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MINLP-based Analytic Hierarchy Process to simplify multi-objective problems: Application to the design of biofuels supply chains using on field surveys

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ABSTRACT

Multi-objective optimization (MOO) is widely used in engineering systems design and planning. The solution of a MOO problem leads to a set of efficient points (Pareto set) from which decision-makers should identify the one that best fits their preferences. Generating this set requires large computational efforts, and the post-optimal analysis of the solutions becomes difficult as the number of objectives increases. This work introduces an approach based on the Analytic Hierarchy Process (AHP) to overcome these limitations. Through the definition of an aggregated objective function calculated using the AHP algorithm, a single-objective model is constructed that provides a unique Pareto solution of the original MOO model. The AHP is combined with a mixed-integer non-linear programming (MINLP) formulation that simplifies its application and is particularly suited to deal with many objectives (like those arising in sustainable engineering problems). The capabilities of the approach are demonstrated through a case study addressing the sustainable sugar/ethanol supply chain design problem.

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1. Introduction

Multi-objective problems are found in many fields, such as production, services and entertainment. The wide variety of conflicting interests that emerge in engineering systems, such as economic, environmental and social concerns, has led to a large variety of MOO problems (Grossmann and Guillén-Gosálbez, 2010). In the recent past, MOO has been extensively used in sustainable engineering problems in which economic, environmental and social criteria must be accounted for in the analysis (Guillén-Gosálbez and Grossmann, 2009; Yue et al., 2014; Miret et al., 2016). For example, Kostin et al. (2012) introduced a stochastic MOO model that optimizes profit and financial risk, whereas Kravanja and Čuček (2013) developed a model to explore the trade-off between profit and sustainability indexes. García and You (2015) contrast capital and operating expenditures with environmental impacts. Some works have applied as well MOO in the area of energy systems opti-

mization (Guillén-Gosálbez et al., 2009; Gebreslassie et al., 2012; Antipova et al., 2013).

Different approaches, known as multi-criteria decision-making (MCDM) techniques (Marler and Arora, 2004), can be found in the literature to tackle multi-objective problems involving conflicting criteria. These MCDM strategies are roughly classified into two groups: multi-objective decision-making methods, usually referred to as multi-objective optimization (MOO), and multi-attribute decision-making techniques (Cortés-Borda et al., 2013; Geldermann and Rentz, 2005). The former group identifies optimal solutions from a set of feasible points (Pareto solutions) using search methods that consider constraints of different nature, while the latter group evaluates and selects alternatives departing from a set of them and based on defined attributes.

MOO models, whether linear, nonlinear or mixed-integer, typically contain an infinite number of Pareto optimal solutions. These Pareto points represent compromise situations, in the sense that it is impossible to enhance one criterion without worsening any of the others. Calculating the complete set of Pareto points of an MOO model may be computationally challenging, as it requires intensive information processing and storage capacity. These limitations

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Table 1
Pairwise comparison scoring (Adapted from Saaty, 1980).

Numerical score	Definition	Interpretation
1	Same importance	Both criteria contribute equally to the final purpose.
3	Weakly more important	Experience and knowledge slightly make preferable one criterion to the other.
5	Moderately more important	Experience and knowledge make quite preferable one criterion to the other.
7	Strongly more important	Experience and knowledge strongly favor one criterion over the other.
9	Absolutely more important	The evidence favoring one criterion over the other is of the highest degree.
2, 4, 6, 8		Intermediate situations (not considered in this work).
Decimals		If more refinement is needed (not considered in this work).

could be circumvented by selecting a subset of Pareto solutions that are particularly appealing and which should be passed to the decision-maker for identifying the final one to be implemented.

A number of works have addressed the problem of reducing the size of the Pareto set of an MOO problem. One possible manner to accomplish this is to incorporate the user's preferences in the resolution process in order to dive into a special region of the Pareto set. This is the underlying idea followed in the works by Branke et al. (2001, 2004), in which evolutionary algorithms are employed. Messac et al. (2003) introduced the normal constraint method to limit the size of the Pareto set, while Montusiewicz and Osyczka (2003) use decomposition strategies for the same purpose. For problems with convex Pareto optimal fronts, Deb (2003) presents a modified domination criterion to alleviate the computational burden of the model. To reduce potential disturbances when producing the Pareto front, Deb and Gupta (2005) present some approaches with enhanced robustness. Farina and Amato (2004) introduce a dominance concept derived from fuzzy optimality to narrow down the Pareto set. More recently, Antipova et al. (2015) applied Pareto filters to reduce the Pareto set and facilitate the post-optimal analysis of its solutions.

In this work, we explore the combined use of AHP and MOO for addressing the solution of complex MOO models. We propose to solve, instead of the original MOO problem, an auxiliary single-objective optimization (SOO) problem that optimizes an aggregated objective function constructed using weights calculated by the Analytic Hierarchy Process (AHP) (Saaty, 1980). The AHP translates qualitative judgments (elicited from a set of surveys completed by "experts" in the problem) into quantitative information. Note that there are many other methods for obtaining weighting factors, e.g. SMART (Simple Multi-Attribute Rating Technique) (Edwards, 1977) and SWING (Von Winterfeldt and Edwards, 1986). However, among them the AHP is one of the most widely used in academia and also in industry (Qian et al., 2007; Vaidya and Kumar, 2006), which has motivated its choice in our work.

Unfortunately, the application of the AHP process poses some challenges. First, the need of gathering different opinions in the AHP surveys so as to reflect a wider spectrum of preferences can sometimes lead to inconsistencies and meaningless weighting factors (Pöyhönen and Hämäläinen, 2001). In addition, the complexity of the AHP method grows with the number of criteria, as this approach is based on performing pairwise comparisons between objectives. We present here an MINLP-based AHP that overcomes these limitations by automatically generating weights with maximum consistency from preferences expressed in a very simplified manner. The customized MINLP greatly facilitates the AHP application by reducing the amount of information required from decision-makers while ensuring that their preferences are expressed in a consistent manner. The MINLP-based AHP can be used to simplify MOO problems, as we do here, or as a standalone tool to facilitate the AHP application anywhere else. The capabilities of our approach are illustrated through its application to the design of biofuels supply chains.

The article is presented in the following order. The next section describes the mathematical background underpinning the

approach presented, followed by the description of the proposed methodology itself. Then, we present a case study (already validated and tested in previous works) that is based on an Argentine sugar cane supply chain (SC). Next, we present some numerical results and discuss them. In the last section of the paper, the conclusions are drawn.

2. Mathematical background

2.1. Multi-objective optimization

A formal representation of a typical MOO problem is given by P1.

$$\begin{aligned}
 \min \quad & \{f_1(x, y), \dots, f_k(x, y), \dots, f_K(x, y)\} \\
 \text{s.t.} \quad & h(x, y) = 0 \\
 & g(x, y) \leq 0 \\
 & x \in \mathfrak{R}, y \in \{0, 1\}
 \end{aligned} \tag{P1}$$

In P1, $f_k(x, y)$ represents the k -th ($k = 1, \dots, K$) objective function; h and g stand for the equality and inequality constraints that the solution sought should satisfy, respectively; and x and y are the continuous and binary variables of the problem, respectively.

We propose to solve P1 by using an auxiliary single-objective model. To this end, we create an aggregated objective function (a composite function of the individual objectives) calculated as a linear weighted sum of individual terms (i.e. objectives) whose weighting factors are obtained using an enhanced AHP methodology. Thereby, we build a SOO model with the same equality and inequality constraints as in P1, but with a single-objective (scalar) objective function rather than a multi-objective (multi-dimensional) one. Thus, this auxiliary single-objective model will provide a single Pareto point of P1, thereby avoiding the exhaustive exploration of its Pareto set and consequently simplifying the entire analysis.

The key issue in this reformulation is the way in which the weighting factors are chosen. We use the AHP method combined with an MINLP optimization model to calculate the weighting factors. This MINLP calculates weighting factors that express the decision-makers' preferences with maximum consistency. Thus, P2 is formulated from P1 as follows:

$$\begin{aligned}
 \min \quad & w_1 f_1(x, y) + \dots + w_k f_k(x, y) + \dots + w_K f_K(x, y) \\
 \text{s.t.} \quad & h(x, y) = 0 \\
 & g(x, y) \leq 0 \\
 & x \in \mathfrak{R}, y \in \{0, 1\}
 \end{aligned} \tag{P2}$$

In P2, w_k is the k -th weighting factor assigned to objective k . Therefore, P2 produces a unique solution (rather than a Pareto set) that best reflects the decision-makers' preferences. As will be later discussed in more detail, this model requires the objectives to be normalized so that they can be optimized all together.

2.2. The Analytic Hierarchy Process

The AHP (Saaty, 1980) is a multi-attribute decision-making method that supports multi-criteria problems by taking into account a hierarchy in the criteria. This method was applied to a variety of industrial problems, such as facility location (Dogan and Bahadir, 2014), supplier selection (Ramanathan, 2007) and SC redesign (Palma-Mendoza, 2014). Particularly, it was successfully implemented in cases where environmental criteria were considered together with other industrial goals, such as materials purchasing (Gloria et al., 2007) or technology selection (Meng et al., 2010). Unlike the present work, the abovementioned ones use AHP as a standalone tool (without integrating it with an optimization technique as we do here).

The starting point of the AHP method includes a set of surveys answered by N decision-makers. These decision-makers – academics, technicians or business people –, are asked to define a hierarchy of criteria (i.e. objectives), from the most to the least important. Next, the traditional AHP process asks the respondents to perform pairwise comparisons between the K objectives. These comparisons make use of the standard Saaty scale, which goes from 1 to 9 (Table 1). Note that even values, 2 to 8, would here reflect intermediate situations. Moreover, rational numbers can also be used if more refinement is required.

Next, N “coefficient matrices” are built using these comparisons values. Let A_n be a coefficient matrix associated with respondent n ($n = 1, \dots, N$). A_n contains the relative importance between the K different objectives. The elements of A_n will be denoted by a_{nij} , where n is an identifier of the survey respondent. Subscripts i and j represent the element position (row and column, respectively). Since $i = 1, \dots, K$, and $j = 1, \dots, K$, then $A_n \in \mathfrak{R}^{K \times K}$. Therefore, a Saaty coefficient matrix A_n is constructed by filling its upper triangle with the pairwise comparison factors:

$$\begin{pmatrix} a_{n11} & \dots & a_{n1K} \\ \vdots & & \vdots \\ a_{nK1} & \dots & a_{nKK} \end{pmatrix}$$

The element a_{nij} is the Saaty scale value resulting from the comparison between objectives i and j made by stakeholder n . Then, it holds that $a_{nji} = 1/a_{nij}$ and the diagonal elements $a_{nii} = 1$ (self-comparison).

Stakeholders may have different backgrounds, knowledge and interests, so they will very likely produce matrices whose values differ to a certain extent. This creates the need to harmonize such matrices in a valid way. Moreover, according to the general AHP method, prior to the matrices aggregation, it is necessary to check the consistency of each of them. Matrix consistency stands for the logical quality of the responses given by a person who performs a survey (see next subsection). Let λ_{\max} be the maximum eigenvalue of a given matrix A_n , then, a consistency index (CI) is calculated for each matrix (Eq. (1)) as follows.

$$CI = \frac{(\lambda_{\max} - K)}{(K - 1)} \quad (1)$$

When λ_{\max} of A_n equals K , then $CI=0$, which implies that the Saaty matrix is fully consistent. If λ_{\max} of A_n is greater than K , then CI will also be greater than 0. To determine whether the value of CI is acceptable or not, a threshold value is used, RI , which is a random consistency index defined by Saaty (1980) and available in tables for matrices of different sizes. A consistency ratio CR is then calculated as in Eq. (2).

$$CR = \frac{CI}{RI} \quad (2)$$

If CR is equal or lower than 0.1 (90% of consistency in the comparisons, and 10% of inconsistency) then matrix A_n is accepted, otherwise is dismissed (Saaty, 1990). Hence, the smaller the CR value, the better. Hence, smaller CR values imply better consistency, and from Eq. (1) it is clear that this can be accomplished by minimizing the value of λ_{\max} , which is always greater or equal than the dimension of the matrix K .

