A CMB lensing analysis of the extended mass distribution of clusters

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ABSTRACT

The aim of this work is to study the anisotropic weak lensing signal associated with the mass distribution of massive clusters of galaxies using the cosmic microwave background (CMB) data. For this purpose, we stack patches of the Planck Collaboration (2018) CMB lensing convergence map centred on SDSS DR8 redMaPPer clusters within the redshift range [0.4, 0.5]. We obtain mean radial profiles of the convergence parameter *κ* finding strong signals at scales as large as 40 Mpc*h*−1. By orienting the clusters along their major axis defined through the galaxy member distribution, we find a significant difference between the parallel and perpendicular-oriented convergence profiles. The amplitude of the profile along the parallel direction is about 50 per cent larger than that along the perpendicular direction, indicating that the clusters are well aligned with the surrounding mass distribution. From a model with an anisotropic surface mass density, we obtain a suitable agreement for both mass and ellipticities of clusters compared to results derived from weak lensing shear estimates, finding strong evidence of the correlation between the galaxy cluster member distribution and the large-scale mass distribution.

Key words: gravitational lensing: weak – methods: data analysis – galaxies: clusters: general – Cosmic background radiation – large-scale structure of Universe.

1 INTRODUCTION

Cluster masses have been widely used to restrict cosmological parameters (Burenin & Vikhlinin [2012;](#page-7-0) Cusworth et al. [2014\)](#page-7-0). In fact, the abundance of clusters above a given massthreshold provides a powerful constrain in Ω_M and σ_8 parameters (e.g. Abdullah et al. [2022;](#page-7-0) Lesci et al. [2022\)](#page-7-0).

Among the different methods to infer cluster masses, weak lensing techniques give reliable estimations since they are less affected by the dynamical state of the clusters (McClintock et al. [2019;](#page-7-0) Murray et al. [2022\)](#page-7-0). Besides, unlike other techniques such as those based on X-ray measurements, the weak lensing method has the advantage of being unaffected by astrophysical sources in the clusters that could bias estimates.

In numerical simulations, clusters show triaxial shapes (Herbonnet et al. [2022\)](#page-7-0), elongated mainly due to the anisotropic large-scale structure and the related accretion process. For this reason, to accurately reproduce the measured density distribution, a two halo anisotropic term must be included (Gonzalez et al. [2022\)](#page-7-0). On the observational side, however, cluster shapes can be only obtained in projection through different tracers such as the member galaxy

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distribution, intracluster light, X-rays hot emitting gas, and weak lensing. Previous weak lensing studies based on shear measurements (Clampitt & Jain [2016;](#page-7-0) van Uitert et al. [2017;](#page-7-0) Shin et al. [2018;](#page-7-0) Gonzalez et al. [2021\)](#page-7-0) have added evidence for cluster haloes with an average ellipticity parameter $\epsilon = \frac{1-q}{1+q} \sim 0.2$, where *q* is the semiaxes relation, $q \leq 1$. These studies are mainly focused on the analysis of the shape of the cluster halo host, neglecting the contribution of the extended mass distribution. On the other hand, related with the surrounding mass distribution in galaxy clusters, Geller et al. [\(2013\)](#page-7-0), Fong et al. [\(2018\)](#page-7-0), and Shin et al. [\(2021\)](#page-7-0) have analysed the expected lensing signal at intermediate scales without fitting the expected elongation at these regions. In this sense, the cosmic microwave background (CMB) lensing signal can be useful to explore the surrounding mass distribution given its large angular extension.

In this paper, we study the convergence map derived from the Planck 2018 lensing data (Planck Collaboration [2020a\)](#page-7-0) around massive clusters of the SDSS DR8 redMaPPer catalogue (Rykoff et al. [2016\)](#page-7-0). This catalogue provides an homogeneously selected sample of massive clusters $M \gtrsim 10^{14} M_{\odot}$, suitable for our analysis. We explore the anisotropies imprinted in the CMB convergence map due to the elongation of the extended surface mass distribution, by orientating the maps taking into account the positions of the cluster galaxy members. In this way, we study the anisotropies of the mass distribution beyond the virial region, in close relation to the largescale structure. Geach & Peacock [\(2017\)](#page-7-0) also study the redMaPPer clusters catalogue using the Planck 2018 lensing data. Unlike the

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present work, the authors analyse smaller CMB reprojected regions of 1◦ around the position of each cluster onto a tangential sky projection with a high-resolution scale of 256 pixels per degree. For this reason, it is observed only a significant signal in the cluster centre neighbourhood, up to ¹⁰ arcmin or around [∼]³ Mpc*h*−1. Here, we focus on a large-scale study with the aim of analysing extended anisotropic mass distribution around clusters.

