

Research Paper

Lifted particles from the fast spinning primary of the Near-Earth Asteroid (65803) Didymos

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ABSTRACT

An increasing number of Near Earth Asteroids (NEAs) in the range of a few hundred metres to a few kilometres in size have relatively high spin rates, from less than 4 h, down to ~ 2.2 h, depending on spectral type. For some of these bodies, local acceleration near the equator may be directed outwards so that lift off of near-equatorial material is possible. In particular, this may be the case for asteroid Didymos, the primary of the (65803) Didymos binary system, which is the target of the DART (NASA) and Hera (ESA) space missions. The study of the dynamics of particles in such an environment has been carried out – in the frame of the Hera mission and the EC-H2020 NEO-MAPP project – according to the available shape model, known physical parameters and orbital information available before the DART impact. The presence of orbiting particles in the system is likely for most of the estimated range of values for mass and volume. The spatial mass density of ejected material is calculated for different particle sizes and at different heliocentric orbit epochs, revealing that large particles dominate the mass density distribution and that small particle abundance depends on observation epoch. Estimates of take off and landing areas on Didymos are also reported. Available estimates of the system mass and primary extents, after the DART mission, confirm that the main conclusions of this study are valid in the context of current knowledge.

1. Introduction

Many Near Earth Asteroids (NEAs) have been discovered in the last two decades, including at sizes smaller than a few km and fast spin rates. Pravec et al. (2008) showed that an excess of slow rotators (spin period $T > 24$ h), as well as fast rotators ($2.2 \text{ h} < T < 2.8 \text{ h}$), is present in the NEA population at size $D > 0.2 \text{ km}$. The former is also found in main belt asteroids, while the excess of fast rotators is not, and it seems to be peculiar to NEAs. It is noteworthy that 2/3 of fast spinning NEAs are binaries (Pravec et al., 2006) and they correspond to the concentration of fast spin rate of primaries of NEA binaries in front of the “spin barrier” at $\approx 2.2 \text{ h}$.

The spin state with which asteroids enter the NEA region is mostly affected by non-catastrophic collisions while in the asteroid belt (Holsapple, 2022), and partially by the non-gravitational YORP effect. YORP is also the main driving source for NEAs spin up once in the inner planet region.

1.1. Asteroid stability limits and spin-up

We recall here the spin limits for mass shedding defining an upper threshold on the rotation rate at which a particle at the equator of a spherical body is at neutral equilibrium between gravity and centrifugal force. For a homogeneous sphere, the relation for the critical spin rate is:

$$\omega_{cr} = \sqrt{\frac{4\pi G\rho}{3}} \quad (1)$$

where ρ is the bulk density of the object. Spin limit depends on asteroid density: e.g., $T = 2.2 \text{ h}$ is the limit corresponding to a spherical body of density $\rho = 2250 \text{ kg/m}^3$, which is typical of S-type gravitational aggregate asteroids; instead, spin limit is $T = 3.0 \text{ h}$ for C-type gravitational aggregate asteroids, with $\rho = 1200 \text{ kg/m}^3$. Such densities differ from

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the density of their meteorite analogues due to macro-porous structure of gravitational aggregates.

As soon as enough spin data were available (Pravec and Harris, 2000), such a spin limit became evident when plotting size vs spin period. Very rarely asteroids larger than 200–300 m in diameter (D) have been observed with a rotational period smaller than 2.2 h. This has led to interpretations of the internal structure of such asteroids. Fast rotators are instead common at $D < 200$ m. Focusing the discussion on the size range 300 m–10 km, the interpretation of the spin limit leads to two slightly different regimes (Holsapple, 2007). For asteroids larger than 3 km, the spin barrier does not constrain whether these are strength-less objects or just cracked but coherent bodies. In fact, the upper limit on the tensile strength – given by the barrier itself – is higher than a scaled tensile strength of cracked but coherent bodies. Instead, for asteroids smaller than 3 km, the maximum possible tensile strength allowed by the spin barrier is too low for these asteroids to be cracked but coherent bodies, so they should have predominantly cohesion-less structures.

Non-coherent asteroids are aggregates that have re-accumulated fragments by self-gravity right after shattering events. On the contrary, internally cracked objects may arise due to shattering at the threshold energy for fragmentation, with little kinetic energy left to reshuffle fragments. Another way of producing cracked structures is by series of sub-catastrophic collisions summing up similar damage in the overall structure as one single barely shattering event (Housen, 2009). In that case, the object may be coherent allowing for some tensile stress.

Both coherent bodies and gravitational aggregates (GA) (often called rubble piles) may withstand spin rates higher than the critical ones for fluids found by Chandrasekhar (1969), and spin ideally up to the spin barrier around 2.2 h before falling apart. In the case of coherent – monolithic – structure, that is due to internal solid state forces, which do withstand spin rates beyond that limit. This is especially the case of bodies smaller than 300 m. Instead, non-coherent asteroids (as gravitational aggregates are) may be spun up and undergo shape change corresponding to a minimum energy configuration – led by dissipative forces (e.g., internal friction) – compatible with increasing angular momentum. That is achieved by rotation about the maximum angular inertia axis. As a result, some of those bodies might become top-shaped (Cheng et al., 2021; Sabuwala et al., 2021).

Therefore, shear strength may be present due to friction and interlocking between GA components (Richardson et al., 2002; Holsapple, 2007; Ferrari et al., 2020), as a reaction to the shear stress due to centrifugal force, increasing structural yield. The presence of interparticle cohesion has also been suggested (Sánchez and Scheeres, 2012; Zhang et al., 2017, 2021), though still a matter of debate. Such shear strength, regardless of its nature, may prevent the whole structure from falling apart when the rotation spin rate exceeds the stability limit for fluid bodies. This mechanism is successful until the spin barrier is reached. At that point, the body is no longer able to adjust the exceeding energy and angular momentum by shape change through energy dissipation by friction. Depending on internal stiffness, fission or mass shedding takes place, eventually leading to asteroid binary or pair/clan formation (Pravec et al., 2019). The mechanisms of formation of NEA binary systems are a matter of debate and are beyond the scope of this study.

1.2. NEA binary systems with fast spinning primary

Many binary systems in the NEA population share a number of common features: (a) small mass ratio (≈ 0.01) for satellite to primary components; (b) fast spin primary; (c) top-shape primary (Naidu et al., 2020; Roberts et al., 2021; Walsh et al., 2012). Of all binary systems with fast rotating primary, we identified a handful near the edge of stability, as reported in Table 1 together with a number of single bodies. In this work, we focus on the Didymos system because of its interest as the target of both DART (NASA) and Hera (ESA) space missions.

Table 1

Some NEA binaries with primaries near the edge of stability. D_p is the size of the primary, D_s/D_p is the satellite/primary size ratio, and T (h) is the primary spin period. Source: Johnston's archive. <https://www.johnstonsarchive.net/astro/asteroidmoons.html>.

Asteroid name	D_p (km)	D_s/D_p	T (h)	Taxonomy type
(65803) Didymos	0.78	0.21	2.26	S
(66063) 1998 RO1	0.80	0.50	2.49	–
(88710) 2001 SL9	0.77	0.32	2.40	Sr, Q
(164121) 2003 YT1	1.10	0.19	2.34	–
(311066) 2004 DC	0.36	0.19	2.57	–
(137170) 1999 HF1	3.6	0.23	2.31	X
(1862) Apollo	1.55	0.05	3.06	Q
(175706) 1996 FG3	1.69	0.29	3.59	C
(185851) 2000 DP107	0.80	0.38	2.77	C
(276049) 2002 CE26	3.5	0.09	3.29	C

However, the 1996 FG3 binary system also was the former goal of the MarcoPolo-R mission and is now the sample return target of the Chinese (CNSA) Zheng He space mission. Beyond binary primaries, it is worth mentioning that some lonely top-shape NEAs also show fast spin rates. This is indeed the case of 2008 EV5, which was the target of the un-selected ESA (2014) MarcoPolo-R mission.

1.2.1. The Didymos system

The NEA binary (65 803) Didymos is the S-type target of the DART (NASA) and Hera (ESA) space missions. Model predictions may be tested by combined data from those two missions, which makes this a particularly interesting system to study. This asteroid is classified as an Apollo NEA with a semimajor axis of $1.6442688843 \pm 1.6 \times 10^{-9}$ au, and a large eccentricity of $0.383882802 \pm 3 \times 10^{-9}$ (pre-DART impact heliocentric ephemeris solution 181). Its perihelion is therefore well inside the inner asteroid belt, where the asteroid spends 1/3 of its orbital period.