After checking the consistency of every individual coefficient matrix A_n , we can follow two basic methods to aggregate the respondents’ preferences. The choice of a particular method depends on whether we consider the group of stakeholders behaving as a single decision-maker or as disjoint individuals (Aczel and Saaty, 1983; Forman and Peniwati, 1998; Escobar and Moreno-Jiménez, 2007). For the former case (which is the one followed in this work due to the nature of the matrices), we aggregate individual judgments (AIJ) by using the element-by-element geometric mean calculated over all of the individual matrices. In the latter, the geometric mean should be instead calculated over the priorities (eigenvectors) resulting from these matrices (aggregation of individual priorities, AIP).

The next step in the AHP process, following the AIJ aggregation method, is to construct a new matrix M using the consistent matrices A_n , in which, as said before, each element m_{ij} is the element-by-element geometric mean of the elements of each A_n (Eq. (3)).

$$M \in \mathfrak{R}^{K \times K}, \quad m_{ij} = \left(\prod_{n=1}^N a_{nij} \right)^{1/N} \quad (3)$$

Finally, the weights are obtained from matrix M by calculating the normalized maximum eigenvalue (Saaty, 1990) (Eq. (4)).

$$\sum_{j=1}^K m_{ij} w_j - \lambda_{\max} w_i = 0, \quad i = 1, \dots, K \quad (4)$$

where w_j are the components of the normalized eigenvector, i.e. the weights sought.

2.3. Consistency in the AHP

A matrix is deemed consistent if its elements satisfy transitivity and reciprocity assumptions. Transitivity implies that $a_{ij} = a_{ik} \cdot a_{kj}$. For example, let us consider a decision-maker for whom objective one is two times more important than objective two ($a_{1,2} = 2$), and objective two is three times better than objective three ($a_{2,3} = 3$). If objective one is six times better than objective three, then transitivity holds. Reciprocity means that $a_{ij} = 1/a_{ji}$. For instance, if a decision-maker prefers objective one twice as much as objective two ($a_{1,2} = 2$); therefore, objective two should be half preferable than objective one ($a_{2,1} = 1/2$). The consistency index (CI) and consistency ratio (CR) defined by Saaty (1980) aim at guaranteeing a necessary degree of compliance with the aforementioned properties. A deep discussion about the acceptance or rejection of AHP matrices can be found elsewhere (Alonso and Lamata, 2006). Note that the scale employed to represent the decision-makers’ judgments lies at the core of this discussion, as when K increases the level of consistency may fall outside acceptance limits (Murphy, 1993).

The number of comparisons (NC) required to build the Saaty matrix increases with the number of objectives according to Eq. (5). Therefore, the comparison process may become cumbersome for the respondent, making it more difficult to reach good consistency levels in the AHP matrices.

$$NC = \frac{1}{2}(k^2 - k) \quad (5)$$

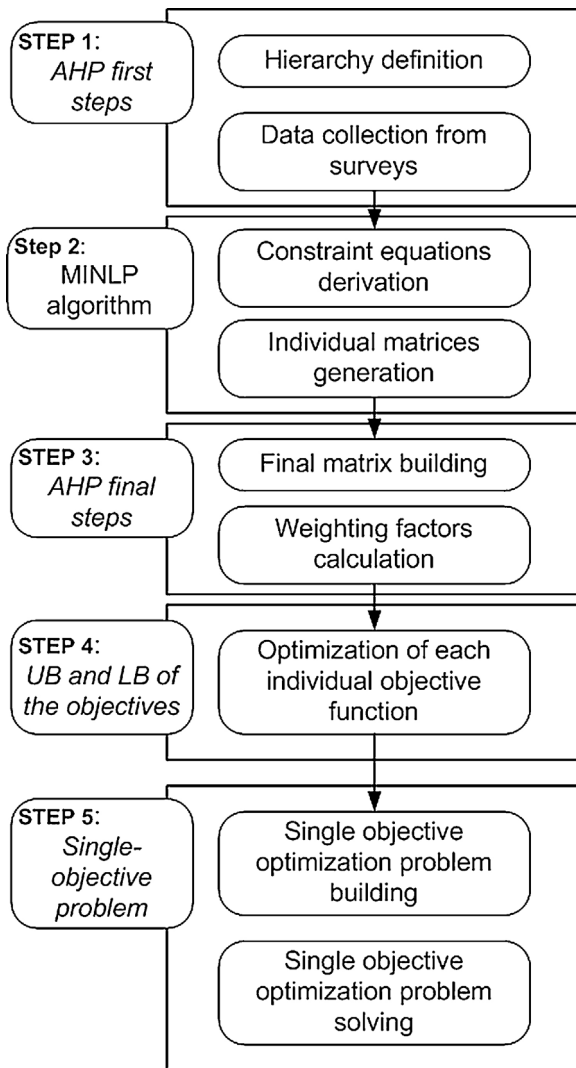


Fig. 1. Five-step flowchart to derive a SOO model from an MOO one.

In order to avoid consistency problems and simultaneously reduce the time spent on answering the surveys, we propose a MINLP that automatically generates consistent weights from a ranking of objectives. Hence, our algorithm generates, from a simplified survey based on a customized scale and in a fast and robust manner, a coefficient matrix that minimizes *CI*. This approach prevents respondents from providing inconsistent weights, thereby facilitating the decision-making process.

3. Proposed methodology

Our approach comprises five steps described in detail in the ensuing sections (see Fig. 1).

Step 1: AHP hierarchy definition and data collection

Following the AHP method, a decision hierarchy is first constructed, where the overall objective is on the top, while the individual ones are arranged in branches downwards. A number of surveys are collected from the decision-makers (respondents), who are asked to evaluate the objectives according to their preferences. In the evaluation process, an arbitrary scale can be used, for example, from 0 to 10 (where 10 represents the score for the most important objective/criterion). As a result of this step, a ranking of objectives is obtained, from more to less important.

Step 2: Generation of pairwise matrices from simplified preferences by using an MINLP algorithm for each individual set of preferences

In this step, the individual pairwise coefficients of the comparison matrices (corresponding to each respondent) of the AHP methodology are obtained using an optimization algorithm. The objective of the algorithm is to determine the elements of matrix A_n (based on the Saaty scale) that minimize the maximum eigenvalue (λ_{\max}) (i.e. that maximize the consistency level). Given that equation 4 has a bilinear term, the model is non-linear and non-convex. Therefore, the resulting formulation leads to a non-convex MINLP. The detailed MINLP formulation is described in detail next.

Objective function:

The MINLP model seeks to minimize the consistency index (recall that lower *CI* values imply better consistency). This is equivalent to minimizing the maximum eigenvalue λ_{\max} (Eq. (4)):

$$\min \lambda_{\max} \quad (6)$$

Constraints:

To compute the maximum eigenvalue, we first need to build the pairwise comparison matrix. Rather than providing the coefficients of the matrix ourselves, we define a set of binary variables that will automatically identify the best coefficients so as to optimize the consistency index. Obviously, we cannot let the model decide arbitrarily those values, as the weights obtained in this manner would barely reflect the decision-makers' preferences. Hence, additional constraints are required to ensure that the values of the binary variables are consistent with the decision-makers' preferences. These preferences are expressed as a ranking of objectives rather than through pairwise coefficients, thereby simplifying the AHP application.

Hence, we start by forcing each element of the upper triangle of the coefficient matrix to take a unique value of the Saaty scale (Eqs. (7) and (8)).

$$a_{ij} = \sum_s q_s y_{ijs} \quad i < j \quad (7)$$

$$\sum_s y_{ijs} = 1 \quad i < j \quad (8)$$

where q_s are the Saaty parameters (1, 3, 5, 7, 9) and y_{ijs} is a binary variable that is one if the Saaty value $s(q_s)$ is assigned to the comparison between i and j , and it is zero otherwise. Hence, Eq. (7) defines the pairwise comparison coefficients from these binary variables, while Eq. (8) ensures that for every comparison between i and j , a single value of the Saaty scale is selected.

The elements of the lower triangle can be calculated according to Eq. (9).

$$a_{ji} = \frac{1}{a_{ij}} \quad \forall i, j \quad (9)$$

This condition can be enforced using the following constraint together with Eq. (7) (note that this reformulation is linear and therefore more convenient):

$$a_{ji} = \sum_s y_{ijs} \frac{1}{q_s} \quad i < j \quad (10)$$

The normalized eigenvector elements w_i required to compute the consistency index (Eq. (11)) lie between zero and one (Eq. (12)) and sum up one (Eq. (13)):

$$\sum_{j=1}^K a_{ij} w_j - \lambda_{\max} \cdot w_i = \sum_{j=1}^K \sum_s q_s y_{ijs} w_j - \lambda_{\max} \cdot w_i = 0, \quad \forall i \quad (11)$$

$$0 \leq w_i \leq 1, \quad \forall i \quad (12)$$

Table 2
 Translation of the ranking scores into constraint equations.

Score difference among two objectives	Logical expression	
	Colloquial expression	Constraint equation
0	Objective <i>i</i> equally important to <i>j</i>	$a_{ij} = 1$
1	Objective <i>i</i> moderately more important than <i>j</i>	$a_{ij} \geq a_{ji} + 1$
2	Objective <i>i</i> strongly more important than <i>j</i>	$a_{ij} \geq a_{ji} + 3$
3 or more	Objective <i>i</i> very strongly more important than <i>j</i>	$a_{ij} \geq a_{ji} + 5$

$$\sum_i w_i = 1 \tag{13}$$

The minimum value of λ_{\max} is equal to the number of objectives (i.e. dimension of the square matrix, *K*) (Eq. (14)).

$$\lambda_{\max} \geq K \tag{14}$$

Eq. (11) includes a product of a binary variable times a continuous one ($y_{ijs} \cdot w_j$). This term can be linearized as follows:

$$\sum_{j=1}^K \sum_s q_s y w_{ijs} - \lambda_{\max} \cdot w_i = 0, \quad \forall i \tag{15}$$

$$0 \leq y w_{ijs} \leq U \cdot y_{ijs}, \quad \forall i, j, s, \quad U = \max \{q_s\} \tag{16}$$

$$w_j - U(1 - y_{ijs}) \leq y w_{ijs} \leq w_j + U(1 - y_{ijs}), \quad \forall i, j, s \tag{17}$$

where $y w_{ijs}$ is now an aggregated auxiliary variable defined via constraints 16 and 17.

Additional constraints are derived based on the ranking of objectives provided by decision-makers. To this end, we define a number of potential relations between objectives based on the Saaty scale (Table 1). Using the numerical difference between the rankings of two consecutive objectives, it is possible to establish logical expressions of relative importance between criteria (Table 2). These logical relationships are then included as constraints in the MINLP. Following this approach, decision-makers define *K*-1 comparisons between objectives, which are then converted into algebraic constraints of the MINLP model. Let us note that it would be possible to define relations between more than two objectives, but this would lead to more formulations and also to the need to devise and fill in more complex surveys.

For every survey, we solve the MINLP to find the matrix with maximum consistency according to the preferences established in that survey. Hence, the MINLP provides as output the pairwise comparison coefficients as well as the weights assigned to every objective according to a given preference elicited in a specific survey. The MINLP can be expressed in compact form as follows:

$$\begin{aligned} \min \quad & \lambda_{\max} \\ \text{s.t.} \quad & \text{Eq. (7) – (8), (10) and (12) – (17)} \\ & K - 1 \text{ ranking constraints} \\ & w \in \mathfrak{R}, y \in \{0, 1\} \end{aligned}$$

Step 3: Computation of weights for the individual objectives from the outcomes of the MINLP

In this step, we aggregate the matrices calculated for each survey *n*. These matrices are filled using the above described algorithm, which uses the decision-makers' comparisons. The weights for each branch of the hierarchy are obtained by applying the Aggregation of Individual Judgements (AIJ) method. This approach first merges the individual matrices, and then calculates the weights (eigenvectors) from the aggregated matrix. Hence, in the AIJ approach, the individual priorities of the respondents are of little interest (the

respondents do not give their opinion on all the branches of the hierarchy tree).