The paper is organized as follows: in Section 2, we detail the data of the CMB lensing map and the cluster catalogue. In Section [3,](#page-2-0) we analyse the mean convergence profiles. In Section [4,](#page-4-0) we describe an anisotropic model that allows us to trace the extended mass distribution and also explore mean masses and ellipticities of the systems. Finally, in Section [5,](#page-6-0) we present a brief summary and discussion of our studies.

2 DATA

2.1 CMB convergence map

In the thin lens approximation (see for instance Meneghetti [2022,](#page-7-0) and references therein), the Laplacian of the effective lens potential in the lens plane takes the form:

$$
\hat{\Psi}(\vec{\theta}) = \frac{2D_{LS}}{c^2 D_L D_S} \int \Phi(D_L, \vec{\theta}, z) dz
$$
\n(1)

where Φ is the tri-dimensional Newtonian potential defined at a given position in the lens plane, θ , and at redshift *z*. D_L , D_S , and *DLS* are the angular diameter distances from the observer to the lens, from the observer to the source, and from the lens to the source, respectively, involved in the lens system. The adimensional convergence parameter κ is proportional to the effective lens potential by:

$$
\Delta_x \Psi(\vec{x}) = 2\kappa(\vec{x}) \tag{2}
$$

which is related to the surface mass density through

$$
\kappa(\vec{x}) = \frac{\Sigma(\vec{x})}{\Sigma_{CR}}\tag{3}
$$

where Σ_{CR} is the critical surface density:

$$
\Sigma_{CR} = \frac{c^2 D_S}{4\pi G D_L D_{LS}}
$$

The observed CMB photons arises from the last-scattering surface, and along their path, each wavelength are affected by both the expansion of the Universe as well as by the mass inhomogeneities (Blanchard & Schneider [1987\)](#page-7-0). Once the structure in the Universe has grown to form, among other systems, clusters of galaxies, each photon crosses several lenses generated by these systems, resulting in a correlation between certain multipoles *l* that would otherwise have been independent of each other and therefore secondary non-Gaussian anisotropies (Zaldarriaga & Seljak [1998\)](#page-7-0) are introduced. Given this, for the CMB photons, the effective lens potential represents an integrated measurement of the mass distribution from the observer to the last scattering surface:

$$
\psi(\mathbf{\hat{n}}) = -2 \int_0^{\chi_*} d\chi \left(\frac{\chi_* - \chi}{\chi_* \chi} \right) \Psi(\chi, \mathbf{\hat{n}}) \tag{4}
$$

where χ_* is the comoving distance up to the last scattering surface and $\Psi(\chi, \hat{\mathbf{n}})$ is the Weyl potential, in comoving coordinates.

Following the formalism proposed in Planck Collaboration [\(2016\)](#page-7-0), which involves equations (2) and (4), the Planck Collaboration

redMaPPer catalogue superposed to the CMB lensing convergence man

Figure 1. redMaPPer cluster positions (red points) superposed to the CMB lensing convergence map in equatorial mollview projection. The lensing map has a FWHM Gaussian smoothing of 5◦ for a better visualization. The mask provided by [PR3](#page-7-0) associated to galactic and extragalactic sources is shown in grey.

provides the *kLM* coefficients:

$$
\kappa_{LM} = \frac{L(L+1)}{2} \psi_{LM} \tag{5}
$$

which allows to reconstruct the CMB convergence map.

In our analysis, we use the data products released in 2018 by the Planck Collaboration [\(2020a\)](#page-7-0), hereafter [PR3.](#page-7-0) We reconstruct the map from the spherical harmonics coefficients k_{LM} provided by the **[PR3](#page-7-0)** release¹, using all the *L*'s available (L_{Max} = 4096) with a FWHM Gaussian kernel of 1° , which is consistent with the range of $L's$ used in CMB power-spectrum analyses (Mirmelstein, Carron & Lewis [2019;](#page-7-0) Planck Collaboration [2020a\)](#page-7-0). These coefficients are derived from SMICA DX12 CMB maps (from temperature only after mean field subtraction, TT).² For an appropriate analysis, we also use the confidence mask provided by [PR3](#page-7-0) release that eliminates the most relevant astrophysical effects of galactic and extragalactic objects imprinted in the temperature CMB maps.