The pre-impact estimations of the system main physical characteristics were the values available when this research started, and numerical simulations were run. The discussion on how post-DART impact estimation may affect results is carried out in Section 5. Didymos, the primary of the binary, had estimated principal axes extent sizes of $832 (\pm 3\%) \times 837 (\pm 3\%) \times 786 (\pm 5\%)$ m, the last of which is the size along its spin axis. A Didymos shape model has been derived using both radar and optical telescope data, clearly indicating a top-shape (Naidu et al., 2020) before the DART and LICIAcube missions imaging. The mass of the system was estimated as $5.278 \times 10^{11} \pm 10\%$ kg (Naidu et al., 2020) from the orbital period of the secondary, named Dimorphos, which is known ($11.9216289 \pm 2.8 \times 10^{-6}$ h. S. Naidu and S. Chesley, personal communication). The spin period of Didymos is 2.2600 ± 0.0001 h (Pravec et al., 2006) and its bulk density was estimated to be 2170 kg/m^3 , with a 30% uncertainty. The size of Dimorphos was estimated to be 164 ± 10 m, compatible with oblate to prolate shape with axes ratio between 0 and 1.3. No information on the spin rate of Dimorphos is available, though it is assumed to be synchronous to its orbital period. Separation between components is 1.19 ± 0.03 km (Naidu et al., 2020).

Available data do not allow predictions about the internal structure of any of the two bodies. Nevertheless, updated estimates of some physical parameters critical to this study available during the publication process of this work (Daly et al., 2023) confirm L and LL ordinary chondrites as the best meteorite analogues for Didymos. Considering that typical grain density of such meteorite complexes is in the 3500–3600 kg/m^3 range, the system bulk density is compatible with at least 30% bulk porosity of its components. Therefore, the primary may have a gravitational aggregate structure with unknown size distribution of components.

1.3. Asteroids on the edge of stability

For some NEAs, the centrifugal force acting on surface particles and boulders at near-equatorial latitudes may slightly overcome the gravitational pull of the asteroid itself in the spinning, non-inertial reference frame of the rotating asteroid. In that case, the radial component of acceleration for surface particles is directed outwards, allowing them to leave the surface and undergo corresponding dynamical evolution. Leaving the surface does not mean that particles are lost from the asteroid. In fact, they start their motion at zero velocity but non-zero acceleration, and as soon as they lift off they move under the gravitational field of the asteroid, the non-inertial apparent forces due to rotation, the Sun's gravity and its radiation, and – in the case of binary systems – the gravitational pull of the secondary. Other forces may act as well on small particles on the surface, like electrostatic or molecular forces (cohesion), with the likely result of sticking them together and potentially undergoing the same dynamical effect as dusty clumps. Moreover, small particles, below 1 mm in size, may be lost from the system under the influence of solar radiation pressure (SRP), but even mm to cm-size particles can have their orbits affected by SRP over a longer span (Yu et al., 2017; Ferrari and Tanga, 2022; Rossi et al., 2022). We may expect, instead, that more massive particles potentially levitate for some time, land on the surface and lift off again, repeating such cycles over and over, or just land at latitudes from which further lift-off is not possible. Alternatively, they may enter mostly unstable orbits and even transfer to the secondary.

Fahnestock and Scheeres (2009) studied the effect of particle lofting due to YORP spin up in a binary system, namely 1999 KW4 (Moshup). They found that transferring angular momentum from the primary to the mutual orbit is possible. Regulation of primary spin at the rate for which material lofting takes place may happen so that the orbital angular momentum of the secondary grows steadily. Apparently, lofting occurs in fast transient episodes separated by long periods of slow spin-up. The authors argue that the end state of the system evolution is likely the separation into two asteroids on closely related heliocentric orbits. That may be a potential origin for “asteroid pairs”.

Campo Bagatin (2013) outlined the possibility of mass lifting as a general mechanism of regolith dispersal in fast spinning Near-Earth asteroids forming “dusty” environment around such bodies.

Yu et al. (2019) investigated mass shedding from the surface of the primary of (65803) Didymos by a semi-analytical approach for shedding conditions. They determined unstable surface areas by combining the analyses and numerical results of SSDEM simulations. The authors find a vast majority of the shedding mass is finally transferred to Dimorphos leading to a cumulative growth which may cause a spiralling-in orbit of the secondary, an effect going in the opposite direction to Fahnestock and Scheeres (2009) finding. Further work on failure modes and mass shedding processes was carried out by Sánchez and Scheeres (2016), Zhang et al. (2021), Ferrari and Tanga (2022) and Hirabayashi et al. (2022).

The main goal of this work is to study the general dynamical features of the lift-off mechanism that may be acting on some of the NEA binary systems listed in Table 1. We use asteroid Didymos as a case study, assuming the best available knowledge to the time of developing the model. Obviously, the actual shape, volume and mass of that asteroid – as well as other physical parameters of the system – will be constrained in much greater detail only after both the DART and Hera missions will characterize the binary system. Here we analyse the dynamical evolution of lifted particles as well as their preference for take-off and landing areas on Didymos. We provide mass density distributions of the material that may currently be, or may have been present around it, assuming a given mass emission rate.

The model set up to study particle dynamics in this system and its validation is introduced in Section 2; results are presented in Sections 3 and 4, and conclusions are discussed in Section 5.

2. Model description

2.1. Mass loss due to fast spin rate

To study under what conditions particles may leave the Didymos surface, we considered the available radar-based Didymos shape model, made of 1000 vertices and 1996 facets (Naidu et al., 2020) (Future, updated work on this matter shall include the shape model of Didymos available after the DART mission). Test particles were initially assumed to be at rest at the geometric centre of each triangular facet. Particles size distribution follow a differential power law $n(r)dn \propto r^\kappa dr$, with index $\kappa = -3.5$. We sampled the following particle size range values: $r_1 = 4.7 \mu\text{m}$, $r_2 = 0.1 \text{ mm}$, $r_3 = 2.3 \text{ mm}$ and $r_4 = 5.3 \text{ cm}$. These are central values of the corresponding logarithmic size bins in which the overall size distribution is divided. In this way, we check particle behaviour from micron-size, very sensitive to solar radiation pressure, to cm-size – which are typical values for dust grains ejected from active asteroids (Moreno et al., 2019; Jewitt and Hsieh, 2022) – to multi-cm size, affected only by gravity. Particle density is assumed to be 3500 kg/m^3 , according to the L and LL meteorite analogue to the S spectral type of Didymos (Dunn et al., 2013).

In the case local acceleration is directed outwards, a particle will take off from the surface and will evolve under the gravitational field of Didymos, the gravitational perturbations generated by the secondary and the Sun, and the solar radiation pressure (SRP), according to the corresponding equation of motion. Under this scheme, at the end of a given integration time, we calculate the total mass of ejected particles at each end state. Based on the trajectories of particles, we defined four possible end states (ES): ES1, particles that lift off and land again on Didymos' surface; ES2, particles that remain in orbit; ES3, particles that are accreted onto the secondary; and ES4, particles that escape from the system (see Section 2.3 for details). We also estimate the mass density in the Didymos system environment as a function of colatitude, longitude, and distance from the surface of the primary.

2.2. Equation of motion

The equation of motion of a particle in a spinning reference system fixed to the primary body can be written as:

$$\frac{d^2 \mathbf{r}_d}{dt^2} = -\nabla U_p + W_2 \frac{\mathbf{r}_d - \mathbf{r}_{P\odot}}{\|\mathbf{r}_d - \mathbf{r}_{P\odot}\|^3} + W_3 \left[\frac{\mathbf{r}_{P\odot} - \mathbf{r}_d}{\|\mathbf{r}_{P\odot} - \mathbf{r}_d\|^3} - \frac{\mathbf{r}_{P\odot}}{r_{P\odot}^3} \right] + W_4 \left[\frac{\mathbf{r}_{dS}}{r_{dS}^3} - \frac{\mathbf{r}_{PS}}{r_{PS}^3} \right] + \boldsymbol{\omega} \times (\mathbf{r}_d \times \boldsymbol{\omega}) + 2\mathbf{v}_d \times \boldsymbol{\omega} \quad (2)$$

