{G}}(u, \Omega) \leq\left(1+\frac{1}{2} \omega_{n} r^{n}\right) \mathcal{J}_{\mathrm{G}}(u, \Omega) \leq\left(1+\frac{1}{2} \omega_{n} r^{n}\right) \mathcal{J}_{\mathrm{G}}(v, \Omega)
$$

for any $v \in W^{1, \mathrm{G}}\left(B_{r}(x)\right)$ such that $v=u$ on $\partial B_{r}(x)$. In short, a minimizer for the "perturbed functional" $\hat{\mathcal{J}}_{\mathrm{G}}(u, \Omega)$ be revealed to be an almost minimizer for the G-energy functional $\mathcal{J}_{\mathrm{G}}(u, \Omega)$ for appropriated choices of constants $\beta$ and $\kappa$. Therefore, it becomes a necessary task to work with almost minimizers instead of minimizers because of the impossibility of dealing with weak solutions of certain discontinuous functionals in certain general frameworks.

Regarding to minimizers in the linear setting, in Alt and Caffarelli's seminal paper [3] concerning regularity minimizers to one-phase Bernoulli energy functional given by

$$
\mathcal{J}_{2}(u, \Omega):=\int_{\Omega}\left(|\nabla u|^{2}+\chi_{\{u>0\}}\right) d x
$$

it is established the locally Lipschitz regularity estimates. Moreover, it can be shown that minimizers $\mathcal{J}_{2}\left(u_{0}, \Omega\right)=\min _{\mathcal{K}} \mathcal{J}_{2}(u, \Omega)$ are solutions of the following free boundary problem

$$
\left\{\begin{array}{rlrl}
\Delta u_{0}(x) & =0 & \text { in } \quad\left\{u_{0}>0\right\} \cap \Omega  \tag{1.4}\\
\left|\nabla u_{0}\right| & =\sqrt{2} & & \text { on } \quad \partial\left\{u_{0}>0\right\} \cap \Omega \\
u(x) & =g(x) & \text { on } \quad \partial \Omega
\end{array}\right.
$$

in an appropriate distributional sense.
The natural motivations to investigate such a class of free boundary problems of Bernoulli type (1.4) comes from the analysis of cavities and jets type problems, see e.g. [12, Section 1.1]. Another relevant models also arise in combustion theory [6], optimal design problems [50, optimization problems with constrained volume [2], shape optimization problems [8], 9] and [10] and phase transitions [47], 48] and 51] just to mention a few scenarios.

Over the past few decades, there has been extensive literature exploring this research topic, particularly in the context of both single and two-phase problems, most notably the celebrated viscosity approach to the associated free boundary developed by Caffarelli in the series of trailblazing works [13], [14] and [15]. We must refer the reader to [28], 31] and [52] for comprehensive modern essays on the subject.

Minimizers of the functional $\mathcal{J}_{p}$ have been also considered by Danielli and Petrosyan in [21], in which the regularity of the free boundary near flat points was addressed. Recently, Lipschitz estimates of the minimizers of the functional $\mathcal{J}_{p}$ has been addressed by DiPierro and Karakhanyan in [37, where the authors also supplied the proof of the Lipschitz regularity when $p=2$ without making use of monotonicity formulaes.

We must also recall Martinez-Wolanski's work [46, which consider the optimization problem of minimizing

$$
\mathcal{J}_{\mathrm{G}, \lambda}(u, \Omega):=\int_{\Omega}\left(\mathrm{G}(|\nabla u|)+\lambda \chi_{\{u>0\}}\right) d x
$$

in the class $W^{1, \mathrm{G}}(\Omega)$ with $u-\phi_{0} \in W_{0}^{1, \mathrm{G}}(\Omega)$, for a bounded function $\phi_{0} \geq 0$ and $\lambda>0$. The authors prove that solutions to the optimization problem are locally Lipschitz continuous. Moreover, such solutions satisfy the corresponding free boundary problem of Bernoulli-type, thereby extending the Alt-Caffarelli's results for the scenario of Orlicz-Sobolev framework. Additionally, they address the Caffarelli's classification scheme: flat and Lipschitz free boundaries are locally $C^{1, \alpha}$ for some $\alpha$ (universal) $\in(0,1)$. In [7] the authors extend these results to quasilinear singular/degenerate operators in the nonhomogeneous setting (i.e. with a nonzero right hand side).

Furthermore, viscosity approaches for one-phase problems driven by the $p$-Laplace and $p(x)$-Laplace operators has been developed in 44 and 40 respectively. Additionally, in [20, the authors obtain the Lipschitz regularity of viscosity solutions of one-phase problems with non-homogeneous degeneracy (fully nonlinear operators with double phase signature) and some regularity properties of their free boundaries were addressed.

Now coming back to the setting of almost minimizers, we observe that since almost minimizers only fulfill a variational inequality, see (1.2), but not a proper PDE, the main obstacle in facing their regularity properties is the lack of a monotonicity formula as minimizers do (cf. 3]). In this regard, it seems to be challenging to derive such techniques to the setting almost minimizers (cf. [23] and [22] for related topics). In particular, in the quite recent article [34], De Silva and Savin developed a non-variational approach, based on Harnack-type inequality, for profiles that do not necessarily satisfy an infinitesimal equation.

We highlight that almost minimizers of $\mathcal{J}_{2}$ were widely investigated recently by several authors. In effect, we must cite the David et al' work [23], where by developing an original approach combining techniques from potential theory and geometric measure theory, the authors obtain uniform rectifiability of the free boundary and, in the one-phase scenario, the corresponding $C^{1, \alpha}$ almost everywhere regularity. Therefore, the Alt-Caffarelli's classical results in [3] were extended
to the framework of almost minimizers. We refer the reader to [22] for generalizations concerning variable coefficients. Moreover, the analysis of the semilinear scenario with variable coefficients

$$
\mathcal{F}_{\gamma}(v ; \Omega)=\int_{\Omega}\left(\langle\mathbb{A}(x) \nabla v, \nabla v\rangle+q_{+}\left(v^{+}\right)^{\gamma}+q_{-}\left(v^{-}\right)^{\gamma}\right) d x, \quad \text { for } \quad 0 \leq \gamma \leq 1 \quad \text { and } \quad q_{ \pm} \geq 0
$$

where $\mathbb{A}$ is a matrix with Hölder continuous coefficients was explored in [29], thereby proving sharp gradient estimates.

In 33, using non-variational techniques, De Silva and Savin provided a different approach from that of [23] and [24] to deal with almost minimizers of $\mathcal{J}_{2}$ and their free boundaries. Precisely, based on ideas developed by them in [34], they showed that almost minimizers of $\mathcal{J}_{2}$ are viscosity solutions in a more general sense. Once this was confirmed, the regularity of the free boundary for almost minimizers follows by applying the De Silva's techniques first developed in 30.

Recently, Dipierro et al in [36] obtained a Lipschitz continuity result to nonnegative almost minimizers for the nonlinear framework, namely for $\mathcal{J}_{p}$ in $B_{1}$, in the case $\max \left\{1, \frac{2 n}{n+2}\right\}<p<\infty$. Precisely, there exists a universal constant $\mathrm{C}=\mathrm{C}(p, n, \beta, \kappa)>0$ such that

$$
\|\nabla u\|_{L^{\infty}\left(B_{1 / 2}\right)} \leq \mathrm{C}\left(1+\|u\|_{W^{1, p}\left(B_{1}\right)}\right)
$$

Additionally, $u$ is uniformly Lipschitz continuous in a neighborhood of contact set $\{u=0\}$. In effect, the authors' approach was strongly inspired by the method introduced by De Silva and Savin in [33. In their setting, the main obstacles faced in are concerned the lack of linearity and the loss of exact descriptions of $p$-harmonic profiles in terms of mean value properties. To overcome such complication, the authors exploit some regularity estimates available in the classical literature.

For the vectorial scenarios we must quote the following contributions:

1. For a singular system with free boundary, De Silva et al in 32 study the regularity properties of vector-valued almost minimizers of the functional

$$
\mathcal{J}_{2}(\mathbf{u} ; \mathrm{D})=\int_{\mathrm{D}}\left(|\nabla \mathbf{u}(x)|^{2}+2|\mathbf{u}|\right) d x
$$

which is strongly related to a version of the classical obstacle problem (see 41).
2. For the weakly coupled vectorial $p$-Laplacian, given constant $\lambda>0$ and a bounded Lipschitz domain $\mathrm{D} \subset \mathbb{R}^{n}$ (for $n \geq 2$ ), Shahgholian et al in [5] Theorem 1.1] address local optimal Lipschitz estimates for almost minimizers of

$$
\mathcal{J}_{p}(\mathbf{v} ; \mathrm{D})=\int_{\mathrm{D}} \sum_{i=1}^{m}\left|\nabla v_{i}(x)\right|^{p}+\lambda \chi_{\{|\mathbf{v}|>\mathbf{0}\}}(x) d x, \quad(\text { for } 1<p<\infty)
$$

where $\mathbf{v}=\left(v_{1}, \cdots, v_{m}\right)$, and $m \in \mathbb{N}$.
Taking into account the above results, we will derive uniform Lipschitz estimates for a general class of almost minimizers of functionals with non-standard growth. Even if our approach is inspired by the works [33] and [36], we highlight that the non-homogeneous nature of our functional entails several difficulties that add to the nonlinear character of the problem already present in the $p$-Laplace case. The lack of sharp embedding results and the hard task of handling modulars and norms (for instance when applying Hölder's inequality) are two of these challenges which are successfully tackled in this manuscript, together with the general technical difficulty of dealing with general behavior different from a power and hence not necessarily homogeneous.

Another gap that we needed to fill was the absence of Campanato-type results dealing with modulars instead of norms. We consider this point to be of independent mathematical interest,
as the results proved here (see Appendix) may be useful in other contexts that pertain regularity in Orlicz-Sobolev settings.

The main regularity result of this proposal is the following (see Section 2 for details on the hypothesis):
Theorem 1.1. Let $\mathrm{G}:[0, \infty) \rightarrow[0, \infty)$ be a Young function such that $g=\mathrm{G}^{\prime}$ is convex and satisfies (1.1) with

$$
\frac{n(\delta+1)}{n-(\delta+1)}>g_{0}+1
$$

Let $u \in W^{1, \mathrm{G}}(\Omega)$ be an almost minimizer of $\mathcal{J}_{\mathrm{G}}$ with exponent $\beta>0$ and constant $\kappa \geq 0$. Then, $u$ is Lipschitz continuous in the interior of $\Omega$. Moreover, for any $\Omega^{\prime} \subset \subset \Omega$ one has

$$
\|\nabla u\|_{L^{\infty}\left(\Omega^{\prime}\right)} \leq \mathrm{CG}^{-1}\left(1+\int_{\Omega} \mathrm{G}(|\nabla u|) d x\right) \quad \text { for any } \quad \Omega^{\prime} \subset \subset \Omega
$$

where $\mathrm{C}=\mathrm{C}\left(\delta, g_{0}, \Omega^{\prime}, \beta, \kappa\right)>0$.
We stress that the nonlinear setting driven by $\mathcal{J}_{\mathrm{G}}(u, \Omega)$ provides further technical obstacles, e.g. the sum of two weak solutions is no longer a weak solution. Therefore, it plays an essential role to develop a theory of $g$-harmonic replacements for our nonlinear scenario to overcome such complications.

Furthermore, we point out that the regularity results in this work do not follow from the nowadays classical literature from calculus of variations for operators with Orlicz-Sobolev structure: Indeed, the integrand of the G-energy functional has a discontinuous signature, instead, the nonstandard growth scenarios that dealt with continuous integrand or even Lipschitz continuous one, see e.g. 1] and 45] for such related topic.

Concerning the strategy of the proof of Theorem 1.1. a dichotomy result is the main step to establishing the optimal Lipschitz continuity. In effect, the dichotomy property ensures that either the average of the G-energy of an almost minimizer to $\mathcal{J}_{\mathrm{G}}$ decreases in a suitable ball or the Luxemburg norm between its gradient and a fixed vector becomes sufficiently small in a proper sense.

Summarizing, either the average of the G-energy of an almost minimizer decreases in a smaller domain, or the almost minimizer is close enough to a linear profile (with good a priori estimates). Once this dichotomy is proved, the next step is to show that one of such alternatives might be improved. Precisely, it will hold a kind of geometric improved of flatness, namely, if an almost minimizer is close to (in the sense of the average of the G-energy) a suitable linear profile, in a ball, then it will be closer to a possibly other linear profile in a smaller ball. Therefore, by iterating such a reasoning, together with the dichotomy property, provides the desired Lipschitz regularity of almost minimizers to $\mathcal{J}_{\mathrm{G}}$,

Finally, in our scenario, we need to show that the sum of G-harmonic replacements solve an equation for which $C^{1, \alpha}$ estimates hold. In effect, this holds true using a linearization strategy, together with the assumptions of the dichotomy. The main difficulty appears in the proof of the improvement of dichotomy's second alternative. The original strategy to solve such an obstacle strongly relies on De Silva-Savin's work [33, where the authors often use harmonic replacements as competitors. This property holds, for harmonic replacements allowing achieve estimates for the average of their energy, exploiting Schauder estimates instead of gradient estimates.

## Some extensions and further comments

We will present a number of interesting building-block models in which our results work as well.

1. Models arising of non-autonomous functionals:

First, by considering the quantitative results (e.g. regularity estimates, Harnack inequality, see references below) we can to deal with the following model cases:

- Problems with ( $p \& q$ )-growth.

$$
u_{0}+W_{0}^{1, p}(\Omega) \ni w \mapsto \int_{\Omega}\left(\mathcal{H}_{0}(x, \nabla w)+\chi_{\{w>0\}}\right) d x,
$$

as long as the integrand $\mathcal{H}_{0}$ enjoys an appropriate double phase type structure

$$
L_{1} \cdot\left(\frac{1}{p}|\xi|^{p}+\frac{1}{q}|\xi|^{q}\right) \leq \mathcal{H}_{0}(x, \xi) \leq L_{2} \cdot\left(\frac{1}{p}|\xi|^{p}+\frac{1}{q}|\xi|^{q}\right),
$$

where $0<L_{1} \leq L_{2}<\infty$ and $1<p<q<\infty$, which make possible to access available existence/regularity results for weak solutions. We recommend to reader see the series of fundamental manuscripts [4], [19, [25] , [26] and [27] for related topics.

- Problems with Uhlenbeck's type structure.

We also stress that our approach is particularly refined and quite far-reaching in order to be employed in other classes of problems. Indeed,
We can also extended our results for Musielak-Orlicz Spaces with non-homogeneous term as follow (see [35, §2.3])

$$
u_{0}+W^{1, \varphi}(\Omega) \ni v \mapsto \int_{\Omega}\left(\varphi(x,|\nabla v|)+\chi_{\{v>0\}}\right) d x
$$

for $(x, \xi) \mapsto \varphi(x,|\xi|)$ with particular structure, including:
$\checkmark p$-growth, i.e., $\varphi(x,|t|)=\frac{1}{p}|t|^{p}$;
$\checkmark$ Orlicz growth, i.e., $\varphi(x,|t|)=\mathrm{G}(|t|)$;
$\checkmark$ Multi phase growth, i.e., $\varphi(x,|t|)=\frac{1}{p}|t|^{p}+\sum_{i=1}^{k} \mathfrak{a}_{i}(x) \frac{1}{q_{i}}|t|^{q}$ for $\leq \mathfrak{a}_{i} \in C^{0,1}(\Omega)$;
just to mention a few, (see [18] and [43, Section 2]).
In this case, $\varphi$ must satisfy the Uhlenbeck's structure: for constants $1<p \leq q<\infty$

$$
t \mapsto \varphi(x, t) \quad \text { is in } \quad C^{1}([0, \infty)) \cap C^{2}((0, \infty)) \quad \text { and } \quad p-1 \leq \frac{t \varphi^{\prime \prime}(x, t)}{\varphi^{\prime}(x, t)} \leq \max _{1 \leq i \leq k}\left\{q_{i}-1\right\} .
$$

2. Models with generalized doubly degenerate growth.

Finally, we may consider a wide class of nonlinear degenerate models with non standard growth properties (cf. [11, and 18] for a survey). An archetypical example we have in mind concerns models of the form

$$
\mathcal{J}_{\mathcal{G}_{\mathrm{G}, \mathrm{H}}}(u, \Omega):=\int_{\Omega}\left(\mathcal{G}_{\mathrm{G}, \mathrm{H}}(x,|\nabla u|)+\chi_{\{u>0\}}\right) d x
$$

where

$$
\mathcal{G}_{\mathrm{G}, \mathrm{H}}(x, \xi):=\mathrm{G}(|\xi|)+\mathfrak{a}(x) \mathrm{H}(|\xi|) \quad \text { with } \quad 0 \leq \mathfrak{a} \in C^{0,1}(\Omega),
$$

for Young functions G, $\mathrm{H}:[0, \infty) \rightarrow[0, \infty)$ with $\mathrm{G}, \mathrm{H} \in \Delta_{2} \cap \nabla_{2}, \mathrm{G} \prec \mathrm{H} \prec \mathrm{G}^{1+\frac{1}{n}}$, and satisfying the Lieberman's condition: there exist constants $\mathrm{c}_{\mathrm{G}}, \mathrm{c}_{\mathrm{G}}^{\prime}, \mathrm{c}_{\mathrm{H}}, \mathrm{c}_{\mathrm{H}}^{\prime} \geq 1$ such that

$$
\mathrm{c}_{\mathrm{G}}^{\prime} \leq \frac{t \mathrm{G}^{\prime}(t)}{\mathrm{G}(t)} \leq \mathrm{c}_{\mathrm{G}} \quad \text { and } \quad \mathrm{c}_{\mathrm{H}}^{\prime} \leq \frac{t \mathrm{H}^{\prime}(t)}{\mathrm{H}(t)} \leq \mathrm{c}_{\mathrm{H}} \quad \text { for all } \quad t>0 .
$$

The rest of the paper is organized as follows: in Section 2 we present the preliminary definitions and results that will be needed throughout the paper; Section 3 is devoted to the proof of the most important technical results of the paper, namely Lemmas 3.1 and 3.3 and, as a consequence, the crucial interior gradient estimate in Corollary 3.4. In Section 4 we prove the main result of this paper, i.e. Theorem 1.1 Finally, the Appendix contains the proof of the Campanato-type regularity result that is used in Corollary 3.4 summarized in Theorem 4.3

## 2 Preliminaries

In this section we present some preliminary definitions and results that will be used in the proofs of the main results of the manuscript. We start with some basic facts regarding Young functions and Orlicz-Sobolev spaces; these are rather well known but we include them for the sake of completeness.