For the reconstruction and visualization, we use the $HEALPIX³$ software (Górski et al. [2005\)](#page-7-0). It allows us to transform the k_{LM} coefficients to a map with a resolution given by $N_{side} = 2048$. The pixel area has a constant value of $A_P = 1.062 \times 10^4$ arcsec².

In order to further check the consistency of our methods and results, we also use the $PR3$ minimum variance (MV) k_{LM} and the TT and MV k_{LM} reconstructed coefficients (Carron, Mirmelstein & Lewis [2022\)](#page-7-0) corresponding to the NPIPE processing pipeline (Planck Collaboration [2020b\)](#page-7-0) (hereafter [PR4\)](#page-7-0).

In Fig. 1, we present the CMB lensing map reconstruction, from **[PR3](#page-7-0) TT** k_{LM} coefficients, with a FWHM Gaussian kernel smoothing of 5◦ together with the distribution of redMaPPer clusters, which will be presented in the next section.

2.2 Cluster samples

We analyse samples derived from the redMaPPer cluster catalogue Rykoff et al. [\(2016\)](#page-7-0) that are identified through a red-sequence algorithm (Rykoff et al. [2014\)](#page-7-0) applied to galaxy overdensities inferred from a percolation procedure on the Sloan Digital Sky Survey Data Release 8 (York et al. [2000;](#page-7-0) Aihara et al. [2011\)](#page-7-0). This catalogue comprises 26 111 galaxy systems with an angular

[¹https://pla.esac.esa.int/#home](https://pla.esac.esa.int/#home)

[²https://wiki.cosmos.esa.int/planck-legacy-archive/index.php/Lensing](https://wiki.cosmos.esa.int/planck-legacy-archive/index.php/Lensing)

[³https://healpix.sourceforge.io/](https://healpix.sourceforge.io/)

Sample	Number of clusters	Redshift z range	$\langle z \rangle$	Richness parameter λ range	$\langle \lambda \rangle$	$\langle M \rangle$ (M_{\odot})
S_1	3000	[0.4, 0.45]	0.427	[31.7, 100]	44.914	$10^{14.304}$
S_2	2774	[0.45, 0.5]	0.475	[31.7, 100]	47.818	$10^{14.374}$
S_3	1574	[0.4, 0.45]	0.420	[21, 31.7]	27.797	$10^{14.027}$

Table 1. Main characteristics of cluster samples. The mean mass $\langle M \rangle$ is calculated following the procedure in Simet et al. [\(2017\)](#page-7-0).

Figure 2. Richness-redshift $(λ – z)$ distribution. Upper-left panel: redMaP-Per catalogue. It can be seen an excess of high values of *λ* at higher *z*. Upper-right panel: Sample *S*1. Richness is distributed nearly homogeneous across the redshift interval. Lower-left panel: Sample S_2 . Here, richness is also distributed nearly homogeneous across the redshift interval. Lower-right panel: Sample S_3 . The observed excess of high values of λ at higher z can induce a bias in the convergence analysis.

coverage of 10 401 square degrees in the redshift range [0.08, 0.6]. The catalogue provides a richness parameter, λ , which is a suitable proxy of cluster mass (e.g. Simet et al. [2017;](#page-7-0) Pereira et al. [2018\)](#page-7-0). This parameter, ranging between 20 and 300, is defined as the sum of the galaxy cluster membership probabilities over all galaxies within a scale-radius *Rλ*:

$$
\lambda = \sum p_{mem} \theta_L \theta_R \tag{6}
$$

where θ_L and θ_R are weights associated to a fixed threshold in luminosity and radius.

In our analysis, we restrict both redshift *z* and richness parameter *λ* ranges to define several samples that are presented in Table 1 together with their main characteristics. The mean mass $\langle M \rangle$ is calculated according to the relation given by Simet et al. [\(2017\)](#page-7-0). Also, we consider clusters within the CMB lensing mask region.

