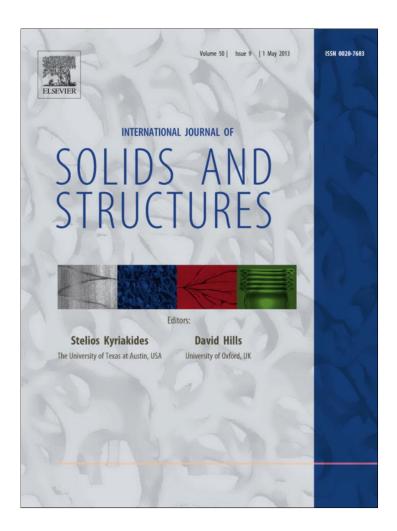
Provided for non-commercial research and education use. Not for reproduction, distribution or commercial use.



This article appeared in a journal published by Elsevier. The attached copy is furnished to the author for internal non-commercial research and education use, including for instruction at the authors institution and sharing with colleagues.

Other uses, including reproduction and distribution, or selling or licensing copies, or posting to personal, institutional or third party websites are prohibited.

In most cases authors are permitted to post their version of the article (e.g. in Word or Tex form) to their personal website or institutional repository. Authors requiring further information regarding Elsevier's archiving and manuscript policies are encouraged to visit:

http://www.elsevier.com/copyright

International Journal of Solids and Structures 50 (2013) 1303-1313



Contents lists available at SciVerse ScienceDirect

# International Journal of Solids and Structures

journal homepage: www.elsevier.com/locate/ijsolstr



# Strain energy change to the insertion of inclusions associated to a thermo-mechanical semi-coupled system

S.M. Giusti <sup>a,\*</sup>, A.A. Novotny <sup>b</sup>, J.E. Muñoz Rivera <sup>b</sup>, J.E. Esparta Rodriguez <sup>b</sup>

<sup>a</sup> Universidad Tecnológica Nacional, Facultad Regional Córdoba UNT/FRC – CONICET, Maestro M. López esq. Cruz Roja Argentina, X5016ZAA Córdoba, Argentina <sup>b</sup> Laboratório Nacional de Computação Científica LNCC/MCT, Av. Getúlio Vargas 333, 25651-075 Petrópolis, RJ, Brazil

#### ARTICLE INFO

#### Article history:

Received 6 October 2012 Received in revised form 19 December 2012 Available online 17 January 2013

#### Kevwords:

Topological derivative Thermo-mechanical semi-coupled system Multi-physic topology optimization Asymptotic analysis

#### ABSTRACT

The topological derivative measures the sensitivity of a given shape functional with respect to an infinitesimal singular domain perturbation. According to the literature, the topological derivative has been fully developed for a wide range of one single physical phenomenon modeled by partial differential equations. In addition, the topological asymptotic analysis associated to multi-physics problems has been reported in the literature only on the level of mathematical analysis of singularly perturbed geometrical domains. In this work, we present the topological derivative in its closed form for the total potential mechanical energy associated to a thermo-mechanical semi-coupled system, when a small circular inclusion is introduced at an arbitrary point of the domain. In particular, we consider the linear elasticity system (modeled by the Navier equation) coupled with the steady-state heat conduction problem (modeled by the Laplace equation). The mechanical coupling term comes out from the thermal stress induced by the temperature field. Since this term is non-local, we introduce a non-standard adjoint state, which allows to obtain a closed form for the topological derivative. Finally, we provide a full mathematical justification for the derived formulas and develop precise estimates for the remainders of the topological asymptotic expansion.

© 2013 Elsevier Ltd. All rights reserved.

## 1. Introduction

The topological derivative represents a first order asymptotic correction term of a given shape functional with respect to a singular domain perturbation (Sokołowski and Żochowski, 1999). It has been applied in topology design optimization (Amstutz et al., 2012), inverse problems (Hintermüller et al., 2012), image processing (Hintermüller and Laurain, 2009), multi-scale constitutive modeling (Giusti et al., 2009), fracture mechanic sensitivity analysis (Van Goethem and Novotny, 2010) and damage evolution modeling (Allaire et al., 2011). See also the book by Novotny and Sokołowski (2013) and references therein.

For the sake of completeness, we recall the basic concepts on topological sensitivity analysis. Let us consider a bounded domain  $\Omega \subset \mathbb{R}^2$ , which is subject to a non-smooth perturbation confined in a small region  $\omega_{\varepsilon}(\hat{x}) = \hat{x} + \varepsilon \omega$  of size  $\varepsilon$ , as shown in Fig. 1. Here,  $\hat{x}$  is an arbitrary point of  $\Omega$  and  $\omega$  is a fixed bounded domain of  $\mathbb{R}^2$ . Associated to the domain  $\Omega$  we introduce a characteristic function  $x \mapsto \chi(x), \ x \in \mathbb{R}^2$ , namely  $\chi = \mathbb{I}_{\Omega}$ . Also, for the topologically perturbed domain we can define a characteristic function of the form

E-mail addresses: sgiusti@civil.frc.utn.edu.ar (S.M. Giusti), novotny@lncc.br (A.A. Novotny), rivera@lncc.br (J.E. Muñoz Rivera), esparta@lncc.br (J.E. Esparta Rodriguez).

 $x \mapsto \chi_{\varepsilon}(\hat{x};x)$ . If the perturbation is given by a perforation, the characteristic function can be written as  $\chi_{\varepsilon}(\hat{x}) = \mathbb{I}_{\Omega} - \mathbb{I}_{\overline{\omega_{\varepsilon}(\hat{x})}}$  and the perforated domain is obtained now as  $\Omega_{\varepsilon} = \Omega \setminus \overline{\omega_{\varepsilon}}$ . Now, by assuming the following topological asymptotic expansion of a given shape functional  $\psi(\chi_{\varepsilon}(\hat{x}))$ , associated to the topologically perturbed domain,

$$\psi(\gamma_{\varepsilon}(\hat{\mathbf{x}})) = \psi(\gamma) + f(\varepsilon)D_T\psi(\hat{\mathbf{x}}) + o(f(\varepsilon)), \tag{1}$$

the function  $\hat{x}\mapsto D_T\psi(\hat{x})$  is called the topological derivative of  $\psi$  at  $\hat{x}$ . In (1),  $\psi(\chi)$  is the shape functional associated to the original (unperturbed) domain and  $f(\varepsilon)$  is a positive function such that  $f(\varepsilon)\to 0$ , when  $\varepsilon\to 0$ . After rearranging (1) we have

$$\frac{\psi(\chi_{\varepsilon}(\hat{x})) - \psi(\chi)}{f(\varepsilon)} = D_T \psi(\hat{x}) + \frac{o(f(\varepsilon))}{f(\varepsilon)}. \tag{2}$$

The limit passage  $\epsilon \to 0$  in the above expression leads to

$$D_T \psi(\hat{x}) = \lim_{\varepsilon \to 0} \frac{\psi(\chi_{\varepsilon}(\hat{x})) - \psi(\chi)}{f(\varepsilon)}.$$
 (3)

Since we are dealing with singular domain perturbations, the shape functionals  $\psi(\chi_{\varepsilon}(\hat{x}))$  and  $\psi(\chi)$  are associated to topologically different domains. Therefore, the above limit is not trivial to be calculated. In particular, we need to perform an asymptotic analysis of the shape functional  $\psi(\chi_{\varepsilon}(\hat{x}))$  with respect to the small parameter

<sup>\*</sup> Corresponding author. Tel.: +54 03515986019.

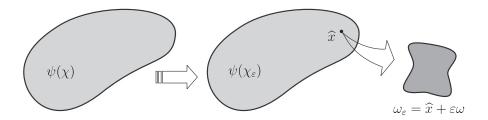


Fig. 1. The topological derivative concept.

 $\varepsilon$ . In order to calculate the topological derivative, in this work we will apply the approach fully developed in the book by Novotny and Sokołowski (2013). The method is based on the following result, whose rigorous mathematical justification can be found in the paper by Nazarov and Sokołowski (2003):

$$D_T \psi(\hat{x}) = \lim_{\varepsilon \to 0} \frac{1}{f'(\varepsilon)} \frac{d}{d\varepsilon} \psi(\chi_{\varepsilon}(\hat{x})). \tag{4}$$

The derivative of  $\psi(\chi_{\varepsilon}(\hat{\mathbf{x}}))$  with respect to  $\varepsilon$  can be seen as the sensitivity of  $\psi(\chi_{\varepsilon}(\hat{\mathbf{x}}))$ , in the classical sense of Delfour and Zolésio (2001) and Sokołowski and Zolésio (1992), to the domain variation produced by an uniform expansion of the perturbation  $\omega_{\varepsilon}$ .

According to the literature, the topological derivative has been fully developed for a wide range of one single physical phenomenon modeled by partial differential equations. In addition, only a few works dealing with multi-physics problems have been reported in the literature, and, in general, the derived formulas are presented in their abstract forms (see, for instance, the paper by Cardone et al. (2010) on topological derivatives for piezoelectric materials). In this work, therefore, we derive the topological derivative in its closed form for the total potential mechanical energy associated to a thermo-mechanical semi-coupled system, when a small circular inclusion is introduced at an arbitrary point of the domain. In particular, we consider the linear elasticity system (modeled by the Navier equation) coupled with the steady-state heat conduction problem (modeled by the Laplace equation). The mechanical coupling term comes out from the thermal stress induced by the temperature field. Since this term is non-local, we introduce a non-standard adjoint state, which simplifies the analysis allowing to obtain a closed form for the topological derivative. Finally, we provide a full mathematical justification for the derived formula and develop precise estimates for the remainders of the topological asymptotic expansion. We note that this result can be applied in technological research areas such as multi-physic topology design of structures under mechanical and/or thermal loads.

This paper is organized as follows. Section 2 describes the model associated to a thermo-mechanical semi-coupled problem. The topological sensitivity analysis is presented in Section 3, where the main result of this work is derived: the topological derivative in its closed form for the total potential mechanical energy associated to a thermo-mechanical semi-coupled system. Also in this section, a computational framework designed to the numerical validation of the topological derivative formula is presented. The paper ends in Section 4 where concluding remarks are presented.

# 2. Formulation of the problem

In this work the topological derivative of the total potential energy associated to the mechanical problem submitted to thermal stresses is derived. The topologically perturbed domain is obtained when a small hole is introduced inside the geometrical domain. Then, the resulting void is filled by an inclusion with a contrast on the elastic, thermal and thermal-expansion material properties.

Therefore, we need to formulate the problems associated to both original and topologically perturbed domains.

#### 2.1. Unperturbed problem

Consider an open and bounded domain  $\Omega \in \mathbb{R}^2$  representing an elastic solid body subject to a linear thermo-mechanical deformation process. Assuming small deformation and variations of temperatures, the functional that represents the total potential energy of the mechanical system for a given temperature field  $\theta$  is written as:

$$\mathcal{J}_{\chi}(u,\theta) := \frac{1}{2} \int_{\Omega} \sigma(u) \cdot \nabla u^{s} - \int_{\Omega} Q(\theta) \cdot \nabla u^{s} - \int_{\Gamma_{N.}} \bar{t} \cdot u, \tag{5}$$

where u represents the displacement field and  $\bar{t}$  is a external traction acting on boundary  $\Gamma_{N_u}$ . The displacement field on the boundary  $\Gamma_{D_u}$  satisfies  $u|_{\Gamma_{D_u}}=\bar{u}$ , being  $\bar{u}$  a prescribed displacement. Moreover, note that  $\Gamma_{D_u}\cap\Gamma_{N_u}=\varnothing$  and  $\overline{\Gamma_{D_u}}\cup\overline{\Gamma_{N_u}}=\partial\Omega$ . The Cauchy stress tensor  $\sigma(u)$  in (5) is defined as:

$$\sigma(u) := \mathbb{C}\nabla u^{s},\tag{6}$$

where  $\nabla u^s$  is used to denote the symmetric part of the gradient of the displacement field u, i.e.

$$\nabla u^s := \frac{1}{2} (\nabla u + (\nabla u)^\top). \tag{7}$$

The induced thermal stress tensor  $Q(\theta)$  in (5) is defined as:

$$Q(\theta) := \mathbb{C}B\theta. \tag{8}$$

Therefore the total stress, i.e. the contribution of the mechanical and thermal stresses, is defined as

$$S(u,\theta) = \sigma(u) - Q(\theta). \tag{9}$$

In addition,  $\mathbb{C}$  denotes the four-order elastic tensor and B denotes the second-order thermo-elastic tensor. In the case of isotropic elastic body, theses tensors are given by:

$$\mathbb{C} = 2\mu II + \lambda(I \otimes I) \quad \text{and} \quad B = \alpha I \Rightarrow \mathbb{C}B = 2\alpha(\lambda + \mu)I, \tag{10}$$

with  $\mu$  and  $\lambda$  denoting the Lame's coefficients, and  $\alpha$  the thermal expansion coefficient. In terms of the engineering constant E (Young's modulus) and  $\nu$  (Poisson's ratio) the above constitutive response can be written as:

$$\mathbb{C} = \frac{E}{1 - v^2} [(1 - v)II + v(I \otimes I)] \quad \text{and} \quad \mathbb{C}B = \frac{\alpha E}{1 - v}I. \tag{11}$$

Considering the previous definitions, we have that the field u is the solution of the following variational problem: given the temperature field  $\theta$ , find  $u \in \mathcal{U}^M$ , such that

$$\int_{\Omega} \sigma(u) \cdot \nabla \eta^s = \int_{\Omega} Q(\theta) \cdot \nabla \eta^s + \int_{\Gamma_{N_u}} \bar{t} \cdot \eta \quad \forall \eta \in \mathcal{V}^M. \tag{12} \label{eq:12}$$

In the variational problem (12), the set  $\mathcal{U}^M$  and the space  $\mathcal{V}^M$  are defined as

S.M. Giusti et al./International Journal of Solids and Structures 50 (2013) 1303–1313

$$\mathcal{U}^{M} := \{ \phi \in H^{1}(\Omega; \mathbb{R}^{2}) : \phi = \bar{u} \text{ on } \Gamma_{D_{u}} \}, \tag{13}$$

$$\mathcal{V}^M := \{ \phi \in H^1(\Omega; \mathbb{R}^2) : \phi = 0 \text{ on } \Gamma_{D_u} \}. \tag{14}$$

Moreover, the temperature field  $\theta$  must satisfy the following variational problem: find  $\theta \in \mathcal{U}^T$ , such that

$$\int_{\Omega} q(\theta) \cdot \nabla \eta = \int_{\Gamma_{N_0}} \bar{q} \eta \quad \forall \eta \in \mathcal{V}^T, \tag{15}$$

where  $\bar{q}$  is a prescribed heat flux on the Neumann boundary  $\Gamma_{N_{\theta}}$ . In the Dirichlet boundary  $\Gamma_{D_{\theta}}$  there is a prescribed temperature denoted as  $\bar{\theta}$ . Then,  $\Gamma_{D_{\theta}} \cap \Gamma_{N_{\theta}} = \varnothing$  and  $\overline{\Gamma_{D_{\theta}}} \cup \overline{\Gamma_{N_{\theta}}} = \partial \Omega$ . The heat flux operator  $q(\theta)$  is defined as

$$q(\theta) = -K\nabla\theta,\tag{16}$$

where K is an second order tensor representing the thermal conductivity of the medium. In the isotropic case, the tensor K can be written as

$$K = kI, (17)$$

being k the thermal conductivity coefficient. In the variational problem (15), the set  $\mathcal{U}^T$  and the space  $\mathcal{V}^T$  are defined as:

$$\mathcal{U}^{T} := \{ \phi \in H^{1}(\Omega) : \phi = \bar{\theta} \text{ on } \Gamma_{D_{\theta}} \}, \tag{18}$$

$$\mathcal{V}^T := \{ \phi \in H^1(\Omega) : \phi = 0 \text{ on } \Gamma_{D_a} \}. \tag{19}$$

**Remark 1.** In the case of a general thermo-elasticity model, the strain rate induces a change in the temperature of the body, leading to a fully coupled system. In our simplified setting, the temperature is completely independent of the mechanical strains, which leads to the so-called thermo-mechanical semi-coupled system. For the mathematical analysis of a fully coupled piezo-electric system in the context of singularly perturbed geometrical domains, see Cardone et al. (2010).