### 2.1 Young functions

An application $\mathrm{G}:[0, \infty) \longrightarrow[0, \infty)$ is said to be a Young function if it admits the integral representation $\mathrm{G}(t)=\int_{0}^{t} g(\tau) d \tau$, where $g$ is a right continuous function defined on $[0, \infty)$ and satisfying:

$$
\left\{\begin{array}{l}
g(0)=0, \quad g(t)>0 \text { for } t>0 \\
g \text { is nondecreasing on }(0, \infty) \\
\lim _{t \rightarrow \infty} g(t)=\infty
\end{array}\right.
$$

From these properties it is easy to see that a Young function $G$ is continuous, nonnegative, strictly increasing and convex on $[0, \infty)$. Further, we recall that we may extend $g$ to the whole $\mathbb{R}$ in an odd fashion: for $t<0 g(t)=-g(-t)$. And we may (and will) assume without loss of generality that $\mathrm{G}(1)=\mathrm{G}^{-1}(1)=1$. Note that $G$ is strictly increasing and hence $\mathrm{G}^{-1}$ is well defined.

In this work we will consider the class of Young functions such that $g=\mathrm{G}^{\prime}$ is an absolutely continuous function that satisfies the condition

$$
\begin{equation*}
\delta \leq \frac{t g^{\prime}(t)}{g(t)} \leq g_{0} \tag{2.1}
\end{equation*}
$$

for some constants $1<\delta \leq g_{0}$. This condition was first considered in the seminal work of G . Lieberman [45] and is the analogous to the ellipticity condition in the linear theory. For our purposes, we will make the (rather standard assumption) that

$$
\begin{equation*}
(\delta+1)^{*}>g_{0}+1 \tag{2.2}
\end{equation*}
$$

where $(\delta+1)^{*}$ is the Sobolev conjugate of $(\delta+1)$, i.e. $(\delta+1)^{*}=\frac{n(\delta+1)}{n-(\delta+1)}$. We will also assume that

$$
g \text { is convex. }
$$

This last assumption is analogous to the degenerate setting in the homogeneous problem, i.e. the case where $p \geq 2$.

Equation (2.1) implies that that G satisfies

$$
\begin{equation*}
\delta+1 \leq \frac{\operatorname{tg}(t)}{\mathrm{G}(t)} \leq g_{0}+1 \tag{2.3}
\end{equation*}
$$

this condition is equivalent to ask $G$ and $\tilde{G}$ to satisfy the $\Delta_{2}$ condition or doubling condition, i.e.,

$$
\begin{equation*}
\mathrm{G}(2 t) \leq 2^{g_{0}+1} \mathrm{G}(t), \quad \tilde{\mathrm{G}}(2 t) \leq 2^{1+\frac{1}{\delta}} \tilde{\mathrm{G}}(t) \tag{2.4}
\end{equation*}
$$

where the complementary function of a Young function $G$ is the Young function $\tilde{G}$ defined as

$$
\tilde{\mathrm{G}}(t)=\sup \{t a-\mathrm{G}(a): a>0\}
$$

The doubling condition allow us to split sums as

$$
\begin{equation*}
\mathrm{G}(a+b) \leq 2^{g_{0}}(\mathrm{G}(a)+\mathrm{G}(b)) \tag{2.5}
\end{equation*}
$$

Moreover, integrating (2.3) we have that

$$
\begin{gather*}
t^{g_{0}+1} \leq \mathrm{G}(t) \leq t^{\delta+1}, \quad \text { if } 0<t \leq 1  \tag{2.6}\\
t^{\delta+1} \leq \mathrm{G}(t) \leq t^{g_{0}+1}, \quad \text { if } t>1
\end{gather*}
$$

As mentioned in the Introduction, the lack of homogeneity is a serious technical difficulty in our context. The following lemma gives the alternatives that hold in this scenario; its proof is elementary so we omit it.

Lemma 2.1. For $\theta \in[0,1]$ and $t \geq 0$

$$
\mathrm{G}(\theta t) \leq \theta \mathrm{G}(t)
$$

and for $\theta \geq 1$ and $t \geq 0$

$$
\mathrm{G}(\theta t) \geq \theta \mathrm{G}(t)
$$

More generally, for any, $\theta, t \geq 0$

$$
\begin{array}{r}
\mathrm{G}(t) \min \left\{\theta^{\delta+1}, \theta^{g_{0}+1}\right\} \leq \mathrm{G}(\theta t) \leq \mathrm{G}(t) \max \left\{\theta^{\delta+1}, \theta^{g_{0}+1}\right\} \\
\mathrm{G}^{-1}(t) \min \left\{\theta^{\frac{1}{\delta+1}}, \theta^{\frac{1}{g_{0}+1}}\right\} \leq \mathrm{G}^{-1}(\theta t) \leq \mathrm{G}^{-1}(t) \max \left\{\theta^{\frac{1}{\delta+1}}, \theta^{\frac{1}{g_{0}+1}}\right\} \tag{2.8}
\end{array}
$$

### 2.2 Orlicz-Sobolev spaces

Given a Young function G and a bounded open set $\Omega \subset \mathbb{R}^{n}$, we consider the spaces $L^{\mathrm{G}}(\Omega)$ and $W^{1, \mathrm{G}}(\Omega)$ defined as follows:

$$
\begin{aligned}
L^{\mathrm{G}}(\Omega) & =\left\{u: \mathbb{R} \rightarrow \mathbb{R} \quad \text { measurable such that } \Phi_{\mathrm{G}, \Omega}(u)<\infty\right\} \\
W^{1, \mathrm{G}}(\Omega) & =\left\{u \in L^{\mathrm{G}}(\Omega) \quad \text { such that } \Phi_{\mathrm{G}, \Omega}(|\nabla u|)<\infty\right\}
\end{aligned}
$$

where the modular $\Phi_{\mathrm{G}, \Omega}(u)$ stands for

$$
\Phi_{\mathrm{G}, \Omega}(u)=\int_{\Omega} \mathrm{G}(|u|) d x
$$

These spaces are endowed with the so-called Luxemburg norm defined as follows:

$$
\|u\|_{L^{\mathrm{G}}(\Omega)}=\inf \left\{\lambda>0: \Phi_{\mathrm{G}, \Omega}\left(\frac{u}{\lambda}\right) \leq 1\right\}
$$

and

$$
\|u\|_{W^{1, \mathrm{G}}(\Omega)}=\|u\|_{L^{\mathrm{G}}(\Omega)}+\|\nabla u\|_{L^{\mathrm{G}}(\Omega)}
$$

In general, it is easy to see that

$$
\begin{equation*}
\|w\|_{L^{\mathrm{G}}(\Omega)} \leq \max \left\{\Phi_{\mathrm{G}, \Omega}(w)^{\frac{1}{g_{0}+1}}, \Phi_{\mathrm{G}, \Omega}(w)^{\frac{1}{\delta+1}}\right\} \tag{2.9}
\end{equation*}
$$

### 2.3 Technical results concerning $g$-harmonic functions

The notion of $g$-harmonic function will of course be of great importance in our work; In effect, $g$-harmonic functions are weak solutions of the equation $\Delta_{g} v=0$ where $\Delta_{g}$ is the $g$-Laplacian operator given by

$$
\Delta_{g} v=\operatorname{div}\left(g(|\nabla v|) \frac{\nabla v}{|\nabla v|}\right)
$$

More precisely, we will be interested in unique weak solutions of the Dirichlet problem

$$
\left\{\begin{align*}
\Delta_{g} v & =  \tag{2.10}\\
0 & \text { in } \quad \Omega \\
v & =h
\end{align*} \quad \text { on } \quad \partial \Omega\right.
$$

Such weak solutions can be constructed as minimizers of the energy functional $u \rightarrow \int_{\Omega} \mathrm{G}(|\nabla u|) d x$ (with fixed Dirichlet boundary condition) via the Direct Method of the Calculus of Variations.

The following proposition will be used, its proof is contained in the Lieberman's fundamental work [45, Section 5]. Before stating it, we recall that a constant will be called universal if it depends only on $n, \delta$ and $g_{0}$ (and eventually $\beta$ or $\kappa$ in Definition 2.7); multiplicative constants will be denoted by $C$ and in the proofs they may change from line to line.

Proposition 2.2. Let $v \in W^{1, \mathrm{G}}\left(B_{R}\right)$ be a $g$-harmonic function. Then,

1. there exists a universal constant $\mathrm{C}>0$ such that for any $x \in B_{R / 2}$

$$
\begin{equation*}
\sup _{B_{R / 4}(x)} \mathrm{G}(|\nabla v|) \leq \mathrm{C} f_{B_{R / 2}(x)} \mathrm{G}(|\nabla v|) d x . \tag{2.11}
\end{equation*}
$$

2. there exist universal constants $\mathrm{C}>0$ and $\alpha \in(0,1)$ such that

$$
\begin{equation*}
\underset{B_{\rho}}{\operatorname{osc}}|\nabla v| \leq \mathrm{C} \sup _{B_{R}}|\nabla v|\left(\frac{\rho}{R}\right)^{\alpha}, \quad 0<\rho<R . \tag{2.12}
\end{equation*}
$$

Remark 2.3. The estimates in Proposition (2.2) still hold under the more general assumption that $v$ satisfies $\operatorname{div}(\mathbb{A}(x) \nabla v)=0$ with $x \mapsto \mathbb{A}(x)$ satisfying the structural condition:

$$
\lambda \frac{g(|z|)}{|z|}|\xi|^{2} \leq \mathbb{A}(x) \xi \cdot \xi \leq \Lambda \frac{g(|z|)}{|z|}|\xi|^{2} .
$$

See [45] for details.
Another important concept that will be used is that of harmonic replacement in a ball, which roughly speaking is the $g$-harmonic that coincides with a given function on the boundary of a ball:

Definition 2.4. The $g$-harmonic replacement of a function $u \in W^{1, G}(\Omega)$ in $B_{r}(x)$ is the unique $g$-harmonic function $v \in W^{1, G}\left(B_{r}(x)\right)$ that coincides with $u$ on $\partial B_{r}(x)$ in the sense of traces, i.e. the unique weak solution of (2.10) with $\Omega=B_{r}(x)$ and $h=u$.

The following technical lemmas will be used later: the first one is a bound on the energy of difference between and function and its $g$-harmonic replacement and the other one is needed to ensure the desired ellipticity (in the sense of Remark 2.3) so that interior estimates apply:

Lemma 2.5. Let $G$ a Young function satisfying (2.1) and such that $\mathrm{G}^{\prime}=g$ is a convex function, $u \in W^{1, G}\left(B_{r}\right)$ and $v$ the $g$-harmonic replacement of $u$ in $B_{r}$. Then the following inequality holds for a universal constant $\mathrm{C}>0$

$$
\int_{B_{r}} \mathrm{G}(|\nabla u-\nabla v|) d x \leq \mathrm{C} \int_{B_{r}} \mathrm{G}(|\nabla u|)-\mathrm{G}(|\nabla v|) d x .
$$

Proof. As $v$ is a weak solution of $\Delta_{g} u=0$, we know that

$$
\begin{equation*}
\int_{B_{r}} g(|\nabla v|) \frac{\nabla v}{|\nabla v|} \nabla \varphi d x=0, \tag{2.13}
\end{equation*}
$$

for all $\varphi \in W_{0}^{1, \mathrm{G}}\left(B_{r}\right)$.
We consider the following convex combination

$$
u^{s}(x)=s u(x)+(1-s) v(x) \quad 0 \leq s \leq 1
$$

Observe that $u^{0}=v$ and $u^{1}=u$. Now using that $u-v \in W_{0}^{1, G}(\Omega)$ and (2.13), we have

$$
\begin{aligned}
\int_{B_{r}} \mathrm{G}(|\nabla u|)-\mathrm{G}(|\nabla v|) d x & =\int_{B_{r}} \mathrm{G}\left(\left|\nabla u^{1}\right|\right)-\mathrm{G}\left(\left|\nabla u^{0}\right|\right) d x \\
& =\int_{B_{r}}\left(\int_{0}^{1} \frac{d}{d s} \mathrm{G}\left(\left|\nabla u^{s}\right|\right) d s\right) d x \\
& =\int_{B_{r}}\left(\int_{0}^{1} g\left(\left|\nabla u^{s}\right|\right) \frac{\nabla u^{s}}{\left|\nabla u^{s}\right|} \cdot \nabla(u-v) d s\right) d x \\
& =\int_{B_{r}} \int_{0}^{1}\left(g\left(\left|\nabla u^{s}\right|\right) \frac{\nabla u^{s}}{\left|\nabla u^{s}\right|}-g(|\nabla v|) \frac{\nabla v}{|\nabla v|}\right) \cdot \nabla(u-v) d s d x
\end{aligned}
$$

Next, note that $u^{s}(x)-v(x)=s u(x)-s v(x)=s(u(x)-v(x))$; then using that

$$
\left(g(|a|) \frac{a}{|a|}-g(|b|) \frac{b}{|b|}\right) \cdot \nabla(a-b) \geq \mathrm{CG}(|a-b|)
$$

for a constant $\mathrm{C}=\mathrm{C}(\delta)>0$ (see [16, Lemma 3.1] for a proof) and (2.7) the last above term is bounded in the following way

$$
\begin{aligned}
\int_{B_{r}} \frac{1}{s} \int_{0}^{1}\left(g\left(\left|\nabla u^{s}\right|\right) \frac{\nabla u^{s}}{\left|\nabla u^{s}\right|}-g(|\nabla v|) \frac{\nabla v}{|\nabla v|}\right) \cdot \nabla\left(u^{s}-v\right) d s d x & \geq \mathrm{C} \int_{0}^{1} \frac{1}{s} \int_{B_{r}} \mathrm{G}\left(\left|\nabla u^{s}-\nabla v\right|\right) d x d s \\
& \geq \mathrm{C} \int_{0}^{1} \frac{s^{g_{0}+1}}{s} \int_{B_{r}} \mathrm{G}(|\nabla u-\nabla v|) d x d s \\
& \geq \frac{\mathrm{C}}{g_{0}+1} \int_{B_{r}}^{\mathrm{G}(|\nabla u-\nabla v|) d x}
\end{aligned}
$$

and the desired inequality follows.
Lemma 2.6. Let $q \in \mathbb{R}^{n}$ and $|h(x)|<\frac{|q|}{2}$. If $\overrightarrow{\mathbf{F}}(z)=g(|z|) \frac{z}{|z|}$ for a Young function satisfying (2.1) and

$$
\mathfrak{A}(x):=\int_{0}^{1} D \overrightarrow{\mathbf{F}}(q+t h(x)) d t
$$

then

$$
\begin{equation*}
\lambda \frac{g(|q|)}{|q|}|\xi|^{2} \leq \mathfrak{A}(x) \xi \cdot \xi \leq \Lambda \frac{g(|q|)}{|q|}|\xi|^{2} \tag{2.14}
\end{equation*}
$$

for any $\xi \in \mathbb{R}^{n} \backslash\{0\}$ and for some constants $0<\lambda \leq \Lambda$ depending only on $\delta$ and $g_{0}$.
Proof. We start by computing $D \overrightarrow{\mathbf{F}}$ : if $i \neq j$

$$
D_{i} \overrightarrow{\mathbf{F}}_{j}(z)=D_{i}\left(g(|z|) \frac{z_{j}}{|z|}\right)=g^{\prime}(|z|) \frac{z_{i} z_{j}}{|z|^{2}}-g(|z|) \frac{z_{i} z_{j}}{|z|^{3}}
$$

while

$$
D_{i} \overrightarrow{\mathbf{F}}_{i}(z)=D_{i}\left(g(|z|) \frac{z_{i}}{|z|}\right)=g^{\prime}(|z|) \frac{z_{i}^{2}}{|z|^{2}}+g(|z|)\left(\frac{1}{|z|}-\frac{z_{i}^{2}}{|z|^{3}}\right)
$$