In that expression, bold characters are vectors, \mathbf{r}_d is the primary to particle position vector, $\mathbf{r}_{P\odot}$ is the primary to the Sun position vector, \mathbf{r}_{dS} is the position vector from the particle to the secondary, and \mathbf{r}_{PS} is the primary to the secondary position vector, as shown in Fig. 1. Here $\mathbf{r}_{P\odot} = \mathbf{r}_d + \mathbf{r}_{d\odot}$, where $\mathbf{r}_{d\odot}$ is the vector from the dust grain to the Sun. The first term of Eq. (2) corresponds to the gravitational field per unit mass of the polyhedral shape of the primary, corresponding to the definition in Werner (1994); the second term is the SRP contribution, where $W_2 = (Q_{pr}/c)[E_\odot/(4\pi)][\pi d^2/(4m_d)]$, the following terms are the solar and the secondary gravitational perturbations, for which: $W_3 = GM_\odot$ and $W_4 = GM_S$; the last two terms are the centripetal and Coriolis force, respectively. The Euler force can be neglected in this scheme because the spin change is an extremely slow process, lasting orders of magnitude longer than any other change in particle motion. Eventually, G is the gravitational constant, M_p is the primary mass, M_S is the secondary mass, M_\odot is the mass of the Sun, Q_{pr} is the efficiency of solar radiation pressure, which is $Q_{pr} \sim 1$ for large absorbing grains (Burns et al., 1979), c is the speed of light, $E_\odot = 3.93 \times 10^{26} \text{ W}$ is the total power radiated by the Sun, d is the particle diameter and m_d its mass: $m_d = \rho_d(\pi/6)d^3$, where ρ_d is particle density. $\boldsymbol{\omega}$ is the angular velocity of the primary ($\boldsymbol{\omega} = 2\pi/T$, where T is the rotational period) and \mathbf{v}_d is the velocity of the particle.

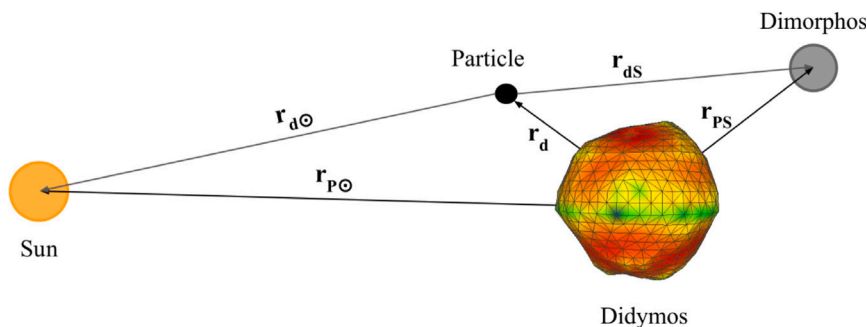


Fig. 1. Schematic illustration of the system with vectors entering Eq. (2).

2.3. Description of the algorithm

Eq. (2) is integrated numerically using a fourth-order Runge–Kutta method. The primary asteroid can be represented as a sphere or any polyhedral shape. In the first case, the surface of the primary is divided into a grid with N_θ colatitude (θ) bins and N_ϕ longitude (ϕ) bins; this grid is extended radially outwards into space with N_r radii (r) bins, forming a total of $N_\theta \times N_\phi \times N_r$ cells. At the beginning, each sample particle is located at the geometrical centre of each surface cell. In the second case, each sample particle is located at the geometrical centre of each triangular facet of the polyhedron, and the $N_\theta \times N_\phi \times N_r$ space grid is defined outside the body, from the point on the surface farthest from the centre of the body, r_F . The mass and particle density are computed in those cells.

To check the validity of the calculation, the primary asteroid was also modelled as a sphere, and the gravitational field of the corresponding homogeneous sphere was analytically calculated. In the general case, the gravitational field corresponding to the polyhedral model is computed following the guidelines given by Werner (1994) at each point in space. In both cases, a point-mass secondary body is assumed. Dimorphos follows a circular orbit on the equatorial plane of Didymos. Moreover, the position and orientation of the binary in the heliocentric ecliptic system are rigorously computed at each time step from its available ephemeris and system pole orientation. The position of the Sun, as seen from the primary, is also computed, and the shadow of the primary on the ejected particles is checked at each time step to set the SRP on each particle either on or off. The shadow produced by Dimorphos on Didymos is not taken into account, as it is less than 5% of the Didymos surface, smaller than other sources of uncertainty in the model. Particles are initially at rest on the surface. A detachment condition is applied to check whether any given particle has an outwards component of local acceleration, which depends strongly on the apparent centrifugal force in the rotating system of the primary. Detachment occurs when $\sum_i F_i \cdot n > 0$, where F_i stands for each force corresponding to the accelerations in Eq. (2), and n is the unit vector normal to the surface facet and directed outwards. Particles, once ejected from the surface of the primary, move in the gravitational field of the two bodies plus the radiation pressure and gravitational perturbing forces of the Sun.

Based on the trajectories of the particles, we define four final states:

- ES1, landing particles: particles with radial distance from the centre equal to or less than r_F , each particle is checked to be outside or inside the surface defined by the shape model. In the first case, the integration process continues, otherwise, the algorithm finds the intersection between the trajectory of the particle and the facet of the shape model. Collision coordinates are recorded, and the particle is labelled as ES1.
- ES2, orbiting particles: particles belong to this group if they are still in orbit at the end of the integration time.

- ES3, particles accreted on Dimorphos: during numerical integration, the position of each particle with respect to Dimorphos is checked at every time step. The gravitational field of Dimorphos is considered as a point-mass source. The case in which the distance between a particle and the position of Dimorphos is less than its equivalent radius, is considered as a collision, and the particle is labelled as ES3.
- ES4, escaping particles: particles located beyond 10^4 m from the centre of mass of Didymos belong to this group. Even if the Hill’s radius of the system is 75 km, the limit is set at 10 km distance from the centre of the system for practical reasons. This is a distance beyond which we found that only a negligible mass density contribution is missed from rare particles orbiting back from outer distance. In fact, mass density away from the primary, even at the Dimorphos distance, is extremely small, and the density profile keeps decreasing further away. This has the benefit of hugely reducing both the storage load and the computational cost with no effect on the mass density calculation.

Fig. 2 shows the surface gravity map of the Didymos shape model of a non-rotating Didymos, built using a mass of 5.229×10^{11} kg with homogeneous density. This is worked out considering that the overall size of Dimorphos is $D_S \approx 0.2 D_P$, and the relationship between masses is $M_S/M_P \sim 0.01$. The lowest gravity regions are clearly located on the equatorial bulge (blue–green colour in Fig. 2). Fig. 3 shows the effective acceleration on the surface of Didymos only at places where it has non-zero outwards component. We assessed the difference between the gravity field of Didymos, taking into account its shape model, against a sphere of equal mass and density, by calculating the radial gravitational field. Obviously, differences are found close to the surface (until approximately 570 m), but both fields converge at larger distances, as expected.

In our model, the difference between the spherical and the polyhedral shape of Didymos is in the definition of spatial cells. Due to the fact that the shape model represents an irregular surface, it is not possible to simply define a surface grid and extend it into space in a uniform way. Instead, we set the longitude and latitude grid to begin at the vertex of the triangular facet at the maximum distance to the centre (r_F). For the Didymos shape model, this spherical inner grid surface begins at $r_F = 427$ m, which is the smallest distance at which mass density outside the body is calculated. This is the minimum radial distance from which spatial density computation is performed. In other terms, this is the spherical surface from which the computation of the mass density is made outside Didymos. The drawback of this approach is that no information is available inside the tiny region in between the shape model surface and the beginning of the 3D grid.

As for the modelling of the shadow cone produced by Didymos, given the moderate depart of the asteroid shape from sphericity, for the sake of simplicity a profile corresponding to a sphere of radius r_F is assumed instead of the shape model itself. That approach has the advantage to save computing time, with a negligible impact on the volume of the projected shadow cone. In addition, in order to

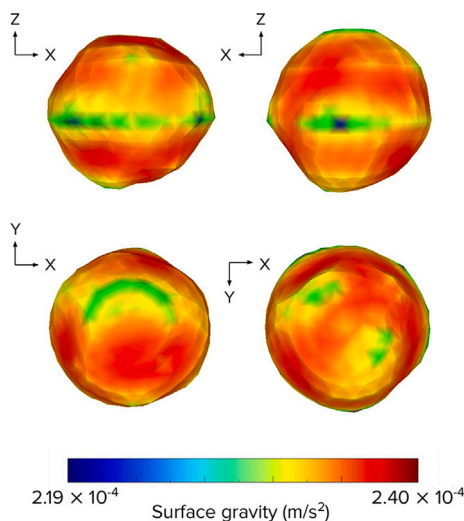


Fig. 2. Surface gravity on a non-rotating Didymos. Top left and right: view of both hemispheres. Bottom left and right: north and south polar region view, respectively. (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

save CPU time, the gravity field of the primary is approximated by its corresponding spherical field at $r > 550$ m, a distance at which the spherical and polyhedral solutions are very close. The relative error is less than 3% at that point, decreasing steadily at larger distance (see Fig. 5).