Finally, in order to simplify further analysis, the following auxiliary problem is introduced: find  $\varphi \in \mathcal{V}^T$ , such that:

$$\int_{\Omega} q(\varphi) \cdot \nabla \eta = \int_{\Omega} Q(\eta) \cdot \nabla u^{s} \quad \forall \eta \in \mathcal{V}^{T}.$$
 (20)

Note that  $\varphi$  can be seen as the adjoint state associated to the thermal stress induced by the temperature  $\theta$  (see, for instance, Sokołowski and Zolésio, 1992).

# 2.2. Perturbed problem

Considering the introduction of a circular inclusion, denoted as  $\omega_{\epsilon}(\hat{x}) := \mathcal{B}_{\epsilon}(\hat{x})$ , with radius  $\epsilon$  and centered at point  $\hat{x}$  in  $\Omega$ , the total potential energy functional associated to the perturbed domain of the mechanical system for a given temperature field  $\theta_{\epsilon}$  can be written as:

$$\mathcal{J}_{\chi_{\varepsilon}}(u_{\varepsilon},\theta_{\varepsilon}) := \frac{1}{2} \int_{\Omega} \sigma_{\varepsilon}(u_{\varepsilon}) \cdot \nabla u_{\varepsilon}^{s} - \int_{\Omega} Q_{\varepsilon}(\theta_{\varepsilon}) \cdot \nabla u_{\varepsilon}^{s} - \int_{\Gamma_{N_{u}}} \bar{t} \cdot u_{\varepsilon}, \quad (21)$$

where  $u_{\varepsilon}$  and  $\theta_{\varepsilon}$  denotes, respectively, the displacement and temperature fields, both associated to the perturbed system. In addition,  $\sigma_{\varepsilon}(u_{\varepsilon})$  and  $Q_{\varepsilon}(\theta_{\varepsilon})$  are used to denote the mechanical and the induced thermal stresses tensors associated to the perturbed problem. These tensors are defined as:

$$\sigma_{\varepsilon}(u_{\varepsilon}) := \gamma_{\varepsilon}^{\mathsf{M}} \mathbb{C} \nabla u_{\varepsilon}^{\mathsf{s}} \quad \text{and} \quad Q_{\varepsilon}(\theta_{\varepsilon}) := \gamma_{\varepsilon}^{\mathsf{M}} \gamma_{\varepsilon}^{\mathsf{c}} \mathbb{C} B \theta_{\varepsilon}, \tag{22}$$

and the corresponding total stress operator  $S_{\epsilon}(u_{\epsilon},\theta_{\epsilon})$  associated to the perturbed problem is given by

$$S_{\varepsilon}(u_{\varepsilon}, \theta_{\varepsilon}) = \sigma_{\varepsilon}(u_{\varepsilon}) - Q_{\varepsilon}(\theta_{\varepsilon}). \tag{23}$$

The contrast parameters in the material properties  $\gamma^M_{\epsilon}$  and  $\gamma^C_{\epsilon}$  are defined as

$$\gamma_{\varepsilon}^{M} := \begin{cases} 1 & \text{in } \Omega \setminus \overline{\mathcal{B}_{\varepsilon}} \\ \gamma^{M} & \text{in } \mathcal{B}_{\varepsilon} \end{cases} \quad \text{and} \quad \gamma_{\varepsilon}^{C} := \begin{cases} 1 & \text{in } \Omega \setminus \overline{\mathcal{B}_{\varepsilon}} \\ \gamma^{C} & \text{in } \mathcal{B}_{\varepsilon} \end{cases}$$
 (24)

with  $\gamma^M$  and  $\gamma^C$  used to denote the values of the contrast on the Young modulus and thermal-expansion coefficient, respectively. In the perturbed configuration, the displacement field satisfies the variational problem: given the temperature field  $\theta_{\varepsilon}$ , find  $u_{\varepsilon} \in \mathcal{U}_{\varepsilon}^M$ , such that

$$\int_{\Omega} \sigma_{\varepsilon}(u_{\varepsilon}) \cdot \nabla \eta^{s} = \int_{\Omega} Q_{\varepsilon}(\theta_{\varepsilon}) \cdot \nabla \eta^{s} + \int_{\Gamma_{N...}} \bar{t} \cdot \eta \quad \forall \eta \in \mathcal{V}_{\varepsilon}^{M}.$$
 (25)

The set  $\mathcal{U}^{\rm M}_{\epsilon}$  and the space  $\mathcal{V}^{\rm M}_{\epsilon}$  in the variational problem (25) are defined as

$$\mathcal{U}_{\varepsilon}^{M} := \{ \phi \in \mathcal{U}^{M} : \llbracket \phi \rrbracket = 0 \text{ on } \partial \mathcal{B}_{\varepsilon} \}, \tag{26}$$

$$\mathcal{V}_{\varepsilon}^{\mathsf{M}} := \{ \phi \in \mathcal{V}^{\mathsf{M}} : \llbracket \phi \rrbracket = 0 \text{ on } \partial \mathcal{B}_{\varepsilon} \}, \tag{27}$$

where the operator  $[\![(\cdot)]\!]$  is introduced to denote the jump of  $(\cdot)$  across the boundary of the perturbation.

In addition, the thermal equilibrium problem can be written in the variational form as: find  $\theta_{\varepsilon} \in \mathcal{U}_{\varepsilon}^{T}$ , such that

$$\int_{\Omega} \mathbf{q}_{\varepsilon}(\theta_{\varepsilon}) \cdot \nabla \boldsymbol{\eta} = \int_{\Gamma_{N_{\varepsilon}}} \bar{\mathbf{q}} \boldsymbol{\eta} \quad \forall \boldsymbol{\eta} \in \mathcal{V}_{\varepsilon}^{\Gamma}, \tag{28}$$

with the thermal flux in the perturbed domain being defined as:

$$q_{\varepsilon}(\theta_{\varepsilon}) := -\gamma_{\varepsilon}^{T} K \nabla \theta_{\varepsilon}, \tag{29}$$

where  $\gamma_{\varepsilon}^{T}$  is the parameter that define the contrast between the thermal (constitutive) properties of the matrix and the inclusion, and is defined by:

$$\gamma_{\varepsilon}^{T} := \begin{cases} 1 & \text{in } \Omega \setminus \overline{\mathcal{B}_{\varepsilon}} \\ \gamma^{T} & \text{in } \mathcal{B}_{\varepsilon} \end{cases}, \tag{30}$$

being  $\gamma^T$  the value of the contrast on the thermal conductivity coefficient. In the variational problem (28) the set  $\mathcal{U}_{\varepsilon}^T$  and the space  $\mathcal{V}_{\varepsilon}^T$  are defined as:

$$\mathcal{U}_{\varepsilon}^{T} := \{ \phi \in \mathcal{U}^{T} : \llbracket \phi \rrbracket = 0 \text{ on } \partial \mathcal{B}_{\varepsilon} \}, \tag{31}$$

$$\mathcal{V}_{\varepsilon}^{\mathsf{T}} := \{ \phi \in \mathcal{V}^{\mathsf{T}} : \llbracket \phi \rrbracket = 0 \text{ on } \partial \mathcal{B}_{\varepsilon} \}. \tag{32}$$

Finally, the auxiliary problem associated to the topologically perturbed domain is written as: find  $\varphi_{\varepsilon} \in \mathcal{V}^{\mathsf{T}}_{\varepsilon}$ , such that:

$$\int_{\Omega} q_{\varepsilon}(\varphi_{\varepsilon}) \cdot \nabla \eta = \int_{\Omega} Q_{\varepsilon}(\eta) \cdot \nabla u^{s} \quad \forall \eta \in \mathcal{V}_{\varepsilon}^{T}, \tag{33}$$

where  $\varphi_{\varepsilon}$  can be interpreted as the adjoint state associated to the thermal stress induced by the perturbed temperature  $\theta_{\varepsilon}$  (see, for instance, Sokołowski and Zolésio, 1992).

# 3. Topological sensitivity analysis

In order to proceed, it is convenient to introduce an analogy to classical continuum mechanics (Gurtin, 1981) where by the shape change velocity field V is identified with the classical velocity field of a deforming continuum and  $\varepsilon$  is identified as a time parameter. Since we are dealing with an uniform expansion of the inclusion  $\mathcal{B}_{\varepsilon}$ , the shape velocity field V satisfies:  $V|_{\partial\Omega}=0$  and  $V|_{\partial\mathcal{B}_{\varepsilon}}=-n$ . Then, the shape derivative of the functional (21) can be written as:

$$\begin{split} \dot{\mathcal{J}}_{\chi_{\epsilon}}(u_{\epsilon},\theta_{\epsilon}) &= \left(\frac{1}{2}\int_{\Omega}\sigma_{\epsilon}(u_{\epsilon})\cdot\nabla u_{\epsilon}^{s} - \int_{\Omega}Q_{\epsilon}(\theta_{\epsilon})\cdot\nabla u_{\epsilon}^{s} - \int_{\Gamma_{N_{u}}}\bar{t}\cdot u_{\epsilon}\right) \\ &= \frac{1}{2}\left(\int_{\Omega}\sigma_{\epsilon}(u_{\epsilon})\cdot\nabla u_{\epsilon}^{s}\right) - \left(\int_{\Omega}Q_{\epsilon}(\theta_{\epsilon})\cdot\nabla u_{\epsilon}^{s}\right) - \int_{\Gamma_{N_{u}}}\bar{t}\cdot\dot{u}_{\epsilon}, \end{split}$$

$$(34)$$

1306

where we use both notations  $(\cdot)$  and  $(\cdot)$  to represent the total derivative with respect to the parameter  $\varepsilon$ . Therefore, we can state the following propositions:

**Proposition 1.** Let  $\mathcal{J}_{\chi_{\varepsilon}}(u_{\varepsilon}, \theta_{\varepsilon})$  be the functional defined by (21). Then, its derivative with respect to the small parameter  $\varepsilon$  is given by

$$\dot{\mathcal{J}}_{\chi_{\varepsilon}}(u_{\varepsilon},\theta_{\varepsilon}) = \int_{\Omega} \Sigma_{\varepsilon} \cdot \nabla V - \int_{\Omega} Q_{\varepsilon}(\dot{\theta}_{\varepsilon}) \cdot \nabla (u_{\varepsilon} - u)^{s}, \tag{35}$$

where V is the shape change velocity field defined in  $\Omega$  that satisfies  $V|_{\partial\Omega}=0$  and  $V|_{\partial\mathcal{B}_{\varepsilon}}=-n$ ;  $\dot{\theta}_{\varepsilon}$  is the material derivative of the temperature field and  $\Sigma_{\varepsilon}$  is a generalization of the classical Eshelby momentum-energy tensor (Eshelby, 1975), given – for this particular case – by

$$\Sigma_{\varepsilon} := \frac{1}{2} ((S_{\varepsilon}(u_{\varepsilon}, \theta_{\varepsilon}) - Q_{\varepsilon}(\theta_{\varepsilon})) \cdot \nabla u_{\varepsilon}^{s}) I - (\nabla u_{\varepsilon})^{\mathsf{T}} S_{\varepsilon}(u_{\varepsilon}, \theta_{\varepsilon}) + [(q_{\varepsilon}(\theta_{\varepsilon}) \cdot \nabla \varphi_{\varepsilon}) I - 2q_{\varepsilon}(\theta_{\varepsilon}) \otimes_{s} \nabla \varphi_{\varepsilon}],$$
(36)

with  $u_{\varepsilon}$ ,  $\theta_{\varepsilon}$  and  $\varphi_{\varepsilon}$  denoting the solutions to (25), (28) and to the auxiliary problem (33).

**Proof.** By making use of Reynolds' Transport Theorem (Gurtin, 1981; Sokołowski and Zolésio, 1992) we obtain the identities

$$\left(\int_{\Omega} \sigma_{\varepsilon}(u_{\varepsilon}) \cdot \nabla u_{\varepsilon}^{s}\right) = \int_{\Omega} (2\sigma_{\varepsilon}(u_{\varepsilon}) \cdot \nabla \dot{u}_{\varepsilon}^{s} - 2\sigma_{\varepsilon}(u_{\varepsilon}) \cdot (\nabla u_{\varepsilon} \nabla V)^{s} + \int_{\Omega} (\sigma_{\varepsilon}(u_{\varepsilon}) \cdot \nabla u_{\varepsilon}^{s}) \operatorname{div} V), \tag{37}$$

$$\begin{split} \left(\int_{\Omega} Q_{\epsilon}(\theta_{\epsilon}) \cdot \nabla u_{\epsilon}^{s}\right)^{\cdot} &= \int_{\Omega} (Q_{\epsilon}(\theta_{\epsilon}) \cdot \nabla \dot{u}_{\epsilon}^{s} - Q_{\epsilon}(\theta_{\epsilon}) \cdot (\nabla u_{\epsilon} \nabla V)^{s} \\ &+ \int_{\Omega} (Q_{\epsilon}(\theta_{\epsilon}) \cdot \nabla u_{\epsilon}^{s}) div V + Q_{\epsilon}(\dot{\theta}_{\epsilon}) \cdot \nabla u_{\epsilon}^{s}. \end{split} \tag{38}$$

Then, by considering the above results in (34), the shape derivative of the functional  $\mathcal{J}_{\gamma_e}(u_{\varepsilon}, \theta_{\varepsilon})$  is given by

$$\dot{\mathcal{J}}_{\chi_{\varepsilon}}(u_{\varepsilon}, \theta_{\varepsilon}) = \int_{\Omega} \left( \frac{1}{2} \left( \left( S_{\varepsilon}(u_{\varepsilon}, \theta_{\varepsilon}) - Q_{\varepsilon}(\theta_{\varepsilon}) \right) \cdot \nabla u_{\varepsilon}^{s} \right) I - (\nabla u_{\varepsilon})^{\top} S_{\varepsilon}(u_{\varepsilon}, \theta_{\varepsilon}) \right) \cdot \nabla V \\
- \int_{\Omega} Q_{\varepsilon}(\dot{\theta}_{\varepsilon}) \cdot \nabla u_{\varepsilon}^{s} + \int_{\Omega} S_{\varepsilon}(u_{\varepsilon}, \theta_{\varepsilon}) \cdot \nabla \dot{u}_{\varepsilon}^{s} - \int_{\Gamma_{V}} \bar{t} \cdot \dot{u}_{\varepsilon}. \tag{39}$$