Then,

$$
\begin{aligned}
D \overrightarrow{\mathbf{F}}(z) \xi \cdot \xi & =\sum_{i \neq j}\left(g^{\prime}(|z|) \frac{z_{i} z_{j}}{|z|^{2}}-g(|z|) \frac{z_{i} z_{j}}{|z|^{3}}\right) \xi_{i} \xi_{j}+\sum_{i}\left(g^{\prime}(|z|) \frac{z_{i}^{2}}{|z|^{2}}+g(|z|)\left(\frac{1}{|z|}-\frac{z_{i}^{2}}{|z|^{3}}\right)\right) \xi_{i}^{2} \\
& =\sum_{i \neq j}\left(g^{\prime}(|z|)-\frac{g(|z|)}{|z|}\right) \frac{z_{i} z_{j} \xi_{i} \xi_{j}}{|z|^{2}}+g^{\prime}(|z|)|\xi|^{2} \\
& =\left(g^{\prime}(|z|)-\frac{g(|z|)}{|z|}\right) \frac{1}{|z|^{2}}(z \cdot \xi)^{2}+\frac{g(|z|)}{|z|}|\xi|^{2} \\
& \geq\left(\frac{g(|z|)}{|z|}-\left(g^{\prime}(|z|)-\frac{g(|z|)}{|z|}\right)\right)|\xi|^{2} \\
& \geq g_{0} \frac{g(|z|)}{|z|}|\xi|^{2} \\
& \geq g^{\prime}(|z|)|\xi|^{2} .
\end{aligned}
$$

This implies

$$
\mathfrak{A}(x) \xi \cdot \xi \geq \int_{0}^{1} g^{\prime}(|q+t h(x)|) d t|\xi|^{2} \geq g^{\prime}\left(\frac{|q|}{2}\right)|\xi|^{2} \geq \delta \frac{g\left(\frac{|q|}{2}\right)}{\frac{|q|}{2}}|\xi|^{2} \geq \lambda \frac{g(|q|)}{|q|}|\xi|^{2}
$$

where $\lambda:=2^{1-g_{0}} \delta$, and we have used that $|q+t h(x)| \geq \frac{|q|}{2}$ by hypothesis, that $g^{\prime}$ is increasing and the doubling condition for $g$. This gives the lower bound on (2.14).

Similarly, we find that

$$
D \overrightarrow{\mathbf{F}}(z) \xi \cdot \xi \leq\left(\frac{g(|z|)}{|z|}+\left(g^{\prime}(|z|)-\frac{g(|z|)}{|z|}\right)\right)|\xi|^{2}=g^{\prime}(|z|)|\xi|^{2}
$$

and

$$
\mathfrak{A}(x) \xi \cdot \xi \leq g^{\prime}\left(\frac{3|q|}{2}\right)|\xi|^{2} \leq g_{0} \frac{g\left(\frac{3|q|}{2}\right)}{\frac{3|q|}{2}}|\xi|^{2} \leq \Lambda \frac{g(|q|)}{|q|}|\xi|^{2}
$$

now with $\Lambda:=\left(\frac{3}{2}\right)^{g_{0}-1} g_{0}$, this time using that $|q+t h(x)| \leq \frac{3|q|}{2}$.

### 2.4 Almost minimizers

In this section we give the rigorous definition of an almost minimizer and show that they satisfy a nice scaling property:

Definition 2.7. A function $u \in W^{1, G}(\Omega)$ is an almost minimizer of $\mathcal{J}_{G}$ with exponent $\beta>0$ and constant $\kappa \geq 0$ if

1. $u \geq 0$ a.e. in $\Omega$;
2. for any ball $B_{r}(x)$ such that $\overline{B_{r}(x)} \subset \Omega$ and any $v \in W^{1, G}\left(B_{r}(x)\right)$ such that $v=u$ on $\partial B_{r}(x)$ in the sense of traces (i.e. $\left.v-u \in W_{0}^{1, G}\left(B_{r}(x)\right)\right)$ it holds that

$$
\mathcal{J}_{\mathrm{G}}\left(u, B_{r}(x)\right) \leq\left(1+\kappa r^{\beta}\right) \mathcal{J}_{\mathrm{G}}\left(v, B_{r}(x)\right)
$$

Almost minimizers satisfy the following scaling property:
Lemma 2.8. If $u \in W^{1, G}\left(B_{1}\right)$ is an almost minimizer of $\mathcal{J}_{G}$ in $B_{1}$ with exponent $\beta>0$ and constant $\kappa$ and $0<r<1$ then $u_{r}(x):=\frac{u(r x)}{r}$ is an almost minimizer of $\mathcal{J}_{G}$ in $B_{1 / r}$ with exponent $\beta>0$ and constant $r^{\beta} \kappa$.

Proof. Assume $u$ is an almost minimizer of $\mathcal{J}_{G}$ in $B_{1}$ with exponent $\beta>0$ and constant $\kappa$. Let $\bar{x} \in B_{1 / r}$ and $\rho>0$ be such that $\overline{B_{\rho}(\bar{x})} \subset B_{1 / r}$ and $v \in W^{1, G}\left(B_{\rho}(\bar{x})\right)$ such that $v=u_{r}$ on $\partial B_{\rho}(\bar{x})$ in the sense of traces.

Denoting $\bar{y}=r \bar{x}$ we have

$$
\overline{B_{\rho}(\bar{x})} \subset B_{1 / r} \Rightarrow \overline{B_{r \rho}(\bar{y})} \subset B_{1}, \quad x \in \partial B_{r \rho}(\bar{y}) \Rightarrow \frac{x}{r} \in \partial B_{\rho}(\bar{x})
$$

Then, by hypothesis

$$
r v\left(\frac{x}{r}\right)=r u_{r}\left(\frac{x}{r}\right)=u(x)
$$

when $x \in \partial B_{r \rho}(\bar{y})$ and therefore

$$
\mathcal{J}_{\mathrm{G}}\left(u, B_{r \rho}(\bar{y})\right) \leq\left(1+\kappa(r \rho)^{\beta}\right) \mathcal{J}_{\mathrm{G}}\left(r v\left(\frac{\dot{ }}{r}\right), B_{r \rho}(\bar{y})\right) .
$$

But changing variables we have that

$$
\begin{aligned}
\mathcal{J}_{\mathrm{G}}\left(u, B_{r \rho}(\bar{y})\right) & =\int_{B_{r \rho}(\bar{y})} \mathrm{G}(|\nabla u(y)|)+\chi_{\{u>0\}} d y \\
& =r^{n} \int_{B_{\rho}(\bar{x})} \mathrm{G}(|\nabla u(r x)|)+\chi_{\{u>0\}}(r x) d x \\
& =r^{n} \int_{B_{\rho}(\bar{x})} \mathrm{G}\left(\left|\nabla u_{r}\right|\right)+\chi_{\left\{u_{r}>0\right\}} d x \\
& =r^{n} \mathcal{J}_{\mathrm{G}}\left(u_{r}, B_{\rho}(\bar{x})\right)
\end{aligned}
$$

and a similar computation can be done to show that

$$
\mathcal{J}_{\mathrm{G}}\left(r v\left(\frac{\dot{\varphi}}{r}\right), B_{r \rho}(\bar{y})\right)=r^{n} \mathcal{J}_{\mathrm{G}}\left(v, B_{\rho}(\bar{x})\right)
$$

and get the desired inequality.

## 3 Dichotomy lemmas

In this section we prove the main technical results needed in the proof of Theorem 1.1. We being with the following dichotomy lemma:

Lemma 3.1. There exists $\varepsilon_{0} \in(0,1)$ such that for every $0<\varepsilon \leq \varepsilon_{0}$ there exist $\eta \in(0,1)$, $M>1$ and $\sigma_{0} \in(0,1)$ depending on $\varepsilon, n, \delta$ and $g_{0}$ such that: if $\sigma \leq \sigma_{0}, a>\mathrm{M}, u \in W^{1, \mathrm{G}}\left(B_{1}\right)$ and the following inequality holds for all $v \in W^{1, \mathrm{G}}\left(B_{1}\right)$ such that $v=u$ on $\partial B_{1}$ :

$$
\mathcal{J}_{\mathrm{G}}\left(u, B_{1}\right) \leq(1+\sigma) \mathcal{J}_{\mathrm{G}}\left(v, B_{1}\right)
$$

then, if we denote

$$
\begin{equation*}
\mathrm{G}(a):=f_{B_{1}} \mathrm{G}(|\nabla u|) d x \tag{3.1}
\end{equation*}
$$

the following dichotomy holds: either

$$
\begin{equation*}
f_{B_{\eta}} \mathrm{G}(|\nabla u|) d x \leq \mathrm{G}\left(\frac{a}{2}\right) \tag{3.2}
\end{equation*}
$$

or

$$
\begin{equation*}
f_{B_{\eta}} \mathrm{G}(|\nabla u-q|) d x \leq \mathrm{G}(\varepsilon a) \tag{3.3}
\end{equation*}
$$

where $q \in \mathbb{R}^{n}$ verifies

$$
\begin{equation*}
\mathrm{G}^{-1}\left(\frac{1}{\mathrm{C}} \mathrm{G}\left(\frac{a}{4}\right)\right)<|q|<\mathrm{C}_{0} a . \tag{3.4}
\end{equation*}
$$

Proof. Let $v$ be the $g$-harmonic replacement of $u$ in $B_{1}$. We start by computing, with the aid of Lemma 2.5 and the definition of almost minimizer,

$$
\begin{aligned}
\int_{B_{1}} \mathrm{G}(|\nabla u-\nabla v|) d x & \leq \mathrm{C} \int_{B_{1}}(\mathrm{G}(|\nabla u|)-\mathrm{G}(|\nabla v|)) d x \\
& \leq \mathrm{C}\left(\int_{B_{1}} \mathrm{G}(|\nabla u|)+\chi_{\{u>0\}} d x-\mathrm{G}(|\nabla v|) d x\right) \\
& =\mathrm{C}\left(\mathcal{J}_{\mathrm{G}}\left(u, B_{1}\right)-\int_{B_{1}} \mathrm{G}(|\nabla v|) d x\right) \\
& \leq \mathrm{C}\left((1+\sigma) \mathcal{J}_{\mathrm{G}}\left(v, B_{1}\right)-\int_{B_{1}} \mathrm{G}(|\nabla v|) d x\right) \\
& =\mathrm{C}\left(\sigma\left(\int_{B_{1}} \mathrm{G}(|\nabla v|) d x+\left|\{v>0\} \cap B_{1}\right|\right)+\left|\{v>0\} \cap B_{1}\right|\right) \\
& \leq \mathrm{C}\left(\sigma \int_{B_{1}} \mathrm{G}(|\nabla v|) d x+1\right) \\
& \leq \mathrm{C}\left(\sigma \int_{B_{1}} \mathrm{G}(|\nabla u|) d x+1\right),
\end{aligned}
$$

the last inequality owing to the fact that $v$ minimizes the energy. Taking average and recalling (3.1) we have

$$
f_{B_{1}} \mathrm{G}(|\nabla u-\nabla v|) d x \leq \mathrm{C}(\sigma \mathrm{G}(a)+1) .
$$

On the other hand, if we fix $x \in B_{\frac{1}{2}}$, by (2.11) in Proposition 2.2 we have

$$
\mathrm{G}(|\nabla v(x)|) \leq \sup _{B_{\frac{4}{4}}(x)} \mathrm{G}(|\nabla v|) \leq \mathrm{C} f_{B_{\frac{1}{2}}(x)} \mathrm{G}(|\nabla v|) d y \leq \mathrm{C} f_{B_{1}} \mathrm{G}(|\nabla u|) d y \leq \mathrm{CG}(a)
$$

so that

$$
\begin{equation*}
\mathrm{G}(|\nabla v|) \leq C \mathrm{G}(a) \text { in } B_{1 / 2} . \tag{3.5}
\end{equation*}
$$

Further, if we denote $q=\nabla v(0)$, and recall (2.12) in Proposition 2.2 we have

$$
\begin{aligned}
f_{B_{\eta}} \mathrm{G}(|\nabla v-q|) d x & \leq f_{B_{\eta}} \mathrm{G}\left(\mathrm{C}\left(\frac{\eta}{\frac{1}{2}}\right)^{\alpha} \sup _{B_{\frac{1}{2}}}|\nabla v|\right) d x \\
& \leq\left(\mathrm{C}\left(\frac{\eta}{\frac{1}{2}}\right)^{\alpha}\right)^{\delta+1} f_{B_{\eta}} \mathrm{G}\left(\sup _{B_{\frac{1}{2}}}|\nabla v|\right) d x \\
& =\mathrm{C} \eta^{\alpha(\delta+1)} \mathrm{G}\left(\sup _{B_{\frac{1}{2}}}|\nabla v|\right)
\end{aligned}
$$

and by (3.5)

$$
f_{B_{\eta}} \mathrm{G}(|\nabla v-q|) d x \leq \mathrm{C} \eta^{\alpha(\delta+1)} \mathrm{G}(a) \quad \text { for all } \eta \leq \frac{1}{2} .
$$

Now, using the $\Delta_{2}$ condition (see (2.4)),

$$
\begin{aligned}
f_{B_{\eta}} \mathrm{G}(|\nabla u-q|) d x & \leq \mathrm{C}\left(f_{B_{\eta}} \mathrm{G}(|\nabla u-\nabla v|) d x+f_{B_{\eta}} \mathrm{G}(|\nabla v-q|) d x\right) \\
& =\mathfrak{I}+\mathfrak{I I}
\end{aligned}
$$

These two terms are bounded using the previous estimates:

$$
\mathfrak{I} \leq \frac{1}{\left|B_{\eta}\right|} \int_{B_{1}} \mathrm{G}(|\nabla u-\nabla v|) d x \leq \frac{\mathrm{C}}{\eta^{n}}(\sigma \mathrm{G}(a)+1)
$$

and

$$
\mathfrak{I I} \leq \mathrm{C} \eta^{\alpha(\delta+1)} \mathrm{G}(a) .
$$

So we get

$$
\begin{equation*}
f_{B_{\eta}} \mathrm{G}(|\nabla u-q|) d x \leq \mathrm{C} \eta^{-n} \sigma \mathrm{G}(a)+\mathrm{C} \eta^{-n}+\mathrm{CG}(a) \eta^{\alpha(\delta+1)} \tag{3.6}
\end{equation*}
$$

and

$$
\begin{equation*}
f_{B_{\eta}} \mathrm{G}(|\nabla u|) d x \leq \mathrm{C} \eta^{-n} \sigma \mathrm{G}(a)+\mathrm{C} \eta^{-n}+\mathrm{CG}(a) \eta^{\alpha(\delta+1)}+\mathrm{CG}(|q|) \tag{3.7}
\end{equation*}
$$

Next, we choose $\sigma=\eta^{n+1}$

$$
\mathrm{C} \eta^{-n} \sigma \mathrm{G}(a)+\mathrm{C} \eta^{-n}+\mathrm{CG}(a) \eta^{\alpha(\delta+1)}=\mathrm{C} \eta \mathrm{G}(a)+\mathrm{C} \eta^{-n}+\mathrm{CG}(a) \eta^{\alpha(\delta+1)}
$$

and $a$ such that

$$
\begin{equation*}
\mathrm{C} \eta \mathrm{G}(a)+\mathrm{C} \eta^{-n}+\mathrm{CG}(a) \eta^{\alpha(\delta+1)} \leq \mathrm{G}(\varepsilon a) \tag{3.8}
\end{equation*}
$$

The inequality (3.8) holds if

$$
a \geq \mathrm{G}^{-1}\left(\frac{\mathrm{C} \eta^{-n}}{\varepsilon^{g_{0}+1}-\mathrm{C} \eta-\mathrm{C} \eta^{\alpha(\delta+1)}}\right)
$$

(Note that the denominator is positive if $\eta$ is small enough.) Then,

$$
f_{B_{\eta}} \mathrm{G}(|\nabla u|) d x \leq \mathrm{G}(\varepsilon a)+\mathrm{CG}(|q|)
$$

Next we split the two possible cases; if

$$
|q| \leq \mathrm{G}^{-1}\left(\frac{1}{\mathrm{C}} \mathrm{G}\left(\frac{a}{4}\right)\right)
$$

making $\varepsilon<1 / 4$ we get

$$
f_{B_{\eta}} \mathrm{G}(|\nabla u|) d x \leq 2 \mathrm{G}\left(\frac{a}{4}\right) \leq \frac{2}{2^{\delta+1}} \mathrm{G}\left(\frac{a}{2}\right) \leq \mathrm{G}\left(\frac{a}{2}\right)
$$

which is the first alternative in the Lemma.
On the other hand, if

$$
|q|>\mathrm{G}^{-1}\left(\frac{1}{\mathrm{C}} \mathrm{G}\left(\frac{a}{4}\right)\right)
$$

then by (3.6)

$$
f_{B_{\eta}} \mathrm{G}(|\nabla u-q|) d x \leq \mathrm{G}(\varepsilon a)
$$

Noting that (3.5) implies the bound on $|q|$ we finish the proof.