With the purpose of defining homogeneous samples not strongly affected by redshift nor richness bias, we first consider the redshift range $0.4 \le z < 0.45$ and select two richness ranges: $21 \le \lambda \le$ 31.7 for sample S_3 and 31.7 < $\lambda \le 100$ for sample S_1 . We adopt the threshold $\lambda = 31.7$ that corresponds to the 3000 richer clusters of sample S_1 . Additionally, we impose an upper limit $\lambda \leq 100$ to avoid spuriously high *λ* values probably associated to biases in the percolation procedure. Then, we consider the same richness interval $(31.7 < \lambda \le 100)$ with a different redshift range: $0.45 \le z \le 0.5$ for sample *S*2. We avoid the use of clusters with redshift lower than 0.4, which are not well suitable for this analysis due to their lower lensing signal.

In the upper-left panel of Fig. 2, we show the richness-redshift (*λ* − *z*) distribution for the catalogue that is complete in richness up to *z* ∼ 0.4. In the upper-right panel, we show the sample *S*1. As it can be seen in this figure, this restricted area provides a quasi-homogeneous distribution of richness parameter *λ* across the redshift interval. We present sample S_2 in the lower-left panel, where we can see that this region also provides a nearly homogeneous distribution across redshift, similarly to sample S_1 . In the lower-right panel, we display sample S_3 . This sample, contrary to S_1 and S_2 , is not complete in richness.

Some main features can be deduced from Table 1 and Fig. 2. It can be seen that S_1 and S_2 samples have similar values of $\langle M \rangle$ and *λ*. For this reason, both samples are well suited for our analysis. The inhomogeneous distribution of redshift and richness parameters in sample S_3 makes this sample unsuitable for a study with wellcontrolled parameters.

3 ANALYSIS

In this section we briefly detail the procedures used to derive mean convergence radial profiles centred on clusters. We also compute oriented profiles according to the parallel and perpendicular directions as defined by the galaxy member distribution. In order to avoid complications related to both SZ imprint on the CMB and great uncertainties due to low statistics fluctuations, we have excluded in the analysis the virialized region around the clusters. Therefore, we consider scales beyond 3 Mpc*h*−1.

3.1 Mean radial *κ* **profiles**

For our study of the convergence parameter κ around clusters, we compute mean radial profiles centred on the clusters. Given that the determination of the *κ* profile for a single cluster has low signal-tonoise ratio, to obtain a smooth κ mean radial profile, it is necessary to stack several convergence map patches centred on the clusters of a given sample. This is accomplished by superposing map patches around each cluster, where their radii is scaled according to the cluster redshift as a function of the projected distance r_p (in units of Mpc*h*−1) to the cluster centre. Over the stacked map, we compute the mean κ profile for 8 arcmin radial bins, also scaled according to the cluster redshift, obtaining profiles as a function of distance for each sample.

We calculate profiles uncertainties through the bootstrap resampling technique, with 300 re-samples for each sample considered. Given that for small separations the number of pixels is low, we expect the statistical uncertainty in this region to be larger. Also, we calculate a CMB map noise level. To accomplish this, we compute 300 new samples with the same number of objects as the sample considered albeit centred in random positions within the redMaPPer region. This map noise level provides a suitable estimate of both the average intrinsic fluctuations in κ as well as the distances at which the results are statistically significant.

As a test of our procedures and the reliability of the expected results, we have analysed the stability of the method in the three samples previously described (see Table 1). First, we study the

Figure 3. Convergence profiles for two richness ranges with its uncertainties. In green, the profile corresponding to sample S_1 . In pink, the profile corresponding to sample S_3 . It can be seen that the profiles differ significantly up to 15 Mpc*h*−1, where the lower signal of sample *S*³ implies that the inclusion of low richness clusters produces a less significant convergence profile. A reference noise level from sample *S*¹ for the CMB convergence map is shown in grey shaded region.

Figure 4. Convergence profiles for two redshift ranges with its uncertainties. In orange, the profile corresponding to sample $S₁$. In violet, the profile corresponding to sample *S*2. It can be seen that both profiles have a reasonable agreement up to 25 Mpc*h*−1. A reference noise level from sample *S*² for the CMB convergence map is shown in grey shaded region.

dependence of the mean κ profiles with respect to the cluster richness *λ*. The results are shown in Fig. 3, where we separate the richness in two different ranges: $21 \le \lambda \le 31.7$ (sample S_3) and $31.7 < \lambda$ ≤ 100 (sample *S*1). These intervals correspond to ∼ 35 per cent and ∼ 65 per cent of the clusters, respectively. It can be seen the significantly larger convergence amplitude for the higher richness clusters up to 15 Mpc*h*−1, as expected due to the tight correlation between cluster mass and richness.