Following this approach, we compute the element-by-element geometric mean to get the final matrix *M* (Eq. (3)). Finally, we use *M* to obtain the weighting factors (w_k) needed to solve the SOO problem (Eq. (4)).

Step 4: Reformulation of the MOO into an SOO: Normalization step

Each of the objectives needs to be normalized before being summed and weighted in the aggregated objective function. To this end, each objective in P1 is first optimized separately. Let (x^k, y^k) be the optimal values of the decision variables when minimizing objective *k* ($k = 1, \dots, K$). Lower and upper bounds on each objective function *k* (f_k and \bar{f}_k , respectively) are calculated as follows:

$$\underline{f}_k = \min \{f_k(x^1, y^1), \dots, f_k(x^K, y^K)\}$$

$$\bar{f}_k = \max \{f_k(x^1, y^1), \dots, f_k(x^K, y^K)\}$$

Once the bounds are obtained, we normalize the objectives as follows:

$$\hat{f}_k = \frac{f_k(x, y) - \underline{f}_k(x, y)}{\bar{f}_k(x, y) - \underline{f}_k(x, y)} \tag{18}$$

where \hat{f}_k is the normalized value for objective *k*.

Step 5: Construction and solution of the SOO model

The lower and upper bounds on the objectives (previous step) and the weights obtained in step 3 are utilized to construct an aggregated objective function for the auxiliary problem P3 as follows:

$$\begin{aligned} \min \quad & \sum_{k=1}^p \omega_k \hat{f}_k(x, y) \\ \text{s.t.} \quad & h(x, y) = 0 \\ & g(x, y) \leq 0 \\ & x \in \mathfrak{R}, y \in \{0, 1\} \end{aligned} \tag{P3}$$

The solution of this SOO problem (P3) will provide the point that best reflects the decision-makers' preferences.

Remarks:

- The solution of P3 is guaranteed to be a Pareto optimal point of P1 because model P3 represents a single iteration of the weighted sum method applied to P1. See Ehrgott (2005) for more details.
- The normalization procedure described above ensures that all of the objective function values belong to the interval [0,1]. Note, however, that any other normalization method could be applied for the same purpose (Cloquell et al., 2001).
- The MINLP contains bilinear terms (Eq 10), which may lead to the existence of multiple local optima (i.e. multimodality). Hence, a global optimization package should be used to ensure convergence to the global optimum within a given epsilon tolerance.
- Other MCDM methods can be applied to obtain the weighting factors to be appended to the objectives, such as ranking methods (Yoon and Hwang, 1995), categorization methods, rating methods and pairwise comparison methods (Marler and Arora, 2004).
- The same approach presented in step 2 for generating matrices with maximum consistency can be used, with little modification, to increase the consistency of a given coefficient matrix *S* with elements s_{ij} . To this end, we would solve a MINLP which would seek to minimize the distance (quantified via norm 1 or norm 2) between the new weights and the current ones subject to an additional constraint that enforces the eigenvalue to be below a given upper bound $\bar{\lambda}$ ensuring a minimum consistency level (Eq. (19)).

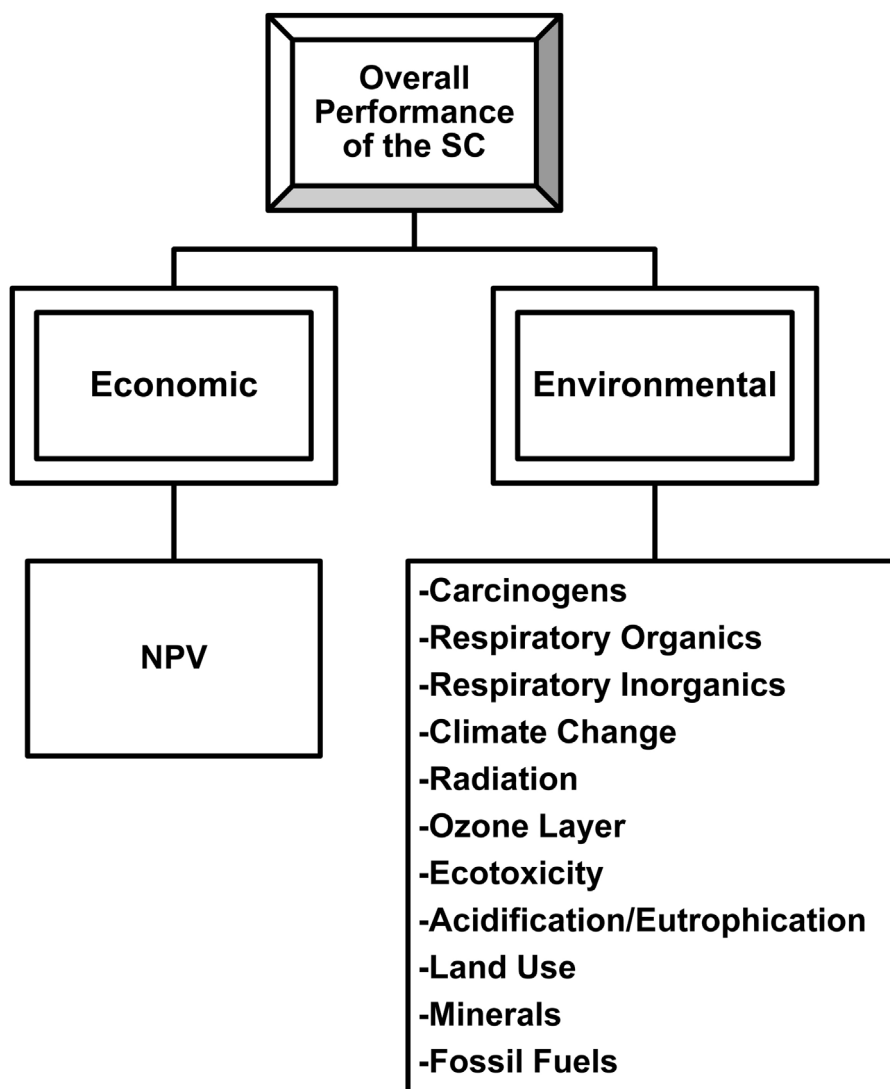


Fig. 2. Schematic of the sugar/bioethanol SC network.

$$\min \sum_j \sum_i |a_{ij} - s_{ij}|, \quad \lambda \leq \bar{\lambda} \quad (19)$$

In this objective function, $a_{ij} \in \mathfrak{R}$ is an element of the desired consistent matrix. The remainder of the formulation would include the constraints given by Eqs. (7), (8), (10) and (12) to Eq. (17).

4. Case study

We test the capabilities of our approach through its application to the model presented by Mele et al. (2011), who first addressed the problem of designing a sugar/ethanol SC considering economic and environmental objectives simultaneously. This problem was later studied by Kostin et al. (2012) and Copado-Méndez et al. (2013).

Fig. 2 depicts the three-echelon SC network considered for the analysis. It encompasses a number of production plants (supplied by sugar cane growers), storage facilities, and markets with an associated demand for each of the final products: white sugar, raw sugar and fuel grade ethanol.

The SC operates over a time horizon divided into annual periods, and considering a geographical area split into regions that match

the 24 provinces of the country. Each region has an associated sugar cane production capacity per period.

According to the production technology, five types of production facilities can be established at each region. Raw and white sugar can be produced either by technologies T1 or T2, whereas ethanol can be obtained through technologies T3, T4 and T5. Byproducts of T1 and T2, molasses and honey, respectively, are converted through T3 and T4 into ethanol, while T5 produces ethanol directly from sugar cane. After being stored in appropriate facilities, products are sent to the customers (markets): technology S1 is used for solid products and S2 for liquids. Several emissions and wastes generated by the process activities are considered in the analysis. Regarding transportation, heavy trucks carry sugar cane, lorry trucks transport sugar and tank trucks transport ethanol, all of them using transportation links that can be established between any SC nodes.

Given are a number of parameters such as: time horizon, product prices, cost data for production, storage and transportation, demand forecast, tax and interest rates, capacity data (for plants, warehouses and transportation means), capital investment, landfill tax, and environmental data (emissions and raw material consumption linked to the SC activities). The aim of the SC design problem is to find the SC network topology of the sugar/bioethanol SC and the strategic decisions to be made so as to minimize the environmental

Table 3

Individual ranking of the decision-makers (10 in total, labelled as A to J) for the environmental objectives (1 Carcinogens, 2 Respiratory inorganics, 3 Respiratory organics, 4 Climate change, 5 Radiation, 6 Ozone layer, 7 Eco-toxicity, 8 Acidification/eutrophication, 9 Land use, 10 Minerals, 11 Fossil fuels).

Decision-maker	Environmental objective										
	1	2	3	4	5	6	7	8	9	10	11
A	10	9	9	8	9	7	8	9	5	4	7
B	9	6	4	10	5	2	7	5	1	3	5
C	9	7	7	9	8	7	7	7	6	6	8
D	8	6	7	9	6	7	8	6	5	5	6
E	8	8	8	8	5	7	6	7	7	6	6
F	7	6	6	9	5	8	6	5	4	4	4
G	9	8	8	10	8	9	8	8	7	7	8
H	9	6	6	8	6	6	6	6	5	5	5
I	0	2	1	9	6	8	7	10	3	4	5
J	6	5	5	7	7	5	5	5	4	5	6

Table 4

Specific constraints added in the MINLP using the ranking provides by decision-maker A in step 1.

Decision Maker A				
Ranking	Environmental Objective	Score		Equations
1	Carcinogens	10	I	$a_{1,2} > a_{1,1} + 1$
2	Respiratory Inorganics	9	II	$a_{2,3} = a_{2,2}$
3	Respiratory Organics	9	III	$a_{3,4} = a_{3,3}$
4	Radiation	9	IV	$a_{4,5} = a_{4,4}$
5	Acidification/Eutrophication	9	V	$a_{5,6} > a_{5,5} + 1$
6	Climate Change	8	VI	$a_{6,7} = a_{6,6}$
7	Ecotoxicity	8	VII	$a_{7,8} > a_{7,7} + 1$
8	Ozone Layer	7	VIII	$a_{8,9} = a_{8,8}$
9	Fossil fuels	7	IX	$a_{9,10} > a_{9,9} + 1$
10	Land Use	5	X	$a_{10,11} > a_{10,10} + 1$
11	Minerals	4		

Table 5

Aggregated coefficient matrix for the Eco-indicator 99 categories (1 Carcinogens, 2 Respiratory inorganics, 3 Respiratory organics, 4 Climate change, 5 Radiation, 6 Ozone layer, 7 Eco-toxicity, 8 Acidification/eutrophication, 9 Land use, 10 Minerals, 11 Fossil fuels).