Since  $\dot{u}_{\varepsilon} \in \mathcal{U}_{\varepsilon}^{M}$ , see the work made by Sokołowski and Zolésio (1992), the terms in  $\dot{u}_{\varepsilon}$  satisfy the state equation (25), then

$$\dot{\mathcal{J}}_{\chi_{\varepsilon}}(u_{\varepsilon}, \theta_{\varepsilon}) = \int_{\Omega} \left( \frac{1}{2} ((S_{\varepsilon}(u_{\varepsilon}, \theta_{\varepsilon}) - Q_{\varepsilon}(\theta_{\varepsilon})) \cdot \nabla u_{\varepsilon}^{s}) I - (\nabla u_{\varepsilon})^{\mathsf{T}} S_{\varepsilon}(u_{\varepsilon}, \theta_{\varepsilon}) \right) \cdot \nabla V \\
- \int_{\Omega} Q_{\varepsilon}(\dot{\theta}_{\varepsilon}) \cdot \nabla u_{\varepsilon}^{s}. \tag{40}$$

Now, adding the term  $\pm \int_\Omega Q_\varepsilon(\theta_\varepsilon)\cdot \nabla u^s$  in the above result, the derivative  $\mathcal{J}_{\chi_\varepsilon}(u_\varepsilon,\theta_\varepsilon)$  can be written alternatively as

$$\dot{\mathcal{J}}_{\chi_{\varepsilon}}(u_{\varepsilon}, \theta_{\varepsilon}) = \int_{\Omega} \left( \frac{1}{2} \left( \left( S_{\varepsilon}(u_{\varepsilon}, \theta_{\varepsilon}) - Q_{\varepsilon}(\theta_{\varepsilon}) \right) \cdot \nabla u_{\varepsilon}^{s} \right) I - \left( \nabla u_{\varepsilon} \right)^{\top} S_{\varepsilon}(u_{\varepsilon}, \theta_{\varepsilon}) \right) \cdot \nabla V \\
- \int_{\Omega} Q_{\varepsilon}(\dot{\theta}_{\varepsilon}) \cdot \nabla (u_{\varepsilon} - u)^{s} - \int_{\Omega} Q_{\varepsilon}(\dot{\theta}_{\varepsilon}) \cdot \nabla u^{s}. \tag{41}$$

On the other hand, the derivative of the state equation (28) with respect to the parameter  $\varepsilon$  is given by

$$\int_{\Omega} q_{\epsilon}(\dot{\theta}_{\epsilon}) \cdot \nabla \eta = -\int_{\Omega} [(q_{\epsilon}(\theta_{\epsilon}) \cdot \nabla \eta)I - 2q_{\epsilon}(\theta_{\epsilon}) \otimes_{s} \nabla \eta] \cdot \nabla V \quad \forall \eta \in \mathcal{V}_{\epsilon}^{T}.$$
(42)

Next, taking  $\eta = \varphi_{\varepsilon}$  in the above expression, we obtain

$$\int_{\Omega} q_{\varepsilon}(\dot{\theta}_{\varepsilon}) \cdot \nabla \varphi_{\varepsilon} = -\int_{\Omega} [(q_{\varepsilon}(\theta_{\varepsilon}) \cdot \nabla \varphi_{\varepsilon})I - 2q_{\varepsilon}(\theta_{\varepsilon}) \otimes_{s} \nabla \varphi_{\varepsilon}] \cdot \nabla V, \quad (43)$$

and tacking  $\eta=\dot{\theta}_{\epsilon}$  in the auxiliary problem (33), we obtain

$$\int_{\Omega} \mathbf{q}_{\varepsilon}(\varphi_{\varepsilon}) \cdot \nabla \dot{\theta}_{\varepsilon} = \int_{\Omega} \mathbf{Q}_{\varepsilon}(\dot{\theta}_{\varepsilon}) \cdot \nabla u^{s}. \tag{44}$$

By using the definition of the heat flux operator (29) and comparing the two last expressions, the following identity holds

$$\int_{\Omega} Q_{\varepsilon}(\dot{\theta}_{\varepsilon}) \cdot \nabla u^{s} = -\int_{\Omega} [(q_{\varepsilon}(\theta_{\varepsilon}) \cdot \nabla \varphi_{\varepsilon})I - 2q_{\varepsilon}(\theta_{\varepsilon}) \otimes_{s} \nabla \varphi_{\varepsilon}] \cdot \nabla V. \quad (45)$$

From the above result, the derivative of the shape functional  $\mathcal{J}_{\chi_{\epsilon}}(u_{\epsilon}, \theta_{\epsilon})$  can be written equivalently in the following form:

$$\dot{\mathcal{J}}_{\chi_{\varepsilon}}(u_{\varepsilon}, \theta_{\varepsilon}) = \int_{\Omega} \left( \frac{1}{2} ((S_{\varepsilon}(u_{\varepsilon}, \theta_{\varepsilon}) - Q_{\varepsilon}(\theta_{\varepsilon})) \cdot \nabla u_{\varepsilon}^{s}) I - (\nabla u_{\varepsilon})^{\mathsf{T}} S_{\varepsilon}(u_{\varepsilon}, \theta_{\varepsilon}) \right) \cdot \nabla V 
+ \int_{\Omega} [(q_{\varepsilon}(\theta_{\varepsilon}) \cdot \nabla \varphi_{\varepsilon}) I - 2q_{\varepsilon}(\theta_{\varepsilon}) \otimes_{s} \nabla \varphi_{\varepsilon}] \cdot \nabla V 
- \int_{\Omega} Q_{\varepsilon}(\dot{\theta}_{\varepsilon}) \cdot \nabla (u_{\varepsilon} - u)^{s},$$
(46)

which leads to the result with  $\Sigma_{\varepsilon}$  given by (36).  $\square$ 

**Proposition 2.** Let  $\mathcal{J}_{\chi_{\varepsilon}}(u_{\varepsilon}, \theta_{\varepsilon})$  be the functional defined by (21). Then, its derivative with respect to the small parameter  $\varepsilon$  is given by

$$\dot{\mathcal{J}}_{\chi_{\varepsilon}}(\mathbf{u}_{\varepsilon}, \theta_{\varepsilon}) = -\int_{\partial \mathcal{B}_{\varepsilon}} \mathbb{I} \Sigma_{\varepsilon} \mathbb{I} \mathbf{n} \cdot \mathbf{n} - \int_{\Omega} Q_{\varepsilon}(\theta_{\varepsilon}') \cdot \nabla (\mathbf{u}_{\varepsilon} - \mathbf{u})^{s}, \tag{47}$$

where  $\theta'_{\epsilon}$  is the spatial derivative of the temperature field and  $\Sigma_{\epsilon}$  is a generalization of the classical Eshelby momentum-energy tensor presented in (36).

**Proof.** By making use of the Reynolds' Transport Theorem (Gurtin, 1981; Sokołowski and Zolésio, 1992), we obtain the following identities:

$$\begin{split} \left(\int_{\Omega} \sigma_{\epsilon}(u_{\epsilon}) \cdot \nabla u_{\epsilon}^{s}\right)^{\cdot} &= \int_{\Omega} 2(\sigma_{\epsilon}(u_{\epsilon}) \cdot \nabla \dot{u}_{\epsilon}^{s} + \operatorname{div}(\sigma_{\epsilon}(u_{\epsilon})) \cdot (\nabla u_{\epsilon})V) \\ &+ \int_{\partial \Omega} \left[ (\sigma_{\epsilon}(u_{\epsilon}) \cdot \nabla u_{\epsilon}^{s})I - 2(\nabla u_{\epsilon})^{\top} \sigma_{\epsilon}(u_{\epsilon}) \right] n \cdot V \\ &+ \int_{\partial \mathcal{B}_{\epsilon}} \mathbb{I}(\sigma_{\epsilon}(u_{\epsilon}) \cdot \nabla u_{\epsilon}^{s})I - 2(\nabla u_{\epsilon})^{\top} \sigma_{\epsilon}(u_{\epsilon}) \mathbb{I} n \cdot V, \end{split}$$

$$(48)$$

$$\begin{split} \left(\int_{\Omega} Q_{\epsilon}(\theta_{\epsilon}) \cdot \nabla u_{\epsilon}^{s}\right) &= \int_{\Omega} (Q_{\epsilon}(\theta_{\epsilon}) \cdot \nabla \dot{u}_{\epsilon}^{s} + Q_{\epsilon}(\theta_{\epsilon}') \cdot \nabla u_{\epsilon}^{s}) \\ &+ \int_{\Omega} \operatorname{div}(Q_{\epsilon}(\theta_{\epsilon})) \cdot (\nabla u_{\epsilon}) V \\ &- \int_{\partial \Omega} \left[ (\nabla u_{\epsilon})^{\top} Q_{\epsilon}(\theta_{\epsilon}) - (Q_{\epsilon}(\theta_{\epsilon}) \cdot \nabla u_{\epsilon}^{s}) I \right] n \cdot V \\ &- \int_{\partial \mathcal{B}_{\epsilon}} \left[ (\nabla u_{\epsilon})^{\top} Q_{\epsilon}(\theta_{\epsilon}) - (Q_{\epsilon}(\theta_{\epsilon}) \cdot \nabla u_{\epsilon}^{s}) I \right] n \cdot V. \end{split}$$

$$(49)$$

Introducing the above expressions in the definitions of the shape derivative (34) and taking into account that: (i)  $\dot{u}_{\varepsilon} \in \mathcal{U}_{\varepsilon}^{M}$ , see the work made by Sokołowski and Zolésio (1992), the terms in  $\dot{u}_{\varepsilon}$  satisfy the state equation (25); (ii)  $\operatorname{div} S_{\varepsilon}(u_{\varepsilon},\theta_{\varepsilon})=0$  in  $\Omega$ ; (iii) adding the term  $\pm \int_{\Omega} Q_{\varepsilon}(\theta_{\varepsilon}') \cdot \nabla u^{s}$ ; and (iv) the shape change velocity field V defined in  $\Omega$  satisfies  $V|_{\partial\Omega}=0$  and  $V|_{\partial\mathcal{B}_{\varepsilon}}=-n$ ; then

$$\begin{split} \dot{\mathcal{J}}_{\chi_{\varepsilon}}(u_{\varepsilon},\theta_{\varepsilon}) &= -\int_{\partial \mathcal{B}_{\varepsilon}} \mathbb{I}\frac{1}{2}((S_{\varepsilon}(u_{\varepsilon},\theta_{\varepsilon}) - Q_{\varepsilon}(\theta_{\varepsilon})) \cdot \nabla u_{\varepsilon}^{s})I \\ &- (\nabla u_{\varepsilon})^{\top} S_{\varepsilon}(u_{\varepsilon},\theta_{\varepsilon}) \mathbf{n} \cdot \mathbf{n} - \int_{\Omega} Q_{\varepsilon}(\theta_{\varepsilon}') \cdot \nabla (u_{\varepsilon} - u)^{s} \\ &- \int_{\Omega} Q_{\varepsilon}(\theta_{\varepsilon}') \cdot \nabla u^{s}. \end{split} \tag{50}$$

By using the relation between the material and spatial derivatives of the temperature field, the above expression can be written as,

$$\dot{\mathcal{J}}_{\chi_{\varepsilon}}(u_{\varepsilon}, \theta_{\varepsilon}) = -\int_{\partial \mathcal{B}_{\varepsilon}} \mathbb{I} \frac{1}{2} ((S_{\varepsilon}(u_{\varepsilon}, \theta_{\varepsilon}) - Q_{\varepsilon}(\theta_{\varepsilon})) \cdot \nabla u_{\varepsilon}^{s}) I 
- (\nabla u_{\varepsilon})^{\top} S_{\varepsilon}(u_{\varepsilon}, \theta_{\varepsilon}) \mathbb{I} n \cdot n - \int_{\Omega} Q_{\varepsilon}(\theta_{\varepsilon}') \cdot \nabla (u_{\varepsilon} - u)^{s} 
- \int_{\Omega} Q_{\varepsilon}(\dot{\theta}_{\varepsilon}) \cdot \nabla u^{s} + \int_{\Omega} Q_{\varepsilon}(\nabla \theta_{\varepsilon} \cdot n) \cdot \nabla u^{s}.$$
(51)

On the other hand, the derivative of the state equation (28) with respect to parameter  $\varepsilon$  is given by

$$\int_{\Omega} q_{\varepsilon}(\dot{\theta}_{\varepsilon}) \cdot \nabla \eta = -\int_{\Omega} [(q_{\varepsilon}(\theta_{\varepsilon}) \cdot \nabla \eta)I - 2q_{\varepsilon}(\theta_{\varepsilon}) \otimes_{s} \nabla \eta] \cdot \nabla V \,\forall \, \eta \in \mathcal{V}_{\varepsilon}^{T}.$$
(52)

Next, tacking  $\eta = \varphi_{\varepsilon}$  in the above expression, we obtain

$$\int_{\Omega} q_{\varepsilon}(\dot{\theta}_{\varepsilon}) \cdot \nabla \varphi_{\varepsilon} = -\int_{\Omega} [(q_{\varepsilon}(\theta_{\varepsilon}) \cdot \nabla \varphi_{\varepsilon})I - 2q_{\varepsilon}(\theta_{\varepsilon}) \otimes_{s} \nabla \varphi_{\varepsilon}] \cdot \nabla V, \quad (53)$$

and tacking  $\eta = \dot{\theta}_{\varepsilon}$  in the auxiliary problem (33), we obtain

$$\int_{\Omega} q_{\varepsilon}(\varphi_{\varepsilon}) \cdot \nabla \dot{\theta}_{\varepsilon} = \int_{\Omega} Q_{\varepsilon}(\dot{\theta}_{\varepsilon}) \cdot \nabla u^{s}. \tag{54}$$

By using the definition of the heat flux operator (29) and comparing the two last expressions, the following identity holds

$$\int_{\Omega} Q_{\varepsilon}(\dot{\theta}_{\varepsilon}) \cdot \nabla u^{s} = -\int_{\Omega} [(q_{\varepsilon}(\theta_{\varepsilon}) \cdot \nabla \varphi_{\varepsilon})I - 2q_{\varepsilon}(\theta_{\varepsilon}) \otimes_{s} \nabla \varphi_{\varepsilon}] \cdot \nabla V. \quad (55)$$