Given its larger signal, in what follows, we will consider this cluster richness threshold (samples S_1 S_1 and S_2 , see Table 1 for details). In Fig. 4, we show mean κ profiles for two redshift ranges: $0.4 \leq z$ $<$ 0.45 (sample *S*₁) and 0.45 $\leq z \leq$ 0.5 (sample *S*₂). As seen in this figure, the mean radial profiles obtained for the different redshifts bins are mutually consistent, in particular in the region up to 25 Mpc*h*−1, as compared to the samples S_1 and S_3 that differ in richness. Also, it can be seen that the profile obtained for sample S_2 has a more gentle decay than S_1 . We argue that these two behaviours are related to the different structures surrounding the cluster samples, influencing the radial profiles at large distances.

In order to test the consistency of our results, we explore the convergence profiles of samples S_1 and S_2 in three different CMB lensing reconstructed maps using the [PR3](#page-7-0) MV, [PR4](#page-7-0) MV, and PR4 TT

Figure 5. Consistency of the convergence profiles for samples S_1 (yellow curves) and *S*² (purple curves). The green solid line corresponds to the [PR3](#page-7-0) TT map. The dashed, dotted, and dash-dotted lines corresponds to [PR3](#page-7-0) MV, [PR4](#page-7-0) MV, and [PR4](#page-7-0) TT maps, respectively. 1*σ* (errorbar), 2*σ* (green shaded), and 3σ (pink shaded) variances corresponding to [PR3](#page-7-0) TT map are shown.

 k_{LM} coefficients. In Fig. 5, it can be seen the convergence profiles of these CMB lensing reconstructed maps compared to the convergence profile of the [PR3](#page-7-0) TT reconstructed map. Also it can be seen the corresponding statistical confidence regions. It can be noticed that in the [PR3](#page-7-0) release there is no difference between TT and MV reconstructed maps profiles. In addition, it can be inferred that there is no a statistically significant difference between the [PR4](#page-7-0) TT and MV profiles and the [PR3](#page-7-0) TT profile.

3.2 Oriented *κ* **profiles**

In order to derive *κ* profiles oriented along the cluster projected major axis, we use the same procedure as in Shin et al. [\(2018\)](#page-7-0) and Gonzalez et al. [\(2021\)](#page-7-0) to calculate the position angles of our cluster samples. We consider an uniform weight $w_k = 1$ and all the galaxy members. Then we stack convergence map patches rotated according to these angles. The stacked aligned κ patches are shown in Fig. [6](#page-4-0) for samples S_1 and S_2 , respectively. For comparison, we also plot the non-aligned stacked patches. It can be seen that the *κ* distribution is preferentially oriented along the cluster major axis direction *x* after the clusters alignment. We notice the miscentring in sample S_1 , as well as a larger departure from a regular shape in S_2 . We argue that these two effects are mainly due to statistical fluctuations arising from both smoothing and large-scale irregularities in the mass distribution. This preferred alignment effect extends to several cluster radii up to ⁴⁰ Mpc*h*−1, which corresponds to [∼]3◦. In both cases, it can be seen that in the cluster nearby regions, *<*1◦, the convergence is nearly isotropic unlike the outer regions where the convergence tends to show strongly elongated shapes. We also notice a low statistical significance beyond $2° (\sim 25 \text{ Mpc}h^{-1})$, as expected from the noise level of the convergence profiles in Figs 3 and 4.

In order to highlight the alignment between the cluster orientation and the underlying mass distribution, we have computed the convergence profile for pixels within 45◦ from the cluster major axis direction, hereafter parallel direction. Similarly, we associate the perpendicular direction to the convergence profile for pixels with relative angles *>*45◦. The resulting parallel and perpendicular convergence κ profiles for samples S_1 and S_2 are shown in Fig. [7.](#page-5-0) For reference, we also plot the total (parallel and perpendicular) radial profile shown and analysed in the previous section (see Fig. 4). The

Figure 6. Stacked convergence maps for samples S_1 (left-hand panels) and *S*² (right-hand panels) with a smoothing corresponding to a FWHM Gaussian kernel of 2◦, for a better visualization. The upper panels show the stacked maps without alignment. The lower panels show the stacked aligned maps. The black circles correspond to an angular scale of 1◦ (solid), 2◦ (dashed) and 3◦ (dotted). It can be seen in the aligned stacked maps that the convergence values are greater in the parallel orientation than in the perpendicular ones.

noise level corresponds to the radial profile. The vertical dotted line correspond to the virialized clustersregion (∼³ Mpc*h*−1) with ^a large *κ* uncertainty determination due to the presence of SZ imprint.