Impactcategory	1	2	3	4	5	6	7	8	9	10	11
1	1	0.8512	1.0603	0.9996	1.1741	2.0343	2.7585	1.8226	3.1575	2.4906	2.9997
2	1.1744	1	1.2782	1.6889	1.4753	2.4713	2.7585	2.6011	3.5536	3.0022	3.2649
3	0.9425	0.7821	1	1.3209	1.0603	2.0341	2.2705	1.885	3.4654	2.2899	3.1027
4	0.9997	0.5919	0.7565	1	1.1072	1.6332	2.408	2.1409	3.0254	2.1405	2.7588
5	0.8511	0.6775	0.9425	0.9026	1	1.7772	2.1407	1.6329	3.3508	2.1592	2.5559
6	0.4913	0.4045	0.4913	0.6122	0.5624	1	1.1159	0.9997	2.0517	1.3903	1.838
7	0.3624	0.3624	0.4402	0.415	0.4668	0.8957	1	0.719	1.3795	1.1159	1.3106
8	0.5483	0.3843	0.5303	0.4668	0.6121	0.9997	1.3903	1	1.9838	1.4259	1.8226
9	0.3165	0.2813	0.2885	0.3304	0.2983	0.4872	0.7246	0.5038	1	0.8024	0.7189
10	0.4013	0.333	0.4366	0.4668	0.463	0.7189	0.8956	0.701	1.2455	1	1.2455
11	0.333	0.3061	0.3221	0.3624	0.3911	0.5438	0.7624	0.5483	1.3903	0.8024	1

impacts while maximizing the economic benefit simultaneously. The environmental impact values are assessed through an LCA (Life Cycle Assessment) analysis. For each region and time period, we need to determine: (i) the type and number of production and storage facilities to be installed or expanded; (ii) the links between facilities and the required transportation means; and (iii) the production rates and material flows (raw material, wastes and final products). Data considered for this analysis can be found in Appendix A.

Mele et al. (2011) solved the aforementioned problem by formulating an MOO mixed-integer linear programming (MILP) formulation. The interested reader can find details on this MILP model in the original publication. The model optimizes, at the same time, the economic profit, quantified via the net present value (NPV), and the environmental performance, assessed through a set of LCA-based metrics, in a similar way as was done in previous works by the authors (Mele et al., 2005; Guillén-Gosálbez et al., 2009). Note that the AHP has been used in the LCA literature as a weighting method to weight impact categories in the Impact Assessment phase of an LCA study (Finnveden, 1999), and was applied to several LCA stud-

Table 6

Aggregated coefficient matrix of the pairwise comparison between economic and environmental criteria.

	Economic	Environmental
Economic	1	2.276
Environmental	0.439	1

ies (Miettinen and Hämäläinen, 1997; Pineda-Henson and Culaba, 2004). AHP has also been combined with LCA-based environmental performance indicators (Hermann et al., 2007), but to our best knowledge, never integrated with mathematical programming.

Hence, the MOO problem has the following 12 objectives: (a) NPV as the economic indicator; and (b) 11 environmental impact categories taken from the Eco-indicator 99 methodology (Appendix B), which include: (1) Carcinogens, (2) Respiratory organics, (3) Respiratory inorganics, (4) Climate change, (5) Radiation, (6) Ozone layer, (7) Ecotoxicity, (8) Acidification/eutrophication, (9) Land use, (10) Minerals, and (11) Fossil fuels.

Table 7
Environmental weighting factors (ω_b) obtained from the AHP methodology and the Eco-indicator 99 (1 Carcinogens, 2 Respiratory inorganics, 3 Respiratory organics, 4 Climate change, 5 Radiation, 6 Ozone layer, 7 Eco-toxicity, 8 Acidification/eutrophication, 9 Land use, 10 Minerals, 11 Fossil fuels).

Impact category	AHP	Eco-indicator 99 Hierarchist	Eco-indicator 99 Individualist	Eco-indicator 99 Egalitarian
1	0.1619	0.1	0.12360	0.0811
2	0.0733	0.1	0.12360	0.0811
3	0.0666	0.1	0.12360	0.0811
4	0.2669	0.1	0.12360	0.0811
5	0.0768	0.1	0.12360	0.0811
6	0.0810	0.1	0.12360	0.0811
7	0.0797	0.1	0.05618	0.1351
8	0.0784	0.1	0.05618	0.1351
9	0.0300	0.1	0.05618	0.1351
10	0.0286	0.05	0.04494	0.0541
11	0.0567	0.05	0.04494	0.0541

Table 8
Weights obtained from the AHP methodology (ω_{NPV} , ω_{env}) for the economic and environmental aspects.

Criteria	Weight
Economic	0.6948
Environmental	0.3052

The environmental methodology used, Eco-indicator 99, groups the impacts into three damage categories: 1 to 6 are aggregated into Damage to Human Health (HH), categories 7 to 9 belong to Damage to Ecosystem Quality (EQ), and categories 10 and 11 belong to Damage to Resources (RS). Furthermore, Eco-indicator 99 provides weighting factors for each of these damage categories. The weighting factors are derived from a panel of experts, and the particular values vary according to the “perspective” considered by the panel: hierarchist, individualist or egalitarian.

Note that one could use these weighting factors to reformulate the MOO model into an SOO one (or bi-objective, if the NPV is also considered as a separate objective). This approach, however, would produce a solution that would reflect the Eco-indicator 99 panel of experts’ preferences, which are too general and therefore not tailored to any specific environmental problem. Hence, a more effective approach to tackle the problem is to elicit the experts’ preferences regarding the SC design problem itself. These regional experts have deeper understanding of the problem and consequently can take better decisions. As an example of the potential limitations of using general weights, note that the geographic scope of a given impact is barely covered in any LCA, despite being of utmost importance for the Argentinean stakeholders. Therefore, using general weights established by panel of experts may lead to poor and meaningless solutions that neglect the context of the environmental problem.

5. Application to the case study

Each of the steps of our approach is described next in the context of the ethanol SC design problem.

Step 1:

Fig. 3 shows the hierarchy tree constructed with the objectives of the SC design problem. To obtain the weighting factors for the SOO model, two groups of 10 experts each were asked to rank the objectives within the same hierarchy level. The first group, composed of PhD students with substantial exposure to LCA and SC design research, performed the evaluations for the objectives in the environmental branch. The second group, conformed by engineers from the local sugar/ethanol industrial activity, compared economic and environmental indicators bearing the enterprise goals in mind.

Experts answered the surveys individually without having the chance of reaching any consensus among them. In the environmen-

Table 9
Final weights (ω_k) for the 12 criteria (1 Carcinogens, 2 Respiratory inorganics, 3 Respiratory organics, 4 Climate change, 5 Radiation, 6 Ozone layer, 7 Eco-toxicity, 8 Acidification/eutrophication, 9 Land use, 10 Minerals, 11 Fossil fuels).

Criteria	Using AHP	Using Eco-indicator 99 perspectives		
		Hierarchist	Individualist	Egalitarian
1	0.0494	0.0305	0.0377	0.0248
2	0.0224	0.0305	0.0377	0.0248
3	0.0203	0.0305	0.0377	0.0248
4	0.0815	0.0305	0.0377	0.0248
5	0.0234	0.0305	0.0377	0.0248
6	0.0247	0.0305	0.0377	0.0248
7	0.0243	0.0305	0.0172	0.0412
8	0.0239	0.0305	0.0172	0.0412
9	0.0092	0.0305	0.0172	0.0412
10	0.0087	0.0153	0.0137	0.0165
11	0.0173	0.0153	0.0137	0.0165
NPV ^a	0.6948	0.6948	0.6948	0.6948
Euclidean distance to AHP	0	0.0378	0.0212	0.0586

^a NPV is the same regardless the approach as its priority is independent of the internal environmental priorities.

tal impact surveys, they were asked to appraise the importance of the 11 impacts in a 0–10 scale (in order to avoid consistency degradation). The objectives in each survey were sorted from most to least important. On the upper level of the hierarchy tree, where only economic and environmental issues are compared, the expert was asked to make one single comparison between both criteria using the Saaty scale. Fig. 4 shows the average and standard deviation of the experts’ valuations of the impacts in a 0–10 scale.

Fig. 4 shows that experts consider carcinogens and climate change (HH) as the most important impacts, while land use and minerals (RS) are the least important. The other objectives are virtually valued in a similar way. Cancer is perceived as a very serious disease, with many people suffering its consequences either directly or indirectly. Meanwhile climate change is one of the main challenges faced by society and constantly being discussed in the media. Hence, it is not surprising that both categories are given more importance than the others. The low standard deviation of climate change (Fig. 4) is quite remarkable and evidences the global awareness on this topic. Conversely, the lower rated impacts are less known and the general social concern on them is still budding. Note that the respondents come from the same geographic region, so they may have similar preferences. Table 3 shows the scores assigned by decision-makers to each impact category.

Step 2:

The ranking values given by decision-makers (A to J in Table 3) were used to define 10 constraints that were added to the MINLP. First, for each respondent, the 11 objectives were ranked according to their score from the most important to the least important. The constraints shown in Table 4 were then derived based on these

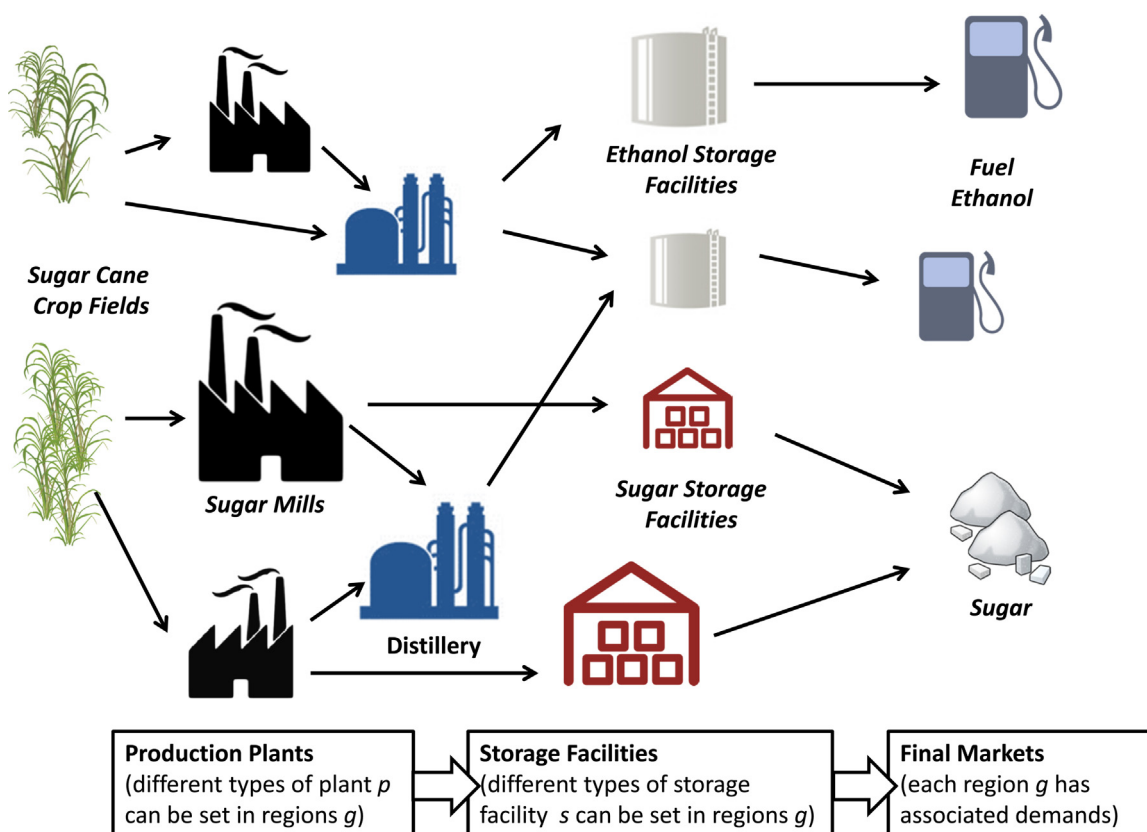


Fig. 3. AHP hierarchy structure for the case study. The overall performance of the SC is located on the top. In the second level two branches are considered: environmental and economic, whereas the environmental branch includes 11 impact categories.