From the above result, the derivative of the shape functional  $\mathcal{J}_{\gamma_{\varepsilon}}(u_{\varepsilon},\theta_{\varepsilon})$  can be written equivalently in the following form,

$$\dot{\mathcal{J}}_{\chi_{\varepsilon}}(u_{\varepsilon}, \theta_{\varepsilon}) = -\int_{\partial \mathcal{B}_{\varepsilon}} \left[ \frac{1}{2} ((S_{\varepsilon}(u_{\varepsilon}, \theta_{\varepsilon}) - Q_{\varepsilon}(\theta_{\varepsilon})) \cdot \nabla u_{\varepsilon}^{s}) I \right] \\
- (\nabla u_{\varepsilon})^{\top} S_{\varepsilon}(u_{\varepsilon}, \theta_{\varepsilon}) \left[ n \cdot n + \int_{\Omega} \left[ (q_{\varepsilon}(\theta_{\varepsilon}) \cdot \nabla \varphi_{\varepsilon}) I \right] \\
- 2q_{\varepsilon}(\theta_{\varepsilon}) \otimes_{s} \nabla \varphi_{\varepsilon} \right] \cdot \nabla V - \int_{\Omega} Q_{\varepsilon}(\theta_{\varepsilon}') \cdot \nabla (u_{\varepsilon} - u)^{s} \\
+ \int_{\Omega} Q_{\varepsilon}(\nabla \theta_{\varepsilon} \cdot n) \cdot \nabla u^{s}. \tag{56}$$

By integrating by parts the second term in the above expression and using the definition of the Eshelby's tensor  $\Sigma_{\epsilon}$ , we have

$$\begin{split} \dot{\mathcal{J}}_{\chi_{\varepsilon}}(u_{\varepsilon},\theta_{\varepsilon}) &= -\int_{\partial\mathcal{B}_{\varepsilon}} \mathbb{E} \Sigma_{\varepsilon} \mathbf{n} \cdot \mathbf{n} - \int_{\Omega} Q_{\varepsilon}(\theta_{\varepsilon}') \cdot \nabla (u_{\varepsilon} - u)^{s} \\ &- \int_{\Omega} \operatorname{div}[(q_{\varepsilon}(\theta_{\varepsilon}) \cdot \nabla \varphi_{\varepsilon})I - 2q_{\varepsilon}(\theta_{\varepsilon}) \otimes_{s} \nabla \varphi_{\varepsilon}] \cdot V \\ &+ \int_{\Omega} Q_{\varepsilon}(\nabla \theta_{\varepsilon} \cdot V) \cdot \nabla u^{s}. \end{split} \tag{57}$$

Taking into account the state equation (28) and the auxiliary problem (33), we observe that the second term in the above expression satisfies the following identity

$$\int_{\Omega} \operatorname{div}[(q_{\varepsilon}(\theta_{\varepsilon}) \cdot \nabla \varphi \varepsilon) I - 2q_{\varepsilon}(\theta_{\varepsilon}) \otimes_{s} \nabla \varphi_{\varepsilon}] \cdot V = \int_{\Omega} Q_{\varepsilon}(\nabla \theta_{\varepsilon} \cdot V) \cdot \nabla u^{s}. \tag{58}$$

Then, the lats two terms in (57) vanish, leading to the result.  $\Box$ 

**Corollary 1.** By considering the relation between the material and spatial derivative of the temperature field, (35) can be written as:

$$\dot{\mathcal{J}}_{\chi_{\varepsilon}}(u_{\varepsilon}, \theta_{\varepsilon}) = \int_{\Omega} \Sigma_{\varepsilon} \cdot \nabla V - \int_{\Omega} Q_{\varepsilon}(\theta_{\varepsilon}') \cdot \nabla (u_{\varepsilon} - u)^{s} \\
- \int_{\Omega} Q_{\varepsilon}(\nabla \theta_{\varepsilon} \cdot V) \cdot \nabla (u_{\varepsilon} - u)^{s}.$$
(59)

By integrating by part the first term of the above expression and using the restriction of the velocity field V on the boundaries  $\partial\Omega$  and  $\partial\mathcal{B}_{\epsilon}$ , we

$$\dot{\mathcal{J}}_{\chi_{\varepsilon}}(u_{\varepsilon}, \theta_{\varepsilon}) = -\int_{\partial \mathcal{B}_{\varepsilon}} \llbracket \Sigma_{\varepsilon} \rrbracket n \cdot n - \int_{\Omega} \operatorname{div} \Sigma_{\varepsilon} \cdot V - \int_{\Omega} Q_{\varepsilon}(\theta_{\varepsilon}') \cdot \nabla (u_{\varepsilon} - u)^{s} \\
- \int_{\Omega} Q_{\varepsilon} (\nabla \theta_{\varepsilon} \cdot V) \cdot \nabla (u_{\varepsilon} - u)^{s}.$$
(60)

By comparing (47) with (60) and recalling that both identities are valid for all  $V \in \Omega$ , the follow result holds true

$$\int_{\Omega} (\operatorname{div}(\Sigma_{\varepsilon}) + \gamma_{\varepsilon}^{\mathsf{M}} \gamma_{\varepsilon}^{\mathsf{C}} (\mathbb{C}B \cdot \nabla (u_{\varepsilon} - u)^{\mathsf{s}}) \nabla \theta_{\varepsilon}) \cdot V = 0 \quad \forall V \in \Omega, \tag{61}$$

Thus, the equation for the balance of the configurational forces (Gurtin, 2000) can be written as:

$$\operatorname{div}(\Sigma_{\varepsilon}) = -\gamma_{\varepsilon}^{\mathsf{M}} \gamma_{\varepsilon}^{\mathsf{C}} (\mathbb{C}B \cdot \nabla (u_{\varepsilon} - u)^{\mathsf{S}}) \nabla \theta_{\varepsilon} \quad \text{in } \Omega.$$
 (62)

 $\begin{aligned} \text{div}(\Sigma_{\varepsilon}) &= -\gamma_{\varepsilon}^{M} \gamma_{\varepsilon}^{C} (\mathbb{C}B \cdot \nabla (u_{\varepsilon} - u)^{s}) \nabla \theta_{\varepsilon} \quad \text{in } \Omega. \end{aligned} \tag{62}$  Note that the first term of the derivative  $\mathcal{J}_{\chi_{\varepsilon}}(u_{\varepsilon}, \theta_{\varepsilon})$  in (47) is given by an integral concentrated on  $\partial \mathcal{B}_\epsilon$  depending on the solution to (25), (28) and (33). The second term, given by a integral over all domain  $\Omega$ , will be treated carefully (see Appendix A).

To analytically solve the integrals expression of the derivative  $\dot{\mathcal{J}}_{\gamma_{\varepsilon}}(u_{\varepsilon},\theta_{\varepsilon})$  it is necessary to perform an asymptotic analysis of the solutions of the PDE's involved in these coupled problems. In order to simplify the analysis, let us use the linearity property of the shape functional with respect to the solution of the thermal problem (28) and split the analysis in two cases: (i)  $\gamma^T = 1$  and (ii)  $\gamma^M = \gamma^C = 1$ .

3.1. *Case* 
$$\gamma^{T} = 1$$

For this particular case,  $\gamma^T = 1$ , we have that the temperature field is not perturbed by the presence of the inclusion  $\mathcal{B}_{\epsilon}$  in the mechanical problem. Then, the temperature for the unperturbed and perturbed problems coincides, i.e.  $\theta_{\varepsilon} = \theta$ . Thus, the derivative of the shape functional can be written as:

$$\dot{\mathcal{J}}_{\chi_{\varepsilon}}(u_{\varepsilon},\theta) = -\int_{\partial \mathcal{B}_{\varepsilon}} \llbracket \Sigma_{\varepsilon} \rrbracket n \cdot n = -\int_{\partial \mathcal{B}_{\varepsilon}} \llbracket \frac{1}{2} ((S_{\varepsilon}(u_{\varepsilon},\theta) - Q_{\varepsilon}(\theta)) \cdot \nabla u_{\varepsilon}^{s}) I 
- (\nabla u_{\varepsilon})^{\top} S_{\varepsilon}(u_{\varepsilon},\theta) \rrbracket n \cdot n.$$
(63)

In order to obtain an explicit expression for the perturbed stress field, we consider the following ansatz for the displacement field

$$u_{\varepsilon}(x) = u(x) + w_{\varepsilon}(x/\varepsilon) + \tilde{u}_{\varepsilon}(x),$$
 (64)

where u(x) is the solution of the unperturbed problem in  $\Omega$ ,  $w_{\varepsilon}(x/\varepsilon)$ the solution to an exterior perturbed problem in  $\mathbb{R}^2$  and  $\tilde{u}_{\varepsilon}(x)$  the remainder, solution to a perturbed problem in  $\Omega$ . The terms in the above expansion requires additional explanation. The function  $w_{\varepsilon}(x/\varepsilon)$  decays to zero at the infinity, i.e.,  $w_{\varepsilon} \to 0$  at  $\infty$ , and compensates the discrepancy introduced by the lower order term of the Taylor series expansion of u around  $\hat{x}$ . The remainder  $\tilde{u}_{\varepsilon}(x)$  is introduced to compensate the discrepancies left by  $w_{\varepsilon}$  on the exterior boundary  $\partial\Omega$  as well as by the higher order term of the Taylor series expansion of u in the neighborhood of  $\mathcal{B}_{\varepsilon}(\hat{x})$ . Then, the mechanical stress satisfies the identity

$$\sigma_{\varepsilon}(u_{\varepsilon}) = \gamma_{\varepsilon}^{\mathsf{M}} \mathbb{C} \nabla u^{\mathsf{s}} + \gamma_{\varepsilon}^{\mathsf{M}} \mathbb{C} \nabla w_{\varepsilon}^{\mathsf{s}} + \gamma_{\varepsilon}^{\mathsf{M}} \mathbb{C} \nabla \tilde{u}_{\varepsilon}^{\mathsf{s}}. \tag{65}$$

Moreover, by introducing the term  $-Q_{\varepsilon}(\theta)$  at both sides of the above expression, the stress field associated to the perturbed domain  $S_{\varepsilon}(u_{\varepsilon},\theta)$  admits the following asymptotic expansion

$$S_{\varepsilon}(u_{\varepsilon},\theta) = \gamma_{\varepsilon}^{\mathsf{M}} \sigma(u) + \sigma_{\varepsilon}(w_{\varepsilon}) + \sigma_{\varepsilon}(\tilde{u}_{\varepsilon}) - \gamma_{\varepsilon}^{\mathsf{M}} \gamma_{\varepsilon}^{\mathsf{C}} Q(\theta), \tag{66}$$

where  $\sigma_{\varepsilon}(w_{\varepsilon})$  is the solution of the exterior problem

S.M. Giusti et al./International Journal of Solids and Structures 50 (2013) 1303-1313

$$\begin{cases} \operatorname{div}(\sigma_{\varepsilon}(w_{\varepsilon})) = 0 & \text{in } \mathbb{R}^{2} \\ \sigma_{\varepsilon}(w_{\varepsilon}) = \gamma_{\varepsilon}^{M} \mathbb{C} \nabla w_{\varepsilon}^{s} \\ \sigma_{\varepsilon}(w_{\varepsilon}) \to 0 & \text{at } \infty \\ \mathbb{I} \sigma_{\varepsilon}(w_{\varepsilon}) \mathbb{I} n = -s_{u} & \text{on } \partial \mathcal{B}_{\varepsilon} \end{cases}$$

$$(67)$$

and the residue  $\tilde{u}_{\varepsilon}$  satisfies the equation

$$\begin{cases} \operatorname{div}(\sigma_{\varepsilon}(\tilde{u}_{\varepsilon})) = 0 & \text{in } \Omega \setminus \overline{\mathcal{B}_{\varepsilon}} \\ \operatorname{div}(\sigma_{\varepsilon}(\tilde{u}_{\varepsilon})) = (1 - \gamma^{C}) \gamma^{M} \mathbb{C} B \nabla \theta & \text{in } \mathcal{B}_{\varepsilon} \\ \sigma_{\varepsilon}(\tilde{u}_{\varepsilon}) = \gamma_{\varepsilon}^{M} \mathbb{C} \nabla \tilde{u}_{\varepsilon}^{s} \\ \tilde{u}_{\varepsilon} = -w_{\varepsilon} & \text{on } \partial \Gamma_{D_{u}} \\ \sigma_{\varepsilon}(\tilde{u}_{\varepsilon}) n = -\sigma_{\varepsilon}(w_{\varepsilon}) n & \text{on } \partial \Gamma_{N_{u}} \\ \|\sigma_{\varepsilon}(\tilde{u}_{\varepsilon})\| n = \varepsilon h_{u} & \text{on } \partial \mathcal{B}_{\varepsilon} \end{cases}$$

$$(68)$$

which has the following estimate  $\|\tilde{u}_{\varepsilon}\|_{H^{1}(\Omega;\mathbb{R}^{2})} = o(\varepsilon)$  (see Appendix A). Moreover, the functions  $s_{u}$  and  $h_{u}$  in (67) and (68), respectively, are given by

$$s_u := (1 - \gamma^M) \sigma(u(\hat{x})) n - (1 - \gamma^M \gamma^C) Q(\theta(\hat{x})) n, \tag{69}$$

$$h_u := (1 - \gamma^M)(\nabla \sigma(u(\zeta))n)n - (1 - \gamma^M \gamma^C)(\nabla Q(\theta(\zeta))n)n, \tag{70}$$

where the points  $\zeta$  and  $\xi$  belong to the interval  $(x, \hat{x})$ .