Remark 3.2. Using the $\Delta_{2}$ condition (see in particular (2.7)) we can replace (3.3) by

$$
\begin{equation*}
f_{B_{\eta}} \mathrm{G}(|\nabla u-q|) d x \leq \varepsilon^{\delta+1} \mathrm{G}(a) \tag{3.9}
\end{equation*}
$$

The following lemma can be seen as an improvement of the previous one in the case where $\varepsilon$ and $\sigma$ are (universally) small enough.

Lemma 3.3. Let $0<a_{0}<a_{1}$ and G a Young function satisfying (2.1) such that $\mathrm{G}^{\prime}=g$ is a convex function. Let $u \in W^{1, G}\left(B_{1}\right)$ with $u \geq 0$ and:

$$
\mathcal{J}_{\mathrm{G}}\left(u, B_{1}\right) \leq(1+\sigma) \mathcal{J}_{\mathrm{G}}\left(v, B_{1}\right)
$$

for all $v \in W^{1, \mathrm{G}}\left(B_{1}\right)$ such that $v=u$ on $\partial B_{1}$. Define $\mathrm{G}(a)$ be as in (3.1) and assume

$$
a_{0} \leq a \leq a_{1}
$$

Assume also that

$$
f_{B_{1}} \mathrm{G}(|\nabla u-q|) d x \leq \mathrm{G}(a) \varepsilon^{\delta+1}
$$

for $\varepsilon$ small enough with $q \in \mathbb{R}^{n}$ satisfying

$$
\begin{equation*}
\mathrm{G}^{-1}\left(\frac{1}{\mathrm{C}} \mathrm{G}\left(\frac{a}{8}\right)\right) \leq|q| \leq 2 \mathrm{C}_{0} a \tag{3.10}
\end{equation*}
$$

with $C_{0}$ given in (3.4).
Then there exist universal constants $\varepsilon_{0}, \alpha, r \in(0,1)$ such that if $\varepsilon<\varepsilon_{0}$ and $\sigma \leq c_{0} G(\varepsilon)$ then

$$
f_{B_{r}} \mathrm{G}(|\nabla u-\tilde{q}|) d x \leq r^{\alpha(\delta+1)} \mathrm{G}(a) \varepsilon^{\delta+1}
$$

where $\tilde{q} \in \mathbb{R}^{n}$ verifies

$$
|q-\tilde{q}| \leq \tilde{C} \varepsilon^{\tau} a \quad \text { where } \quad \tau=\frac{\delta+1}{g_{0}+1}
$$

Proof. Let $\hat{v}$ be the $g$-harmonic replacement of $u$ in $B_{1 / 2}$ and define

$$
\begin{cases}v=\hat{v} & \text { in } B_{1 / 2} \\ v=u & \text { in } B_{1} \backslash B_{1 / 2}\end{cases}
$$

Since $v \in W^{1, G}\left(B_{1}\right)$ and $v=u$ on $\partial B_{1}$ we have

$$
\begin{aligned}
\mathcal{J}_{\mathrm{G}}\left(u, B_{1 / 2}\right)+\mathcal{J}_{\mathrm{G}}\left(u, B_{1} \backslash B_{1 / 2}\right) & =\mathcal{J}_{\mathrm{G}}\left(u, B_{1}\right) \\
& \leq \mathcal{J}_{\mathrm{G}}\left(v, B_{1}\right)+\sigma \mathcal{J}_{\mathrm{G}}\left(v, B_{1}\right) \\
& =\mathcal{J}_{\mathrm{G}}\left(v, B_{1 / 2}\right)+\mathcal{J}_{\mathrm{G}}\left(v, B_{1} \backslash B_{1 / 2}\right)+\sigma \mathcal{J}_{\mathrm{G}}\left(v, B_{1}\right)
\end{aligned}
$$

so

$$
\mathcal{J}_{\mathrm{G}}\left(u, B_{1 / 2}\right) \leq \mathcal{J}_{\mathrm{G}}\left(v, B_{1 / 2}\right)+\sigma \mathcal{J}_{\mathrm{G}}\left(v, B_{1}\right)
$$

Now using the definition of $\mathcal{J}_{G}$ on the previous inequality we have

$$
\int_{B_{1 / 2}} \mathrm{G}(|\nabla u|) d x+\left|\{u>0\} \cap B_{1 / 2}\right| \leq \int_{B_{1 / 2}} \mathrm{G}(|\nabla v|) d x+\left|B_{1 / 2}\right|+\sigma \mathcal{J}_{\mathrm{G}}\left(v, B_{1}\right)
$$

and hence

$$
\int_{B_{1 / 2}} \mathrm{G}(|\nabla u|)-\mathrm{G}(|\nabla v|) d x \leq\left|B_{1 / 2}\right|-\left|\{u>0\} \cap B_{1 / 2}\right|+\sigma \mathcal{J}_{\mathrm{G}}\left(v, B_{1}\right)
$$

Using Lemma 2.5, the fact that

$$
\left|B_{1 / 2}\right|-\left|\{u>0\} \cap B_{1 / 2}\right|=\left|\{u=0\} \cap B_{1 / 2}\right|
$$

and that

$$
\mathcal{J}_{\mathrm{G}}\left(v, B_{1}\right) \leq \int_{B_{1}} \mathrm{G}(|\nabla u|) d x+\left|B_{1}\right| \leq\left|B_{1}\right|(\mathrm{G}(a)+1)
$$

we arrive at the following inequality:

$$
\begin{equation*}
\int_{B_{1 / 2}} \mathrm{G}(|\nabla u-\nabla v|) d x \leq \mathrm{C} \sigma(\mathrm{G}(a)+1)+\left|\{u=0\} \cap B_{1 / 2}\right| \tag{3.11}
\end{equation*}
$$

Next we will prove that

$$
\begin{equation*}
\left|\{u=0\} \cap B_{1 / 2}\right| \leq \mathrm{C} \varepsilon^{\delta+1} \varepsilon^{\gamma} \tag{3.12}
\end{equation*}
$$

for some $\gamma \in(0,1)$. We start out by defining

$$
\mathfrak{l}(x):=q \cdot x+b
$$

with

$$
b:=f_{B_{1}} u(x) d x
$$

Notice that

$$
f_{B_{1}}(u(x)-\mathfrak{l}(x)) d x=-f_{B_{1}} q \cdot x d x=0
$$

Denote

$$
f_{B_{1}}(u(x)-\mathfrak{l}(x)) d x=(u-\mathfrak{l})_{B_{1}}
$$

we have by Poincaré inequality

$$
\begin{equation*}
\left\|u-\mathfrak{l}-(u-\mathfrak{l})_{B_{1}}\right\|_{L^{\mathrm{G}}\left(B_{1}\right)}=\|u-\mathfrak{l}\|_{L^{\mathrm{G}}\left(B_{1}\right)} \leq \mathrm{C}\|\nabla(u-\mathfrak{l})\|_{L^{\mathrm{G}}\left(B_{1}\right)} \tag{3.13}
\end{equation*}
$$

Now, we want to use the fact that

$$
f_{B_{1}} \mathrm{G}(|\nabla u-q|) d x \leq \mathrm{CG}(a) \varepsilon^{\delta+1}
$$

so we need to compare modulars and norms. Applying (2.9) to $w=\nabla(u-l)$ and using the previous inequality we have

$$
\begin{equation*}
\|\nabla(u-\mathfrak{l})\|_{L^{\mathrm{G}}\left(B_{1}\right)} \leq \mathrm{C} \varepsilon^{\tau} \mathrm{G}(a)^{\frac{1}{g_{0}+1}} \tag{3.14}
\end{equation*}
$$

and by (3.13)

$$
\|u-\mathfrak{l}\|_{L^{\mathrm{G}}\left(B_{1}\right)} \leq \mathrm{C} \varepsilon^{\tau} \mathrm{G}(a)^{\frac{1}{g_{0}+1}}
$$

Next, we point out that if we denote $\mathfrak{l}^{-}:=\min \{0, l\}$ then $l^{-} \leq|u-l|$ and hence

$$
\mathrm{G}\left(\frac{\mathfrak{l}^{-}}{\lambda}\right) \leq \mathrm{G}\left(\frac{|u-\mathfrak{l}|}{\lambda}\right)
$$

and we get

$$
\begin{equation*}
\left\|\mathfrak{l}^{-}\right\|_{L^{\mathrm{G}}\left(B_{1}\right)} \leq\|u-\mathfrak{l}\|_{L^{\mathrm{G}}\left(B_{1}\right)} \leq \mathrm{C} \varepsilon^{\tau} \mathrm{G}(a)^{\frac{1}{g_{0}+1}} \tag{3.15}
\end{equation*}
$$

Next, we claim that

$$
\begin{equation*}
\mathfrak{l}(x) \geq \tilde{\mathrm{c}} \mathrm{G}(a)^{\frac{1}{g_{0}+1}} \tag{3.16}
\end{equation*}
$$

in $B_{1 / 2}$ for sufficiently small $\varepsilon$ and some constant $\tilde{c}$. Let us denote

$$
\sigma:=\mathrm{G}(a)^{\frac{1}{g_{0}+1}}
$$

to ease notation and suppose that (3.16) does not hold, i.e. for any $c$ there exists $x_{0} \in B_{1 / 2}$ such that

$$
\mathfrak{l}\left(x_{0}\right)<\mathrm{c} \sigma
$$

Since $\mathfrak{l}\left(x_{0}\right)=q \cdot x_{0}+b$ and hence

$$
\mathfrak{l}(x)-b \in\left[\frac{-|q|}{2}, \frac{|q|}{2}\right]
$$

this yields

$$
\mathrm{c} \sigma>b-\frac{|q|}{2}
$$

or

$$
\begin{equation*}
\mathrm{c} \sigma+\frac{|q|}{2}>b \tag{3.17}
\end{equation*}
$$

Let

$$
\mathcal{B}:=\left\{x=-\frac{t q}{|q|}+\eta, t \in\left[\frac{6}{8}, \frac{7}{8}\right], \eta \in B_{1 / 8}\right\}
$$

so that, in particular, $\mathcal{B} \subset B_{1}$.
Now, for $x \in \mathcal{B}$ and using (3.17)

$$
\mathfrak{l}(x)=-t|q|+\eta \cdot q+b<\mathrm{c} \sigma+\frac{|q|}{2}-\frac{6}{8}|q|+\frac{1}{8}|q|=\mathrm{c} \sigma-\frac{1}{8}|q|
$$

but then (3.10) gives

$$
\mathfrak{l}(x)<\mathrm{c} \sigma-\frac{1}{8} \mathrm{G}^{-1}\left(\frac{1}{\mathrm{C}} \mathrm{G}\left(\frac{\sigma}{8}\right)\right)
$$

from which we get the bound

$$
\mathfrak{l}(x)<\mathrm{c} \sigma-\frac{\mathrm{C}}{64} \sigma .
$$

which taking $\mathrm{c}>0$ small enough gives $\mathfrak{l}(x)<-\overline{\mathrm{C}} \sigma$ for a positive constant $\overline{\mathrm{C}}$. Inserting this into (3.15) gives

$$
\varepsilon^{\tau} \sigma \geq\left\|\mathfrak{l}^{-}\right\|_{L^{\mathrm{G}}\left(B_{1}\right)}>\|\overline{\mathrm{C}} \sigma\|_{L^{\mathrm{G}}\left(B_{1}\right)}
$$

which is a contradiction if $\varepsilon>0$ is small enough. Therefore (3.16) must hold.
The next step of the proof is divided into two cases according to the embedding properties of Orlicz-Sobolev spaces (see [1, Sections 8.27-8.35]). First, if

$$
\int_{1}^{\infty} \frac{\mathrm{G}^{-1}(\tau)}{\tau^{1+\frac{1}{n}}} d \tau=\infty
$$

we consider the the Sobolev conjugate of G

$$
\left(\mathrm{G}^{*}\right)^{-1}(t):=\int_{0}^{t} \frac{\mathrm{G}^{-1}(\tau)}{\tau^{1+\frac{1}{n}}} d \tau
$$

Then, we have that

$$
\|u-\mathfrak{l}\|_{L^{\mathrm{G}^{*}}\left(B_{1}\right)} \leq \mathrm{C}\|\nabla(u-\mathfrak{l})\|_{L^{\mathrm{G}}\left(B_{1}\right)}
$$

(here we have also used (3.13)) which combined with (3.14) gives

$$
\|u-\mathfrak{l}\|_{L^{\mathrm{G}^{*}}\left(B_{1}\right)} \leq \mathrm{C} \varepsilon^{\tau} \mathrm{G}(a)^{\frac{1}{g_{0}+1}}
$$

On the other hand, (3.16) gives that

$$
\left\|\mathfrak{l}^{-}\right\|_{L^{\mathrm{G}^{*}}\left(B_{1}\right)} \geq \mathrm{cG}(a)^{\frac{1}{g_{0}+1}}\left\|\chi_{\{u=0\} \cap B_{1 / 2}}\right\|_{\mathrm{G}^{*}} \geq \mathrm{cG}(a)^{\frac{1}{g_{0}+1}}\left|\{u=0\} \cap B_{1 / 2}\right|^{1 /(\delta+1)^{*}}
$$

and putting both inequalities together we obtain

$$
\mathrm{cG}(a)^{\frac{1}{g_{0}+1}}\left|\{u=0\} \cap B_{1 / 2}\right|^{1 /(\delta+1)^{*}} \leq \mathrm{C} \varepsilon^{\tau} \mathrm{G}(a)^{\frac{1}{g_{0}+1}}
$$

or

$$
\left|\{u=0\} \cap B_{1 / 2}\right| \leq \mathrm{C} \varepsilon^{\tau(\delta+1)^{*}}=\mathrm{C} \varepsilon^{\delta+1} \varepsilon^{\gamma}
$$

which is (3.12) with $\gamma=\tau(\delta+1)^{*}-(\delta+1)>0$ (being positive owing to (2.2)).
The second case is when

$$
\int_{1}^{\infty} \frac{\mathrm{G}^{-1}(\tau)}{\tau^{1+\frac{1}{n}}} d \tau<\infty
$$

in which the Morrey-type embedding holds and (again using Poincaré)

$$
\sup _{B_{1}}|u-\mathfrak{l}| \leq \mathrm{C}\|\nabla(u-\mathfrak{l})\|_{L^{\mathrm{G}}\left(B_{1}\right)}
$$

so that

$$
\sup _{B_{1}}|u-\mathfrak{l}| \leq \mathrm{C} \varepsilon^{\tau} \mathrm{G}(a)^{\frac{1}{g_{0}+1}}
$$

But then, using again (3.16), we have that in $B_{1 / 2}$

$$
\tilde{\mathrm{c}} \mathrm{G}(a)^{\frac{1}{g_{0}+1}}-u \leq \mathfrak{l}-u \leq \sup _{B_{1}}|u-\mathfrak{l}| \leq \mathrm{C} \varepsilon^{\tau} \mathrm{G}(a)^{\frac{1}{g_{0}+1}}
$$

so that, for $x \in B_{1 / 2}$

$$
\mathrm{G}(a)^{\frac{1}{g_{0}+1}}\left(\tilde{\mathrm{c}}-\mathrm{C} \varepsilon^{\tau}\right) \leq u(x)
$$

which means that $u(x)>0$ if $\varepsilon>0$ is small enough. In this case

$$
\left|\{u=0\} \cap B_{1 / 2}\right|=0
$$

and (3.12) is therefore proved.
With the aid of (3.12), (3.11) reads

$$
\begin{equation*}
\int_{B_{1 / 2}} \mathrm{G}(|\nabla u-\nabla v|) d x \leq \mathrm{C} \sigma(\mathrm{G}(a)+1)+\mathrm{C}_{0} \varepsilon^{\delta+1} \varepsilon^{\gamma} \tag{3.18}
\end{equation*}
$$

This readily implies, using (2.5) and the hypothesis, that

$$
\begin{aligned}
\int_{B_{1 / 2}} \mathrm{G}(|\nabla v-q|) d x & \leq \mathrm{C}\left(\int_{B_{1 / 2}} \mathrm{G}(|\nabla u-q|) d x+\int_{B_{1 / 2}} \mathrm{G}(|\nabla u-\nabla v|) d x\right) \\
& \leq \mathrm{C} \varepsilon^{\delta+1} \mathrm{G}(a)+\mathrm{C} \sigma(\mathrm{G}(a)+1)+\mathrm{C}_{0} \varepsilon^{\delta+1} \varepsilon^{\gamma}
\end{aligned}
$$