The code input data are the orbital and physical parameters of the system taken from the mentioned Hera Didymos Reference Model (ESA internal document). Further inputs are the perihelion epoch, the dates of start and end of integration, the integration time step used in the Runge–Kutta procedure, the mass loss rate, and particles properties, i.e., their radii, density and the exponent of their size frequency distribution (SFD). Other running parameters are also given: the number of particle size bins, which are conveniently spaced logarithmically to be consistent with the power-law distribution, the time intervals, the radius limit for mass density computation, and the escaping distance, i.e., the distance at which particles are considered to escape the system and no longer contribute to density in the considered space range. See Sections 2.3.1 and 2.3.2 for details.

2.3.1. Time integration procedure

When we look at the image of a comet tail, we need to keep in mind that particles were ejected from the comet surface at any time before the time at which the image was taken, let us call that time $t(\leq T_{obs})$. A similar situation can be envisioned in the case of Didymos ejected particles. The following numerical procedure for reproducing such a situation is applied.

Let us call T_{start} the time at which the programme checks, for the first time, the particle surface detachment condition at any given surface facet. The final T_{obs} time is instead the time at which the calculation of the particle mass and number density is made (in the analogy above, this corresponds to the time at which the observation of the system environment is made). The total integration time is $T_{obs} - T_{start}$, which is divided by the number of time intervals n_t , so that $\Delta t = (T_{obs} - T_{start})/n_t$ is the length of each time integration period. One sample particle of each size is located on every surface facet. At the beginning (T_{start}), the detachment condition for each particle size is checked, if this is met, the sample particle starts its motion under the action of the corresponding forces, by using a 4th-order R-K integrator, with an integration time step H (see Fig. 4). This is done for all particle sizes. Many different values for the R-K integration time step were

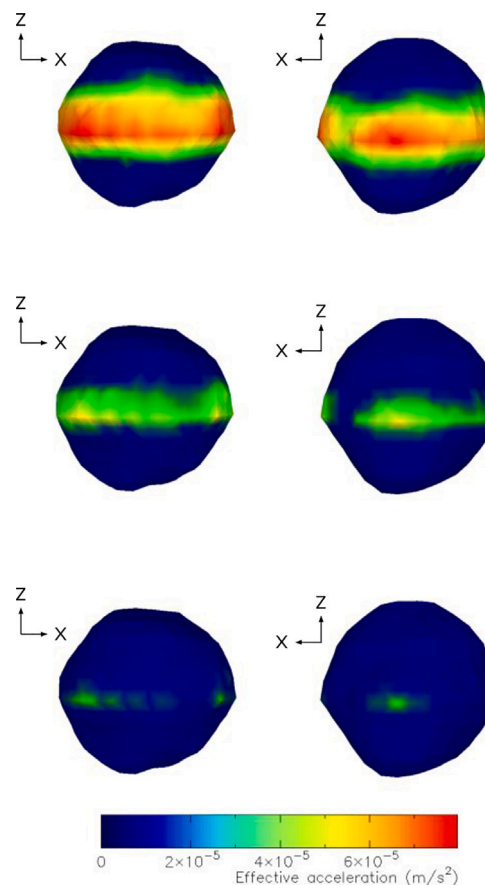


Fig. 3. Effective acceleration on Didymos surface (gravity plus apparent centrifugal force) for different Didymos bulk densities. Only acceleration with non-nil outward radial component is plotted. Top: low density case with 1813 kg/m^3 , same physical parameters as in simulation (M_2, V_6). Mid: nominal density case, 2104 kg/m^3 , same physical parameters as in simulation (M_4, V_4). Bottom: high density case, 2411 kg/m^3 , physical parameters as in simulation (M_7, V_3). The corresponding ratios of centripetal to gravitational acceleration at average equatorial radii ($a_c/g = \omega^2 r_{eq}^3 / (GM_p)$) are 1.29, 1.11, and 0.97, respectively. Notice that even in the (M_7, V_3) case, with average $a_c/g < 1$, equatorial surface irregularities may allow for lift-off locations.

tried, the value finally adopted corresponds to the largest one safely allowing for convergence in numerical integration. Once integration is over, that is, at $t = T_{obs}$, the same procedure is repeated at the initial time $T_{start} + \Delta t$ ($\Delta t \gg H$), and so on. This is necessary because we need to consider the evolution of particles potentially leaving their facet at all n_t equally spaced times between T_{start} and T_{obs} . The same process is carried out for all surface facets. In this way, the emission of sample particles is checked along the whole integration time. At time T_{obs} , the number of particles in orbit (ES2) is counted at each space cell. Instead, particles that hit the surface of the primary or the secondary (ES1, ES3), or reach the escape distance (ES4) at some time, do not contribute to space density (ES2), but their end state is recorded. At the end of the whole integration time for all surface facets, the data corresponding to the end-state of all sample particles are stored, as well as their position in space, and the mass density as a function of longitude, colatitude and radial distance from the centre of Didymos (see Fig. 8 and Fig. 9).

2.3.2. Mass density calculation

Once the end state of sample particles is known, it is necessary to compute the absolute mass at each end state. Therefore, we face the problem of how to translate sample particle statistics into the corresponding actual mass at each end state. First of all, we need to make assumptions on the mass emission rate; in addition, the mass and number of particles have to be scaled according to the adopted SFD.

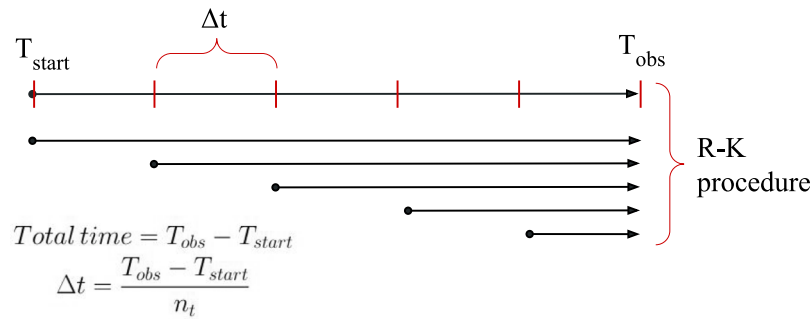


Fig. 4. Integration time scheme for a sample particle initially at any surface cell or facet. Each particle is integrated n_t times, starting at different times spaced by Δt . The corresponding Sun-Primary-Secondary orbit configuration is updated accordingly at all n_t times.

Active asteroids show a diversity of mass-loss mechanisms including sublimation, impacts, fast rotation, electrostatics, thermal effects, etc. Estimates of rotation mass shedding in fast spinning rubble-pile asteroids range from 10^{-7} kg/s, reported for asteroid (101 955) Bennu (Lauretta et al., 2019b,a; Hergenrother et al., 2019), to 2.3 kg/s (Hui et al., 2019), and 35 kg/s (Jewitt et al., 2019; Sanchez et al., 2019) in the case of (6478) Gault. Episodic mass loss ranging from 1 to 10 kg/s have been derived for multi-tailed asteroid P/2013 P5 (PANSTARRS) (Moreno et al., 2014), which can be clearly attributed to mass shedding due to rotational instability (Jewitt et al., 2015). To date, no observation of this kind of activity has been reported for Didymos, so this parameter is unknown. For this reason, we considered a constant reference value of mass production rate for Didymos, that was set arbitrarily to $dM/dt = 1$ kg/s for the whole asteroid. A suitable fraction of such value is used only for cells for which the lift-off condition is met, no particle will meet the lift-off condition at most surface cells far from the equator though. The contribution of ejected particles to the mass and number density in each space cell is computed as follows. The mass ejected per unit surface area is calculated as $(dM/dt)/(4\pi R_p^2)$, where dM/dt is the assumed mass production rate on the whole surface, R_p is the Didymos radius, and the mass ejected per surface cell in a time interval $\Delta t'$ is:

$$M_{cell} = \frac{1}{4\pi R_p^2} \frac{dM}{dt} S_{cell} \Delta t' \quad (3)$$

where S_{cell} is the area of the surface cell. The total mass is distributed according to the already mentioned SFD in the radius range $[r_{min}, r_{max}]$. In a given size bin $[r_i, r_j]$ within such range, the number of particles ejected from each cell in a given time interval is:

$$N_{bin} = M_{cell} \frac{3}{4} \frac{1}{\pi \rho_{particle}} \frac{\int_{r_i}^{r_j} r^{\kappa} dr}{\int_{r_{min}}^{r_{max}} r^{\kappa+3} dr} \quad (4)$$

and the corresponding emitted mass is:

$$M_{bin} = N_{bin} \frac{4}{3} \pi \rho_{particle} \frac{\int_{r_i}^{r_j} r^{\kappa+3} dr}{\int_{r_i}^{r_j} r^{\kappa} dr} \quad (5)$$

The mass and the number of particles are updated accordingly in every space cell where sample particles are located at the end of integration. The mass and number of particles are finally divided by the cell volume to get the corresponding mass and number density.