By considering a polar system of coordinates  $(r,\phi)$  centered at point  $\hat{x}$  (center of the inclusion  $\mathcal{B}_{\varepsilon}$ ) and aligned with the principal directions of the tensor  $S(u,\theta)$  associated to the original domain  $\Omega$ , the components of the tensor  $\sigma_{\varepsilon}(w_{\varepsilon})$  are given by (see, for instance, Little, 1973):

• Exterior solution  $(r \ge \varepsilon)$ 

$$\begin{split} \sigma_{\varepsilon}(w_{\varepsilon})^{rr} &= -\frac{1 - \gamma^{M}}{1 + a\gamma^{M}} \frac{\varepsilon^{2}}{r^{2}} \left( \frac{\sigma_{1} + \sigma_{2}}{2} \right) \\ &- \frac{1 - \gamma^{M}}{1 + b\gamma^{M}} \frac{\varepsilon^{2}}{r^{2}} \left( 4 - 3 \frac{\varepsilon^{2}}{r^{2}} \right) \left( \frac{\sigma_{1} - \sigma_{2}}{2} \right) \cos 2\phi \\ &+ \frac{1 - \gamma^{M} \gamma^{C}}{1 + a\gamma^{M}} \frac{\varepsilon^{2}}{r^{2}} \left( \frac{Q_{1} + Q_{2}}{2} \right), \end{split} \tag{71}$$

$$\begin{split} \sigma_{\varepsilon}(w_{\varepsilon})^{\phi\phi} &= \frac{1 - \gamma^{M}}{1 + a\gamma^{M}} \frac{\varepsilon^{2}}{r^{2}} \left(\frac{\sigma_{1} + \sigma_{2}}{2}\right) - 3\frac{1 - \gamma^{M}}{1 + b\gamma^{M}} \frac{\varepsilon^{4}}{r^{4}} \left(\frac{\sigma_{1} - \sigma_{2}}{2}\right) \cos 2\phi \\ &- \frac{1 - \gamma^{M}\gamma^{C}}{1 + a\gamma^{M}} \frac{\varepsilon^{2}}{r^{2}} \left(\frac{Q_{1} + Q_{2}}{2}\right), \end{split} \tag{72}$$

$$\sigma_{\varepsilon}(w_{\varepsilon})^{\phi r} = -\frac{1 - \gamma^{M}}{1 + h \gamma^{M}} \frac{\varepsilon^{2}}{r^{2}} \left(2 - 3\frac{\varepsilon^{2}}{r^{2}}\right) \left(\frac{\sigma_{1} - \sigma_{2}}{2}\right) \sin 2\phi. \tag{73}$$

• Interior solution (0 < r <  $\varepsilon$ )

$$\sigma_{\varepsilon}(w_{\varepsilon})^{rr} = \frac{a\gamma^{M}(1-\gamma^{M})}{1+a\gamma^{M}} \left(\frac{\sigma_{1}+\sigma_{2}}{2}\right)$$

$$+ \frac{b\gamma^{M}(1-\gamma^{M})}{1+b\gamma^{M}} \left(\frac{\sigma_{1}-\sigma_{2}}{2}\right) \cos 2\phi$$

$$- \frac{a\gamma^{M}(1-\gamma^{M}\gamma^{C})}{1+a\gamma^{M}} \left(\frac{Q_{1}+Q_{2}}{2}\right), \tag{74}$$

$$\begin{split} \sigma_{\varepsilon}(w_{\varepsilon})^{\phi\phi} &= \frac{a\gamma^{M}(1-\gamma^{M})}{1+a\gamma^{M}} \left(\frac{\sigma_{1}+\sigma_{2}}{2}\right) \\ &- \frac{b\gamma^{M}(1-\gamma^{M})}{1+b\gamma^{M}} \left(\frac{\sigma_{1}-\sigma_{2}}{2}\right) \cos 2\phi \\ &- \frac{a\gamma^{M}(1-\gamma^{M}\gamma^{C})}{1+a\gamma^{M}} \left(\frac{Q_{1}+Q_{2}}{2}\right), \end{split} \tag{75}$$

$$\sigma_{\varepsilon}(w_{\varepsilon})^{\phi r} = -\frac{b\gamma^{M}(1-\gamma^{M})}{1+b\gamma^{M}} \left(\frac{\sigma_{1}-\sigma_{2}}{2}\right) \sin 2\phi. \tag{76}$$

where  $\sigma_{1,2}$  and  $Q_{1,2}$  are, respectively, the principal stress associated to the tensor  $\sigma(u)$  and  $Q(\theta)$  of the unperturbed domain  $\Omega$ , evaluated at the point  $\hat{x} \in \Omega$ . In addition, the constants a and b in (71)–(76) depend only on Poisson's ratio v of the matrix, and are given by

$$a = \frac{1+v}{1-v}$$
 and  $b = \frac{3-v}{1+v}$ . (77)

Finally, using the asymptotic expansions presented in (71)–(76), we have that the derivative  $\dot{\mathcal{J}}_{\chi_E}$  is given by the following expression:

$$\dot{\mathcal{J}}_{\chi_{\varepsilon}}(u_{\varepsilon},\theta) = -\frac{\pi\varepsilon}{E} \left( \frac{1 - \gamma^{M}}{1 + b\gamma^{M}} \right) \left[ 4\sigma(u) \cdot \sigma(u) + \frac{\gamma^{M}(b - 2a) - 1}{1 + a\gamma^{M}} (\operatorname{tr}\sigma(u))^{2} \right] \\
- \frac{\pi\varepsilon}{2E} \left( \frac{1 - \gamma^{M}\gamma^{C}}{1 + a\gamma^{M}} \right) \left[ (1 - \gamma^{M}\gamma^{C})(1 + \nu) (\operatorname{tr}Q(\theta))^{2} \right] \\
- 4\operatorname{tr}\sigma(u) \operatorname{tr}Q(\theta) + o(\varepsilon), \tag{78}$$

where  $tr(\cdot)$  denotes the trace operator of tensor  $(\cdot)$ .

3.2. Case 
$$\gamma^M = 1$$
 and  $\gamma^C = 1$ 

In this case the restriction  $\gamma^M=1$  and  $\gamma^C=1$  is introduced in expression (47), then the derivative of the shape functional  $\mathcal{J}_{\chi_{\epsilon}}(u_{\epsilon},\theta_{\epsilon})$  is given by:

$$\dot{\mathcal{J}}_{\chi_{\varepsilon}}(u_{\varepsilon},\theta_{\varepsilon}) = \int_{\partial \mathbb{B}} \mathbb{I}(q_{\varepsilon}(\theta_{\varepsilon}) \cdot \nabla \varphi_{\varepsilon}) I - 2q_{\varepsilon}(\theta_{\varepsilon}) \otimes_{s} \nabla \varphi_{\varepsilon} \mathbb{I} n \cdot n + \mathcal{E}(\varepsilon), \tag{79}$$

where the term  $\mathcal{E}(\varepsilon)$  is given by

$$\mathcal{E}(\varepsilon) = -\int_{\Omega} Q_{\varepsilon}(\theta_{\varepsilon}') \cdot \nabla (u_{\varepsilon} - u)^{s}. \tag{80}$$

The temperature field  $\theta_{\varepsilon}$  associated to the perturbed problem admits the following asymptotic expansion:

$$\theta_{\varepsilon}(\mathbf{x}) = \theta(\mathbf{x}) + \nu_{\varepsilon}(\mathbf{x}/\varepsilon) + \widetilde{\theta}_{\varepsilon}(\mathbf{x}), \tag{81}$$

where  $\theta(x)$  is the solution of the unperturbed problem in  $\Omega$ ,  $\nu_{\varepsilon}(x/\varepsilon)$  the solution to an exterior perturbed problem in  $\mathbb{R}^2$  and  $\widetilde{\theta}_{\varepsilon}(x)$  the remainder, solution to a perturbed problem in  $\Omega$ . The function  $\nu_{\varepsilon}(x/\varepsilon)$  is such that  $\nu_{\varepsilon} \to 0$  at  $\infty$  and it compensates the discrepancy left by the lower order term of the Taylor series expansion of  $\theta$  in the neighborhood of  $\hat{x}$ . The remainder  $\widetilde{\theta}_{\varepsilon}(x)$  compensates the discrepancies introduced by  $\nu_{\varepsilon}$  on the exterior boundary  $\partial\Omega$  and by the higher order term of the Taylor series expansion of  $\theta$  around  $\mathcal{B}_{\varepsilon}(\hat{x})$ . In particular,  $\nu_{\varepsilon}$  is the solution of the exterior problem

$$\begin{cases} \operatorname{div}(q_{\varepsilon}(v_{\varepsilon})) = 0 & \text{in } \mathbb{R}^{2} \\ q_{\varepsilon}(v_{\varepsilon}) = -\gamma_{\varepsilon}^{T} K \nabla v_{\varepsilon} \\ v_{\varepsilon} \to 0 & \text{at } \infty \\ \llbracket v_{\varepsilon} \rrbracket = 0 & \text{on } \partial \mathcal{B}_{\varepsilon} \\ \llbracket q_{\varepsilon}(v_{\varepsilon}) \rrbracket \cdot n = -(1 - \gamma^{T}) \nabla \theta(\hat{\mathbf{x}}) \cdot n & \text{on } \partial \mathcal{B}_{\varepsilon} \end{cases}$$
(82)

and the remainder  $\tilde{\theta}_{\varepsilon}$  must be satisfies the following equation:

$$\begin{cases} \operatorname{div}(q_{\varepsilon}(\widetilde{\theta}_{\varepsilon})) = 0 & \text{in } \Omega \\ q_{\varepsilon}(\widetilde{\theta}_{\varepsilon}) = -\gamma_{\varepsilon}^{T} K \nabla \widetilde{\theta}_{\varepsilon} \\ \widetilde{\theta}_{\varepsilon} = -\nu_{\varepsilon} & \text{on } \Gamma_{D_{\theta}} \\ q_{\varepsilon}(\widetilde{\theta}_{\varepsilon}) \cdot n = -q_{\varepsilon}(\nu_{\varepsilon}) \cdot n & \text{on } \Gamma_{N_{\theta}} \\ \|q_{\varepsilon}(\widetilde{\theta}_{\varepsilon})\| \cdot n = \varepsilon (1 - \gamma^{T}) (\nabla q(\theta(\zeta))n) \cdot n & \text{on } \partial \mathcal{B}_{\varepsilon} \end{cases}$$
(83)

which has the following estimate  $\|\widetilde{\theta}_{\varepsilon}\|_{H^1(\Omega)} = o(\varepsilon)$  (see Appendix A). Moreover, the point  $\zeta$  in (83) belongs to the interval  $(x,\hat{x})$ . In addition, the solution  $\nu_{\varepsilon}$  to the exterior problem can be obtained by

1308

using a standard separation of variables technique, together with the Fourier series method. Then, the solution of the problem (82) is explicitly written in compact notation as:

• Exterior solution  $(r \ge \varepsilon)$ 

$$\nu_{\varepsilon}(\mathbf{x}/\varepsilon) = \frac{1 - \gamma^{\mathsf{T}}}{1 + \gamma^{\mathsf{T}}} \frac{\varepsilon^2}{\|\mathbf{x} - \hat{\mathbf{x}}\|^2} \nabla \theta(\hat{\mathbf{x}}) \cdot (\mathbf{x} - \hat{\mathbf{x}}). \tag{84}$$

• Interior solution ( $0 < r < \varepsilon$ )

$$v_{\varepsilon}(\mathbf{x}/\varepsilon) = \frac{1 - \gamma^{\mathsf{T}}}{1 + \gamma^{\mathsf{T}}} \nabla \theta(\hat{\mathbf{x}}) \cdot (\mathbf{x} - \hat{\mathbf{x}}). \tag{85}$$

Following the same steps as before, we assume that the field  $\phi_e$ , solution of the auxiliary problem (33), admits an asymptotic expansion of the form

$$\varphi_{\varepsilon}(x) = \varphi(x) + p_{\varepsilon}(x/\varepsilon) + \widetilde{\varphi}_{\varepsilon}(x), \tag{86}$$

where  $p_{\varepsilon}$  is the solution of the exterior problem

$$\begin{cases} \operatorname{div}(q_{\varepsilon}(p_{\varepsilon})) = 0 & \text{in } \mathbb{R}^{2} \\ q_{\varepsilon}(p_{\varepsilon}) = -\gamma_{\varepsilon}^{T} K \nabla p_{\varepsilon} \\ p_{\varepsilon} \to 0 & \text{at } \infty \\ \llbracket p_{\varepsilon} \rrbracket = 0 & \text{on } \partial \mathcal{B}_{\varepsilon} \\ \llbracket q_{\varepsilon}(p_{\varepsilon}) \rrbracket \cdot n = -(1 - \gamma^{T}) \nabla \varphi(\hat{x}) \cdot n & \text{on } \partial \mathcal{B}_{\varepsilon} \end{cases}$$
(87)

and the remainder  $\tilde{\varphi}_{\varepsilon}$  must be satisfies the following equation:

$$\begin{cases} \operatorname{div}(q_{\varepsilon}(\widetilde{\varphi}_{\varepsilon})) = 0 & \text{in } \Omega \setminus \overline{\mathcal{B}_{\varepsilon}} \\ \operatorname{div}(q_{\varepsilon}(\widetilde{\varphi}_{\varepsilon})) = -(1 - \gamma^{T})\mathbb{C}B \cdot \nabla u^{s} & \text{in } \mathcal{B}_{\varepsilon} \\ q_{\varepsilon}(\widetilde{\varphi}_{\varepsilon}) = -\gamma_{\varepsilon}^{T}K\nabla\widetilde{\varphi}_{\varepsilon} \\ \widetilde{\varphi}_{\varepsilon} = -p_{\varepsilon} & \text{on } \Gamma_{D_{\theta}} \\ q_{\varepsilon}(\widetilde{\varphi}_{\varepsilon}) \cdot \mathbf{n} = -q_{\varepsilon}(p_{\varepsilon}) \cdot \mathbf{n} & \text{on } \Gamma_{N_{\theta}} \\ \llbracket q_{\varepsilon}(\widetilde{\varphi}_{\varepsilon}) \rrbracket \cdot \mathbf{n} = \varepsilon(1 - \gamma^{T})(\nabla q(\varphi(\xi))\mathbf{n}) \cdot \mathbf{n} & \text{on } \partial \mathcal{B}_{\varepsilon} \end{cases}$$
(88)

which has the following estimate  $\|\widetilde{\varphi}_{\varepsilon}\|_{H^{1}(\Omega)} = o(\varepsilon)$  (see Appendix A). Moreover, the point  $\xi$  in (88) belongs to the interval  $(x,\hat{x})$ . In addition, by applying separation of variables technique and the Fourier series method, the solution  $\varphi_{\varepsilon}$  to the exterior problem (87) can be explicitly written in compact notation as:

• Exterior solution  $(r \ge \varepsilon)$ 

$$p_{\varepsilon}(x/\varepsilon) = \frac{1 - \gamma^{\mathsf{T}}}{1 + \gamma^{\mathsf{T}}} \frac{\varepsilon^2}{\|x - \hat{x}\|^2} \nabla \varphi(\hat{x}) \cdot (x - \hat{x}). \tag{89}$$

• Interior solution ( $0 < r < \varepsilon$ )

$$p_{\varepsilon}(x/\varepsilon) = \frac{1 - \gamma^{T}}{1 + \gamma^{T}} \nabla \varphi(\hat{x}) \cdot (x - \hat{x}). \tag{90}$$

Finally, using the asymptotic expansions presented in (84), (85), (89) and (90), and recalling the estimate for (80) (see Appendix A); we have that the derivative of the functional  $\mathcal{J}_{\chi_{\epsilon}}(u_{\epsilon}, \theta_{\epsilon})$  is given by the following expression:

$$\dot{\mathcal{J}}_{\chi_{\epsilon}}(u_{\epsilon},\theta_{\epsilon}) = -4\pi\epsilon \frac{1-\gamma^{T}}{1+\gamma^{T}}\nabla\theta\cdot\nabla\varphi + o(\epsilon). \tag{91} \label{eq:91}$$

# 3.3. Topological derivative

In order to calculate the topological derivative, we shall adopt the methodology developed in Novotny et al. (2003) whereby the topological derivative is obtained as

$$D_{T}(\hat{x}) = \lim_{\varepsilon \to 0} \frac{1}{f'(\varepsilon)} \dot{\mathcal{J}}_{\chi_{\varepsilon}}(u_{\varepsilon}, \theta_{\varepsilon}), \tag{92}$$

where the function  $f(\varepsilon)$  is the size of the perturbation, i.e.  $f(\varepsilon) = \pi \varepsilon^2 \Rightarrow f'(\varepsilon) = 2\pi \varepsilon$ .