Now using the fact that $\sigma \leq \mathrm{c}_{0} \varepsilon^{\delta+1}\left(\mathrm{c}_{0}>0\right.$ to be chosen later) and recalling that $\varepsilon^{\gamma} \leq \mathrm{G}(a)$ and $a \in\left[a_{0}, a_{1}\right]$ and the we arrive at

$$
\begin{equation*}
\int_{B_{1 / 2}} \mathrm{G}(|\nabla v-q|) d x \leq \mathrm{C} \varepsilon^{\delta+1} \mathrm{G}(a) \tag{3.19}
\end{equation*}
$$

The next step is to show that (3.19) implies

$$
\begin{equation*}
|\nabla v(x)-q| d x \leq \mathrm{C} \cdot(\varepsilon a)^{\nu}, \forall x \in B_{1 / 2} \tag{3.20}
\end{equation*}
$$

for some $\mathrm{C}>0, \nu \in(0,1)$ and $\varepsilon$ small enough.
Assume that (3.20) is false, then there exists $\hat{x} \in B_{1 / 2}$ such that

$$
|\nabla v(\hat{x})-q| d x>\mathrm{C} \cdot(\varepsilon a)^{\nu}
$$

By interior regularity, for any $x \in B_{1 / 8}(\hat{x})$ we have

$$
|\nabla v(x)-\nabla v(\hat{x})| d x \leq \mathrm{C}|x-\hat{x}|^{\alpha}
$$

with a constant $\mathrm{C}>0$ that, thanks to (2.11), depends only on $n, g_{0}$ and $a_{1}$. Then,

$$
\begin{aligned}
|\nabla v(x)-q| & \geq|\nabla v(\hat{x})-q|-|\nabla v(x)-\nabla v(\hat{x})| \\
& >\mathrm{C} \cdot(\varepsilon a)^{\nu}-\mathrm{C}|x-\hat{x}|^{\alpha} \\
& \geq \frac{\mathrm{C} \cdot(\varepsilon a)^{\nu}}{2}
\end{aligned}
$$



$$
\begin{aligned}
\int_{B_{1 / 2}} \mathrm{G}(|\nabla v(x)-q|) d x & \geq \int_{B} \mathrm{G}(|\nabla v(x)-q|) d x \\
& \geq \mathrm{G}\left(\frac{\mathrm{C} \cdot(\varepsilon a)^{\nu}}{2 \mathrm{C}}\right)\left|\frac{\mathrm{C} \cdot(\varepsilon a)^{\nu}}{2 \mathrm{C}}\right|^{n / \alpha}\left|B_{1}\right|
\end{aligned}
$$

This, together with (3.19) gives

$$
\mathrm{G}\left(\frac{\mathrm{C} \cdot(\varepsilon a)^{\nu}}{2}\right)\left(\frac{\mathrm{C} \cdot(\varepsilon a)^{\nu}}{2}\right)^{n / \alpha}\left|B_{1}\right| \leq \mathrm{C} \varepsilon^{\delta+1} \mathrm{G}(a)
$$

or, using (2.6),

$$
\left(\frac{\mathrm{C} \cdot(\varepsilon a)^{\nu}}{2}\right)^{g_{0}+1+\frac{n}{\alpha}}\left|B_{1}\right| \leq \varepsilon^{\delta+1} \mathrm{G}(a)
$$

which gives a contradiction choosing $\nu$ appropriately and for $\varepsilon$ small enough thus proving (3.20).
Next we consider the vectorial function $\overrightarrow{\mathbf{F}}: \mathbb{R}^{n} \longrightarrow \mathbb{R}^{n}$ given by

$$
\overrightarrow{\mathbf{F}}(z):=g(|z|) \frac{z}{|z|}
$$

and compute

$$
\begin{aligned}
\overrightarrow{\mathbf{F}}(\nabla v)-\overrightarrow{\mathbf{F}}(q) & =\int_{0}^{1} \frac{d}{d t} \overrightarrow{\mathbf{F}}(q+t(\nabla v-q)) d t \\
& =\int_{0}^{1} D \overrightarrow{\mathbf{F}}(q+t(\nabla v-q)) \cdot(\nabla v-q) d t \\
& =\mathfrak{A}(x)(\nabla v-q)
\end{aligned}
$$

with $\mathfrak{A}(x):=\int_{0}^{1} D \overrightarrow{\mathbf{F}}(q+t(\nabla v-q)) d t$. Nonetheless, we have that

$$
\operatorname{div} \overrightarrow{\mathbf{F}}(\nabla v)=\operatorname{div} \overrightarrow{\mathbf{F}}(q)=0
$$

and hence

$$
\operatorname{div}(\mathfrak{A}(x)(\nabla v-q))=0
$$

Applying interior estimates (i.e. using Proposition 2.2 with Remark 2.3 and Lemma 2.6) and using (3.19) we have that

$$
\mathrm{G}(\mid \nabla v(x)-q) \mid) \leq \sup _{B_{R / 4}(x)} \mathrm{G}(|\nabla v-q|) \leq \mathrm{C} f_{B_{R / 2}(x)} \mathrm{G}(|\nabla v-q|) d x \leq \mathrm{CG}(a) \varepsilon^{\delta+1}
$$

or, since G is increasing,

$$
|\nabla v(x)-q| \leq \mathrm{CG}^{-1}\left(\mathrm{G}(a) \varepsilon^{\delta+1}\right)
$$

In particular,

$$
|\bar{q}|:=|\nabla v(0)-q| \leq \mathrm{CG}^{-1}\left(\mathrm{G}(a) \varepsilon^{\delta+1}\right)
$$

so that

$$
|\nabla v(x)-q-\bar{q}| \leq 2 \mathrm{CG}^{-1}\left(\mathrm{G}(a) \varepsilon^{\delta+1}\right), x \in B_{1 / 2}
$$

This, using again (2.12) in Proposition 2.2 we have

$$
f_{B_{r}} \mathrm{G}(|\nabla v-q-\bar{q}|) d x \leq f_{B_{r}} \mathrm{G}\left(\mathrm{C}\left(\frac{r}{\frac{1}{2}}\right)^{\mu} \sup _{B_{\frac{1}{2}}}|\nabla v-q-\bar{q}|\right) \leq \mathrm{C} r^{\mu(\delta+1)} \mathrm{G}(a) \varepsilon^{\delta+1}
$$

This and (3.18), together with the doubling condition, give

$$
\begin{aligned}
f_{B_{r}} \mathrm{G}(|\nabla u-q-\bar{q}|) d x & \leq \mathrm{C}\left(f_{B_{r}} \mathrm{G}(|\nabla u-\nabla v|) d x+f_{B_{r}} \mathrm{G}(|\nabla v-q-\bar{q}|) d x\right) \\
& \leq \frac{\mathrm{C}}{r^{n}}\left(\sigma(\mathrm{G}(a)+1)+\mathrm{C}_{0} \varepsilon^{\delta+1} \varepsilon^{\gamma}\right)+\mathrm{C} r^{\mu(\delta+1)} \mathrm{G}(a) \varepsilon^{\delta+1} \\
& \leq \tilde{\mathrm{C}} r^{-n} \sigma(\mathrm{G}(a)+1)+\tilde{\mathrm{C}} r^{-n} \varepsilon^{\delta+1} \varepsilon^{\gamma}+\tilde{\mathrm{C}} r^{\mu(\delta+1)} \mathrm{G}(a) \varepsilon^{\delta+1}
\end{aligned}
$$

Now defining $\alpha_{0}:=\mu$ and for $\alpha<\alpha_{0}$, we set

$$
r^{\delta+1}=(3 \tilde{\mathrm{C}})^{\frac{1}{\alpha-\alpha_{0}}}, \quad \varepsilon_{0}:=\left(\frac{r^{\alpha(\delta+1)+n} \mathrm{G}\left(a_{0}\right)}{3 \tilde{\mathrm{C}}}\right)^{\frac{1}{\gamma}}, \quad \mathrm{c}_{0}:=\frac{r^{\alpha(\delta+1)+n} \mathrm{G}\left(a_{0}\right)}{3 \tilde{\mathrm{C}}\left(\mathrm{G}\left(a_{1}\right)+1\right)}
$$

so that

$$
\begin{aligned}
& \tilde{\mathrm{C}} r^{\mu(\delta+1)} \mathrm{G}(a) \varepsilon^{\delta+1}=\tilde{\mathrm{C}} r^{\left(\alpha_{0}-\alpha\right)(\delta+1)} r^{\alpha(\delta+1)} \mathrm{G}(a) \varepsilon^{\delta+1}=\frac{1}{3} r^{\alpha(\delta+1)} \mathrm{G}(a) \varepsilon^{\delta+1} \\
& \tilde{\mathrm{C}} r^{-n} \varepsilon^{\delta+1} \varepsilon^{\gamma} \leq \tilde{\mathrm{C}} r^{-n} \frac{r^{\alpha(\delta+1)+n} \mathrm{G}\left(a_{0}\right)}{4 \tilde{\mathrm{C}}} \varepsilon^{\delta+1} \leq \frac{1}{3} r^{\alpha(\delta+1)} \mathrm{G}(a) \varepsilon^{\delta+1} \\
& \tilde{\mathrm{C}} r^{-n} \sigma(\mathrm{G}(a)+1) \leq \tilde{\mathrm{C}} r^{-n} \frac{r^{\alpha(\delta+1)+n} \mathrm{G}\left(a_{0}\right)}{4 \tilde{\mathrm{C}}\left(\mathrm{G}\left(a_{1}\right)+1\right)} \varepsilon^{\delta+1}(\mathrm{G}(a)+1) \leq \frac{1}{3} r^{\alpha(\delta+1)} \mathrm{G}(a) \varepsilon^{\delta+1} .
\end{aligned}
$$

All this gives

$$
f_{B_{r}} \mathrm{G}(|\nabla u-q-\bar{q}|) d x \leq r^{\alpha(\delta+1)} \mathrm{G}(a) \varepsilon^{\delta+1}
$$

and hence the desired result with $\tilde{q}:=q+\bar{q}$.

As a consequence of the previous lemma we obtain the crucial $L^{\infty}$ estimate for the gradient of an almost minimizer for sufficiently small $\kappa$.

Corollary 3.4. Let $a_{1}>a_{0}>0$ and let $u$ be an almost minimizer of $\mathcal{J}_{G}$ in $B_{1}$ with constant $\kappa$ and exponent $\beta$. Set

$$
\mathrm{G}(a):=f_{B_{1}} \mathrm{G}(|\nabla u|) d x
$$

and assume there exist $q \in \mathbb{R}^{n}$ and constants $\mathrm{C}_{0}, \mathrm{C}_{1}>0$ such that

$$
\begin{equation*}
\mathrm{G}(a) \in\left[a_{0}, a_{1}\right], \quad f_{B_{1}} \mathrm{G}(|\nabla u-q|) d x \leq \mathrm{C}_{1} \varepsilon^{\delta+1} \mathrm{G}(a), \quad \mathrm{G}^{-1}\left(\frac{1}{C} \mathrm{G}\left(\frac{a}{4}\right)\right)<|q|<2 \mathrm{C}_{0} a \tag{3.21}
\end{equation*}
$$

Then there exist $\varepsilon_{0}, \kappa_{0}>0$ and $\gamma \in(0,1)$ depending on $n, \delta, g_{0}, \beta, a_{0}$ and $a_{1}$ such that for $0<\varepsilon \leq \varepsilon_{0}$ and $0<\kappa \leq \kappa_{0} \varepsilon^{\delta+1}$ there exists a linear function

$$
\mathfrak{l}(x):=q \cdot x+b
$$

such that

$$
\|u-\mathfrak{l}\|_{C^{1, \gamma}\left(B_{1 / 2}\right)} \leq \mathrm{CG}^{-1}\left(\mathrm{C} \rho^{-n-\alpha(\delta+1)} \varepsilon^{\delta+1} \mathrm{G}(a)\right)
$$

where $\mathrm{C}=\mathrm{C}\left(n, \delta, g_{0}\right)>0$.
Moreover

$$
\begin{equation*}
\|\nabla u\|_{L^{\infty}\left(B_{1 / 2}\right)} \leq \hat{\mathrm{C}} a \tag{3.22}
\end{equation*}
$$

where $\hat{\mathrm{C}}>0$ is a universal constant.
Proof. We may assume that $u$ is an almost minimizer in $B_{2}$ with the same constant and exponent. The goal is to iterate Lemma 3.3 with $\alpha:=\min \left\{\frac{\alpha_{0}}{2}, \frac{\beta}{g_{0}+1}\right\}, \alpha_{0}$ from Lemma 3.3.

We are going to show by induction that for some $\rho \in(0,1), \tilde{\mathrm{C}}>0$ universal and all $k \geq 0$ there exists $q_{k} \in \mathbb{R}^{n}$ such that

$$
\begin{align*}
& f_{B_{\rho^{k}}} \mathrm{G}\left(\left|\nabla u-q_{k}\right|\right) d x \leq \mathrm{C} \rho^{k \alpha(\delta+1)} \varepsilon^{\delta+1} \mathrm{G}(a),  \tag{3.23}\\
& \mathrm{G}^{-1}\left(\frac{1}{\mathrm{C}} \mathrm{G}\left(\frac{a}{8}\right)\right)-\tilde{\mathrm{C}} \varepsilon^{\tau} a\left(\frac{1-\rho^{k \alpha \tau}}{1-\rho^{\alpha \tau}}\right) \leq\left|q_{k}\right| \leq 2 \mathrm{C}_{0} a+\tilde{\mathrm{C}} \varepsilon^{\tau} a\left(\frac{1-\rho^{k \alpha \tau}}{1-\rho^{\alpha \tau}}\right),  \tag{3.24}\\
& \mathrm{G}\left(\frac{|q|}{2}\right) \leq f_{B_{\rho^{k}}} \mathrm{G}(|\nabla u|) d x \leq 2 \mathrm{G}(|q|) \tag{3.25}
\end{align*}
$$

with

$$
\tau:=\left(\frac{\delta+1}{g_{0}+1}\right)
$$

For $k=0$, pick $q_{0}:=q$; then (3.23) and (3.24) follow just from the corresponding inequalities in (3.21).

Now for the inductive step let $r:=\rho^{k}$ and $u_{r}(x):=\frac{1}{r} u(r x)$ and get, by inductive hypothesis, that

$$
f_{B_{1}} \mathrm{G}\left(\left|\nabla u_{r}-q_{k}\right|\right) d x \leq \mathrm{C}_{1} \rho^{k \alpha(\delta+1)} \varepsilon^{\delta+1} \mathrm{G}(a)=\mathrm{C}_{1} \varepsilon_{k}^{\delta+1} \mathrm{G}(a)
$$

if we set $\varepsilon_{k}:=\rho^{k \alpha} \varepsilon$. Then, Lemma 3.3 implies that there exists $q_{k+1} \in \mathbb{R}^{n}$ such that

$$
f_{B_{\rho}} \mathrm{G}\left(\left|\nabla u_{r}-q_{k+1}\right|\right) d x \leq \mathrm{C}_{1} \varepsilon_{k}^{\delta+1} \mathrm{G}(a) \rho^{(\delta+1) \alpha}=\mathrm{C}_{1} \rho^{(k+1) \alpha(\delta+1)} \varepsilon^{\delta+1} \mathrm{G}(a)
$$

and

$$
\begin{equation*}
\left|q_{k}-q_{k+1}\right|<\tilde{\mathrm{C}} a \varepsilon_{k}^{\tau}=\mathrm{C} a \varepsilon^{\tau} \rho^{k \alpha \tau} \tag{3.26}
\end{equation*}
$$

But, rescaling the integral back (and recalling the definition of $r$ ), we have that

$$
\begin{aligned}
f_{B_{\rho}} \mathrm{G}\left(\left|\nabla u_{r}-q_{k+1}\right|\right) d x & =\frac{1}{\rho^{n}\left|B_{1}\right|} \int_{B_{\rho}} \mathrm{G}\left(\left|\nabla u_{r}-q_{k+1}\right|\right) d x \\
& =\frac{1}{(r \rho)^{n}\left|B_{1}\right|} \int_{B_{r} \rho} \mathrm{G}\left(\left|\nabla u-q_{k+1}\right|\right) d x \\
& =f_{B_{\rho^{k+1}}} \mathrm{G}\left(\left|\nabla u-q_{k+1}\right|\right) d x
\end{aligned}
$$

so (3.23) is proved. Incidentally, we point out that the application of Lemma 3.3 is where the smallness restriction on $\kappa$ appears.