It can be seen that for both samples that the parallel profile has a significantly larger signal in a wide range of scales (from ∼5 to 40 Mpc*h*^{−1}) than the perpendicular ones. This behaviour is associated to the strong alignment between the inner non-linear virialized region (where the galaxy members use to calculate the position angles are located) and the large-scale mass distribution as provided by the convergence κ map. It is remarkable the fact that the alignment relates the distribution of galaxies, within [∼]1–2 Mpc*h*−1, and the mass density fluctuations at scales of at least 40 Mpc*h*−1. This is particularly significant for the higher redshift bin (sample *S*2).

4 ANISOTROPIC LARGE-SCALE MASS DISTRIBUTION MODEL

In this section, we apply the anisotropic lensing model proposed by Gonzalez et al. [\(2022\)](#page-7-0) to model the obtained *κ* convergence CMB data. The lensing effect produced by an ellipsoidal mass density can be studied through the surface mass density distribution $\Sigma(R)$ with *R* the ellipsoidal radial coordinate $R^2 = r^2(q\cos^2(\theta) + \sin^2(\theta)/q)$ with a semi-axis ratio $q \le 1$ (van Uitert et al. [2017\)](#page-7-0). Following Schneider [\(1996\)](#page-7-0), we define the ellipticity parameter $\epsilon = \frac{1-q}{1+q}$ in order to obtain a multipolar expansion:

$$
\Sigma(R) \equiv \Sigma(r,\theta) := \Sigma_0(r) + \epsilon \Sigma_0'(r) \cos(2\theta) \tag{7}
$$

where θ is the relative position angle of the source with respect to the major axis of the density mass distribution. Σ_0 y Σ'_0 are the monopolar and quadrupolar components, respectively. Σ_0 is related

to the axis-symmetrical mass distribution while the quadrupole component is defined in terms of the monopole as:

$$
\Sigma_0' = -r \frac{d \Sigma_0(r)}{dr} \tag{8}
$$

corresponding to an elongated mass distribution.

Based on the halo model, the total surface density distribution can be described according to the sum of a first and second halo components. The first halo term is modelled assuming a spherically symmetric NFW profile (Navarro, Frenk & White [1997\)](#page-7-0), which can be parametrised by the radius that encloses a mean density equal to 200 times the critical density of the Universe, R_{200} , and a dimensionless concentration parameter, c_{200} :

$$
\rho_{1h}(r) = \frac{\rho_{\rm crit}\delta_c}{(r/r_s)(1+r/r_s)^2},\tag{9}
$$

where $r_s = R_{200}/c_{200}$ is the scale radius, ρ_{crit} is the critical density of the Universe, and δ_c is the characteristic overdensity described by:

$$
\delta_c = \frac{200}{3} \frac{c_{200}^3}{\ln(1 + c_{200}) - c_{200}/(1 + c_{200})}.
$$
\n(10)

We define M_{200} as the mass within R_{200} that can be obtained as:

$$
M_{200} = 200 \,\rho_{\rm crit} (4/3) \pi \, R_{200}^3 \tag{11}
$$

To model this component, we consider the mean mass specified in Table [1,](#page-2-0) and we fix the concentration taking into account the relation given by Diemer & Joyce [\(2019\)](#page-7-0) that is in agreement with the Simet et al. [\(2017\)](#page-7-0) model for the mass calculation.

The tri-dimensional density profile of the second halo term is modelled considering the halo-matter correlation function, *ξ hm*, as:

$$
\rho_{2h}(r) = \rho_m \xi_{hm} = \rho_{\rm crit} \Omega_m (1+z)^3 b(M_{200}, \langle z \rangle) \xi_{mm}
$$
 (12)

where ρ_m is the mean density of the Universe, satisfying:

$$
\rho_m = \rho_{\rm crit} \Omega_m (1+z)^3
$$

and the halo-matter correlation function isrelated to thematter-matter correlation function through the halo bias (Seljak et al. [2005\)](#page-7-0):

$$
\xi_{hm}=b(M_{200},\langle z\rangle)\xi_{mm}
$$

We set the halo bias by adopting Tinker et al. [\(2010\)](#page-7-0) model calibration.