Due to the linearity property of the shape functional with respect to the thermal problem (28), it is possible to write the topological derivative of the functional  $\mathcal{J}_{\chi_{\epsilon}}(u_{\epsilon},\theta_{\epsilon})$  based on the results given in (78) and (91). Then, the final expression of the topological derivative becomes a scalar function defined over the unperturbed domain  $\Omega$ , that is

$$\begin{split} D_T(\hat{x}) &= -\frac{1}{2E} \left( \frac{1-\gamma^M}{1+b\gamma^M} \right) \left[ 4\sigma(u) \cdot \sigma(u) + \frac{\gamma^M(b-2a)-1}{1+a\gamma^M} (\operatorname{tr} \sigma(u))^2 \right] \\ &- \frac{1}{4E} \left( \frac{1-\gamma^M \gamma^C}{1+a\gamma^M} \right) [(1-\gamma^M \gamma^C)(1+\nu) (\operatorname{tr} Q(\theta))^2 \\ &- 4\operatorname{tr} \sigma(u) \operatorname{tr} Q(\theta)] - 2\frac{1-\gamma^T}{1+\gamma^T} \nabla \theta \cdot \nabla \varphi. \end{split} \tag{93}$$

Notice that the first term is classic in the topological asymptotic analysis for the elasticity problem. The linearity property mentioned previously appears explicitly in the last term of the above results, see term involving the contrast parameter  $\gamma^T$ . On the other hand, the non-linear dependence of the problem with the thermoelastic constitutive properties appears, also explicitly, in the term with the contrast parameters  $\gamma^M \gamma^C$ . These two last terms represent the contribution of the thermal problem to the elastic stress problem.

#### 3.4. Numerical validation

The analytical formula for the topological derivative presented in (93), can be validated by using the computational framework described in this section. To this end, we define (for a finite value of  $\varepsilon$ ) the function  $g_{\varepsilon}(\hat{x})$  as:

$$g_{\varepsilon}(\hat{x}) := \frac{\psi(\chi_{\varepsilon}(\hat{x})) - \psi(\chi)}{f(\varepsilon)}.$$
(94)

Clearly, the above definition have the following property,

$$\lim_{\varepsilon \to 0} g_{\varepsilon}(\hat{x}) = D_{T}(\hat{x}). \tag{95}$$

A numerical approximation of  $D_T(\hat{x})$  can be obtained by calculating the functions  $\psi(\chi_{\varepsilon}(\hat{x}))$  and  $\psi(\chi)$ , for a sequences of decreasing values of  $\varepsilon$  and then using (94) to compute the corresponding estimates  $g_{\varepsilon}(\hat{x})$  for  $D_T(\hat{x})$ . The values of the function  $\psi$  are computed numerically by means of standard finite element procedure for the elasticity problem with thermal stresses. The domain considered in the verification is a unit square with material properties given by: Young's modulus E=1, Poisson's ratio v=1/3, thermal conductivity k=1 and thermal expansion coefficient  $\alpha=1$ . The perturbed domains are obtained by introducing circular inclusions of radii

$$\varepsilon \in \{0.160, 0.080, 0.040, 0.010, 0.005\},\tag{96}$$

centered at  $\hat{x}=(0.5,0.5)$ , with the origin of the coordinate system positioned at the bottom left corner. The finite element mesh used to discretise the perturbed domain contains a total number of 962560 three-nodded elements and 481921 nodes. To solve the thermal problem, we set the temperature  $\bar{\theta}=0$  on the boundary denoted as  $\Gamma_{D_{\theta}}$ . On the boundary  $\Gamma_{N_{\theta}}$ , an external heat flux  $\bar{q}=1$  is prescribed, see Fig. 2(a). In addition, the remainder part of the boundary remains insulated. For the mechanical problem, we prescribe the displacement on  $\Gamma_{D_u}$  to be  $\bar{u}=0$  and tractions  $\bar{t}=1$  on  $\Gamma_{N_u}$ , see Fig. 2(b). Due to the definition of the auxiliary problems (20) and (33), the boundary conditions for these problems are the same as the thermal problem on  $\Gamma_{D_{\theta}}$  and with homogeneous data on  $\Gamma_{N_{\theta}}$ .

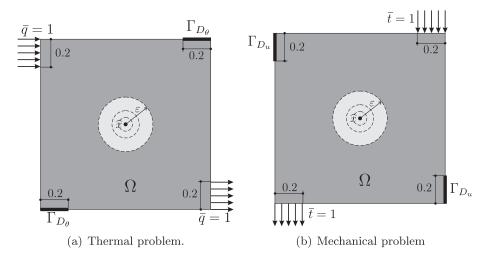


Fig. 2. Domain and boundary conditions.

The study is conducted for two combinations of the contrast parameters  $\gamma^{\rm M}$ ,  $\gamma^{\rm C}$  and  $\gamma^{\rm T}$ . The analyzed cases are given by:

- Case A:  $\gamma^M=\gamma^C=\gamma^T=1/3$  , Case B:  $\gamma^M=\gamma^T=\gamma^C=3$  .

The normalized obtained results  $(g_{\varepsilon}/D_T)$  are plotted in Fig. 3, where the analytical topological derivative and the numerical approximations for each value of  $\varepsilon$  are shown. It can be seen that the numerical topological derivatives converge to the corresponding analytical value for all cases. This confirms the validity of the proposed formula (93).

According to the numerical experiments, the obtained formula (93) remains valid only for small (infinitesimal) inclusions. The case associated to topological perturbations of finite size has been analyzed by Faria and Novotny (2009), Bonnet (2009), Silva et al. (2010), and Hintermüller et al. (2012), for instance.

# 4. Final comments

The topological derivative in its closed form for the total potential mechanical energy associated to a thermo-mechanical semi-coupled system, when a circular inclusion is introduced at

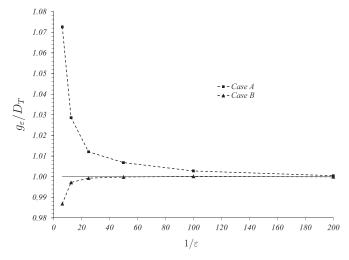


Fig. 3. Results of numerical verification.

an arbitrary point of the domain, has been derived. In particular, the linear elasticity system (modeled by the Navier equation) coupled with the steady-state heat conduction problem (modeled by the Laplace equation) has been considered. The mechanical coupling term comes out from the thermal stresses induced by the temperature field. Since this term is non-local, a non-standard adjoint state has been introduced, which allowed to obtain a closed form for the topological derivative. In addition, a full mathematical justification for the derived formulas and precise estimates for the remainders of the topological asymptotic expansion have been provided. Finally, we remark that this information can be potentially used in a number of applications of practical interest such as multi-physic topology design of structures under mechanical and/or thermal loads.

### Acknowledgments

This research was partly supported by ANPCyT (National Agency for Scientific and Technical Promotion) and PID-UTN (Research and Development Program of the National Technological University) of Argentina, under Grants No. PICT 2010-1259 and PID/IFN 1417, respectively. Also, we received support from CNPq (Brazilian Research Council) and FAPERJ (Research Foundation of the State of Rio de Janeiro, Brazil), under Grants 470597/ 2010-0 and E-26/102.204/2009, respectively. J.E. Esparta was supported by CAPES (Brazilian Higher Education Staff Training Agency). The support of all these agencies is gratefully acknowledged.

### Appendix A. Estimation of the remainders

**Lemma 1.** Let  $\tilde{u}_{\varepsilon}$  be solution to (68) or equivalently solution to the following variational problem: find  $\tilde{u}_{\varepsilon} \in \tilde{\mathcal{U}}_{\varepsilon}$ , such that

$$\int_{\Omega} \sigma_{\epsilon}(\tilde{u}_{\epsilon}) \cdot \nabla \eta^{s} = \epsilon^{2} \int_{\Gamma_{N_{u}}} \sigma(g_{u}) n \cdot \eta + \epsilon \int_{\partial \mathcal{B}_{\epsilon}} h_{u} \cdot \eta + \int_{\mathcal{B}_{\epsilon}} b_{u} \cdot \eta \quad \forall \eta \in \widetilde{\mathcal{V}}_{\epsilon},$$
(A.1)

where the set  $\widetilde{\mathcal{U}}_{\varepsilon}$  and the space  $\widetilde{\mathcal{V}}_{\varepsilon}$  are defined as

$$\widetilde{\mathcal{U}}_{\epsilon}:=\{\phi\in H^1(\Omega;\mathbb{R}^2): \llbracket\phi\rrbracket=0 \text{ on } \partial\mathcal{B}_{\epsilon}, \ \phi_{|_{\Gamma_{D_u}}}=\epsilon^2g_u\}, \tag{A.2}$$

$$\widetilde{\mathcal{V}}_{\varepsilon} := \{ \phi \in H^1(\Omega; \mathbb{R}^2) : \llbracket \phi \rrbracket = 0 \text{ on } \partial \mathcal{B}_{\varepsilon}, \ \phi_{|_{\Gamma_{D_n}}} = 0 \}, \tag{A.3}$$

and with functions  $g_u, h_u$  and  $b_u$ , independents of the small parameter  $\epsilon$ , given by

$$g_{u} := -\varepsilon^{-2} w_{\varepsilon}, \tag{A.4}$$

$$h_u := (1 - \gamma^M)(\nabla \sigma(u(\zeta))n)n - (1 - \gamma^M \gamma^C)(\nabla Q(\theta(\zeta))n)n), \tag{A.5}$$

$$b_u := -(1 - \gamma^{\mathsf{C}})\gamma^{\mathsf{M}} \operatorname{div}(\mathsf{Q}(\theta)), \tag{A.6}$$

where the points  $\zeta$  and  $\xi$  belong to the interval  $(x, \hat{x})$ . Then, we have the following estimate for the remainder  $\tilde{u}_{\epsilon}$ 

$$\|\tilde{u}_{\varepsilon}\|_{H^{1}(\Omega:\mathbb{R}^{2})} \leqslant C\varepsilon^{1+\delta},$$
 (A.7)

where C is a constant independent of the parameter  $\varepsilon$  and  $\delta > 0$ .

**Proof.** By taking  $\eta = \tilde{u}_{\varepsilon} - \phi_{\varepsilon}$  in (A.1), where  $\phi_{\varepsilon}$  is the lifting of the Dirichlet boundary data  $\varepsilon^2 g_u$  on  $\Gamma_{D_u}$ , we have

$$\begin{split} \int_{\Omega} \sigma_{\varepsilon}(\tilde{u}_{\varepsilon}) \cdot \nabla \tilde{u}_{\varepsilon}^{s} &= \varepsilon^{2} \int_{\Gamma_{N_{u}}} \sigma(g_{u}) n \cdot \tilde{u}_{\varepsilon} + \varepsilon^{2} \int_{\Gamma_{D_{u}}} g_{u} \cdot \sigma(\tilde{u}_{\varepsilon}) n \\ &+ \varepsilon \int_{\partial B_{\varepsilon}} h_{u} \cdot \tilde{u}_{\varepsilon} + \int_{B_{\varepsilon}} b_{u} \cdot \tilde{u}_{\varepsilon}. \end{split} \tag{A.8}$$

From the Cauchy-Schwarz inequality we obtain

$$\begin{split} \int_{\Omega} \sigma_{\varepsilon}(\tilde{u}_{\varepsilon}) \cdot \nabla \tilde{u}_{\varepsilon}^{s} &\leq \varepsilon^{2} \|\sigma(g_{u})n\|_{H^{-1/2}(\Gamma_{N_{u}};\mathbb{R}^{2})} \|\tilde{u}_{\varepsilon}\|_{H^{1/2}(\Gamma_{N_{u}};\mathbb{R}^{2})} \\ &+ \varepsilon^{2} \|g_{u}\|_{H^{1/2}(\Gamma_{D_{u}};\mathbb{R}^{2})} \|\sigma(\tilde{u}_{\varepsilon})n\|_{H^{-1/2}(\Gamma_{D_{u}};\mathbb{R}^{2})} \\ &+ \varepsilon \|h_{u}\|_{H^{-1/2}(\partial\mathcal{B}_{\varepsilon};\mathbb{R}^{2})} \|\tilde{u}_{\varepsilon}\|_{H^{1/2}(\partial\mathcal{B}_{\varepsilon};\mathbb{R}^{2})} \\ &+ \|b_{u}\|_{L^{2}(\mathcal{B}_{\varepsilon};\mathbb{R}^{2})} \|\tilde{u}_{\varepsilon}\|_{L^{2}(\mathcal{B}_{\varepsilon};\mathbb{R}^{2})}. \end{split} \tag{A.9}$$

Taking into account the trace theorem, we have

$$\begin{split} \int_{\Omega} \sigma_{\varepsilon}(\tilde{u}_{\varepsilon}) \cdot \nabla \tilde{u}_{\varepsilon}^{s} &\leq (\varepsilon^{2} C_{1} + \varepsilon \|h_{u}\|_{L^{2}(\mathcal{B}_{\varepsilon};\mathbb{R}^{2})}) \|\tilde{u}_{\varepsilon}\|_{H^{1}(\Omega;\mathbb{R}^{2})} \\ &+ \|b_{u}\|_{L^{2}(\mathcal{B}_{\varepsilon};\mathbb{R}^{2})} \|\tilde{u}_{\varepsilon}\|_{L^{2}(\mathcal{B}_{\varepsilon};\mathbb{R}^{2})} \\ &\leq \varepsilon^{2} C_{2} \|\tilde{u}_{\varepsilon}\|_{H^{1}(\Omega;\mathbb{R}^{2})} + \varepsilon C_{3} \|\tilde{u}_{\varepsilon}\|_{L^{2}(\mathcal{B}_{\varepsilon};\mathbb{R}^{2})}, \end{split} \tag{A.10}$$

where we have used the interior elliptic regularity of functions u and  $\theta$ , solution to problems (12) and (15), respectively. For the estimation of the last term in the right-hand side of the above expression we will use the Hölder inequality together with the Sobolev embedding theorem. In fact, we can find an estimate for the remainder  $\tilde{u}_{\varepsilon}$  of the form  $\|\tilde{u}_{\varepsilon}\|_{H^1(\Omega;\mathbb{R}^2)} \leqslant C\varepsilon^{1+\delta}$ , with  $\delta>0$  small. In particular, for 1/p+1/q=1, we have

$$\begin{split} \|\tilde{u}_{\varepsilon}\|_{L^{2}(\mathcal{B}_{\varepsilon};\mathbb{R}^{2})} & \leq \left[ \left( \int_{\mathcal{B}_{\varepsilon}} \|\tilde{u}_{\varepsilon}\|^{2p} \right)^{\frac{1}{p}} \left( \int_{\mathcal{B}_{\varepsilon}} 1^{2q} \right)^{\frac{1}{q}} \right]^{\frac{1}{2}} \\ & = \pi^{1/2q} \, \varepsilon^{1/q} \|\tilde{u}_{\varepsilon}\|_{L^{2p}(\mathcal{B}_{\varepsilon};\mathbb{R}^{2})} \\ & = \pi^{1/2q} \, \varepsilon^{1/q} \|\tilde{u}_{\varepsilon}\|_{L^{2q/(q-1)}(\mathcal{B}_{\varepsilon};\mathbb{R}^{2})} \leq \varepsilon^{\delta} C \|\tilde{u}_{\varepsilon}\|_{H^{1}(\Omega;\mathbb{R}^{2})}, \end{split} \tag{A.11}$$

where  $\delta=1/q$ , with q>1, and the constant C independent of the small parameter  $\varepsilon$ . Next, by introducing the above result in (A.10) we have.

$$\int_{\Omega} \sigma_{\varepsilon}(\tilde{u}_{\varepsilon}) \cdot \nabla \tilde{u}_{\varepsilon}^{s} \leqslant \varepsilon^{1+\delta} C_{4} \|\tilde{u}_{\varepsilon}\|_{H^{1}(\Omega; \mathbb{R}^{2})}. \tag{A.12}$$