2.4. Model validation

In order to check the validity of our model when applied to the polyhedral representation of solid bodies, we compared the results obtained for the dynamical evolution of particles departing from analytical and polyhedral representations of a spherical body made of 5120 facets (see Fig. 5). In both cases, the same mass and equivalent size of Didymos were used, $M_p = 5.229 \times 10^{11}$ kg and $R = 400$ m, respectively. The density profiles are in very good agreement even at small distances from the body surface. Simulations were run over 30 days.

3. Summary of model simulations

The current Didymos system physical parameters are known with wide uncertainties (see Section 1). For this reason, we first mapped the mass-volume parameter space and related each pair of values with the corresponding total orbiting mass obtained by our model. Then, we focused on the nominal parameters for the Didymos mass and size and we performed a detailed analysis of the particle detachment and landing process by means of numerical simulations. The wide heliocentric distance of the Didymos system – due to its high eccentricity – led us to study the particle behaviour around very different locations (perihelion and aphelion) of the system, and under the corresponding initial epoch conditions, in the case of full orbit integrations. The whole set of simulations carried out is outlined next.

- Simulation 1: Conditions for mass lift-off. The first goal is to study under what conditions it is possible to find mass around the primary. Thus, we combined 7 values of each mass and volume parameters of Didymos within estimated uncertainty. That resulted in 49 numerical runs, one per each corresponding value of bulk density (see Table 3). We let the system evolve during 30 days, near the perihelion epoch, starting on August 28, 2020, ending on September 26, 2020. Performing simulation runs around perihelion is the worst case for particle survival, as SRP is more efficient in perturbing their motion and taking particles away from the system.
- Simulation 2: Evolution in one full orbit (starting at perihelion). Here we used the nominal mass and volume of Didymos, setting the corresponding nominal bulk density. The simulation was run over a full heliocentric orbit of Didymos (770 days), starting and ending around the perihelion epoch (from August 28, 2020 to October 7, 2022). The behaviour of small (r_1 , r_2 and r_3) and large (r_4) particles were analysed separately to study the effect of the SRP.
- Simulation 3: Evolution in one full orbit (starting at aphelion). We used the same physical parameters as in Simulation 2, but the simulation was run over a full heliocentric orbit of Didymos (770 days), starting and ending around the aphelion epoch (from September 15, 2021 to October 25, 2023). Again, the analysis of small and large particles was done separately.
- Simulation 4: Short term evolution around perihelion. By using the nominal mass and volume of the Didymos primary, the system evolved over 30 days around the perihelion epoch, starting on August 28, 2020 and ending on September 26, 2020.
- Simulation 5: Short term evolution around aphelion. Analogous to Simulation 4, but over 30 days around the aphelion epoch, starting on September 15, 2021 and ending on October 15, 2021.

We run short term (30 days) simulations to be able to catch the main features of the orbiting mass for the whole set of 49 runs in

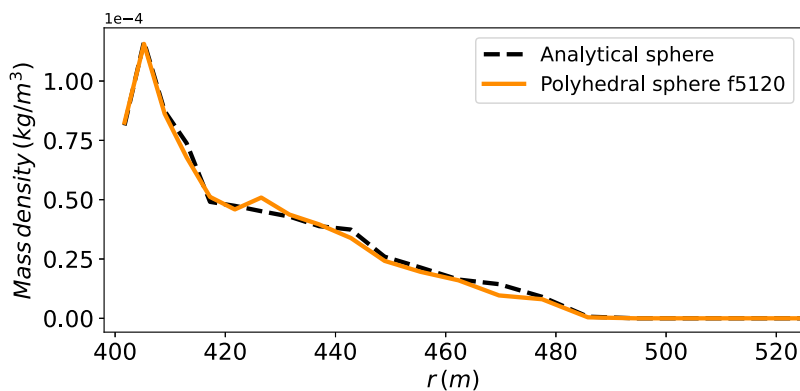


Fig. 5. Comparison between radial mass density distributions for the analytical and polyhedral (5120 facets) representation of a sphere.

Table 2

Orbital parameters of the Didymos system used in the simulations.

Source: Didymos Reference Model, ESA.

Didymos system		
Semimajor axis	1.6444327821	au
Eccentricity	0.38393203178	-
Inclination	3.40808504153	deg
Argument of perihelion	319.245071345	deg
Longitude of ascending node	73.2392391311	deg
Perihelion epoch	11.6146/9/2020	dd/mm/yyyy
Dimorphos secondary orbit		
Semimajor axis	1190	m
Orbital period	11.9216	h

Table 3

Input values in Simulation 1. Different Didymos bulk densities are obtained combining mass and volume values.

Mass ($\times 10^{11}$ kg)						
M_1	M_2	M_3	M_4	M_5	M_6	M_7
4.687	4.867	5.048	5.229	5.409	5.590	5.771
Volume ($\times 10^8$ m ³)						
V_1	V_2	V_3	V_4	V_5	V_6	V_7
2.209	2.301	2.393	2.485	2.584	2.684	2.783

Simulation 1 and to underline (Simulations 4 and 5) the dependence of the outcome for small particles on the observation epoch. This choice, in the case of Simulation 1, was motivated, on one hand, by the fact that full orbit simulations are very time consuming. On the other hand, the behaviour of particles – as far as mass distribution is concerned – does not change around a given epoch, beyond some 20 days. Therefore, we considered a safe strategy to perform 30-day runs around the least favourable epoch for particle survival.

Orbital parameters used in simulations are shown in Table 2. Table 3 summarizes the volume and mass parameter space ranges, and the system physical parameters are introduced in Table 4.

4. Results

4.1. Conditions for mass lift-off (Simulation 1)

In Fig. 6, each square gives the orbiting mass at the end of each simulation after 30 days around perihelion, normalized to the maximum orbiting mass value. The central cross corresponds to the nominal case, which will be analysed further in the next sections (Simulations 2 to 5). Particle detachment takes place at the nominal spin rate for most values in the chosen Didymos physical parameter space, except for three parameter combinations (see Table 3).

Table 4

Set of input parameter values for the Didymos system in Simulation 2 to 5. Nominal mass and volume correspond to the (M_4 , V_4) set in Table 3.

Parameter	Value	Units
Didymos rotation period	2.26	h
Didymos mass	5.229×10^{11}	kg
Didymos volume	2.48548175×10^8	m ³
Didymos density	2104	kg/m ³
Dimorphos diameter	164.0	m
$N_r \times N_\theta \times N_\phi$	$50 \times 36 \times 36$	-
Δt	10.0	min
Time integration step (H)	100	s
Distance for mass density computation	$[r_F, 1500]$	m
Escaping distance for ES4	1×10^4	m

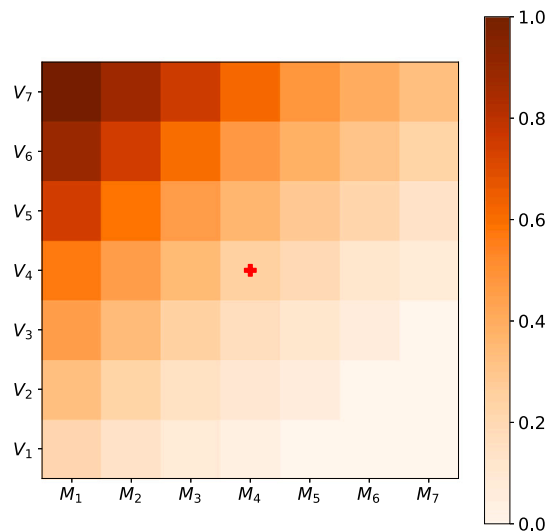


Fig. 6. Results of Simulation 1. M_i and V_j are input values for the modelled mass and volume of Didymos. Each square represents the spatial mass corresponding to different (M_i , V_j) sets (see Table 3). The colour bar shows the output orbiting mass normalized to the maximum value, in the case the evolution is followed during 30 days around perihelion. The red cross stands for the nominal bulk density. Simulations corresponding to (M_6 , V_1), (M_7 , V_1) and (M_7 , V_2) result in no mass in orbit at perihelion. (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

4.2. Particle evolution after one full orbit (Simulations 2 and 3)

In Simulations 2 and 3, we analyse particle end states after they leave the surface and the corresponding lifetimes (Table 5). Depending on size, more than 97% of particles fall back onto the surface of the primary (ES1). The time required to land back also depends on particle

Table 5

Percentage of particles in each end-state (ES) and corresponding median life time (t_l). $r_1 = 4.7 \mu\text{m}$, $r_2 = 0.1 \text{ mm}$, $r_3 = 2.36 \text{ mm}$ and $r_4 = 5.3 \text{ cm}$.