Regarding (3.24), we can compute, using the inductive hypothesis and (3.26),

$$
\begin{aligned}
\left|q_{k+1}\right| & \leq\left|q_{k+1}-q_{k}\right|+\left|q_{k}\right| \\
& \leq{\mathrm{C} a \varepsilon^{\tau} \rho^{k \alpha \tau}+2 \mathrm{C}_{0} a+\tilde{\mathrm{C}} \varepsilon^{\tau} a\left(\frac{1-\rho^{k \alpha \tau}}{1-\rho^{\alpha \tau}}\right) .}^{\text {. }} .
\end{aligned}
$$

Then, we have that

$$
\begin{equation*}
\left|q_{k+1}\right| \leq 2 \mathrm{C}_{0} a+\tilde{\mathrm{C}} \varepsilon^{\tau} a\left(\rho^{k \alpha \tau}+\frac{1-\rho^{k \alpha \tau}}{1-\rho^{\alpha \tau}}\right)=2 \mathrm{C}_{0} a+\tilde{\mathrm{C}} \varepsilon^{\tau} a\left(\frac{1-\rho^{(k+1) \alpha \tau}}{1-\rho^{\alpha \tau}}\right) \tag{3.27}
\end{equation*}
$$

which is the upper bound on (3.24). For the lower bound, recall again that the inductive hypothesis and (3.26) give

$$
\begin{aligned}
\left|q_{k+1}\right| & \geq\left|q_{k}\right|-\left|q_{k+1}-q_{k}\right| \\
& \geq \mathrm{G}^{-1}\left(\frac{1}{\mathrm{C}} \mathrm{G}\left(\frac{a}{8}\right)\right)-\tilde{\mathrm{C}} \varepsilon^{\tau} a\left(\frac{1-\rho^{k \alpha \tau}}{1-\rho^{\alpha \tau}}\right)-\tilde{\mathrm{C}} a \varepsilon^{\tau} \rho^{k \alpha \tau} a .
\end{aligned}
$$

It remains to prove (3.25).

$$
\begin{aligned}
f_{B_{\rho^{k+1}}} \mathrm{G}(|\nabla u|) d x-\mathrm{G}(|q|) & \leq \frac{\mathrm{C}}{2}\left(f_{B_{\rho^{k+1}}} \mathrm{G}\left(\left|\nabla u-q_{k+1}\right|\right) d x+\mathrm{G}\left(\left|q_{k+1}\right|\right)-\mathrm{G}(|q|)\right) \\
& \leq \frac{\mathrm{C}}{2}\left(\mathrm{C} \rho^{(k+1) \alpha(\delta+1)} \varepsilon^{\delta+1} \mathrm{G}(a)+\sum_{j=0}^{k}\left|\mathrm{G}\left(\left|q_{j+1}\right|\right)-\mathrm{G}\left(\left|q_{j}\right|\right)\right|\right)
\end{aligned}
$$

Now, for some $q_{j}^{*}$ between $q_{j+1}$ and $q_{j}$ we have

$$
\left|\mathrm{G}\left(\left|q_{j+1}\right|\right)-\mathrm{G}\left(\left|q_{j}\right|\right)\right|=g\left(\left|q_{j}^{*}\right|\right)\left|q_{j+1}-q_{j}\right|
$$

and recalling that $g$ is increasing we have

$$
\begin{aligned}
\sum_{j=0}^{k}\left|\mathrm{G}\left(\left|q_{j+1}\right|\right)-\mathrm{G}\left(\left|q_{j}\right|\right)\right| & \leq \sum_{j=0}^{k} g\left(\left|q_{j+1}\right|\right)\left|q_{j+1}-q_{j}\right| \\
& \leq \mathrm{C} \sum_{j=0}^{k}\left(\mathrm{c} g(a)+\mathrm{c} \varepsilon^{\delta \tau} g(a)\right) a\left(\varepsilon \rho^{j \alpha}\right)^{\tau} \\
& =\mathrm{C}\left(\mathrm{c} g(a) a \varepsilon^{\tau}+\mathrm{c} \varepsilon^{\delta \tau} g(a) a \varepsilon^{\tau}\right) \sum_{j=0}^{k} \rho^{j \alpha \tau} \\
& \leq \mathrm{C}\left(\mathrm{G}(a) \varepsilon^{\tau}+\varepsilon^{(\delta+1) \tau} \mathrm{G}(a)\right) \frac{1}{1-\rho^{\alpha \tau}} \\
& =\mathrm{C}\left(1+\frac{1}{1-\rho^{\alpha \tau}}\right) \varepsilon^{\tau} \mathrm{G}(a)
\end{aligned}
$$

Putting this inequality together with the previous one, we wind up with

$$
\left|f_{B_{\rho^{k+1}}} \mathrm{G}(|\nabla u|) d x-\mathrm{G}(|q|)\right| \leq \mathrm{C}\left(\varepsilon^{\tau}+\varepsilon^{\delta}\right) \mathrm{G}(a) \leq \mathrm{G}\left(\frac{|q|}{2}\right)
$$

as desired.
Now we want to apply the Campanato-type estimate in the Appendix (Theorem 4.3) with $\Omega=B_{1 / 2}$ and $\lambda=n+\alpha(\delta+1)>n$; for that, we must first show that

$$
\begin{equation*}
\varrho^{-\lambda} \inf _{\xi \in \mathbb{R}^{n}} \int_{B_{1 / 2} \cap B_{\varrho}\left(x_{0}\right)} \mathrm{G}(|\nabla u-q-\xi|) d x \leq \mathrm{C} \varepsilon^{\delta+1} \mathrm{G}(a) . \tag{3.28}
\end{equation*}
$$

For that we split the cases $\varrho \in(0,1)$ and $\varrho \geq 1$.
In the latter case the bound is obtained by

$$
\varrho^{-\lambda} \inf _{\xi \in \mathbb{R}^{n}} \int_{B_{1 / 2} \cap B_{\varrho}\left(x_{0}\right)} \mathrm{G}(|\nabla u-q-\xi|) d x \leq \int_{B_{1 / 2}} \mathrm{G}(|\nabla u-q|) d x \leq\left|B_{1}\right| f_{B_{1}} \mathrm{G}(|\nabla u-q|) d x
$$

and the hypothesis.
If $\varrho \in(0,1)$ then we use a $\rho$-adyc argument: let $\rho^{k+1} \leq \varrho \leq \rho^{k}$ and use the (3.23) to bound

$$
\begin{aligned}
\varrho^{-\lambda} \inf _{\xi \in \mathbb{R}^{n}} \int_{B_{1 / 2} \cap B_{\varrho}\left(x_{0}\right)} \mathrm{G}(|\nabla u-q-\xi|) d x & \leq \rho^{-\lambda(k+1)} \int_{B_{1 / 2} \cap B_{\rho^{k}\left(x_{0}\right)}} \mathrm{G}\left(\left|\nabla u-q_{k}\right|\right) d x \\
& \leq \rho^{-\lambda(k+1)+k n}\left|B_{1}\right| f_{B_{\rho^{k}\left(x_{0}\right)}} \mathrm{G}\left(\left|\nabla u-q_{k}\right|\right) d x \\
& \leq \mathrm{C} \rho^{-(n+\alpha(\delta+1))(k+1)+k n+k \alpha(\delta+1)}\left|B_{1}\right| \varepsilon^{\delta+1} \mathrm{G}(a) \\
& =\mathrm{C} \rho^{-n-\alpha(\delta+1)}\left|B_{1}\right| \varepsilon^{\delta+1} \mathrm{G}(a)
\end{aligned}
$$

and we get (3.28).
Since we already have a bound on $\int_{B_{1 / 2}} \mathrm{G}(|\nabla u-q|) d x$, Theorem 4.3 says that $\nabla u-q$ belongs to $C^{0, \gamma}\left(B_{1 / 2}\right)$ and

$$
\begin{equation*}
[\nabla u-q]_{C^{0, \gamma}\left(B_{1 / 2}\right)} \leq \mathrm{CG}^{-1}\left(\rho^{-n-\alpha(\delta+1)} \varepsilon^{\delta+1} \mathrm{G}(a)\right) \tag{3.29}
\end{equation*}
$$

Now if we define $\mathfrak{l}(x)=u(0)+x \cdot q$ then in $B_{1 / 2}$ it holds

$$
|u(x)-\mathfrak{l}(x)|=\left|\frac{d}{d t} \int_{0}^{1}(\nabla u(t x)-q) \cdot x d t\right| \leq \mathrm{CG}^{-1}\left(\rho^{-n-\alpha(\delta+1)} \varepsilon^{\delta+1} \mathrm{G}(a)\right)
$$

and therefore

$$
\|u-\mathfrak{l}\|_{L^{\infty}\left(B_{1 / 2}\right)} \leq \mathrm{CG}^{-1}\left(\rho^{-n-\alpha(\delta+1)} \varepsilon^{\delta+1} \mathrm{G}(a)\right)
$$

which together with (3.29) and a standard interpolation inequality (see for instance [39, page 9]) gives the first part of the result.

As for (3.22), simply note that

$$
\|\nabla u\|_{L^{\infty}\left(B_{1 / 2}\right)} \leq\|\nabla(u-q)\|_{L^{\infty}\left(B_{1 / 2}\right)}+|q|
$$

But taking limit in (3.27) we have

$$
|q| \leq 2 \mathrm{C}_{0} a+\tilde{\mathrm{C}} \varepsilon^{\tau} a\left(\frac{1}{1-\rho^{\alpha \tau}}\right)
$$

and therefore

$$
\|\nabla u\|_{L^{\infty}\left(B_{1 / 2}\right)} \leq \mathrm{CG}^{-1}\left(\mathrm{C} \rho^{-n-\alpha(\delta+1)} \varepsilon^{\delta+1} \mathrm{G}(a)\right)+2 \mathrm{C}_{0} a+\tilde{\mathrm{C}} \varepsilon^{\tau} a\left(\frac{1}{1-\rho^{\alpha \tau}}\right) \leq \hat{\mathrm{C}} a
$$

as desired.

## 4 Proof of the Theorem 1.1

In this section we give the proof of Theorem 1.1. As is customary we reduce the proof to the case where $\Omega$ is a ball, the general case following from a covering procedure.

Proof of Theorem 1.1. Let us define

$$
\mathrm{G}(a(\tau)):=f_{B_{\tau}} \mathrm{G}(|\nabla u|) d x
$$

and for $r \in(0, \eta]$ we want to show that

$$
\begin{equation*}
\mathrm{G}(a(r)) \leq \mathrm{C}(\eta, \mathrm{M})(1+\mathrm{G}(a(1))), \tag{4.1}
\end{equation*}
$$

Let consider the set $\mathcal{K} \subset \mathbb{N}=\{0,1,2, \cdots\}$ containing all the $k$ such that

$$
\begin{equation*}
\mathrm{G}\left(a\left(\eta^{k}\right)\right) \leq \eta^{-n} \mathrm{M}+2^{-k} \mathrm{G}(a(1)) \tag{4.2}
\end{equation*}
$$

It is easy to check that $0 \in \mathcal{K}$, then $\mathcal{K} \neq \emptyset$. So, we have two different possibilities: $\mathcal{K}=\mathbb{N}$ or $\mathcal{K} \subset \mathbb{N}$ and $\mathcal{K} \neq \mathbb{N}$.

In the case $\mathcal{K}=\mathbb{N}$ we have that for $r \in(0,1)$ there exists a (minimum) value of $k \geq 0$ such that $\eta^{k+1} \leq r<\eta^{k}$. Then

$$
\begin{aligned}
\mathrm{G}(a(r)) & =f_{B_{r}} \mathrm{G}(|\nabla u|) d x \\
& \leq \frac{\left|B_{\eta^{k}}\right|}{\left|B_{r}\right|} f_{B_{\eta^{k}}} \mathrm{G}(|\nabla u|) d x \\
& \leq \eta^{-n} \mathrm{G}\left(a\left(\eta^{k}\right)\right) \\
& \leq \eta^{-n}\left(\eta^{-n} \mathrm{M}+2^{-k} \mathrm{G}(a(1))\right) \\
& \leq \mathrm{C}(\eta, \mathrm{M})(1+\mathrm{G}(a(1)))
\end{aligned}
$$

so (4.1) holds.

In the other case, there exists a minimum integer $k+1$ for which the inequality fails (4.2). Further, it must happen that

$$
\begin{equation*}
\mathrm{G}\left(a\left(\eta^{k}\right)\right)>\mathrm{M} \tag{4.3}
\end{equation*}
$$

if not, we have that

$$
\mathrm{G}\left(a\left(\eta^{k+1}\right)\right) \leq \eta^{-n} \mathrm{G}\left(a\left(\eta^{k}\right)\right) \leq \eta^{-n} \mathrm{M} \leq \eta^{-n} \mathrm{M}+2^{-(k+1)} \mathrm{G}(a(1))
$$

and (4.2) is also satisfied for $k+1$.
Now, $\mathrm{G}\left(a\left(\eta^{k}\right)\right)>\mathrm{M}$ gives, owing to Lemma 3.1 in $B_{\eta}$ we have that either

$$
\mathrm{G}\left(a\left(\eta^{k+1}\right)\right) \leq \mathrm{G}\left(\frac{a\left(\eta^{k}\right)}{2}\right)
$$

or

$$
f_{B_{\eta^{k+1}}} \mathrm{G}(|\nabla u-q|) d x \leq \varepsilon^{\delta+1} \mathrm{G}\left(a\left(\eta^{k}\right)\right)
$$

where $q \in \mathbb{R}^{n}$ verifies

$$
\frac{1}{\mathrm{C}} \mathrm{G}\left(\frac{a\left(\eta^{k}\right)}{4}\right)<\mathrm{G}(|q|)<\mathrm{CG}\left(a\left(\left(\eta^{k}\right)\right)\right.
$$

Suppose that $\mathrm{G}\left(a\left(\eta^{k+1}\right)\right) \leq \mathrm{G}\left(\frac{a\left(\eta^{k}\right)}{2}\right) \leq \frac{\mathrm{G}\left(a\left(\eta^{k}\right)\right)}{2}$. Since

$$
\begin{equation*}
\mathrm{G}\left(a\left(\eta^{k+1}\right)\right)>\eta^{-n} \mathrm{M}+2^{-(k+1)} \mathrm{G}(a(1)) \geq \frac{\eta^{-n} \mathrm{M}+2^{-k} \mathrm{G}(a(1))}{2} \geq \frac{\mathrm{G}\left(a\left(\eta^{k}\right)\right)}{2} \tag{4.4}
\end{equation*}
$$

this leads to a contradiction.
If the second alternative holds true, then we are in situation to apply Corollary 3.4. Observe that by (4.3) and (4.4) we have that

$$
\mathrm{G}\left(a\left(\eta^{k+1}\right)\right) \geq \frac{\mathrm{M}}{2}
$$

On the other hand,

$$
\mathrm{G}\left(a\left(\eta^{k+1}\right)\right) \leq \eta^{-n} \mathrm{G}\left(a\left(\eta^{k}\right)\right) \leq \eta^{-n}\left(\eta^{-n} \mathrm{M}+2^{-k} \mathrm{G}(a(1))\right) \leq \eta^{-n}\left(\eta^{-n} \mathrm{M}+\mathrm{G}(a(1))\right)
$$

Now, we apply Corollary 3.4 with $a_{0}=\frac{\mathrm{M}}{2}$ and $a_{1}=\eta^{-n}\left(\eta^{-n} \mathrm{M}+\mathrm{G}(a(1))\right)$ and taking $2 \varepsilon$ instead $\varepsilon$. Then

$$
f_{B_{\eta}^{k+1}} \mathrm{G}(|\nabla u-q|) d x \leq(2 \varepsilon)^{\delta+1} \mathrm{G}\left(a\left(\eta^{k}\right)\right)
$$

and

$$
\begin{equation*}
\left.\|\nabla u\|_{L^{\infty}\left(B_{\eta^{k+1}}^{2}\right.}\right) \leq \mathrm{C} a\left(\eta^{k}\right) \tag{4.5}
\end{equation*}
$$

By (4.5), for all $r \in\left(0, \frac{\eta^{k+1}}{2}\right)$.

$$
\begin{aligned}
\mathrm{G}(a(r)) & =f_{B_{r}} \mathrm{G}(|\nabla u|) d x \leq \mathrm{CG}\left(a\left(\eta^{k}\right)\right) \leq \mathrm{C}\left(\eta^{-n} \mathrm{M}+2^{-k} \mathrm{G}(a(1))\right) \\
& \leq \mathrm{C}\left(\eta^{-n} \mathrm{M}+\mathrm{G}(a(1))\right) \leq \mathrm{C}(\mathrm{M}, \eta)(1+\mathrm{G}(a(1)))
\end{aligned}
$$

If $r \in\left[\frac{\eta^{k+1}}{2}, \eta\right)$ then there exists $k_{r}$ such that $\eta^{k_{r}+1}<r \leq \eta^{k_{r}}$. Then

$$
\frac{1}{\eta^{k_{r}}} \leq \frac{1}{r} \leq \frac{2}{\eta^{k_{r}+1}}
$$

and

$$
k_{r} \leq k+\mathrm{C}_{*}
$$

So, there are two cases, first suppose that $k_{r} \in\{0, \cdots, k\}$ then

$$
\begin{aligned}
\mathrm{G}(a(r)) & =\frac{1}{\mid B_{\eta^{k_{r}+1} \mid}} \int_{B_{\eta}^{k_{r}}} \mathrm{G}(|\nabla u|) d x \leq \eta^{-n} \mathrm{G}\left(\eta^{k_{r}}\right) \leq \eta^{-n}\left(\eta^{-n} \mathrm{M}+2^{-k_{r}} \mathrm{G}(a(1))\right) \\
& \leq \eta^{-n}\left(\eta^{-n} \mathrm{M}+\mathrm{G}(a(1))\right) \leq \mathrm{C}(\mathrm{M}, \eta)(1+\mathrm{G}(a(1)))
\end{aligned}
$$