Finally, from the coercivity of the bilinear form on the left-hand side of (A.1), namely,

$$c\|\tilde{u}_{\varepsilon}\|_{H^{1}(\Omega;\mathbb{R}^{2})}^{2} \leqslant \int_{\Omega} \sigma_{\varepsilon}(\tilde{u}_{\varepsilon}) \cdot \nabla \tilde{u}_{\varepsilon}^{s}, \tag{A.13}$$

we obtain

$$\|\tilde{u}_{\epsilon}\|_{H^{1}(\Omega;\mathbb{R}^{2})}\leqslant C_{5}\epsilon^{1+\delta}, \tag{A.14}$$

which leads to the result, with  $C_5 = C_4/c$ .  $\square$ 

**Lemma 2.** Let  $\widetilde{\theta}_{\varepsilon}$  be solution to (83) or equivalently solution to the following variational problem: find  $\widetilde{\theta}_{\varepsilon} \in \widetilde{\mathcal{U}}_{\varepsilon}$  such that

$$-\int_{\Omega}q_{\varepsilon}(\widetilde{\theta}_{\varepsilon})\cdot\nabla\eta=\varepsilon^{2}\int_{\Gamma_{N}}q(g_{\theta})\cdot n\eta+\varepsilon\int_{\partial\mathcal{B}_{\varepsilon}}h_{\theta}\eta\quad\forall\eta\in\widetilde{\mathcal{V}}_{\varepsilon},\quad (A.15)$$

where the set  $\widetilde{\mathcal{U}}_{\epsilon}$  and the space  $\widetilde{\mathcal{V}}_{\epsilon}$  are defined as

$$\widetilde{\mathcal{U}}_{\epsilon}:=\{\phi\in H^1(\Omega): \llbracket\phi\rrbracket=0 \text{ on } \partial\mathcal{B}_{\epsilon}, \; \phi_{|_{\Gamma_{D_{\alpha}}}}=-\epsilon^2g_{\theta}\}, \tag{A.16}$$

$$\widetilde{\mathcal{V}}_{\varepsilon} := \{ \phi \in H^1(\Omega) : \llbracket \phi \rrbracket = 0 \text{ on } \partial \mathcal{B}_{\varepsilon}, \ \phi_{|_{\Gamma_{\mathbf{D}_{\varepsilon}}}} = 0 \}, \tag{A.17}$$

and with functions  $g_{\theta}$  and  $h_{\theta}$ , independents of the small parameter  $\epsilon$ , given by

$$\mathbf{g}_{\theta} := \varepsilon^{-2} \nu_{\varepsilon},\tag{A.18}$$

$$h_{\theta} := -(1 - \gamma^{T})(\nabla q(\theta(\xi))n) \cdot n, \tag{A.19}$$

where the point  $\xi$  belongs to the interval  $(x, \hat{x})$ . Then, we have the following estimate for the remainder  $\tilde{\theta}_{\scriptscriptstyle E}$ 

$$\|\widetilde{\theta}_{\varepsilon}\|_{H^1(\Omega)} \leqslant C\varepsilon^2,$$
 (A.20)

where C is a constant independent of the parameter  $\epsilon$ .

**Proof.** By taking  $\eta = \tilde{\theta}_{\varepsilon} - \phi_{\varepsilon}$  in (A.15), where  $\phi_{\varepsilon}$  is the lifting of the Dirichlet boundary data  $\varepsilon^2 g_{\theta}$  on  $\Gamma_{D_{\theta}}$ , we have

$$\begin{split} -\int_{\Omega}q_{\epsilon}(\widetilde{\theta}_{\epsilon})\cdot\nabla\widetilde{\theta}_{\epsilon} &= \epsilon^{2}\int_{\Gamma_{N_{\theta}}}q(g_{\theta})\cdot n\,\widetilde{\theta}_{\epsilon} + \epsilon^{2}\int_{\Gamma_{D_{\theta}}}g_{\theta}\,q(\widetilde{\theta}_{\epsilon})\cdot n\\ &+ \epsilon\int_{\partial\mathcal{B}}h_{\theta}\,\widetilde{\theta}_{\epsilon}. \end{split} \tag{A.21}$$

From the Cauchy-Schwarz inequality we obtain

$$\begin{split} -\int_{\Omega} q_{\varepsilon}(\widetilde{\theta}_{\varepsilon}) \cdot \nabla \widetilde{\theta}_{\varepsilon} &\leqslant \varepsilon^{2} \| q(g_{\theta}) \cdot n \|_{H^{-1/2}(\Gamma_{N_{\theta}})} \| \widetilde{\theta}_{\varepsilon} \|_{H^{1/2}(\Gamma_{N_{\theta}})} \\ &+ \varepsilon^{2} \| g_{\theta} \|_{H^{1/2}(\Gamma_{D_{\theta}})} \| q(\widetilde{\theta}_{\varepsilon}) \cdot n \|_{H^{-1/2}(\Gamma_{D_{\theta}})} \\ &+ \varepsilon \| h_{\theta} \|_{H^{-1/2}(\partial \mathcal{B}_{\kappa})} \| \widetilde{\theta}_{\varepsilon} \|_{H^{1/2}(\partial \mathcal{B}_{\kappa})}. \end{split} \tag{A.22}$$

Taking into account the trace theorem, we have

$$\begin{split} -\int_{\Omega} q_{\varepsilon}(\widetilde{\theta}_{\varepsilon}) \cdot \nabla \widetilde{\theta}_{\varepsilon} & \leqslant \varepsilon^{2} C_{1} \|\widetilde{\theta}_{\varepsilon}\|_{H^{1}(\Omega)} + \varepsilon^{2} C_{2} \|\nabla \widetilde{\theta}_{\varepsilon}\|_{L^{2}(\Omega)} \\ & + \varepsilon \|h_{\theta}\|_{L^{2}(\mathcal{B}_{\varepsilon})} \|\widetilde{\theta}_{\varepsilon}\|_{H^{1}(\mathcal{B}_{\varepsilon})} \\ & \leqslant \varepsilon^{2} C_{1} \|\widetilde{\theta}_{\varepsilon}\|_{H^{1}(\Omega)} + \varepsilon^{2} C_{3} \|\widetilde{\theta}_{\varepsilon}\|_{H^{1}(\Omega)} \\ & + \varepsilon^{2} C_{4} \|\widetilde{\theta}_{\varepsilon}\|_{H^{1}(\Omega)} \\ & \leqslant \varepsilon^{2} C_{5} \|\widetilde{\theta}_{\varepsilon}\|_{H^{1}(\Omega)}, \end{split} \tag{A.23}$$

where we have used the interior elliptic regularity of function  $\theta$ , solution to problem (15). Finally, from the coercivity of the bilinear form on the left-hand side of (A.15), namely,

$$c\|\widetilde{\theta}_{\varepsilon}\|_{H^{1}(\Omega)}^{2} \leqslant -\int_{\Omega} q_{\varepsilon}(\widetilde{\theta}_{\varepsilon}) \cdot \nabla \widetilde{\theta}_{\varepsilon}, \tag{A.24}$$

we obtain

$$\|\widetilde{\theta}_{\varepsilon}\|_{H^{1}(\Omega)} \leqslant C\varepsilon^{2},$$
 (A.25)

which leads to the result, with  $C = C_5/c$ .  $\square$ 

**Lemma 3.** Let  $\widetilde{\theta}_{\varepsilon}$  be solution to (83). Then, its derivative with respect to  $\varepsilon$  has the following estimate

$$\|\widetilde{\theta}_{\varepsilon}'\|_{H^1(\Omega)} \leqslant C\varepsilon,$$
 (A.26)

where C is a constant independent of the parameter  $\varepsilon$ .

1312

**Proof.** The convergence follows by the property of the asymptotic expansions of solutions which can be differentiated term by term under the appropriate decrease order rule for the remainders of the expansions, namely  $O'(\varepsilon^m) = O(\varepsilon^{m-1})$ . See the work by Nazarov and Sokołowski (2003), for instance. Therefore, the result follows by Lemma 2 together with the rule  $O'(\varepsilon^2) = O(\varepsilon)$ .  $\square$ 

**Lemma 4.** Let  $\widetilde{\varphi}_{\varepsilon}$  be solution to (88) or equivalently solution to the following variational problem: find  $\widetilde{\varphi}_{\varepsilon} \in \widetilde{\mathcal{U}}_{\varepsilon}$  such that

$$-\int_{\Omega}q_{\varepsilon}(\widetilde{\varphi}_{\varepsilon})\cdot\nabla\eta=\varepsilon^{2}\int_{\Gamma_{N_{\theta}}}q(g_{\varphi})\cdot\mathbf{n}\,\eta+\varepsilon\int_{\partial\mathcal{B}_{\varepsilon}}\mathbf{h}_{\varphi}\,\eta+\int_{\mathcal{B}_{\varepsilon}}\mathbf{b}_{\varphi}\,\eta\quad\forall\eta\in\widetilde{\mathcal{V}}_{\varepsilon},$$
(A 27)

where the set  $\widetilde{\mathcal{U}}_{\epsilon}$  and the space  $\widetilde{\mathcal{V}}_{\epsilon}$  are defined as

$$\widetilde{\mathcal{U}}_{\varepsilon} := \{ \phi \in H^1(\Omega) : \llbracket \phi \rrbracket = 0 \text{ on } \partial \mathcal{B}_{\varepsilon}, \ \phi_{|_{\Gamma_{D_{\alpha}}}} = -\varepsilon^2 g_{\phi} \}, \tag{A.28}$$

$$\widetilde{\mathcal{V}}_{\epsilon}:=\{\phi\in H^1(\Omega): \llbracket\phi\rrbracket=0 \text{ on }\partial\mathcal{B}_{\epsilon}, \; \phi_{|_{\Gamma_{D_\alpha}}}=0\}, \tag{A.29}$$

and with functions  $g_{\phi}, h_{\phi}$  and  $b_{\phi}$ , independent of the small parameter  $\varepsilon$ , given by

$$\mathbf{g}_{\omega} := \varepsilon^{-2} \mathbf{p}_{\varepsilon},\tag{A.30}$$

$$h_{\omega} := -(1 - \gamma^{T})(\nabla q(\theta(\xi))n) \cdot n, \tag{A.31}$$

$$b_{\omega} := -(1 - \gamma^{T})\alpha \operatorname{tr} \sigma(u), \tag{A.32}$$

where the point  $\xi$  belongs to the interval  $(x,\hat{x})$ . Then, we have the following estimate for the remainder  $\widetilde{\varphi}_{\varepsilon}$ 

$$\|\widetilde{\varphi}_{\varepsilon}\|_{H^{1}(\Omega)} \leqslant C\varepsilon^{1+\delta}, \tag{A.33}$$

where the constant C is independent of the parameter  $\varepsilon$  and  $\delta > 0$ .

**Proof.** By taking  $\eta = \widetilde{\varphi}_{\varepsilon} - \phi_{\varepsilon}$  in (A.15), where  $\phi_{\varepsilon}$  is the lifting of the Dirichlet boundary data  $\varepsilon^2 g_{\omega}$  on  $\Gamma_{D_0}$ , we have

$$\begin{split} &-\int_{\Omega}q_{\epsilon}(\widetilde{\varphi}_{\epsilon})\cdot\nabla\widetilde{\varphi}_{\epsilon}=\epsilon^{2}\int_{\Gamma_{N_{\theta}}}q(g_{\varphi})\cdot\boldsymbol{n}\,\widetilde{\varphi}_{\epsilon}+\epsilon^{2}\int_{\Gamma_{D_{\theta}}}g_{\varphi}\,q(\widetilde{\varphi}_{\epsilon})\cdot\boldsymbol{n}\\ &+\epsilon\int_{\partial\mathcal{B}_{-}}h_{\varphi}\,\widetilde{\varphi}_{\epsilon}+\int_{\mathcal{B}_{-}}b_{\varphi}\,\widetilde{\varphi}_{\epsilon}. \end{split} \tag{A.34}$$

From the Cauchy-Schwarz inequality we obtain

$$\begin{split} -\int_{\Omega} q_{\varepsilon}(\widetilde{\varphi}_{\varepsilon}) \cdot \nabla \widetilde{\varphi}_{\varepsilon} & \leqslant \varepsilon^{2} \| q(g_{\varphi}) \cdot n \|_{H^{-1/2}(\Gamma_{N_{\theta}})} \| \widetilde{\varphi}_{\varepsilon} \|_{H^{1/2}(\Gamma_{N_{\theta}})} \\ & + \varepsilon^{2} \| g_{\varphi} \|_{H^{1/2}(\Gamma_{D_{\theta}})} \| q(\widetilde{\varphi}_{\varepsilon}) \cdot n \|_{H^{-1/2}(\Gamma_{D_{\theta}})} \\ & + \varepsilon \| h_{\varphi} \|_{H^{-1/2}(\partial \mathcal{B}_{\varepsilon})} \| \widetilde{\varphi}_{\varepsilon} \|_{H^{1/2}(\partial \mathcal{B}_{\varepsilon})} \\ & + \| b_{\varphi} \|_{L^{2}(\mathcal{B}_{\varepsilon})} \| \widetilde{\varphi}_{\varepsilon} \|_{L^{2}(\mathcal{B}_{\varepsilon})}. \end{split} \tag{A.35}$$

Taking into account the trace theorem, we have

$$\begin{split} -\int_{\Omega} q_{\epsilon}(\widetilde{\varphi}_{\epsilon}) \cdot \nabla \widetilde{\varphi}_{\epsilon} & \leqslant \epsilon^{2} C_{1} \|\widetilde{\varphi}_{\epsilon}\|_{H^{1}(\Omega)} + \epsilon^{2} C_{2} \|\nabla \widetilde{\varphi}_{\epsilon}\|_{L^{2}(\Omega)} \\ & + \epsilon \|h_{\varphi}\|_{L^{2}(\mathcal{B}_{\epsilon})} \|\widetilde{\varphi}_{\epsilon}\|_{H^{1}(\mathcal{B}_{\epsilon})} \\ & + \|b_{\varphi}\|_{L^{2}(\mathcal{B}_{\epsilon})} \|\widetilde{\varphi}_{\epsilon}\|_{L^{2}(\mathcal{B}_{\epsilon})} \\ & \leqslant \epsilon^{2} C_{1} \|\widetilde{\varphi}_{\epsilon}\|_{H^{1}(\Omega)} + \epsilon^{2} C_{3} \|\widetilde{\varphi}_{\epsilon}\|_{H^{1}(\Omega)} \\ & + \epsilon^{2} C_{4} \|\widetilde{\varphi}_{\epsilon}\|_{H^{1}(\Omega)} + \epsilon C_{5} \|\widetilde{\varphi}_{\epsilon}\|_{L^{2}(\mathcal{B}_{\epsilon})}, \end{split} \tag{A.36}$$

where we have used the interior elliptic regularity of functions  $\theta$  and u. By using the Hölder inequality together with the Sobolev embedding theorem, the last term in the right-hand side of the above expression is given by

$$\|\widetilde{\varphi}_{\varepsilon}\|_{L^{2}(\mathcal{B}_{\varepsilon})} \leqslant \varepsilon^{\delta} C \|\widetilde{\varphi}_{\varepsilon}\|_{H^{1}(\Omega)}, \tag{A.37}$$

where  $\delta=1/q$ , with q>1, and the constant C independent of the small parameter  $\varepsilon$ . Next, by introducing the above result in (A.36) we have

$$-\int_{\Omega} q_{\varepsilon}(\widetilde{\varphi}_{\varepsilon}) \cdot \nabla \widetilde{\varphi}_{\varepsilon} \leqslant \varepsilon^{1+\delta} C_{6} \|\widetilde{\varphi}_{\varepsilon}\|_{H^{1}(\Omega)}. \tag{A.38}$$

Finally, from the coercivity of the bilinear form on the left-hand side of (A.15), namely,

$$c\|\widetilde{\varphi}_{\varepsilon}\|_{H^{1}(\Omega)}^{2} \leqslant -\int_{\Omega} q_{\varepsilon}(\widetilde{\varphi}_{\varepsilon}) \cdot \nabla \widetilde{\varphi}_{\varepsilon}, \tag{A.39}$$

we obtain

$$\|\widetilde{\varphi}_{\varepsilon}\|_{H^{1}(\Omega)} \leqslant C\varepsilon^{1+\delta},$$
 (A.40)

which leads to the result, with  $C = C_6/c$ .