		ES1 (%)	t_l (h)	ES2 (%)	t_l (h)	ES3 (%)	t_l (h)	ES4 (%)	t_l (h)
Simulation 2	r_1	97.114	0.81	0.002	3.55	0.070	2.61	2.814	6.28
	r_2	99.975	3.14	0.009	2.65	0.014	3.94	0.002	37.2
	r_3	98.682	3.83	0.066	45.5	1.190	81.4	0.062	152
	r_4	97.383	4.44	0.181	99.9	2.206	102	0.230	604
Simulation 3	r_1	97.120	0.81	0.001	2.37	0.071	2.58	2.808	6.28
	r_2	99.964	3.14	0.021	5.57	0.013	3.92	0.002	38.6
	r_3	98.628	3.83	0.134	73.9	1.175	81.4	0.063	147
	r_4	97.376	4.47	0.184	102	2.214	101	0.226	586

size. In general, for any ES, the larger the particle, the longer its lifetime. Particles of radius r_1 spend on average 0.81 h orbiting the asteroid before landing on its surface, while particles r_4 may orbit more than 4 h before landing. In addition, as expected, most particles that escape the system (ES4) correspond to size r_1 . However, that end state probability is only 2.814%. When such particles pass from the shadow cone generated by the asteroid to the illuminated region, they are quickly removed from the system, typically after 6 hours. On the contrary, a small fraction of r_2 , r_3 and r_4 size particles are eliminated, and they are able to survive in the environment of the asteroid between 37 and 600 h, before they are removed. Instead, particles that are accreted onto the secondary (ES3) are mostly r_4 , followed by r_3 . Such particles stay in orbit for some 100 and 81 h, respectively, before reaching Dimorphos. r_1 and r_2 particles have lower probabilities of reaching the moonlet, taking 2.5 to 4 h, driven by SRP. At the end of the integration time, there are mostly large particles orbiting the system. r_3 size particles are able to stay in orbit about 46 h in Simulation 2 and 74 h in Simulation 3, and this difference is related to still some weak interaction with SRP at such size range. On the other hand, r_4 particles have a median lifetime in orbit of ~ 100 hours and no influence of the SRP is detectable any longer.

These results can be easily understood by comparing the effect of the gravitational force (F_g) due to Didymos on any given particle, with respect to the corresponding solar radiation force (F_{rad}), as a function of the distance to the centre of the asteroid (a):

$$\frac{F_g}{F_{rad}} = \frac{4}{3} \frac{GM_p c \rho_d \frac{d}{2}}{Q_{pr} F_\odot} \frac{1}{a^2} \quad (6)$$

$F_\odot = E_\odot/4\pi a^2$ is the solar flux at the heliocentric distance of the asteroid system, and the other parameters are the same as in Section 2.2. The ratio between the two force contributions is plotted in Fig. 7. A horizontal gray line divides the distance to Didymos into two regimes, one is dominated by gravity and the other one by solar radiation force. The gray vertical line shows the distance to Dimorphos and the coloured curves represent the relationship between the two mentioned forces for different particle sizes. Solid and dashed curves correspond to motion around perihelion and aphelion, respectively. Particles of size r_1 evolve almost completely under the action of SRP, whereas particles of size r_2 are affected by both SRP and F_g . Instead, motion of particles of size r_3 and r_4 are dominated by the gravity force. That implies that there is no smooth transition between the behaviour of particles of size r_1 and r_3 and the corresponding mean lifetimes in ES2. Lifetimes are shorter around perihelion (Simulation 2) than around aphelion (Simulation 3) due to different SRP force acting on them. These results are comparable with the work by Ferrari and Tanga (2022). They also show that, in such low-gravity environment, SRP plays an important role in the dynamics of small dust grains. Instead, particles larger than a few millimetres are mostly affected by the Didymos gravitational force within the orbit of Dimorphos.

4.3. Density distribution of orbiting mass

4.3.1. Small particles

Here, we focus on the analysis of the behaviour of small particles (r_1 , r_2 and r_3) that are in ES2 at the end of Simulations 2, 3, 4 and 5. Mass density profiles as a function of radial distance from the centre of the primary are shown in Fig. 8 (top). This is obtained by integrating on cells in colatitude and longitude at any given radial distance. Plots begin at $r_F = 427 \text{ m}$, the origin of spatial cells. In density profiles, maxima are found at $r \sim 475 \text{ m}$ in the case of Simulations 2 and 4, at $r \sim 481 \text{ m}$ in Simulation 3, and at $r \sim 458 \text{ m}$ in Simulation 5. Therefore, the largest mass density of orbiting particles is 31 to 54 metres above the mentioned reference distance from the centre, r_F . Beyond such distance, mass density steadily decreases, as expected. As a result, orbiting mass density in simulation runs around perihelion (Simulation 4) is smaller than for the corresponding simulation around aphelion (Simulation 5). This is due to the strong influence of SRP on small particles. The outcome of density profiles for 30 days integration time are very similar to those obtained integrating over a full orbit of the system around the Sun. This is the case both for perihelion and aphelion epoch starting time. Therefore, the amount of small particles in the system environment at a given time strongly depends on the epoch at which the mass density observation is made.

The colatitude density profile (See Fig. 8, bottom), together with the radial density profile, show that orbiting particles are mostly located in a thin disk, with maximum density on the equatorial plane. However, the disk is not symmetrical at north and south of the equator due to Didymos topographical shape model inhomogeneities. On the northern hemisphere, landing location is spread over 25 degrees, between 65° and 90° colatitude, while, on the southern hemisphere, the distribution extends up to 30 degrees, between 90° and 120° colatitude. The density mass difference between observation about perihelion and aphelion is also shown in the colatitude density profile (Fig. 8, bottom).

The analysis of particle motion and mass density shows that although most ejected particles return to the surface of the primary with short orbit lifetimes (a few hours), a continuous lift-off process supplies them into space.

4.3.2. Large particles

This section extends the analysis of results including particles of radius r_4 , not affected by SRP. Fig. 9 shows the corresponding radial and colatitude mass distributions. This also applies to any object of size larger than r_4 , as they are essentially affected only by gravitational and non-inertial force terms.

When large particles are considered, there is no substantial difference in orbital mass density at aphelion with respect to perihelion, although the radial density profile at aphelion (Simulation 5) is slightly larger than the corresponding density at perihelion (Simulation 4) over the whole considered domain. Large particles are the greatest contributors to orbiting mass density, which is equal around both epochs. Instead, small particles contribute more at aphelion than at perihelion, building up the very small difference between densities observed around the two different epochs (see Fig. 9). The disc-like distribution of particles in orbit at a given time is shown in Fig. 10, in the case of Simulation 4.

It is interesting to notice that the probability ($p_2(r)$) for small particles to have orbital end state (ES2) is smaller as size decreases (see Table 5). Similarly, duration of orbits is shorter for small particles with respect to large ones ($\delta t_2(r)$, normalized). Both effects combine in the size frequency distribution of particles found to be in orbit at a given time, that can be described as $n_o(r)dn = n(r)dn p_2(r) \delta t_2(r) dr \propto r^{-3.5} p_2(r) \delta t_2(r) dr \propto r^{\kappa_o} dr$, with $\kappa_o \approx -3$. In summary, the SFD of particles observed in orbit (ES2) looks to be shallower than the original asteroid surface population assumption ($\kappa = -3.5$), and is therefore skewed towards large particles.