If $k_{r}>k$ then

$$
\begin{aligned}
\mathrm{G}(a(r)) & =\frac{1}{\mid B_{\eta^{k+\mathrm{C}_{*}+1}}} \int_{B_{\eta}^{k}} \mathrm{G}(|\nabla u|) d x \leq \eta^{-n\left(\mathrm{C}_{*}+1\right)} \mathrm{G}\left(\eta^{k}\right) \leq \eta^{-n\left(\mathrm{C}_{*}+1\right)}\left(\eta^{-n} \mathrm{M}+2^{-k} \mathrm{G}(a(1))\right) \\
& \leq \eta^{-n\left(\mathrm{C}_{*}+1\right)}\left(\eta^{-n} \mathrm{M}+\mathrm{G}(a(1))\right) \leq \mathrm{C}(\mathrm{M}, \eta)(1+\mathrm{G}(a(1)))
\end{aligned}
$$

so, the proof of (4.1) is completed.
Now, we extend (4.1) for balls with center $x_{0}$ and radius small enough. So, for all $r \in[0, \eta]$ we have

$$
\begin{equation*}
\mathrm{G}\left(a\left(r, x_{0}\right)\right) \leq \mathrm{C}(\eta, \mathrm{M})(1+\mathrm{G}(a(1))), \tag{4.6}
\end{equation*}
$$

where

$$
\mathrm{G}\left(a\left(r, x_{0}\right)\right):=f_{B_{r}\left(x_{0}\right)} \mathrm{G}(|\nabla u|) d x
$$

For $x_{0} \in B_{\frac{1}{2}}$

$$
\mathrm{G}\left(\left|\nabla u\left(x_{0}\right)\right|\right)=\lim _{r \rightarrow 0} \mathrm{G}\left(a\left(r, x_{0}\right)\right) \leq \mathrm{C}(\eta, \mathrm{M})\left(1+\mathrm{G}(a(1))=\mathrm{C} \cdot\left(1+\int_{B_{1}} \mathrm{G}(|\nabla u|) d x\right)\right.
$$

Finally, we obtain

$$
\|\nabla u\|_{L^{\infty}\left(B_{\frac{1}{2}}\right)} \leq \mathrm{G}^{-1}\left(1+\int_{B_{1}} \mathrm{G}(|\nabla u|) d x\right)
$$

## Appendix: a Campanato-type estimate

In this section we prove a Campanato-type result in the context of Orlicz modulars, i.e. that functions with appropriate average decay are Hölder continuous. As far as the authors' are concerned, this result is new in the specialized literature and hence has independent interest. The proof follows Fernández Bonder's personal notes [38] for the homogeneous setting.

Let us denote

$$
\Omega_{x_{0}, \varrho}:=\Omega \cap B_{\varrho}\left(x_{0}\right) \quad \text { and } \quad u_{x_{0}, \varrho}:=\frac{1}{\left|\Omega_{x_{0}, \varrho}\right|} \int_{\Omega_{x_{0}, \varrho}} u(x) d x=f_{\Omega_{x_{0}, \varrho}} u(x) d x
$$

For our purposes, the analogous of the $L^{p}$ norm and Campanato seminorm (see for instance [42]) will be given, for $\lambda \geq 0$, by

$$
\begin{equation*}
\Phi(u):=\int_{\Omega} \mathrm{G}(|u|) d x, \quad \Phi_{\lambda}(u):=\sup _{\substack{x_{0} \in \Omega \\ \varrho>0}} \varrho^{-\lambda} \int_{\Omega_{x_{0}, \varrho}} \mathrm{G}\left(\left|u-u_{x_{0}, \varrho}\right|\right) d x \tag{4.7}
\end{equation*}
$$

These quantities are not homogeneous and hence not a norm/seminorm, but they capture the essential properties that will be used to prove the desired continuity.

We will work with functions satisfying

$$
\begin{equation*}
\Phi(u)+\Phi_{\lambda}(u) \leq \mathrm{C}_{\Phi} \tag{4.8}
\end{equation*}
$$

for some constant $\mathrm{C}_{\Phi}$. The first step is to prove that every point in $\Omega$ is a Lebesgue point of $u$ :
Proposition 4.1. If $u$ satisfies (4.8) and $\lambda>n$ then there exists $\tilde{u}=u$ a.e. such that

$$
\lim _{r \rightarrow 0^{+}} u_{x_{0}, r}=\tilde{u}\left(x_{0}\right)
$$

uniformly in $\Omega$.
Proof. Step 1. Let $0<r_{1}<r_{2}$. Then for $y \in B_{r_{1}}\left(x_{0}\right)$ and using (2.5) we have that

$$
\mathrm{G}\left(\left|u_{x_{0}, r_{1}}-u_{x_{0}, r_{2}}\right|\right) \leq 2^{g_{0}}\left(\mathrm{G}\left(\left|u_{x_{0}, r_{1}}-u(y)\right|\right)+\mathrm{G}\left(\left|u_{x_{0}, r_{2}}-u(y)\right|\right)\right)
$$

Integrating over $B_{r_{1}}\left(x_{0}\right)$ we get that

$$
\left|B_{1}\right| r_{1}^{n} \mathrm{G}\left(\left|u_{x_{0}, r_{1}}-u_{x_{0}, r_{2}}\right|\right) \leq 2^{g_{0}} \Phi_{\lambda}(u)\left(r_{1}^{\lambda}+r_{2}^{\lambda}\right)
$$

and we get

$$
\mathrm{G}\left(\left|u_{x_{0}, r_{1}}-u_{x_{0}, r_{2}}\right|\right) \leq 2^{g_{0}} \frac{r_{1}^{\lambda}+r_{2}^{\lambda}}{\left|B_{1}\right| r_{1}^{n}} \Phi_{\lambda}(u)
$$

or

$$
\begin{equation*}
\left|u_{x_{0}, r_{1}}-u_{x_{0}, r_{2}}\right| \leq \mathrm{G}^{-1}\left(2^{g_{0}} \frac{r_{1}^{\lambda}+r_{2}^{\lambda}}{\left|B_{1}\right| r_{1}^{n}} \Phi_{\lambda}(u)\right) \tag{4.9}
\end{equation*}
$$

Step 2. We will iterate (4.9) dyadically; for $j \in \mathbb{N}_{0}$ and fixed $r>0$ we have

$$
\mathrm{G}\left(\left|u_{x_{0}, 2^{-(j+1)} r}-u_{x_{0}, 2^{-j_{r}}}\right|\right) \leq 2^{g_{0}} \frac{2^{-(j+1) \lambda} r^{\lambda}+2^{-j \lambda} r^{\lambda}}{\left|B_{1}\right| 2^{(-j-1) n} r^{n}} \Phi_{\lambda}(u)
$$

This means that

$$
\left|u_{x_{0}, 2^{-(j+1)} r}-u_{x_{0}, 2^{-j} r}\right| \leq \mathrm{G}^{-1}\left(\frac{2^{g_{0}}}{\left|B_{1}\right|} \Phi_{\lambda}(u)\right) r^{\frac{\lambda-n}{g_{0}+1}} 2^{\frac{j(n-\lambda)}{g_{0}+1}}
$$

and since

$$
\left|u_{x_{0}, r}-u_{x_{0}, 2^{-k} r}\right| \leq \sum_{j=0}^{k}\left|u_{x_{0}, 2^{-(j+1)} r}-u_{x_{0}, 2^{-j} r}\right|
$$

we get

$$
\begin{equation*}
\left|u_{x_{0}, r}-u_{x_{0}, 2^{-k} r}\right| \leq \mathrm{G}^{-1}\left(\frac{2^{g_{0}}}{\left|B_{1}\right|} \Phi_{\lambda}(u)\right) r^{\frac{\lambda-n}{g_{0}+1}} \sum_{j=0}^{k} 2^{\frac{j(n-\lambda)}{g_{0}+1}} \tag{4.10}
\end{equation*}
$$

Step 3. Now we can use (4.10) in the following way

$$
\begin{aligned}
\left|u_{x_{0}, 2^{-k} r}-u_{x_{0}, 2^{-(k+i) r}}\right| & \leq \mathrm{G}^{-1}\left(\frac{2^{g_{0}}}{\left|B_{1}\right|} \Phi_{\lambda}(u)\right)\left(\frac{r}{2^{k}}\right)^{\frac{\lambda-n}{g_{0}+1}} \sum_{j=0}^{i-1} 2^{\frac{j(n-\lambda)}{g_{0}+1}} \\
& \leq \mathrm{CG}^{-1}\left(\frac{2^{g_{0}}}{\left|B_{1}\right|} \Phi_{\lambda}(u)\right)\left(\frac{r}{2^{k}}\right)^{\frac{\lambda-n}{g_{0}+1}}
\end{aligned}
$$

where $\mathrm{C}>0$ depends only on $g_{0}, n$ and $\lambda$. In particular $\left\{u_{x_{0}, 2^{-k_{r}}}\right\}_{k}$ is a Cauchy sequence (uniformly in $x_{0}$ ) and hence has a limit which we call $\tilde{u}\left(x_{0}\right)$ :

$$
\lim _{k \rightarrow \infty} u_{x_{0}, 2^{-k_{r}}}=: \tilde{u}\left(x_{0}\right) .
$$

Notice that: a) for almost every $x_{0}$ Lebesgue's Differentiation Theorem says that $\tilde{u}\left(x_{0}\right)=u\left(x_{0}\right)$; and b) $\tilde{u}$ does not depend on the specific choice of $r$. Indeed, passing to the limit as $i \rightarrow \infty$ above we obtain that

$$
\left|u_{x_{0}, 2^{-k} r}-\tilde{u}\left(x_{0}\right)\right| \leq \mathrm{CG}^{-1}\left(\frac{2^{g_{0}}}{\left|B_{1}\right|} \Phi_{\lambda}(u)\right)\left(\frac{r}{2^{k}}\right)^{\frac{\lambda-n}{g_{0}+1}}
$$

and then, if we consider a $r^{\prime}>0$, we can bound, using (4.9) and the previous inequality

$$
\begin{aligned}
\left|u_{x_{0}, 2^{-k} r^{\prime}}-\tilde{u}\left(x_{0}\right)\right| & \leq\left|u_{x_{0}, 2^{-k} r^{\prime}}-u_{x_{0}, 2^{-k} r}\right|+\left|u_{x_{0}, 2^{-k} r}-\tilde{u}\left(x_{0}\right)\right| \\
& \leq \mathrm{G}^{-1}\left(2^{g_{0}} \frac{r^{\prime \lambda}+r^{\lambda}}{\left|B_{1}\right| r^{\prime n}} \Phi_{\lambda}(u) 2^{-k(\lambda-n)}\right)+\mathrm{CG}^{-1}\left(\frac{2^{g_{0}}}{\left|B_{1}\right|} \Phi_{\lambda}(u)\right)\left(\frac{r}{2^{k}}\right)^{\frac{\lambda-n}{g_{0}+1}} \\
& \leq 2^{-k \frac{\lambda-n}{g_{0}+1}}\left(\mathrm{G}^{-1}\left(2^{g_{0}} \frac{r^{\prime \lambda}+r^{\lambda}}{\left|B_{1}\right| r^{\prime n}} \Phi_{\lambda}(u)\right)+\mathrm{CG}^{-1}\left(\frac{2^{g_{0}}}{\left|B_{1}\right|} \Phi_{\lambda}(u)\right) r^{\frac{\lambda-n}{g_{0}+1}}\right)
\end{aligned}
$$

which goes to 0 as $k \rightarrow \infty$.
Finally, we go from discrete to continuous: we pass to the limit on $k$ to obtain in (4.10) to get

$$
\begin{equation*}
\left|u_{x_{0}, r}-\tilde{u}\left(x_{0}\right)\right| \leq \mathrm{G}^{-1}\left(\frac{2^{g_{0}}}{\left|B_{1}\right|} \Phi_{\lambda}(u)\right) r^{\frac{\lambda-n}{g_{0}+1}} \sum_{j=0}^{\infty} 2^{\frac{j(n-\lambda)}{g_{0}+1}} \tag{4.11}
\end{equation*}
$$

and taking the limit $r \rightarrow 0^{+}$we get the desired uniform convergence.
Next we want to show that $u$ is indeed Hölder continuous in $\Omega$. We identify it with $\tilde{u}$ and drop the $\sim$ for simplicity.

Proposition 4.2. If $u$ satisfies (4.8) and $\lambda>n$ then there exists $\mathrm{C}=\mathrm{C}\left(n, g_{0}, \lambda\right)>0$ such that

$$
\sup _{\substack{x, y \in \Omega \\ x \neq y}} \frac{|u(x)-u(y)|}{|x-y|^{\gamma}} \leq \mathrm{CG}^{-1}\left(\frac{2^{g_{0}}}{\left|B_{1}\right|} \Phi_{\lambda}(u)\right)
$$

with $\gamma=\frac{\lambda-n}{g_{0}+1}$.
Proof. We start with the following claim: if $x, y \in \Omega$ and $r=2|x-y|$ then

$$
\left|u_{x, r}-u_{y, r}\right| \leq \mathrm{CG}^{-1}\left(\frac{2^{g_{0}}}{\left|B_{1}\right|} \Phi_{\lambda}(u)\right)|x-y|^{\gamma}
$$

with $\gamma=\frac{\lambda-n}{g_{0}+1}$.
To prove the claim we note that for $z \in B_{r}(x) \cap B_{r}(y)$ it holds that

$$
\mathrm{G}\left(\left|u_{x, r}-u_{y, r}\right|\right) \leq 2^{g_{0}}\left(\mathrm{G}\left(\left|u_{x, r}-u(z)\right|\right)+\mathrm{G}\left(\left|u_{y, r}-u(z)\right|\right)\right)
$$

and so integrating over $B_{r}(x) \cap B_{r}(y)$ we get that

$$
\begin{aligned}
\left|B_{r}(x) \cap B_{r}(y)\right| \mathrm{G}\left(\left|u_{x, r}-u_{y, r}\right|\right) & \leq 2^{g_{0}}\left(\int_{B_{r}(x)} \mathrm{G}\left(\left|u_{x, r}-u(z)\right|\right) d z+\int_{B_{r}(y)} \mathrm{G}\left(\left|u_{y, r}-u(z)\right|\right) d z\right) \\
& \leq 2^{g_{0}+1} r^{\lambda} \Phi_{\lambda}(u)
\end{aligned}
$$

which leads to

$$
\left|u_{x, r}-u_{y, r}\right| \leq \mathrm{G}^{-1}\left(\frac{1}{\left|B_{r}(x) \cap B_{r}(y)\right|} 2^{g_{0}+1} r^{\lambda} \Phi_{\lambda}(u)\right)
$$

The claim follows simply by noting that $B_{\frac{r}{2}}(x) \subset B_{r}(x) \cap B_{r}(y)$.
Since

$$
|u(x)-u(y)| \leq\left|u(x)-u_{x, r}\right|+\left|u_{x, r}-u_{y, r}\right|+\left|u_{y, r}-u(y)\right|
$$

the proposition follows using the claim and (4.11).
We remark that $\Phi_{\lambda}(u)$ is equivalent to

$$
\sup _{\substack{x_{0} \in \Omega \\ \varrho>0}} \varrho^{-\lambda} \inf _{\xi \in \mathbb{R}} \int_{\Omega_{x_{0}, \varrho}} \mathrm{G}(|u(x)-\xi|) d x
$$

indeed, one inequality being trivial, the other one follows by noting that Jensen's inequality gives

$$
\mathrm{G}\left(\left|u_{x_{0}, \varrho}-\xi\right|\right)=\mathrm{G}\left(\left|f_{\Omega_{x_{0}, \varrho}}(u(x)-\xi) d x\right|\right) \leq f_{\Omega_{x_{0}, e}} \mathrm{G}(|u(x)-\xi|) d x
$$

from where

$$
\begin{aligned}
\int_{\Omega_{x_{0}, e}} \mathrm{G}\left(\left|u(x)-u_{x_{0}, \varrho}\right|\right) d x & \leq 2^{g_{0}}\left(\int_{\Omega_{x_{0}, \varrho}} \mathrm{G}(|u(x)-\xi|) d x+\int_{\Omega_{x_{0}, \varrho}} \mathrm{G}\left(\left|\xi-u_{x_{0}, \varrho}\right|\right) d x\right) \\
& \leq 2^{g_{0}+1} \int_{\Omega_{x_{0}, e}} \mathrm{G}(|u(x)-\xi|) d x
\end{aligned}
$$

In summary, we have the following theorem:
Theorem 4.3. Let $u$ be a measurable function satisfying

$$
\int_{\Omega} \mathrm{G}(|u|) d x+\sup _{\substack{x_{0} \in \Omega \\ \varrho>0}} \varrho^{-\lambda} \inf _{\xi \in \mathbb{R}} \int_{\Omega_{x_{0}, e}} \mathrm{G}(|u(x)-\xi|) d x \leq \mathrm{C}_{0}
$$

for some positive constant $\mathrm{C}_{0}$ and $\lambda>n$. Then, $u \in C^{0, \gamma}(\Omega)$ with $\gamma=\frac{\lambda-n}{g_{0}+1}$ and

$$
\sup _{\substack{x, y \in \Omega \\ x \neq y}} \frac{|u(x)-u(y)|}{|x-y|^{\gamma}} \leq \mathrm{CG}^{-1}\left(\sup _{\substack{x_{0} \in \Omega \\ \varrho>0}} \varrho^{-\lambda} \inf _{\xi \in \mathbb{R}} \int_{\Omega_{x_{0}, \varrho}} \mathrm{G}(|u(x)-\xi|) d x\right)
$$

Remark 4.4. One could consider $\lambda=n+g_{0}+1$ in the previous theorem and obtain $u \in C^{0,1}(\Omega)$, i.e. $u$ is Lipschitz continuous in $\Omega$.