**Lemma 5.** Let  $\theta_{\varepsilon}$ ,  $u_{\varepsilon}$  and u solution of the problems (28), (25) and (12). Then, we have the following estimate for the remainder  $\mathcal{E}(\varepsilon)$  in (80):

$$\mathcal{E}(\varepsilon) \leqslant C\varepsilon^2,$$
 (A.41)

where C is a constant independent of the parameter  $\varepsilon$ .

**Proof.** By tacking into account the definition of the mechanical and thermal stress operators  $\sigma_{\varepsilon}$  and  $Q_{\varepsilon}$ , respectively, the remainder term  $\mathcal{E}(\varepsilon)$  in (80) can be alternatively written as:

$$\mathcal{E}(\varepsilon) = -\int_{\Omega} \gamma_{\varepsilon}^{\mathsf{C}} \mathsf{B} \theta_{\varepsilon}^{\mathsf{r}} \cdot \sigma_{\varepsilon}(u_{\varepsilon} - u). \tag{A.42}$$

Next, by considering the definition of the contrast  $\gamma_{\varepsilon}^{C}$  and the ansatz (64) and (81), the above expression is given by

$$\begin{split} \mathcal{E}(\varepsilon) &= -\int_{\Omega \setminus \overline{\mathcal{B}_{\varepsilon}}} B \nu_{\varepsilon}' \cdot \sigma_{\varepsilon}(w_{\varepsilon}) - \int_{\mathcal{B}_{\varepsilon}} \gamma^{\mathsf{C}} B \nu_{\varepsilon}' \cdot \sigma_{\varepsilon}(w_{\varepsilon}) - \int_{\Omega \setminus \overline{\mathcal{B}_{\varepsilon}}} B \widetilde{\theta}_{\varepsilon}' \cdot \sigma_{\varepsilon}(w_{\varepsilon}) \\ &- \int_{\mathcal{B}_{\varepsilon}} \gamma^{\mathsf{C}} B \widetilde{\theta}_{\varepsilon}' \cdot \sigma_{\varepsilon}(w_{\varepsilon}) - \int_{\Omega \setminus \overline{\mathcal{B}_{\varepsilon}}} B \nu_{\varepsilon}' \cdot \sigma_{\varepsilon}(\tilde{u}_{\varepsilon}) - \int_{\mathcal{B}_{\varepsilon}} \gamma^{\mathsf{C}} B \nu_{\varepsilon}' \cdot \sigma_{\varepsilon}(\tilde{u}_{\varepsilon}) \\ &- \int_{\Omega} B \widetilde{\theta}_{\varepsilon}' \cdot \sigma_{\varepsilon}(\tilde{u}_{\varepsilon}). \end{split} \tag{A.43}$$

Since  $\nu_{\varepsilon}'=0$  in  $\mathcal{B}_{\varepsilon}$  and  $\sigma_{\varepsilon}(\phi)=\sigma(\phi)$  in  $\Omega\setminus\overline{\mathcal{B}_{\varepsilon}}$ , the remainder  $\mathcal{E}(\varepsilon)$  is given by

$$\begin{split} \mathcal{E}(\varepsilon) &= -\int_{\Omega\setminus\overline{\mathcal{B}_{\varepsilon}}} B\nu_{\varepsilon}' \cdot \sigma(w_{\varepsilon}) - \int_{\Omega\setminus\overline{\mathcal{B}_{\varepsilon}}} B\widetilde{\theta}_{\varepsilon}' \cdot \sigma(w_{\varepsilon}) - \int_{\mathcal{B}_{\varepsilon}} \gamma^{\mathsf{C}} B\widetilde{\theta}_{\varepsilon}' \cdot \sigma_{\varepsilon}(w_{\varepsilon}) \\ &- \int_{\Omega\setminus\overline{\mathcal{B}_{\varepsilon}}} B\nu_{\varepsilon}' \cdot \sigma(\tilde{u}_{\varepsilon}) - \int_{\Omega} B\widetilde{\theta}_{\varepsilon}' \cdot \sigma_{\varepsilon}(\tilde{u}_{\varepsilon}). \end{split} \tag{A.44}$$

From the Cauchy-Schwarz inequality we obtain

$$\begin{split} \mathcal{E}(\varepsilon) &\leq C_{1} \| \nu_{\varepsilon}' \|_{L^{2}(\Omega \setminus \overline{\mathcal{B}_{\varepsilon}})} \| \sigma(w_{\varepsilon}) \|_{L^{2}(\Omega \setminus \overline{\mathcal{B}_{\varepsilon}}; \mathbb{R}^{2})} \\ &+ C_{1} \| \widetilde{\theta}_{\varepsilon}' \|_{L^{2}(\Omega \setminus \overline{\mathcal{B}_{\varepsilon}})} \| \sigma(w_{\varepsilon}) \|_{L^{2}(\Omega \setminus \overline{\mathcal{B}_{\varepsilon}}; \mathbb{R}^{2})} \\ &+ C_{2} \| \widetilde{\theta}_{\varepsilon}' \|_{L^{2}(\mathcal{B}_{\varepsilon})} \| \sigma_{\varepsilon}(w_{\varepsilon}) \|_{L^{2}(\mathcal{B}_{\varepsilon}; \mathbb{R}^{2})} \\ &+ C_{1} \| \nu_{\varepsilon}' \|_{L^{2}(\Omega \setminus \overline{\mathcal{B}_{\varepsilon}})} \| \sigma(\tilde{u}_{\varepsilon}) \|_{L^{2}(\Omega \setminus \overline{\mathcal{B}_{\varepsilon}}; \mathbb{R}^{2})} \\ &+ C_{3} \| \widetilde{\theta}_{\varepsilon}' \|_{L^{2}(\Omega)} \| \sigma_{\varepsilon}(\tilde{u}_{\varepsilon}) \|_{L^{2}(\Omega \setminus \overline{\mathcal{B}_{\varepsilon}}; \mathbb{R}^{2})}. \end{split} \tag{A.45}$$

By considering the asymptotic expansion of  $\nu_{\varepsilon}$  presented in (84) its derivative with respect to  $\varepsilon$  can be written as  $v'_{\varepsilon} = \varepsilon g_{\nu}(x)$  in  $\Omega \setminus \overline{\mathcal{B}_{\varepsilon}}$ , with the function  $g_{\nu}$  independent of the parameter  $\varepsilon$ . After introducing a change of variables of the form  $y = \varepsilon^{-1} x$ , we have

$$\|v_{\varepsilon}'\|_{L^{2}(\Omega\setminus\overline{\mathcal{B}_{\varepsilon}})} = \left(\int_{\Omega\setminus\overline{\mathcal{B}_{\varepsilon}}} |\varepsilon g_{v}(x)|^{2}\right)^{\frac{1}{2}} = \varepsilon \left(\int_{\mathbb{R}^{2}\setminus\overline{\mathcal{B}_{1}}} |g_{v}(y)|^{2}\right)^{\frac{1}{2}} \leqslant \varepsilon C_{4},$$
(A.46)

where we have used the fact that function  $g_v(y)$  is regular at infinity, i.e.,  $g_v(y) \to 0$  when  $||y|| \to \infty$ . In the same way, by considering (71)–(73) and the same change of variables, we obtain

$$\|\sigma(w_{\varepsilon})\|_{L^{2}(\Omega\setminus\mathcal{B}_{\varepsilon};\mathbb{R}^{2})} = \varepsilon \left(\int_{\mathbb{R}^{2}\setminus\overline{\mathcal{B}_{1}}} \|\sigma(h_{\sigma}(y))\|^{2}\right)^{\frac{1}{2}} \leqslant \varepsilon C_{5}, \tag{A.47}$$

being the function  $h_{\sigma}(x)$  independent of the parameter  $\varepsilon$  and regular at infinity, such that,  $\sigma(h_{\sigma}(y)) \to 0$  when  $\|y\| \to \infty$ . By taking into account the fact that function  $\sigma_{\varepsilon}(w_{\varepsilon})$  is independent of the parameter  $\varepsilon$  in  $\mathcal{B}_{\varepsilon}$ , we can write  $\sigma_{\varepsilon}(w_{\varepsilon}) = \sigma(b_{\sigma}(x))$  in  $\mathcal{B}_{\varepsilon}$ . Then, we have

$$\|\sigma_{\varepsilon}(w_{\varepsilon})\|_{L^{2}(\mathcal{B}_{\varepsilon};\mathbb{R}^{2})} = \left(\int_{\mathcal{B}_{\varepsilon}} \|\sigma(b_{\sigma}(x))\|^{2}\right)^{\frac{1}{2}} \leqslant \varepsilon C_{6}. \tag{A.48}$$

Next, by introducing the above results in (A.45), we have

$$\begin{split} \mathcal{E}(\varepsilon) &\leqslant \varepsilon^2 C_7 + \varepsilon C_8 \|\widetilde{\theta}_{\varepsilon}'\|_{L^2(\Omega \setminus \overline{\mathcal{B}_{\varepsilon}})} + \varepsilon C_9 \|\widetilde{\theta}_{\varepsilon}'\|_{L^2(\mathcal{B}_{\varepsilon})} \\ &+ \varepsilon C_{10} \|\sigma(\tilde{u}_{\varepsilon})\|_{L^2(\Omega \setminus \overline{\mathcal{B}_{\varepsilon}}; \mathbb{R}^2)} + C_3 \|\widetilde{\theta}_{\varepsilon}'\|_{L^2(\Omega)} \|\sigma_{\varepsilon}(\tilde{u}_{\varepsilon})\|_{L^2(\Omega; \mathbb{R}^2)}, \\ &\leqslant \varepsilon^2 C_7 + \varepsilon C_{11} \|\widetilde{\theta}_{\varepsilon}'\|_{H^1(\Omega)} + \varepsilon C_{12} \|\tilde{u}_{\varepsilon}\|_{H^1(\Omega; \mathbb{R}^2)} \\ &+ C_{13} \|\widetilde{\theta}_{\varepsilon}'\|_{H^1(\Omega)} \|\tilde{u}_{\varepsilon}\|_{H^1(\Omega; \mathbb{R}^2)}, \end{split} \tag{A.49}$$

Finally, by considering the Lemmas 1-3, we obtain

$$\mathcal{E}(\varepsilon) \leqslant C\varepsilon^2,$$
 (A.50)

which leads to the results, with C independent of the parameter  $\varepsilon$ .  $\square$ 

#### References

- Allaire, G., Jouve, F., Van Goethem, N., 2011. Damage and fracture evolution in brittle materials by shape optimization methods. Journal of Computational Physics 230 (12), 5010–5044.
- Amstutz, S., Novotny, A.A., de Souza Neto, E.A., 2012. Topological derivative-based topology optimization of structures subject to Drucker-Prager stress

- constraints. Computer Methods in Applied Mechanics and Engineering, 123-136
- Bonnet, M., 2009. Higher-order topological sensitivity for 2-D potential problems. International Journal of Solids and Structures 46 (11–12), 2275–2292.
- Cardone, G., Nazarov, S., Sokolowski, J., 2010. Asymptotic analysis polarization matrices and topological derivatives for piezoelectric materials with small voids. SIAM Journal on Control and Optimization 48 (6), 3925–3961.
- Delfour, M.C., Zolésio, J.P., 2001. Shapes and Geometries. Advances in Design and Control. Society for Industrial and Applied Mathematics (SIAM), Philadelphia,
- Eshelby, J.D., 1975. The elastic energy-momentum tensor. Journal of Elasticity 5 (3-4), 321–335.
- Rocha de Faria, J., Novotny, A.A., 2009. On the second order topological asymptotic expansion. Structural and Multidisciplinary Optimization 39 (6), 547–555.
- Giusti, S.M., Novotny, A.A., de Souza Neto, E.A., Feijóo, R.A., 2009. Sensitivity of the macroscopic elasticity tensor to topological microstructural changes. Journal of the Mechanics and Physics of Solids 57 (3), 555–570.
- Gurtin, M.E., 1981. An Introduction to Continuum Mechanics. Mathematics in Science and Engineering, vol. 158. Academic Press, New York.
- Gurtin, M.E., 2000. Configurational Forces as Basic Concept of Continuum Physics. Applied Mathematical Sciences, vol. 137. Springer-Verlag, New York.
- Hintermüller, M., Laurain, A., 2009. Multiphase image segmentation and modulation recovery based on shape and topological sensitivity. Journal of Mathematical Imaging and Vision 35, 1–22.
- Hintermüller, M., Laurain, A., Novotny, A.A., 2012. Second-order topological expansion for electrical impedance tomography. Advances in Computational Mathematics 36 (2), 235–265.
- Little, R.W., 1973. Elasticity. Prentice-Hall, New Jersey.
- Nazarov, S.A., Sokołowski, J., 2003. Asymptotic analysis of shape functionals. Journal de Mathématiques Pures et Appliquées 82 (2), 125–196.
- Novotny, A.A., Feijóo, R.A., Padra, C., Taroco, E., 2003. Topological sensitivity analysis. Computer Methods in Applied Mechanics and Engineering 192 (7–8), 803–829.
- Novotny, A.A., Sokołowski, J., 2013. Topological Derivatives in Shape Optimization. Interaction of Mechanics and Mathematics. Springer.
- Silva, M., Matalon, M., Tortorelli, D.A., 2010. Higher order topological derivatives in elasticity. International Journal of Solids and Structures 47 (22–23), 3053– 3066
- Sokołowski, J., Żochowski, A., 1999. On the topological derivative in shape optimization. SIAM Journal on Control and Optimization 37 (4), 1251–1272.
- Sokołowski, J., Zolésio, J.P., 1992. Introduction to Shape Optimization Shape Sensitivity Analysis. Springer-Verlag, Berlin, Germany.
- Van Goethem, N., Novotny, A.A., 2010. Crack nucleation sensitivity analysis. Mathematical Methods in the Applied Sciences 33 (16), 197–1994.