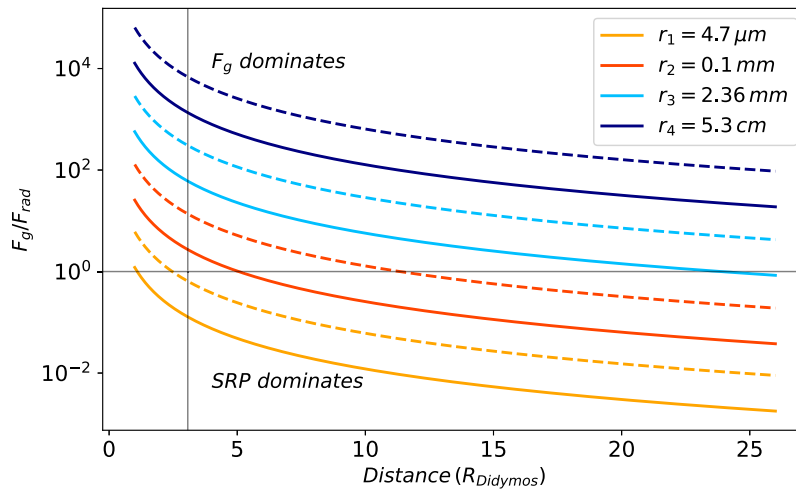


Fig. 7. Ratio between the gravitational force of Didymos (F_g) and the solar radiation force (F_{rad}) acting on particles, as a function of the distance to the centre of the asteroid. The horizontal gray line divides space into two regimes, one is dominated by gravity and the other one by SRP force. The gray vertical line indicates the distance to Dimorphos. Coloured curves represent different particle sizes. Solid and dashed curves correspond to motion around perihelion and aphelion, respectively. (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

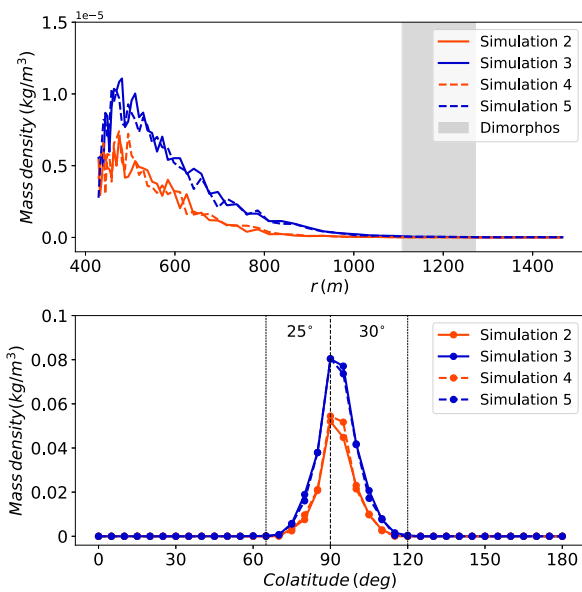


Fig. 8. Density profiles of mass in orbit around Didymos corresponding to small particles: r_1 , r_2 and r_3 . Top: radial profile after one full heliocentric orbit (Simulations 2 and 3), and after 30 days around perihelion and aphelion epochs (Simulations 4 and 5). The gray area corresponds to Dimorphos extents. Bottom: mass density profile as a function of colatitude for Simulations 2, 3, 4 and 5. Simulations outcome correspond to the assumed overall value for mass ejection rate (1 kg/s).

4.4. Distribution of landing particles

Fig. 11 shows – for Simulation 5, as an example – a mass density colour map distribution of the initial position of particles that are able to lift off the surface. At the beginning of any run, particles lie at the geometrical centre of the shape model triangular facets, hence a discrete distribution appears in Fig. 11. The detachment area surrounds the equatorial plane, but it is not symmetrical with respect to it. The maximum detachment latitudes to the north and to the south of the equator are $\theta_N \sim 28^\circ$ and $\theta_S \sim 19^\circ$, respectively, in all the cases, in both Simulations 2 to 5. After detachment, most lifted particles (more than 97%) land back on the surface of the primary. Fig. 12

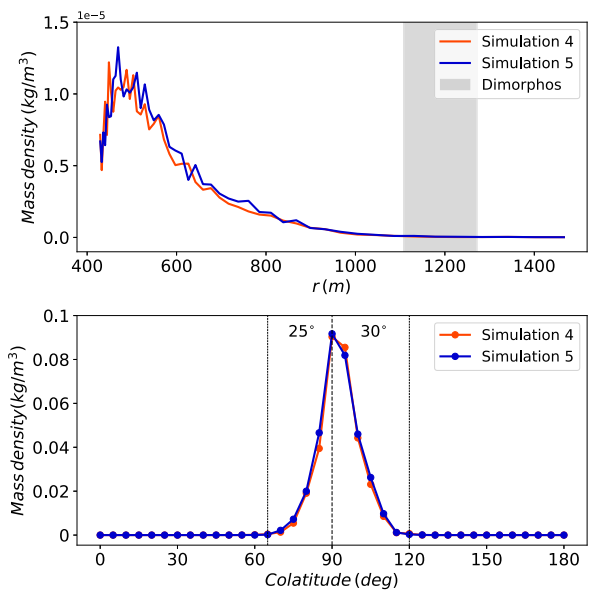


Fig. 9. Density profiles of mass in orbit around Didymos, including small particles, r_1 , r_2 , r_3 , and large particles, r_4 . Top: radial profile after 30 days around perihelion (Simulations 4) and aphelion (Simulations 5). The gray area corresponds to Dimorphos extents. Bottom: mass density profile regarding colatitude.

(bottom) shows landing locations after 30 days of evolution. During this time, the gravitational field of Didymos, the gravitational perturbation of the Sun and Dimorphos, and the SRP, modify particle trajectories, increasing their orbital inclination and allowing them to reach mid and high landing latitudes, typically higher than detachment positions. The colour map shows that the density distribution peak in colatitude lies near the equatorial plane. It is important to note that particles landing at low latitudes can likely leave the surface again. Indeed, such particles are a reservoir for later material ejection. Instead, particles falling at mid and high latitudes would not be dynamically able to lift off again from their new location.

However, mass sliding mechanism towards low latitudes are known to have taken place on asteroids Bennu and Ryugu (Sabuwala et al.,

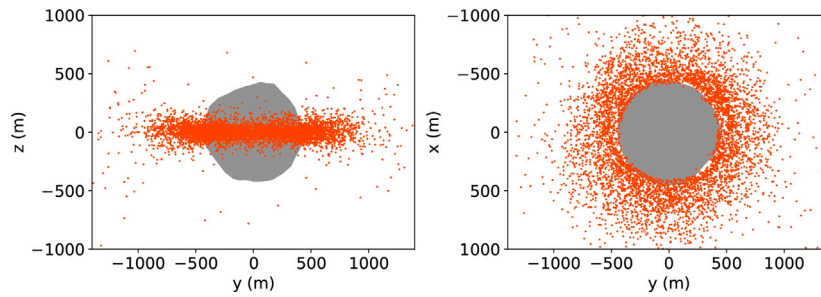


Fig. 10. Side and polar view snapshots of orbiting particles around Didymos at the end of Simulation 4. Particles of all sizes are included. All particles are represented by not-to-scale dots.

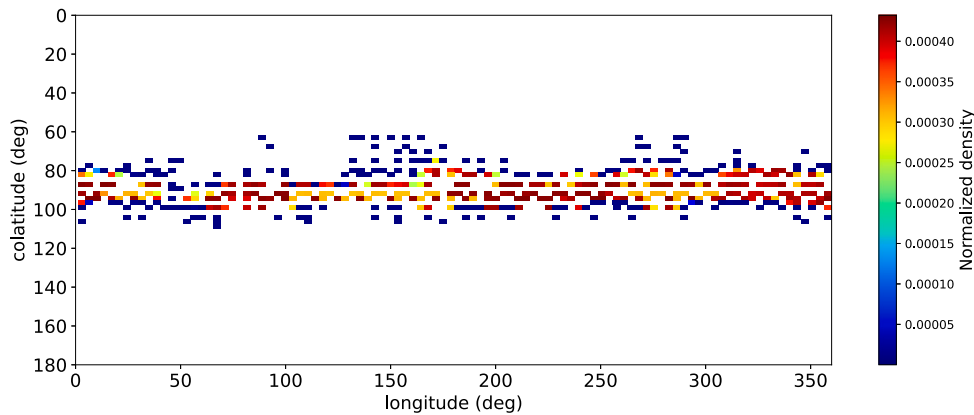


Fig. 11. Initial position of lifted particles on the Didymos surface. At the beginning, the position corresponds to the geometrical centre of each triangular facet. The plot corresponds to Simulation 3. (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