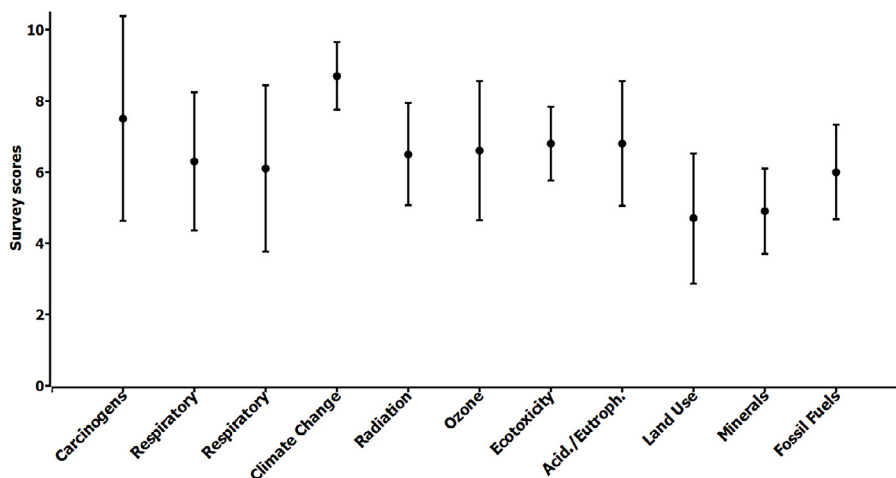


Fig. 4. Respondents' answers on environmental impacts. Black dots represent the average value whereas vertical bars represent the standard deviation of the surveys.

scores for respondent A. The resulting mathematical formulation was implemented in GAMS[®] v.24.0.2 and solved with the general-purpose MINLP solver BARON (Sahinidis, 2014), which guarantees convergence to the global optimum within an epsilon tolerance. The problems were solved in an Intel[®] Core 2 Duo, 4Gb RAM computer. Each model includes 464 single variables, 319 discrete variables and 266 constraints, and leads to a CPU time of around 30 min for an optimality gap of 0%. Let us note that the processing time required by the analyst to translate each survey into model equations is about 15 min. We obtain therefore 10 Saaty matrices with the maximum possible consistency for each respondent's preferences.

Step 3:

After obtaining the 10 individual coefficient matrices for the environmental criteria, we calculated a harmonized matrix according to Eq. (3) (see Table 5). For the upper level in the hierarchy tree, a single comparison matrix was obtained in a similar way by computing the geometric mean of the individual comparisons (made in step 1) between economic and environmental concerns. This last matrix is shown in Table 6.

For both matrices (Tables 5 and 6), we obtained the corresponding weights (eigenvectors) assigned to each objective. Table 7 displays the weights (ω_b) for each environmental impact b . For comparison purposes, the Eco-indicator 99 priorities (under the

Table 10
Solutions found optimizing each objective of the problem. (1 Carcinogens, 2 Respiratory inorganics, 3 Respiratory organics, 4 Climate change, 5 Radiation, 6 Ozone layer, 7 Eco-toxicity, 8 Acidification/eutrophication, 9 Land use, 10 Minerals, 11 Fossil fuels).

SOO problem objective	Objective function values, f_k											
	NPV (\$)	1	2	3	4	5	6	7	8	9	10	11
NPV	1.41·10 ⁹	1.12·10 ⁷	1.05·10 ⁵	1.71·10 ⁹	−1.50·10 ⁸	4.88·10 ⁵	2.05·10 ⁴	1.87·10 ⁷	8.12·10 ⁸	1.87·10 ⁹	4.85·10 ⁶	2.34·10 ⁸
1	−4.91·10 ⁸	5.30·10 ⁶	4.49·10 ⁴	7.75·10 ⁸	−6.66·10 ⁷	2.36·10 ⁵	9.58·10 ³	8.38·10 ⁶	3.68·10 ⁸	8.51·10 ⁸	2.37·10 ⁶	1.09·10 ⁸
2	−4.95·10 ⁸	5.34·10 ⁶	4.47·10 ⁴	7.90·10 ⁸	−6.63·10 ⁷	2.73·10 ⁵	1.02·10 ⁴	8.54·10 ⁶	3.74·10 ⁸	8.79·10 ⁸	2.59·10 ⁶	1.14·10 ⁸
3	−4.98·10 ⁸	5.30·10 ⁶	4.49·10 ⁴	7.75·10 ⁸	−6.66·10 ⁷	2.36·10 ⁵	9.58·10 ³	8.38·10 ⁶	3.68·10 ⁸	8.51·10 ⁸	2.37·10 ⁶	1.09·10 ⁸
4	8.23·10 ⁸	1.11·10 ⁷	1.07·10 ⁵	1.72·10 ⁹	−1.51·10 ⁸	4.83·10 ⁵	2.05·10 ⁴	1.89·10 ⁷	8.14·10 ⁸	1.87·10 ⁹	4.78·10 ⁶	2.34·10 ⁸
5	−4.95·10 ⁸	5.30·10 ⁶	4.49·10 ⁴	7.75·10 ⁸	−6.66·10 ⁷	2.36·10 ⁵	9.58·10 ³	8.38·10 ⁶	3.68·10 ⁸	8.51·10 ⁸	2.37·10 ⁶	1.09·10 ⁸
6	−4.95·10 ⁸	5.30·10 ⁶	4.49·10 ⁴	7.75·10 ⁸	−6.66·10 ⁷	2.36·10 ⁵	9.58·10 ³	8.38·10 ⁶	3.68·10 ⁸	8.51·10 ⁸	2.37·10 ⁶	1.09·10 ⁸
7	−4.99·10 ⁸	5.30·10 ⁶	4.49·10 ⁴	7.75·10 ⁸	−6.66·10 ⁷	2.36·10 ⁵	9.58·10 ³	8.38·10 ⁶	3.68·10 ⁸	8.51·10 ⁸	2.37·10 ⁶	1.09·10 ⁸
8	−5.07·10 ⁸	5.30·10 ⁶	4.49·10 ⁴	7.75·10 ⁸	−6.66·10 ⁷	2.36·10 ⁵	9.58·10 ³	8.38·10 ⁶	3.68·10 ⁸	8.51·10 ⁸	2.37·10 ⁶	1.09·10 ⁸
9	−4.84·10 ⁸	5.30·10 ⁶	4.49·10 ⁴	7.75·10 ⁸	−6.66·10 ⁷	2.36·10 ⁵	9.58·10 ³	8.38·10 ⁶	3.68·10 ⁸	8.51·10 ⁸	2.37·10 ⁶	1.09·10 ⁸
10	−5.00·10 ⁸	5.30·10 ⁶	4.49·10 ⁴	7.75·10 ⁸	−6.66·10 ⁷	2.36·10 ⁵	9.58·10 ³	8.38·10 ⁶	3.68·10 ⁸	8.51·10 ⁸	2.37·10 ⁶	1.09·10 ⁸
11	−5.00·10 ⁸	5.30·10 ⁶	4.49·10 ⁴	7.75·10 ⁸	−6.66·10 ⁷	2.36·10 ⁵	9.58·10 ³	8.38·10 ⁶	3.68·10 ⁸	8.51·10 ⁸	2.37·10 ⁶	1.09·10 ⁸

Table 11
Extreme values for the objective functions.

Objective	f_k	\bar{f}_k
NPV (M\$)	−5.07E+02	1.41E+03
Carcinogens (DALY)	5.30E+06	1.12E+07
Respiratory inorganics (DALY)	4.47E+04	1.07E+05
Respiratory organics (DALY)	7.75E+08	1.72E+09
Climate change (DALY)	−1.51E+08	−6.63E+07
Radiation (DALY)	2.36E+05	4.88E+05
Ozone layer (DALY)	9.58E+03	2.05E+04
Ecotoxicity (m ² year)	8.38E+06	1.89E+07
Acidification/eutrophication (m ² year)	3.68E+08	8.14E+08
Land use (m ² year)	8.51E+08	1.87E+09
Minerals (MJ)	2.37E+06	4.85E+06
Fossil fuels (MJ)	1.09E+08	2.34E+08

three perspectives) are listed as well in the same table. Table 8 shows the weighting factors for the environmental (ω_{env}) and economic (ω_{NPV}) indicators, whereas Table 9 shows the combined weights (after merging all the weights) for the 12 criteria considered in this study. The combined environmental weights were calculated as in Eq. (20).

$$\omega_k = \omega_b \cdot \omega_{env}, \quad \forall k/k \text{ is an environmental objective,} \quad (20)$$

whereas the economic weight ω_{NPV} , is the same in all of the cases, as it does not depend on the individual weights assigned to each environmental indicator. Table 9 also shows the Euclidean distance between the AHP weighting factors and those taken from the Eco-indicator 99. These results reinforce the observation made when analyzing Fig. 4, namely, that the weights given by a panel of general experts may differ greatly from the weights established by those regional experts specialized on the specific problem.

Step 4:

The MILP-SOO models that optimize each individual objective separately were implemented in GAMS (Rosenthal, 2015) and solved with CPLEX 11.0 on a PC with AMD Phenom(tm) II N830 Triple-Core processor (4Gb RAM). Each model includes 47,249 continuous variables, 10,962 discrete variables and 48,546 constraints, with the associated CPU time ranging from 4.1 to 18.2 s. Table 10 shows the solutions found, whereas Table 11 shows the extreme values obtained for each objective function.

Step 5:

Model P3 was constructed and solved using the weights obtained in step 3. The model size is similar to that of the SOO models in step 4. A solution with an absolute optimality gap of 10^{-4} was obtained in 551 s using the same processor as in step 4.

6. Results and discussion

The SOO problem (P3) was solved first using the AHP weights, and then using the weighting factors given by the three Eco-indicator 99 perspectives (Table 9). Finding these solutions took 359, 314 and 404 s for the hierarchist, individualist and egalitarian perspectives, respectively, for an optimality gap of 10^{-4} , with the same piece of equipment as before. Table 12 shows the corresponding objective function values. Essentially, the egalitarian solution differs greatly from the AHP-based one in terms of NPV value (44%), and less (11%) in terms of environmental impacts. On average, the largest mismatch corresponds to respiratory diseases by organics and climate change. The AHP solutions attempts to reduce climate change more than the other solutions, incurring in an extra cost that makes the NPV drop compared to the maximum NPV solution.

A radar chart (Fig. 5) is plotted to show the normalized value reached by every SOO solution in each criterion. The normalization procedure is that explained in step 4. Every line in Fig. 5 stands for a solution that connects its performance in every criterion (objective function). The dashed line with starred markers is the solution resulting from the SOO problem using the AHP-based weights. The line with squared markers is the extreme solution of the MOO problem with maximum NPV. The solutions corresponding to the SOO problem with the Eco-indicator 99 weighting are depicted by triangles (hierarchist), diagonal crosses (individualist) and diamonds (egalitarian). As observed, some objectives are strongly correlated, as when one increases so do the others and vice versa (acidification/eutrophication correlates with ecotoxicity, while respiratory inorganics correlates with respiratory organics). The p -value test for the hypothesis of no correlation has been used to justify this observation in a quantitative way. All p -values fall below a significance level of 0.05; hence the correlation among the k objectives is significant.

A further analysis shows that the AHP, hierarchist and individualist solutions feature high NPV values (low values indeed after normalizing the original NPV values). The last row of Table 12 shows the Euclidean distance between the solutions and the maximum NPV solution. According to these figures, the individualist solution is the closest one to the maximum NPV point, whereas the egalitarian solution is the farthest one. The AHP-based solution is relatively close to the maximum NPV one, mainly because they both show similar environmental impacts despite differing in NPV values.

Fig. 5 Radar plot for the best NPV solution and the solutions calculated with the weights of the AHP-based method and the weights of the three Eco-Indicator 99 perspectives

Table 12
 Values of the criteria obtained for the solutions.