Definition 4.5 ([49, Definition 1.2]). Let $p \in[1, \infty)$ and a $\psi:(0, \infty) \rightarrow(0, \infty)$ be a continuous function. We define the generalized Campanato space

$$
\mathcal{L}_{p, \psi}(\Omega):=\left\{f: \Omega \rightarrow \mathbb{R}:\|f\|_{\mathcal{L}_{p, \psi}(\Omega)}:=\sup _{B_{r}\left(x_{0}\right) \subset \Omega} \frac{1}{\psi(r)}\left(f_{B_{r}\left(x_{0}\right)}\left|f(x)-f_{B_{r}\left(x_{0}\right)}\right|^{p} d x\right)^{\frac{1}{p}}<\infty\right\}
$$

Remark 4.6. Observe that $\|f\|_{\mathcal{L}_{p, \psi}(\Omega)}$ is a norm (modulo constant functions), thus $\mathcal{L}_{p, \psi}(\Omega)$ defines a Banach space. Moreover, if $p=1$ and $\psi \equiv 1$, then $\mathcal{L}_{1,1}(\Omega)=\operatorname{BMO}(\Omega)$. Finally, if $p=1$ and $\psi(r)=r^{\gamma}$ (for some $0<\gamma \leq 1$ ), then $\mathcal{L}_{1, r^{\gamma}}(\Omega)$ coincides with standard spaces $C^{0, \gamma}(\Omega)$.

We also consider now the following functional space

$$
\operatorname{BMO}^{*}(\Omega):=\left\{u: \Omega \rightarrow \mathbb{R}:\|u\|_{\mathrm{BMO}^{*}(\Omega)}:=\sup _{\substack{x_{0} \in \Omega \\ \rho>0}} f_{\Omega_{x_{0}, \rho}}\left|u-u_{x_{0}, \rho}\right| d x<\infty\right\}
$$

Now, we will suppose that $\Omega$ satisfies a $\hat{c}_{0}-$ uniform positive density ( $\hat{c}_{0}-U P D$ for short), i.e., there exists a universal constant $\hat{c}_{0} \in(0,1)$ such that

$$
\frac{\left|\Omega_{x_{0}, \rho}\right|}{\left|B_{\rho}\left(x_{0}\right)\right|}=\frac{\left|\Omega \cap B_{\rho}\left(x_{0}\right)\right|}{\left|B_{\rho}\left(x_{0}\right)\right|} \geq \hat{\mathrm{c}}_{0} \quad \forall x_{0} \in \bar{\Omega} \text { and } \rho>0 .
$$

Remember we are assuming that $\Omega$ is a bounded Lipschitz domain, thus it fulfils $\hat{\mathrm{c}}_{0}-\mathrm{UPD}$ property for some $\hat{c}_{0} \in(0,1)$.

Finally, taking into account the above definitions and using Jensen's inequality for concave functions, we can conclude in the borderline case, i.e., $\lambda=n$ (see (4.7) and (4.8)) the following:

$$
\begin{aligned}
\|u\|_{\mathrm{BMO}^{*}(\Omega)} & :=\sup _{\substack{x_{0} \in \Omega \\
\rho>0}} f_{\Omega_{x_{0}, \rho}}\left|u-u_{x_{0}, \rho}\right| d x \\
& =\sup _{\substack{x_{0} \in \Omega \\
\rho>0}} f_{\Omega_{\Omega_{0}, \rho}} \mathrm{G}^{-1}\left(\mathrm{G}\left(\left|u-u_{x_{0}, \rho}\right|\right)\right) d x \\
& \leq \sup _{\substack{x_{0} \in \Omega \\
\rho>0}} \mathrm{G}^{-1}\left(f_{\Omega_{x_{0}, \rho}} \mathrm{G}\left(\left|u-u_{x_{0}, \rho}\right|\right) d x\right) \\
& \leq \mathrm{G}^{-1}\left(\sup _{\substack{x_{0} \in \Omega}} f_{\Omega_{x_{0}, \rho}} \mathrm{G}\left(\left|u-u_{x_{0}, \rho}\right|\right) d x\right) \\
& \leq \mathrm{G}^{-1}\left(\hat{\mathrm{c}}_{0}^{-1} \omega_{n}^{-1} \sup _{\substack{x_{0} \in \Omega \\
\rho>0}} \frac{1}{\rho^{n}} \int_{\Omega_{x_{0}, \rho}} G\left(\left|u-u_{x_{0}, \rho}\right|\right) d x\right) \\
& \leq \mathrm{G}^{-1}\left(\hat{\mathrm{c}}_{0}^{-1} \omega_{n}^{-1} \mathrm{C}_{\Phi}\right) .
\end{aligned}
$$

Therefore, $u \in \operatorname{BMO}^{*}(\Omega)$ provided $\lambda=n$ and $\Omega$ fulfils a $\hat{c}_{0}-\mathrm{UPD}$ property.

## Acknowledgments

The authors would like to thank Julián Fernández Bonder for lending his notes on Morrey estimates for fractional Sobolev spaces, from which the ideas for the Appendix were taken.
A. Silva was partially supported by ANPCyT under grant PICT 2019-3837, by CONICET under grant PIP 11220210100238 CO and by UNSL under grant PROICO 03-2023. J.V. da Silva has been partially supported by CNPq-Brazil under Grant No. 307131/2022-0 and FAEPEXUNICAMP 2441/23 Editais Especiais - PIND - Projetos Individuais (03/2023). H. Vivas was partially supported by ANPCyT under grant PICT 2019-03530.

## References

[1] R. A. Adams and J.J.F. Fournier. Sobolev spaces, volume 140 of Pure and Applied Mathematics (Amsterdam). Elsevier/Academic Press, Amsterdam, second edition, 2003.
[2] N. Aguilera, H. W. Alt, and L. A. Caffarelli. An optimization problem with volume constraint. SIAM J. Control Optim., 24(2):191-198, 1986.
[3] H. W. Alt and L. A. Caffarelli. Existence and regularity for a minimum problem with free boundary. J. Reine Angew. Math., 325:105-144, 1981.
[4] P. Baroni, M. Colombo, and G. Mingione. Regularity for general functionals with double phase. Calc. Var. Partial Differential Equations, 57(2):Paper No. 62, 48, 2018.
[5] M. Bayrami, M. Fotouhi, and H. Shahgholian. Lipschitz regularity of a weakly coupled vectorial almost-minimizers for the p-laplacian. https://doi.org/10.48550/arXiv.2311.09073, 2023.
[6] H. Berestycki, L. A. Caffarelli, and L. Nirenberg. Uniform estimates for regularization of free boundary problems. In Analysis and partial differential equations, volume 122 of Lecture Notes in Pure and Appl. Math., pages 567-619. Dekker, New York, 1990.
[7] J. E. M. Braga, R. A. Leitão, and J. E. L. Oliveira. Free boundary theory for singular/degenerate nonlinear equations with right hand side: a non-variational approach. Calc. Var. Partial Differential Equations, 59(2):Paper No. 86, 29, 2020.
[8] D. Bucur and G. Buttazzo. Variational methods in shape optimization problems, volume 65 of Progress in Nonlinear Differential Equations and their Applications. Birkhäuser Boston, Inc., Boston, MA, 2005.
[9] D. Bucur and A. Giacomini. Shape optimization problems with Robin conditions on the free boundary. Ann. Inst. H. Poincaré C Anal. Non Linéaire, 33(6):1539-1568, 2016.
[10] D. Bucur and B. Velichkov. A free boundary approach to shape optimization problems. Philos. Trans. Roy. Soc. A, 373(2050):20140273, 15, 2015.
[11] S.-S. Byun and J. Oh. Regularity results for generalized double phase functionals. Anal. PDE, 13(5):1269-1300, 2020.
[12] L. Caffarelli and S. Salsa. A geometric approach to free boundary problems, volume 68 of Graduate Studies in Mathematics. American Mathematical Society, Providence, RI, 2005.
[13] L. A. Caffarelli. A Harnack inequality approach to the regularity of free boundaries. I. Lipschitz free boundaries are $C^{1, \alpha}$. Rev. Mat. Iberoamericana, 3(2):139-162, 1987.
[14] L. A. Caffarelli. A Harnack inequality approach to the regularity of free boundaries. III. Existence theory, compactness, and dependence on $X$. Ann. Scuola Norm. Sup. Pisa Cl. Sci. (4), 15(4):583-602, 1988.
[15] L. A. Caffarelli. A Harnack inequality approach to the regularity of free boundaries. II. Flat free boundaries are Lipschitz. Comm. Pure Appl. Math., 42(1):55-78, 1989.
[16] N. A Cantizano, A. M. Salort, and J. F Spedaletti. Continuity of solutions for the $\phi$ laplacian operator. Proceedings of the Royal Society of Edinburgh Section A: Mathematics, 151(4):1355-1382, 2021.
[17] J. A. Carrillo and R. S. Gvalani. Phase transitions for nonlinear nonlocal aggregation-diffusion equations. Comm. Math. Phys., 382(1):485-545, 2021.
[18] I. Chlebicka. A pocket guide to nonlinear differential equations in Musielak-Orlicz spaces. Nonlinear Anal., 175:1-27, 2018.
[19] M. Colombo and G. Mingione. Regularity for double phase variational problems. Arch. Ration. Mech. Anal., 215(2):443-496, 2015.
[20] J. V. da Silva, G. C. Rampasso, G. C. Ricarte, and H. A. Vivas. Free boundary regularity for a class of one-phase problems with non-homogeneous degeneracy. Israel J. Math., 254(1):155200, 2023.
[21] D. Danielli and A. Petrosyan. A minimum problem with free boundary for a degenerate quasilinear operator. Calc. Var. Partial Differential Equations, 23(1):97-124, 2005.
[22] G. David, M. Engelstein, M. Smit Vega Garcia, and T. Toro. Regularity for almost-minimizers of variable coefficient Bernoulli-type functionals. Math. Z., 299(3-4):2131-2169, 2021.
[23] G. David, M. Engelstein, and T. Toro. Free boundary regularity for almost-minimizers. Adv. Math., 350:1109-1192, 2019.
[24] G. David and T. Toro. Regularity of almost minimizers with free boundary. Calc. Var. Partial Differential Equations, 54(1):455-524, 2015.
[25] C. De Filippis and G. Mingione. On the regularity of minima of non-autonomous functionals. J. Geom. Anal., 30(2):1584-1626, 2020.
[26] C. De Filippis and G. Mingione. Lipschitz bounds and nonautonomous integrals. Arch. Ration. Mech. Anal., 242(2):973-1057, 2021.
[27] C. De Filippis and J. Oh. Regularity for multi-phase variational problems. J. Differential Equations, 267(3):1631-1670, 2019.
[28] G. De Philippis, L. Spolaor, and B. Velichkov. Regularity of the free boundary for the twophase Bernoulli problem. Invent. Math., 225(2):347-394, 2021.
[29] O. S. de Queiroz and L.S. Tavares. Almost minimizers for semilinear free boundary problems with variable coefficients. Math. Nachr., 291(10):1486-1501, 2018.
[30] D. De Silva. Free boundary regularity for a problem with right hand side. Interfaces Free Bound., 13(2):223-238, 2011.
[31] D. De Silva, F. Ferrari, and S. Salsa. Recent progresses on elliptic two-phase free boundary problems. Discrete Contin. Dyn. Syst., 39(12):6961-6978, 2019.
[32] D. De Silva, S. Jeon, and H. Shahgholian. Almost minimizers for a singular system with free boundary. J. Differential Equations, 336:167-203, 2022.
[33] D. De Silva and O. Savin. Almost minimizers of the one-phase free boundary problem. Comm. Partial Differential Equations, 45(8):913-930, 2020.
[34] D. De Silva and O. Savin. Quasi-Harnack inequality. Amer. J. Math., 143(1):307-331, 2021.
[35] L. Diening, P. Harjulehto, P. Hästö, and M. Růžička. Lebesgue and Sobolev spaces with variable exponents, volume 2017 of Lecture Notes in Mathematics. Springer, Heidelberg, 2011.
[36] S. Dipierro, F. Ferrari, N. Forcillo, and E. Valdinoci. Lipschitz regularity of almost minimizers in one-phase problems driven by the $p$-laplace operator. To appear in Indiana University Mathematics Journal. arXiv preprint arXiv:2206.03238, 2023.
[37] S. Dipierro and A. L. Karakhanyan. Stratification of free boundary points for a two-phase variational problem. Adv. Math., 328:40-81, 2018.
[38] J. Fernández Bonder. Estimaciones de Morrey para espacios de Sobolev fraccionarios. Personal Notes, 2023.
[39] X. Fernández-Real and X. Ros-Oton. Regularity theory for elliptic PDE, volume 28 of Zurich Lectures in Advanced Mathematics. EMS Press, Berlin, [2022] © 2022.
[40] F. Ferrari and C. Lederman. Regularity of Lipschitz free boundaries for a $p(x)$-Laplacian problem with right hand side. J. Math. Pures Appl. (9), 171:26-74, 2023.
[41] A. Figalli. Regularity of interfaces in phase transitions via obstacle problems-Fields Medal lecture. In Proceedings of the International Congress of Mathematicians-Rio de Janeiro 2018. Vol. I. Plenary lectures, pages 225-247. World Sci. Publ., Hackensack, NJ, 2018.
[42] E. Giusti. Direct methods in the calculus of variations. World Scientific Publishing Co., Inc., River Edge, NJ, 2003.
[43] P. Hästö and J. Ok. Maximal regularity for local minimizers of non-autonomous functionals. J. Eur. Math. Soc. (JEMS), 24(4):1285-1334, 2022.
[44] R. Leitão and G. Ricarte. Free boundary regularity for a degenerate problem with right hand side. Interfaces Free Bound., 20(4):577-595, 2018.
[45] G. M. Lieberman. The natural generalization of the natural conditions of Ladyzhenskaya and Ural'tseva for elliptic equations. Comm. Partial Differential Equations, 16(2-3):311-361, 1991.
[46] S. Martínez and N. Wolanski. A minimum problem with free boundary in Orlicz spaces. Adv. Math., 218(6):1914-1971, 2008.
[47] A. Petrosyan and E. Valdinoci. Density estimates for a degenerate/singular phase-transition model. SIAM J. Math. Anal., 36(4):1057-1079, 2005.
[48] A. Petrosyan and E. Valdinoci. Geometric properties of Bernoulli-type minimizers. Interfaces Free Bound., 7(1):55-77, 2005.
[49] M. Shi, R. Arai, and E. Nakai. Commutators of integral operators with functions in Campanato spaces on Orlicz-Morrey spaces. Banach J. Math. Anal., 15(1):Paper No. 22, 41, 2021.
[50] E. V. Teixeira. Optimal design problems in rough inhomogeneous media: existence theory. Amer. J. Math., 132(6):1445-1492, 2010.
[51] E. Valdinoci. Flatness of Bernoulli jets. Math. Z., 254(2):257-298, 2006.
[52] B. Velichkov. Regularity of the One-phase Free Boundaries, volume 28 of Lecture Notes of the Unione Matematica Italiana. Springer Cham, 2023.


[^0]:    *João Vitor da Silva. Universidade Estadual de Campinas - UNICAMP. Department of Mathematics. Campinas - SP, Brazil. E-mail address: jdasilva@unicamp.br
    $\dagger$ Analía Silva. Departamento de Matemática, FCFMyN, Universidad Nacional de San Luis and Instituto de Matemática Aplicada San Luis (IMASL), UNSL - CONICET. Ejercito de los Andes 950, D5700HHW, San Luis, Argentina. E-mail address: acsilva@unsl.edu.ar
    ${ }^{\ddagger}$ Hernán Vivas. Centro Marplatense de Investigaciones Matemáticas (CEMIM), Universidad Nacional de Mar del Plata, CIC, CONICET. Deán Funes 3350, 7600, Mar del Plata, Argentina. E-mail address: havivas@unmdp.edu.ar