Thus, the radial surface density distribution can be modelled taking into account essentially the monopolar and quadrupolar terms (equation 7) of a main halo mass distribution, Σ_{1h} , and a contribution to the mass from the cluster neighbourhood, Σ_{2h} , corresponding to a second halo term, with independent ellipticity parameters:

$$
\Sigma(R) \sim \Sigma_{1h}(r) + \epsilon_{1h} \Sigma'_{1h}(r) \cos(2\theta) + \Sigma_{2h}(r) + \epsilon_{2h} \Sigma'_{2h}(r) \cos(2\theta)
$$
\n(13)

This model assumes that the mass density distribution of the main halo, as well as the second halo term, are elongated along the same directions. Although a misalignment between the two haloes terms can exist, this expected misalignment will bias the estimated elongation of the second halo term to lower values.

We derive estimators of cluster mass and ellipticity from the convergence maps following the procedures detailed in Gonzalez et al. [\(2022\)](#page-7-0) for the shear components. The model mass estimator arises from the integration of equation (13) on θ , which gives:

$$
\Sigma(r) = \Sigma_{1h}(r) + \Sigma_{2h}(r) \tag{14}
$$

This estimator can be compared to the observed radial *κ* profile.

Figure 7. Convergence lensing parameter *κ* profile for sample S_1 (upper panel) and S_2 (lower panel) as a function of the projected distance to the cluster centres (black dotted line). Brown and yellow curves correspond to parallel and perpendicular directions as defined previously in the text, respectively. The green shaded region around the mean radial profile correspond to the radial uncertainty calculate through a bootstrap resampling technique with 300 re-samples from the considered sample. The horizontal grey shaded region is the map noise level calculated through 300 random profiles. The vertical dotted line represent two mean virial radius (∼³ Mpc*h*−1), where ^a significant SZ effect is expected.

By multiplying equation [\(13\)](#page-4-0) by $cos(2\theta)$ and integrating in θ , we obtain the model ellipticity estimators:

$$
\Sigma_{proj}(r) = \epsilon_{1h} \Sigma'_{1h}(r) + \epsilon_{2h} \Sigma'_{2h}(r) \tag{15}
$$

which is related with the anisotropic contribution and can be compared with the observed lensing effect, by averaging the convergence *κ* in angular bins:

$$
\kappa_{proj}(r) = \frac{\sum_{j} \kappa_{j}(r) cos(2\theta_{j})}{\sum_{j} cos^{2}(2\theta_{j})}
$$
\n(16)

In Fig. [8,](#page-6-0) we show the adopted model for the monopole (equation 15) together with the observed radial convergence profiles and the corresponding uncertainties. It can be seen the good behaviour of the model in the central range of distances [8, 40] Mpc*h*−¹ for the estimated mass derived from the richness–massrelation as a function of redshift for the redMaPPer clusters. It is worth noticing that our mass estimation through Simet et al. [\(2017\)](#page-7-0) model is in agreement with that given in Geach & Peacock (2017) ; for details, see their fig. 3) in the richness range for samples S_1 and S_2 .

The low-level agreement observed at small separations can be explained from the gaussian smoothing of the map and the low number of pixels in the first bins. Also, it is important to take into account that in these regions there exists a SZ effect that decreases the signal and may affect our measurements. Besides, we notice that this model aims at the analysis of weak lensing by clusters for both, observations (Gonzalez et al. [2021\)](#page-7-0) and simulations (Gonzalez et al. [2022\)](#page-7-0). Thus, several CMB lensing effects are not considered by this approach. Nevertheless, we acknowledge that the results are in a general good agreement in spite of the larger scales involved in our analysis.