Criterion (unit)	Max NPV	AHP	Eco-Indicator 99		
			Hierarchist	Individualist	Egalitarian
NPV (M\$)	1406.72	1285.60	1271.19	1350.00	718.00
Carcinogens (DALY)	$1.12 \cdot 10^7$	$1.12 \cdot 10^7$	$1.03 \cdot 10^7$	$1.11 \cdot 10^7$	$1.02 \cdot 10^7$
Resp. organics (DALY)	$1.05 \cdot 10^5$	$1.04 \cdot 10^5$	$9.94 \cdot 10^4$	$1.04 \cdot 10^5$	$9.89 \cdot 10^4$
Resp. inorganics (DALY)	$1.71 \cdot 10^9$	$1.71 \cdot 10^9$	$1.60 \cdot 10^9$	$1.70 \cdot 10^9$	$1.59 \cdot 10^9$
Climate change (DALY)	$-1.50 \cdot 10^8$	$-1.49 \cdot 10^8$	$-1.41 \cdot 10^8$	$-1.49 \cdot 10^8$	$-1.40 \cdot 10^8$
Radiation (DALY)	$4.88 \cdot 10^5$	$4.94 \cdot 10^5$	$4.48 \cdot 10^5$	$4.86 \cdot 10^5$	$4.42 \cdot 10^5$
Ozone layer (m ² year)	$2.05 \cdot 10^4$	$2.06 \cdot 10^4$	$1.90 \cdot 10^4$	$2.03 \cdot 10^4$	$1.88 \cdot 10^4$
Ecotoxicity (m ² year)	$1.87 \cdot 10^7$	$1.87 \cdot 10^7$	$1.76 \cdot 10^7$	$1.86 \cdot 10^7$	$1.75 \cdot 10^7$
Acidif./eutroph. (m ² year)	$8.12 \cdot 10^8$	$8.10 \cdot 10^8$	$7.59 \cdot 10^8$	$8.06 \cdot 10^8$	$7.54 \cdot 10^8$
Land use (m ² year)	$1.87 \cdot 10^9$	$1.87 \cdot 10^9$	$1.75 \cdot 10^9$	$1.86 \cdot 10^9$	$1.73 \cdot 10^9$
Minerals (MJ)	$4.85 \cdot 10^6$	$4.90 \cdot 10^6$	$4.43 \cdot 10^6$	$4.80 \cdot 10^6$	$4.36 \cdot 10^6$
Fossil fuels (MJ)	$2.34 \cdot 10^8$	$2.34 \cdot 10^8$	$2.17 \cdot 10^8$	$2.31 \cdot 10^8$	$2.15 \cdot 10^8$
Euclidean distance to Max NPV (10 ⁶)	0	121.14	219.20	58.85	715.66

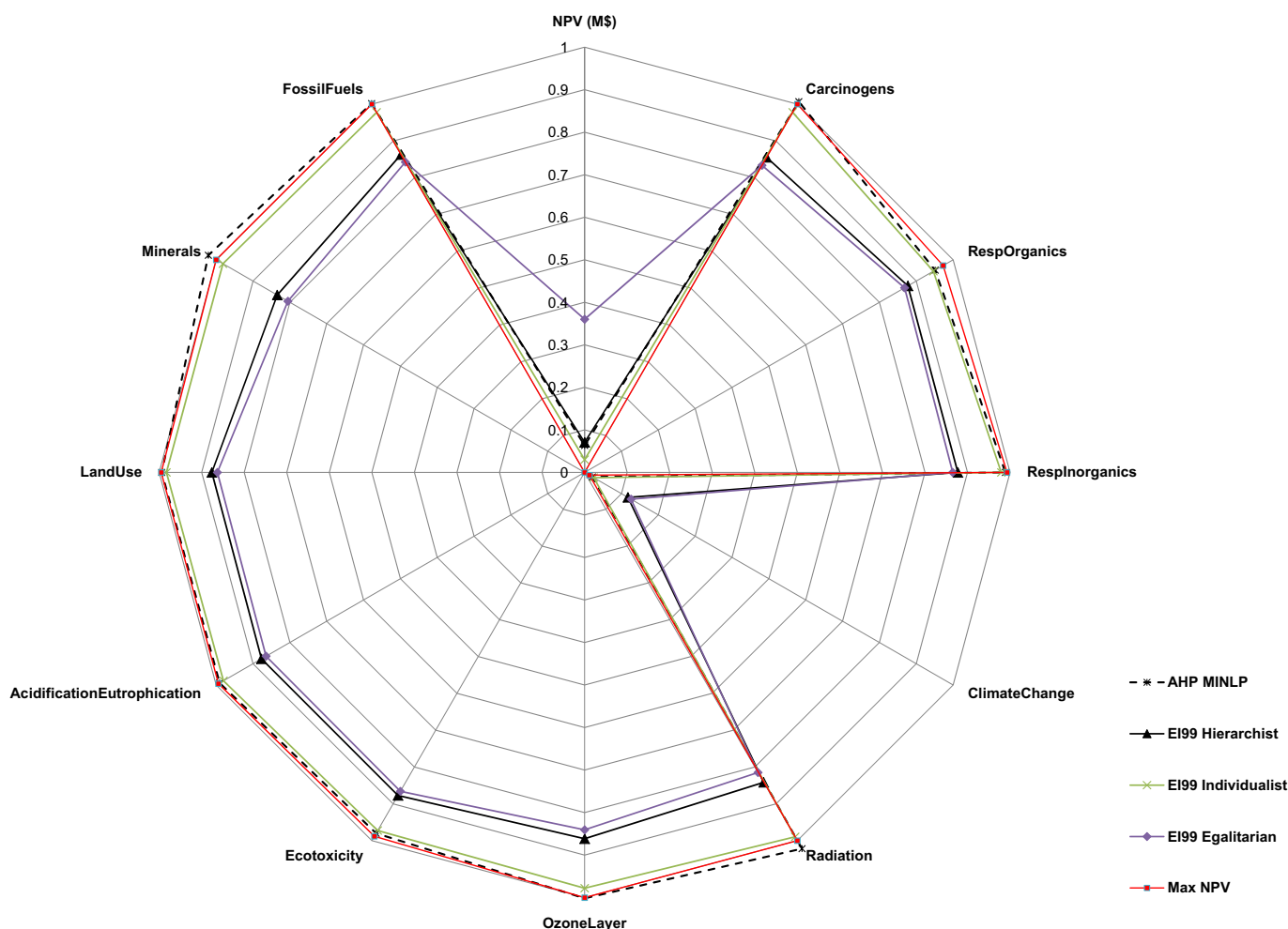


Fig. 5. Radar plot for the best NPV solution and the solutions calculated with the weights of the AHP-based method and the weights of the three Eco-Indicator 99 perspectives.

Three specific solutions for the sugar/ethanol SC design problem are chosen for comparison purposes: the solution with maximum NPV, the one obtained by applying the proposed AHP-based method and one of the solutions coming from the Eco-indicator 99-based weighting factors (hierarchist perspective). This perspective is used more often than the egalitarian or individualist ones.

Fig. 6 shows the SC structure corresponding to each solution, specifying the number and type of production facilities, their location and the existence of distribution channels. Due to space limitations, we show only the decisions associated with the first

year of the 6-year time horizon of the model. Storage facilities are not represented for clarity.

The solution with maximum NPV has the lowest number of installed facilities (9 in total). This design entails the lowest possible costs to satisfy the SC demand. Here, technologies T2 and T4 (production of sugar and ethanol from honey) prevail. Conversely, the AHP solution leads to the highest number of installed facilities (13 facilities of different types: T1, T2, T4 and T5). In this case study, the Eco-indicator 99 solution represents an intermediate situation (12 facilities) that lies closer to the AHP solution than the

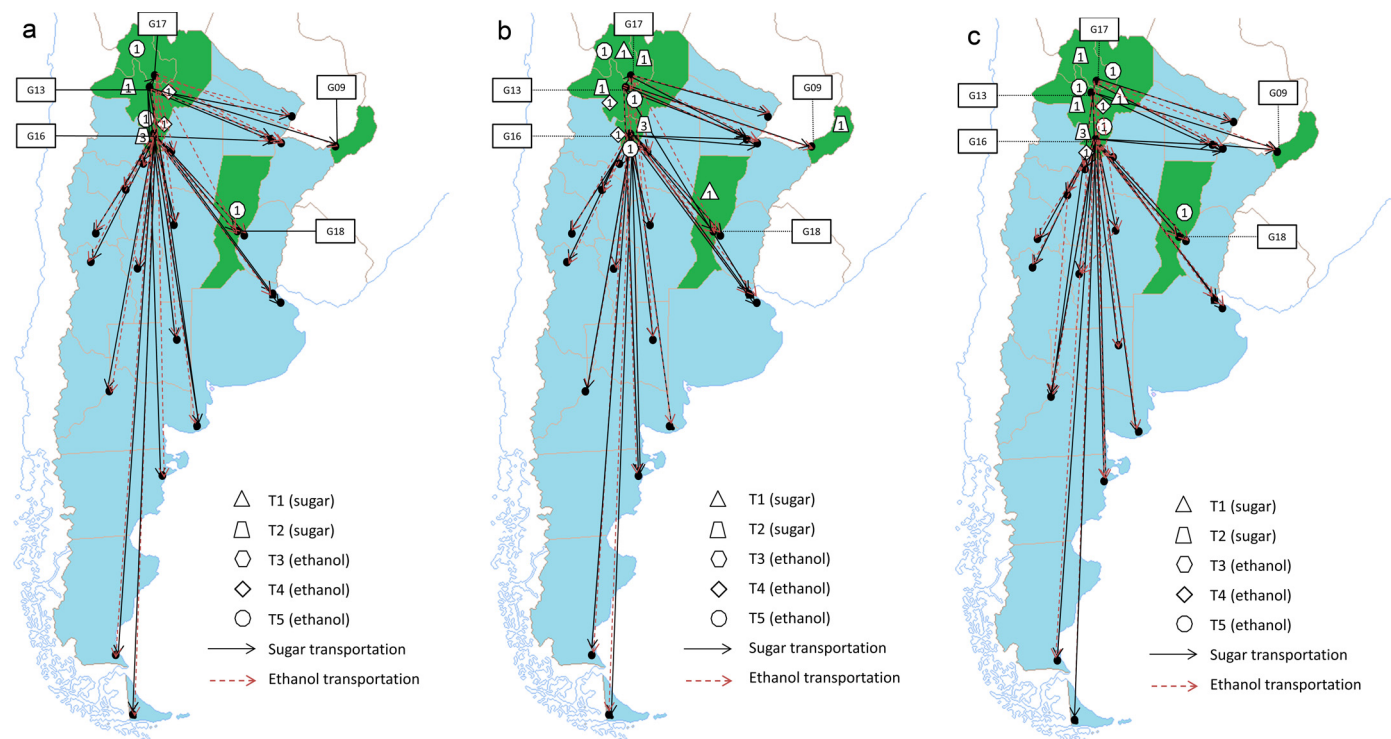


Fig. 6. SC structure, year 1, corresponding to (a) the maximum NPV solution (b) the AHP-based solution, and (c) the hierarchist Eco-indicator 99-based solution.

maximum NPV one. In all three solutions, transportation needs are rather similar and therefore not presented.

The maximum NPV and AHP-based solutions show relatively close capital investments: 1,827.4 and 2,022.2 M\$, respectively. The distribution network shows no big differences, since in all of the cases the demand requirements need to be met. The hierarchist solution presents higher plant investment (3000 M\$) than the AHP-based one. This illustrates the different results that can be generated when decisions are made on the basis of general panels of experts (Eco-indicator 99) in lieu of local stakeholders. In this particular case, SC configurations are similar indeed, mainly because the weightings factors presented in Table 9 are also similar. On the other hand, the environmental effects look rather diluted, since the NPV is highly rated among the various objectives.

7. Conclusions

This paper presents a methodology to solve MOO problems that integrates mathematical programming with the AHP, a widely used and well established multi-attribute decision-making algorithm. In essence, our approach identifies a single Pareto point that is consistent with the decision-makers' preferences, thereby simplifying greatly the analysis. A real-world case study based on the sugar/ethanol industry in Argentina was used to demonstrate the capabilities of the proposed methodology.