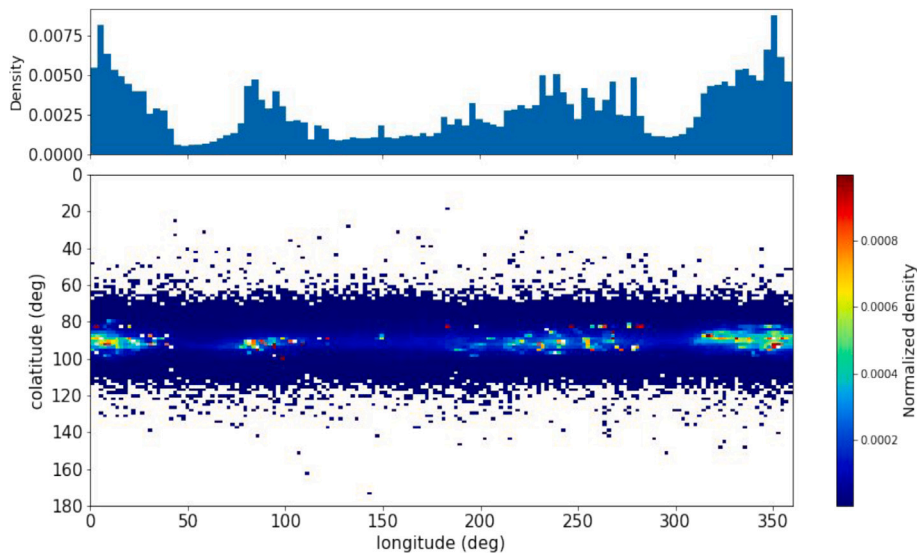


Fig. 12. Final particle landing sites on the Didymos surface. Top: landing distribution in longitude. Bottom: colour map with the landing positions in longitude and colatitude. The plot corresponds to Simulation 3. (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

2021), such effect may drive mass back to the equatorial region, re-fuelling the take off and landing process. Fig. 12 (top) shows non-homogeneous landing distribution in longitude. This behaviour is related to the topography of the asteroid in the equatorial region. Particles flight heights are low, so lifted-particles preferentially land on relatively high terrains around the equator.

5. Discussion and conclusions

Primary fast spin up in NEA binary systems is relatively common. We study the possibility that mass is able to take off the surface of such bodies, taking (65803) Didymos NEA binary system as a study case because it is the DART (NASA) and Hera (ESA) space missions

target. The latest available shape model for the asteroid at the time of carrying on this study was used. We set up a model to study the dynamical behaviour of the particles that are able to take off the surface due to the primary fast spin. The gravitational field of the asteroid is taken into account, together with all non-inertial forces in the asteroid rotating frame. Perturbations due to the satellite, Dimorphos, and the Sun are suitably considered, as well as SRP.

We explored the Didymos primary mass and volume parameter space to assess under what asteroid density conditions particle detachment from the surface is possible. We find that most values in that parameter space allow for particle lift-off. In the nominal case, that is possible in a region limited to the $(+28^\circ, -19^\circ)$ latitude interval around the equatorial plane, non-symmetric due to the primary irregular shape. Available range of mass and volume estimates is compatible with the possibility of having a disk of particles of different sizes around Didymos. The actual mass density is hard to predict as the rate of mass emission is unknown. Nevertheless, our model finds the mass distributions in colatitude and distance from the asteroid according to assumed parameters. Maximum values for the mass density distribution show up at very low latitudes and at some 30 to 50 m away from the average primary equatorial radius, decreasing steadily at larger distance.

Most lifted particles ($>97\%$) do land back on the surface, with variable lifetimes depending on size, but typically smaller than 5 h. Small particles have shorter lifetimes than large ones because of SRP. In fact, when small particles take off on the day side of the asteroid, they are quickly pushed back to the surface, and their flight time is shorter the stronger the SRP is. When such particles take off in the night side, they follow ballistic trajectories until they typically land back or, in the case they reach the terminator, they are pushed away from the system by SRP. Particle landing locations are not evenly distributed in longitude, concentrating instead in equatorial morphology highs. This is because most particles only reach low altitudes with respect to their original take off location, and they eventually stumble into such highs on their flight path. It is interesting to notice that the latitude landing range distribution is wider than that of lift-off distribution location. As a consequence, some particles may land at latitudes from which they can no longer take off.

SRP has an important effect on small particle dynamics, to the point that, for such particles, mass density in space happens to be a function of the orbital phase at which it is observed (T_{obs}). Didymos has a very eccentric orbit, such that heliocentric distance changes from 1.013 to 2.276 au. This results in very different contributions from the solar tide and SRP at different distance from the Sun. Total mass surrounding Didymos at aphelion is more than double ($\approx 9/4$) than at perihelion for sub-cm size particles. Instead, looking at the overall mass in orbit, including large particles – not affected by SRP – no significant difference is found, due to the contribution of large particles to total mass. The size distribution of particles in orbit looks shallower ($\kappa \approx -3$) than their size distribution on the asteroid ($\kappa = -3.5$) due to smaller probability and lifetime in orbit of small particles with respect to large ones.

In conclusion, our model shows that the presence of mass in orbit around Didymos, or similarly shaped fast spinning NEAs, is possible. That includes the potential presence of boulders around the system, that may eventually reach the secondary ($\approx 2\%$ probability) at this stage. In any case, as outlined in Section 1.3, the existence and observability of mass around the system may depend on which primary rotational phase and which secondary orbital phase Didymos is undergoing at the time of observation, according to the mechanism described by Fahnestock and Scheeres (2009).

Right after the completion of this study, the DART spacecraft successfully impacted Dimorphos, and first results derived from the images of both the DRACO camera on board DART and the LEIA and LUKE cameras on board the CubeSat LICIAcube (ASI: Agenzia Spaziale Italiana) have been published (Daly et al., 2023). Daly et al. (2023) report a

set of freshly estimated values for the critical parameters in this study: the mass of the system, $(5.6 \pm 0.5) \times 10^{11}$ kg; the equatorial extents, 850 ± 5 m on average; the equivalent diameter of both Didymos, 761 ± 26 m, and Dimorphos, 151 ± 5 m (uncertainties are given at $1 - \sigma$ level). Therefore, the mass of Didymos can also be easily estimated, assuming equal density for the two bodies. We are conscious that the Didymos shape model is preliminary, however, such set of parameters tends to confirm the possibility of mass lift-off from the equatorial region of Didymos. In fact, even in the worst case compatible with available uncertainty ranges (largest system mass, smallest Dimorphos equivalent diameter, largest Didymos equivalent diameter, and smallest Didymos equatorial extent), the ratio between the centripetal and gravitational acceleration at the equator, $a_c/g = \omega^2 r_{eq}^3 / (GM_p)$ is larger than 1 (1.07), indicating outwards acceleration. a_c/g is the driving magnitude here (rather than density), where ω is the spin rate and r_{eq} is the equatorial radius of Didymos. The nominal values from Daly et al. (2023) give $a_c/g = 1.235$, which is very close to the (M_1, V_4) set, providing more mass in orbit than our nominal case. $a_c/g = 1$ for $r'_{eq} = 396$ m, which is the minimum distance from the spin axis at which lift-off is possible, some 30 m smaller than the estimated equatorial radius extent.

It is interesting to notice that the estimated bulk density is reported as 2400 ± 300 kg/m³, a value that would inhibit mass shedding on a sphere spinning at the Didymos spin rate. The bulk density of a body is the critical parameter only in the case in which its shape is fixed. Comparing a sphere with an equal mass oblate spheroid with equatorial axis a and shortest axis c , the corresponding critical spin rate is

$$\omega'_{cr} = \sqrt{\frac{4\pi G \rho' c}{3 a}} \quad (7)$$

At equal critical spin rate, the relationship between the density of the oblate shaped and the spherical body is $\rho'/\rho = a/c$. E.g., for an oblate body with $a/c = 1.37$ (the case of Didymos, as its extent along spin axis is estimated to be 620 ± 15 m by Daly et al. (2023)), the critical density is $\rho' = 2924$ kg/m³, while, for an equal mass spherical Didymos, it would be $\rho = 2134$ kg/m³.

Indications of the presence of dust around Didymos can be envisioned by looking at the LICIAcube images. However, we prefer to avoid speculation at this point, and we delay further interpretation to a forthcoming companion paper. Once further estimate improvement of the main physical parameters and an updated Didymos shape model – pre-Hera mission – will be available, a refined model will be carried out on the “real” Didymos system.

We also plan to study the interplay between mass ejected from Dimorphos by the DART impact and the stationary mass distribution around the system — if any. In fact, that may potentially affect the actual mass density to be estimated by the Hera rendezvous with the Didymos system in 2027 and the calibration of instrumentation on board.

Declaration of competing interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

Data availability

Data will be made available on request.

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