We study the behaviour of the quadrupolar terms, which are derived from the monopolar ones (equation [8\)](#page-4-0), and their respective ellipticities. With this aim, we fit the projected radial profile (equation 16) with respect to the ellipticity estimators (equation 15). Given that we neglect in our analysis the internal region which is sensitive to the main halo component, we fix the ellipticity for this term at $\epsilon_{1h} = 0.2$ that corresponds to a quasi-spherical halo shape and is in concordance with the previous redMaPPer ellipticity measurements (Shin et al. [2018;](#page-7-0) Gonzalez et al. [2021\)](#page-7-0). Taking this into account,

Figure 8. Density monopolar model compared to mean radial convergence profile for samples *S*¹ (left-hand panel) and *S*² (right-hand panel). In dashed blue, it can be seen the sum of the first halo term (dotted green) and second halo term (dotted pink) of the anisotropic density model calculated through $\langle M \rangle$ of samples S_1 and S_2 . In orange, the mean radial convergence profiles with its uncertainty. It can be seen the good agreement of the model with respect to the measurements. The results on lower scales than 5 Mpc*h*−¹ have great statistical uncertainties and larger contamination of SZ effect.

Figure 9. Fitting of the mean radial projected profile with respect to the anisotropic density quadrupolar model. In dashed green, it can be seen that the sum of the first halo term (dotted brown) and second halo term (dotted orange) of the anisotropic density model with ellipticities ϵ_{1h} and ϵ_{2h} . In violet, the mean radial projected profile and its uncertainties calculated through equation [\(16\)](#page-5-0). For sample *S*₁ (upper panel), the ellipticity parameters are $\epsilon_{1h} = 0.2$ and $\epsilon_{2h} = 0.24 \pm 0.03$, corresponding to a quasi-spherical halo shape. For sample *S*₂ (lower panel), the ellipticity parameters are $\epsilon_{1h} = 0.2$ and $\epsilon_{2h} =$ 0.51 ± 0.04 , which is related to a elongated halo shape. The grey shaded region shows the fitting uncertainty.

we use non-linear least squares to fit the second halo term that has the largest contribution to the surface density profile in the analysed radial range. We estimate the uncertainty in ϵ_{2h} by means of the fitting covariance matrix. We notice that the estimated amplitude uncertainties are small, within the measurement errors, providing suitable associated ellipticity values. In Fig. 9, we show the resulting mean radial profile for the theoretical quadrupolar terms $\epsilon_{1h} \Sigma'_{1h}(r)$ and $\epsilon_{2h} \Sigma'_{2h}$ with ellipticities ϵ_{1h} and ϵ_{2h} for samples S_1 and S_2 . As it can be seen in this figure, samples S_1 and S_2 have different second

halo ellipticity parameter values being:

$$
\epsilon_{2h} = 0.24 \pm 0.03
$$
, Sample S_1
\n $\epsilon_{2h} = 0.51 \pm 0.04$, Sample S_2 (17)

Given the different redshift depth of samples S_1 and S_2 , we fix the corresponding fitting regions[10, 40], [17, 40] Mpc*h*−1, respectively. We also notice that in the high redshift sample, the fit is less accurate than for sample S_1 , requiring a higher value of ϵ . We argue that these effects are caused by the strong alignment of the high redshift clusters at scales where there is still a significant convergence signal in the parallel direction.

5 CONCLUSIONS

Due to its large angular extension and depth, there is a great potential in the investigations of CMB lensing map for the analysis of the mass distribution at large scales. These studies provide important alternative information to weak gravitational lensing research, involving shear estimations by background galaxies. In our work, we perform a statistical study of the convergence κ obtained from the temperature map of the CMB from the Planck 18 survey centred on rich galaxy clusters samples extracted from the redMaPPer catalogue. We find a significant excess in the convergence κ values around clusters, which extends several tens of Mpc*h*−1. We study this *κ* profile for different richness samples as well as redshift intervals. We obtain, as expected, a larger amplitude for the higher richness samples and similar results for the redshift ranges explored. When clusters are aligned along their galaxy member distribution major axis, we find a significant difference between the *κ* values along the parallel and perpendicular directions. Remarkably, this difference persists at scales as large as 40 Mpc*h*−1, indicating that this alignment is strongly conditioned by the large-scale mass anisotropic distribution. We study an anisotropic surface mass density model associated to the clusters, which is in reasonable agreement with the observational results obtained. From this analysis, we estimate the mean ellipticity of the second halo term for samples S_1 , $\epsilon_{2h} = 0.24 \pm 0.03$ and S_2 , ϵ_{2h} = 0.51 \pm 0.04, consistent with an extended, highly flattened mass distribution oriented along the cluster major axis.

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DATA AVAILABILITY

The data underlying this article will be shared on reasonable request. The data sets used in this article were derived from sources in the public domain. Data products and observations from Planck, https: [//pla.esac.esa.int.](https://pla.esac.esa.int)

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