Numerical results allow us to draw some important conclusions. First, the weighting factors derived from the proposed AHP-based methodology (which are consistent with the preferences of a set of decision-makers with deep knowledge on the problem) may differ significantly from the weighting scheme used in general methodologies, such as the Eco-indicator 99. Hence, using general approaches in a particular problem might lead to solutions that do not fully reflect the stakeholders' preferences. Second, the complexity of MOO is greatly reduced by our method: (i) the surveys can be completed more easily compared to the standalone application of the AHP; and (ii) the MOO is solved using an auxiliary

single-objective model, thereby avoiding the need to calculate a large number of Pareto points.

The proposed methodology brings a new insight into the design problem by introducing consistent judgments based on the relative importance of the objectives considered. This solution provides an aggregated and comprehensive performance indicator for the entire SC. This aggregated indicator is constructed on the basis of the decision-makers' preferences, which are explicitly incorporated in the optimization model. Our tool could assist authorities in the analysis of strategic policies in the field of agro-industries and energy, facilitating the consensus among all the players involved in the decision-making process.

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Appendix A. Case study data

The demands of the Argentine regions considered in the analysis are presented in Table A1. Sugar, raw sugar and ethanol prices (537, 375 and 869 \$/t, respectively) are considered constant along the time horizon and the same assumption applies to their respective demands in each region. The distance between two regions was calculated as the remoteness among the respective province capitals through main roads. Distance data is shown in Table A2. The time horizon considered in our case is 6 years long. Each province of Argentina has an associated crop capacity for sugar cane that we assume constant along the time horizon. Specifically sugar cane can be grown only in 5 provinces of Argentina. The crop capacities for these regions are shown in Table A3. The production capacities for the technologies considered in this case study are exposed in Table A4. We consider a minimum storage capacity for solid and

Table A1
 Product demand, t/yr.

Province name	Region identifier	Product form		
		White Sugar	Raw Sugar	Ethanol
Buenos Aires DC	G01	76615	38307	84276
Córdoba	G02	84126	42063	92539
Corrientes	G03	25438	12719	27982
Buenos Aires	G04	379269	189634	417196
La Rioja	G05	9715	4857	10686
Mendoza	G06	43565	21783	47922
Neuquén	G07	13721	6860	15093
Entre Ríos	G08	31547	15774	34702
Misiones	G09	27141	13570	29855
Chubut	G10	11517	5759	12669
Chaco	G11	26440	13220	29084
Santa Cruz	G12	5709	2854	6279
Salta	G13	30746	15373	33821
San Juan	G14	17526	8763	19279
San Luis	G15	11017	5508	12118
Tucumán	G16	37156	18578	40871
Jujuy	G17	17126	8563	18838
Santa Fe	G18	81122	40561	89234
La Pampa	G19	8413	4206	9254
Santiago	G20	21733	10866	23906
Catamarca	G21	8613	4306	9474
Río Negro	G22	15023	7511	16525
Formosa	G23	13520	6760	14872
Tierra del Fuego	G24	3205	1602	3525

Table A2
 Distances between regions, km.

	G01	G02	G03	G04	G05	G06	G07	G08	G09	G10	G11	G12	G13	G14	G15	G16	G17	G18	G19	G20	G21	G22	G23	G24
G01	0	711	933	60	1167	1080	1178	511	1008	1379	953	2542	1542	1140	800	1229	1565	484	607	1070	1122	948	1098	3162
G02	711	0	900	768	460	680	1153	360	1118	1524	880	2638	844	600	420	597	867	340	667	439	433	1208	1031	3258
G03	933	900	0	990	1024	1490	1913	573	335	2206	20	3369	830	1460	1190	794	853	540	1388	635	857	1774	186	3989
G04	60	768	990	0	1224	1137	1159	568	1065	1371	1010	2533	1599	1197	857	1286	1622	541	664	1127	1173	924	1236	3153
G05	1167	460	1024	1224	0	612	1427	820	1333	1872	1007	3087	704	355	559	382	727	800	1015	389	171	1565	1139	3707
G06	1080	680	1490	1137	612	0	815	952	1710	1628	1470	2783	1311	166	264	872	1329	930	789	1007	725	1342	1600	3403
G07	1178	1153	1913	1159	1427	815	0	1413	2075	746	1880	1909	1997	981	890	1581	2020	1373	535	1618	1536	557	2020	2529
G08	511	360	573	568	820	952	1413	0	758	1715	590	2887	1107	950	691	794	1130	30	855	635	803	1252	746	3507
G09	1008	1118	335	1065	1333	1710	2075	758	0	2356	332	3511	1142	1708	1449	1086	1165	785	1518	927	1179	1896	508	4131
G10	1379	1524	2206	1371	1872	1628	746	1715	2356	0	2236	1172	2308	1705	1382	2107	2331	1685	857	1986	1900	809	2450	1792
G11	953	880	20	1010	1007	1470	1880	590	332	2236	0	3388	813	1460	1190	774	833	540	1368	618	820	1756	173	4008
G12	2542	2638	3369	2533	3087	2783	1909	2887	3511	1172	3388	0	3482	2868	2545	3192	3505	2850	2020	3070	3167	1952	3593	620
G13	1542	844	830	1599	704	1311	1997	1107	1142	2308	813	3482	0	1150	1264	310	90	1077	1462	472	533	2066	959	4102
G14	1140	600	1460	1197	355	166	981	950	1708	1705	1460	2868	1150	0	320	708	1163	920	848	840	497	1509	1540	3488
G15	800	420	1190	857	559	264	890	691	1449	1382	1190	2545	1264	320	0	838	1287	660	525	859	674	1087	1345	3165
G16	1229	597	794	1286	382	872	1581	794	1086	2107	774	3192	310	708	838	0	328	764	1257	164	221	1803	925	3812
G17	1565	867	853	1622	727	1329	2020	1130	1165	2331	833	3505	90	1163	1287	328	0	1092	1485	490	563	2095	921	4125
G18	484	340	540	541	800	930	1373	30	785	1685	540	2850	1077	920	660	764	1092	0	828	605	777	1218	709	3470
G19	607	667	1388	664	1015	789	535	855	1518	857	1368	2020	1462	848	525	1257	1485	828	0	1129	1065	580	1492	2640
G20	1070	439	635	1127	389	1007	1618	635	927	1986	618	3070	472	840	859	164	490	605	1129	0	234	1669	751	3690
G21	1122	433	857	1173	171	725	1536	803	1179	1900	820	3167	533	497	674	221	563	777	1065	234	0	1645	985	3787
G22	948	1208	1774	924	1565	1342	557	1252	1896	809	1756	1952	2066	1509	1087	1803	2095	1218	580	1669	1645	0	1922	2572
G23	1098	1031	186	1236	1139	1600	2020	746	508	2450	173	3593	959	1540	1345	925	921	709	1492	751	985	1922	0	4213
G24	3162	3258	3989	3153	3707	3403	2529	3507	4131	1792	4008	620	4102	3488	3165	3812	4125	3470	2640	3690	3787	2572	4213	0

Table A3
 Crop capacity, t/yr.

Province	Associated region	Capacity
Misiones	G09	62040
Salta	G13	2068000
Tucumán	G16	12220000
Jujuy	G17	4324000
Santa Fe	G18	125960

Table A4
 Minimum and maximum production capacities of each technology (tons of main product per year).

	Production technologies				
	T1	T2	T3	T4	T5
minimum production capacity	30000	30000	10000	10000	10000
maximum production capacity	350000	350000	300000	300000	300000

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Table A5
Parameters used to assess the capital cost for different production technologies.

	α_{pgt}^{Pr} (\$)	β_{pgt}^{Pr} (\$ yr/t)
T1	5,350,000	535
T2	5,350,000	535
T3	7,710,000	771
T4	7,710,000	771
T5	9,070,000	907

Table A6
Parameters used to evaluate the capital cost for different storage technologies.

	α_{sgt}^{Pr} (\$)	β_{sgt}^{Pr} (\$ yr/t)
S1	1,220,000	122
S2	18,940,000	1894

Table A7
Parameters for capital and operating cost calculation for different transportation modes.

	heavy truck	medium truck	tanker truck
average speed (km/h)	55	60	65
capacity (ton per trip)	30	25	20
availability of transportation mode (h/d)	18	18	18
cost of establishing transportation mode (\$)	30,000	30,000	30,000
driver wage (\$/h)	10	10	10
fuel economy (km/L)	5	5	5
fuel price (\$/L)	0.85	0.85	0.85
general expenses (\$/d)	8.22	8.22	8.22
load/unload time of product (h/trip)	6	6	6
maintenance expenses (\$/km)	0.0976	0.0976	0.0976

liquid materials of 200 tons, and a maximum capacity of 2 billion tons. We assume a storage period of 10 days. The maximum possible capital investment has been set to 109 M\$. The cost coefficients for production technologies are listed in Table A5 whereas costs for storage facility types are listed in Table A6. Sugar production cost is equal to 265 \$/t and ethanol production cost is 317 \$/t. Storage cost for all type of products is assumed to be 0.365 \$/(t yr). The capital and operating costs are calculated with the parameters presented in Table A7. The minimum transportation capacity of heavy trucks, medium trucks and tanker trucks matches the minimum flow rate of the corresponding transportation mode (Table A7), whereas the maximum flow rates are 6.25, 6.25 and 6.00 Mt/yr respectively. The interest rate, tax rate, and salvage value are 0.1, 0.3 and 0.2 respectively. Finally, every kind of liquid residue (vinasses) is supposed to have a landfill tax equal to 0.1 \$/t.

Appendix B. Environmental impact categories in eco-indicator 99

Eco-indicator 99 considers 11 environmental impact categories (Goedkoop and Spriensma, 1999), which are aggregated into three broader damage categories: Human Health, Ecosystem Quality and Resources.

Damage to Human Health

1-*Carcinogens*: carcinogenic effects due to emissions of carcinogenic substances to air, water and soil. Damage is expressed in Disability Adjusted Life Years (DALY)/kg emission.

2-*Respiratory organics*: respiratory effects resulting from summer smog, due to emissions of organic substances to air, causing respiratory effects. Damage is expressed in DALY/kg emission.

3-*Respiratory inorganics*: respiratory effects resulting from winter smog caused by emissions of dust, sulfur and nitrogen oxides to air. Damage is expressed in (DALY)/kg emission.

4-*Climate change*: damage, expressed in DALY/kg emission, resulting from an increase of diseases and death caused by climate change.

5-*Radiation*: damage, expressed in DALY/kg emission, resulting from radioactive radiation.

6-*Ozone layer*: damage, expressed in DALY/kg emission, due to increased UV radiation as a result of emission of ozone depleting substances to air.

Damage to Ecosystem Quality

7-*Ecotoxicity*: damage to ecosystem quality, as a result of emission of ecotoxic substances to air, water and soil. Damage is expressed in Potentially Affected Fraction (PAF)-m²·year/kg emission.

8-*Acidification/Eutrophication*: damage to ecosystem quality, as a result of emission of acidifying substances to air. Damage is expressed in Potentially Disappeared Fraction (PDF)-m²·year/kg emission.

9-*Land use*: Land use (in manmade systems) affects species diversity. Based on field observations, a scale is developed expressing species diversity per type of land use. Species diversity depends on the type of land use and the size of the area. Both regional effects and local effects are taken into account in the impact category. Damage is expressed in Potentially Disappeared Fraction (PDF)-m²·year/m².

Damage to Resources

10-*Minerals*: Mankind will always extract the best resources first, leaving the lower quality resources for future extraction. The damage of resources will be experienced by future generations, as they will have to invest more energy to extract the remaining resources. This extra effort is expressed as “surplus energy” per kg mineral or ore, because of decreasing ore grades.

11-*Fossil fuels*: Surplus energy per extracted MJ, kg or m³ fossil fuel, as a result of lower quality resources.

Weighting criteria

Eco-indicator 99 weights the damage categories to yield a single score: the eco-indicator. Eco indicator 99 requires that this weighting process is performed according to one of three different ‘perspectives’. Each perspective responds to one of the ‘archetypes’ taken from the Cultural Theory framework, frequently used in social science. As a consequence, there are three different versions of the Eco-indicator 99 methodology, according to the perspective used in the weighting process: hierarchist, individualist, and egalitarian. The hierarchist version is the one recommended when the analyst is not sure about which perspective to choose.

Appendix C. Mathematical model

Following the model introduced by Mele et al. (2011), the equations used in our case study are presented below:

Notation

<i>i</i>	Materials
<i>g</i>	Regions
<i>l</i>	Transportation modes
<i>p</i>	Manufacturing technologies
<i>s</i>	storage technologies

t	Time periods	FCI	Fixed capital investment
b	Environmental impact category	FOC_t	Facility operating cost in time t
Sets		$FTDC_t$	Fraction of the total depreciable capital in time t
$IL(l)$	Set of materials that can be transported via transportation mode l	GC_t	General cost
$IM(p)$	Set of main products for each technology p	LC_t	Labor cost
$IS(s)$	Set of materials that can be stored via storage technology s	MC_t	Maintenance cost
SEP	Set of products that can be sold	NE_t	Net earnings in time t
$SI(i)$	Set of storage technologies that can store materials i	NP_{pgt}	Number of installed plants with technology p in region g in time t
Parameters		NPV	Net present value of SC
α_{pgt}^{Pr}	Fixed investment coefficient for technology p	NS_{sgt}	Number of installed storages with storage technology s in region g in time t
α_{sgt}^{Pr}	Fixed investment coefficient for storage technology s	NT_{lt}	Number of transportation units l
β_{pgt}^{Pr}	Variable investment coefficient for technology p	$PCapp_{pgt}$	Existing capacity of technology p in region g in time t
β_{sgt}^{Pr}	Variable investment coefficient for storage technology s	$PCapE_{pgt}$	Expansion of the existing capacity of technology p in region g in time t
ρ_{pi}	Material balance coefficient of material i in technology p	$Q_{ilgg't}$	Flow rate of material i transported by mode l from region g to g' in time period t
τ	Minimum desired percentage of the available installed capacity	Rev_t	Revenue in time t
φ	Tax rate	$SCap_{sgt}$	Capacity of storage s in region g in time t
ω_b	Weighting factor among environmental impact categories b	$SCapE_{sgt}$	Expansion of the existing capacity of storage s in region g in time t
$\omega_{NPV}, \omega_{env}$	Weighting factors between NPV and environmental impact, respectively	ST_{isgt}	Total inventory of material i in region g stored by technology s in time t
avl_l	Availability of transportation mode l	$TOCt$	Transportation operating cost in time t
$CapCrop_{gt}$	Total capacity of sugar cane plantations in region g in time t	PE_{ipgt}	Production rate of material i in technology p in region g in time t
DW_{lt}	Driver wage	PT_{igt}	Total production rate of material i in region g in time t
$EL_{gg'}$	Distance between g and g'	PU_{igt}	Purchase of material i in region g in time t
EPU_b	Impact value b for purchases of sugar cane	TI_b	Total impact value for category b
$EPE_{b,p}$	Impact value b for production in plant p	$X_{lgg't}$	Binary variable, which is equal to 1 if material flow between two regions g and g' is established and 0 otherwise
$EQ_{b,l}$	Impact value b for transportation by transport mode l	W_{igt}	Amount of wastes i generated in region g in period t
\overline{FCI}	Upper limit for capital investment		
FE_l	Fuel consumption of transportation mode l		
FP_{lt}	Fuel price		
GE_{lt}	General expenses of transportation mode l		
LT_{igt}	Landfill tax		
ME_l	Maintenance expenses of transportation mode l		
\overline{PCap}_p	Maximum capacity of technology p		
\underline{PCap}_p	Minimum capacity of technology p		
\overline{PR}_{igt}	Prices of final products		
\overline{Q}_l	Maximum capacity of transportation mode l		
\underline{Q}_l	Minimum capacity of transportation mode l		
\overline{SCap}_s	Maximum capacity of storage technology s		
\underline{SCap}_s	Minimum capacity of storage technology s		
\overline{SD}_{igt}	Actual demand of product i in region g in time t		
SP_l	Average speed of transportation mode l		
sv	Salvage value		
T	Number of time intervals		
$TCap_l$	Capacity of transportation mode l		
TMC_{lt}	Cost of establishing transportation mode l in period t		
UPC_{ipgt}	Unit production cost		
USC_{isgt}	Unit storage cost		
Variables			
CF_t	Cash flow in time t		
DC_t	Disposal cost in time t		
DTS_{igt}	Delivered amount of material i in region g in period t		
IPU_b	Environmental impact b for purchases		
IPE_b	Environmental impact b for manufacturing		
IQ_b	Environmental impact b for transportation		
FC_t	Fuel cost		

Mass Balances Constraints

$$\sum_{s \in IS(i,s)} ST_{isgt-1} + PT_{igt} + PU_{igt} + \sum_{l \in IL(i,l)g' \neq g} \sum_{g'} Q_{ilg'gt} = \sum_{s \in IS(i,s)} ST_{isgt} + DTS_{igt} + \sum_{l \in IL(i,l)g \neq g'} \sum_{g'} Q_{ilgg't} + W_{igt} \quad \forall i, g, t \quad (A.1)$$

$$PT_{igt} = \sum_p PE_{ipgt} \quad \forall i, g, t \quad (A.2)$$

$$PE_{ipgt} = \rho_{pi} PE_{i'pgt} \quad \forall i, p, g, t \quad \forall i' \in IM(i, p) \quad (A.3)$$

$$PU_{igt} \leq CapCrop_{gt} \quad i = \text{sugarcane}, \quad \forall g, t \quad (A.4)$$

$$\sum_{i \in IS(i,s)} ST_{isgt} \leq SCap_{sgt} \quad \forall s, g, t \quad (A.5)$$

$$ALL_{igt} = \sigma DTS_{igt} \quad \forall i, g, t \quad (A.6)$$

$$2ALL_{igt} \leq \sum_{s \in IS(i,s)} SCap_{sgt} \quad \forall i, g, t \quad (A.7)$$

$$DTS_{igt} \leq SD_{igt} \quad \forall i, g, t \quad (A.8)$$

$$X_{lgg't} + X_{l'g't} = 1 \quad \forall l, t, g, g'(g' \neq g) \quad (A.9)$$

Capacity Constraints

$$\tau PCap_{pgt} \leq PE_{ipgt} \leq PCap_{pgt} \quad \forall i, p, g, t \quad (A.10)$$

$$PCap_{pgt} = PCap_{pgt-1} + PCapE_{pgt} \quad \forall p, g, t \quad (A.11)$$

$$\overline{PCap}_p NP_{pgt} \leq PCapE_{pgt} \leq \overline{PCap}_p NP_{pgt} \quad \forall p, g, t \quad (A.12)$$

$$SCap_{pgt} = SCap_{pgt-1} + SCapE_{pgt} \quad \forall s, g, t \quad (A.13)$$

$$SCap_p NS_{sgt} \leq SCapE_{sgt} \leq \overline{SCap}_p NS_{sgt} \quad \forall s, g, t \quad (A.14)$$

$$\underline{Q}_l X_{lgg't} \leq \sum_{i \in IL(i,l)} Q_{lgg't} \leq \overline{Q}_l X_{lgg't} \quad \forall l, g, g', t (g' \neq g) \quad (A.15)$$

Objective Function

$$Net\ Present\ Value \\ NPV = \sum_t \frac{CF_t}{(1+ir)^{t-1}} \quad (A.16)$$

$$CF_t = NE_t - FTDC_t \quad t = 1, \dots, T - 1 \quad (A.17)$$

$$CF_t = NE_t - FTDC_t + svFCI \quad t = T \quad (A.18)$$

$$NE_t = (1 - \phi)(Rev_t - FOC_t - TOC_t) + \phi DEP_t \quad \forall t \quad (A.19)$$

$$Rev_t = \sum_{i \in SEP(i)} \sum_g DTS_{igt} PR_{igt} \quad \forall t \quad (A.20)$$

$$FOC_t = \sum_i \sum_g \sum_{p \in IM(i,p)} UPC_{ipgt} PE_{ipgt} + \sum_i \sum_g \sum_{s \in IS(i,s)} USC_{isgt} All_{igt} + DC_t \quad \forall t \quad (A.21)$$

$$DC_t = \sum_i \sum_g W_{igt} LT_{igt} \quad \forall t \quad (A.22)$$

$$TOC_t = FC_t + LC_t + MC_t + GC_t \quad \forall t \quad (A.23)$$

$$FC_t = \sum_{i \in IL(i,l)} \sum_g \sum_{g' \neq g} \sum_l DW_{lt} \left[\frac{2EL_{g'g} Q_{lgg't}}{FE_l TCap_l} \right] FP_{lt} \quad \forall t \quad (A.24)$$

$$LC_t = \sum_{i \in IL(i,l)} \sum_g \sum_{g' \neq g} \sum_l DW_{lt} \left[\frac{Q_{lgg't}}{TCap_l} \left(\frac{2EL_{g'g}}{SP_l} + LUT_l \right) \right] \quad \forall t \quad (A.25)$$

$$MC_t = \sum_{i \in IL(i,l)} \sum_g \sum_{g' \neq g} \sum_l ME_l \frac{2EL_{g'g} Q_{lgg't}}{TCap_l} \quad \forall t \quad (A.26)$$

$$GC_t = \sum_l \sum_{t' < t} GE_{lt} NT_{lt'} \quad \forall t \quad (A.27)$$

$$DEP_t = \frac{(1 - sv)FCI}{T} \quad \forall t \quad (A.28)$$

$$FCI = \sum_p \sum_g \sum_t (\alpha_{pgt}^{Pr} NP_{pgt} + \beta_{pgt}^{Pr} PCapE_{pgt}) + \sum_s \sum_g \sum_t (\alpha_{sgt}^{St} NS_{sgt} + \beta_{sgt}^{St} SCapE_{sgt}) + \sum_l \sum_t NT_{lt} TMC_{lt} \quad (A.29)$$

$$\sum_{t \leq T} NT_{lt} = \sum_{i \in IL(i,l)} \sum_g \sum_{g' \neq g} \sum_t \frac{Q_{lgg't}}{av_l TCap_l} \left(\frac{2EL_{gg'}}{SP_l} + LUT_l \right) \quad \forall l \quad (A.30)$$

$$FCI \leq \overline{FCI} \quad (A.31)$$

$$FTDC_t = \frac{FCI}{T} \quad \forall t \quad (A.32)$$

Environmental Impacts

$$IPU_b = EPU_b \sum_g \sum_t PU_{igt} \quad \forall ti = \text{sugarcane} \quad (A.33)$$

$$IPE_b = \sum_{i \in MP(l)} \sum_p \sum_g \sum_t EPE_{bp} PE_{ipgt} \quad \forall b \quad (A.34)$$

$$IQ_b = \sum_{i \in IL(i,l)} \sum_l \sum_g \sum_{g' \neq g} \sum_t EQ_b EL_{gg'} Q_{lgg't} \quad \forall b \quad (A.35)$$

$$TI_b = IPU_b + IPE_b + IQ_b \quad \forall b \quad (A.36)$$

SO objective Function

As seen before the objective function of the SO optimization model is a weighted sum. This function returns the overall performance of the SC according to economic and environmental criteria. The factor ω_b indicate the relative importance of the environmental impact categories and the factors ω_{NPV} y ω_{env} show the relative importance between economic and environmental concerns. Therefore, the global performance of the SC can be stated as follows (step 5):

$$Perf = \omega_{NPV} NPV_{NORM} + \omega_{env} \sum_b \omega_b TI_{bNORM} \quad (A.37)$$

where NPV_{NORM} and TI_{bNORM} are the normalized objective functions calculated using the extreme solutions of step 4.

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