# Characterization of nonsignaling correlations from mutual information 

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#### Abstract

We present a characterization of the set of nonsignaling correlations in terms of a two-dimensional representation that involves the maximal value of a Bell functional and the mutual information between the parties. In particular, we apply this representation to the bipartite Bell scenario with two measurements and two outcomes. In terms of these physically meaningful quantities and through numerical optimization methods and some analytical results, we investigate the frontier between the different subsets of the nonsignaling correlations, focusing on the quantum and postquantum ones. Our analysis exhibits that there is a trade-off between the amount of classical correlations existing between the parties and the magnitude of the violation of a given Bell inequality. Notably, the Tsirelson bound appears as a singular point of this trade-off without resorting to quantum mechanics.


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## I. INTRODUCTION

When a set of spatially separated systems is considered, the complete characterization from physical principles of the set of quantum correlations that can exist between is still an open problem. The simplest attempt to do so corresponds to the no-signalling principle [1,2], which is well known to give place to a set of correlations for which those achievable within the quantum mechanics formalism are just a subset. There are more sophisticated physical principles trying to define the frontier between quantum correlations and correlations that cannot be obtained from quantum mechanics. These proposals include the principle of information causality [3], nontrivial communication complexity [4], no advantage for nonlocal computation [5], macroscopic locality [6], and local orthogonality [7] to name a few. Some of them are able to provide a good approximation to the set of quantum correlations or can even describe it exactly in some particular scenarios, but a general physical principle defining the quantum set in the general case is yet unknown and one of the main open problems in this research field.

In this work, we present an alternative approach to the problem of characterizing quantum correlations using a twodimensional representation of the nonsignaling set. We focus on the bipartite scenario where two spatially separated parties have access to two dichotomic measurement choices each. This representation makes use of two real functionals acting on the set of correlations: the CHSH functional, which is a well-known quantity, directly related to the geometry of the nonsignaling set; and the mutual information between the parties, which is a faithful measure of the strength of
the correlations that exist between them. We characterize the boundaries of the different sets of correlations and show the natural appearance of the Tsirelson bound as a singular point in this representation. Interestingly, this singular point emerges without assuming the quantum mechanics formalism.

The paper is organized as follows. In Sec. II we define the scenario we will be using throughout this work, discuss some previous results, and provide some relevant definitions. Section III contains our main results and is divided in three parts. In Sec. III A we discuss the particular case of symmetrical behaviors which are relevant for our approach. In Sec. III B we give some insights about how quantum correlations are distributed on our two-dimensional representation and in Sec. III C we show an interesting fact which suggests that the Tsirelson bound could be obtained in a device-independent manner. Finally, in Sec. IV we summarize our results.

## II. SCENARIO AND DEFINITIONS

## A. Nonsignaling set

We will focus on the standard device-independent Bell scenario ( $2,2,2$ ): two parties, Alice and Bob, each of which has access to a device with two inputs (measurement choices) and outputs. We note by $x \in\{0,1\}$ and $y \in\{0,1\}$ the measurement choices of Alice and Bob, respectively; and $a$ and $b$ their possible outcomes, which take values $\{-1,1\}$. This kind of scenario is completely described once the 16 conditional probabilities $p(a b \mid x y)$ are given, which are usually referred as behaviors [8]. Each behavior can be represented by a vector with real components $\mathbf{p}=\{p(a b \mid x y)\}$ that satisfies
the normalization condition $\sum_{a b} p(a b \mid x y)=1$ and the positivity constraints $p(a b \mid x y) \geqslant 0$. Thus, leaving an amount of 12 independent parameters.

Additional constraints can be imposed based on physical considerations. The first one defines $\mathcal{N S}$, the nonsignaling set, with behaviors whose marginal probabilities are locally well defined [1,2]:

$$
\begin{array}{ll}
p(a \mid x)=\sum_{b} p(a b \mid x y) & \forall x \\
p(b \mid y)=\sum_{a} p(a b \mid x y) & \forall y \tag{1}
\end{array}
$$

These conditions guarantee that instantaneous communication between the parties is forbidden, which is required to preserve the causality principle. The $\mathcal{N} \mathcal{S}$ set in the $(2,2,2)$ scenario is then an eight-dimensional polytope embedded in $\mathbb{R}^{16}$. In this case, instead of specifying a behavior in terms of the 16 components, a particularly simple parametrization of $\mathcal{N S}$ is given in terms of eight correlators $\left\{\left\langle A_{x}\right\rangle,\left\langle B_{y}\right\rangle,\left\langle A_{x} B_{y}\right\rangle\right\}$ :

$$
\begin{align*}
\left\langle A_{x}\right\rangle & \equiv \sum_{a} a p(a \mid x), \quad\left\langle B_{y}\right\rangle \equiv \sum_{b} b p(b \mid y) \\
\left\langle A_{x} B_{y}\right\rangle & \equiv \sum_{a b} a b p(a b \mid x y) \tag{2}
\end{align*}
$$

from which any behavior can be obtained as [9]

$$
\begin{equation*}
p(a b \mid x y)=\frac{1}{4}\left(1+a\left\langle A_{x}\right\rangle+b\left\langle B_{y}\right\rangle+a b\left\langle A_{x} B_{y}\right\rangle\right) \tag{3}
\end{equation*}
$$

and using (1) we can also obtain the marginals in terms of the correlators. It is easy to check that all the mean values defined above are real numbers lying in $[-1,1]$. Therefore, the $\mathcal{N S}$ set can also be described as the intersection of the hypercube $[-1,1]^{8} \subset \mathbb{R}^{8}$ and the 16 semispaces defined by the positivity conditions.

Let us introduce two interesting subsets of $\mathcal{N S}$ that will be useful for our analysis. The first one is the well-known correlation space $\mathcal{C}[1,10]$, defined by the set of behaviors with $\left\langle A_{x}\right\rangle=\left\langle B_{y}\right\rangle=0$ for all $x$ and $y$. This set describes devices that work as perfectly unbiased coins with no dependence on the inputs. Notice also that in this case the positivity conditions are automatically satisfied, so the correlation space is a fourdimensional subset of $\mathcal{N S}$ in one-to-one correspondence with all the points in the hypercube $[-1,1]^{4}$. The other subset of $\mathcal{N S}$ is the set $\mathcal{S Y} \mathcal{M}$ of symmetric behaviors, corresponding to those elements of $\mathcal{N S}$ that are invariant under exchange of the devices. Formally, it is obtained by imposing three additional constraints to the correlators that parametrize the nonsignaling polytope: $\left\langle A_{x}\right\rangle=\left\langle B_{y}\right\rangle$ for $x=y$ and $\left\langle A_{0} B_{1}\right\rangle=\left\langle A_{1} B_{0}\right\rangle$ which makes $\mathcal{S Y} \mathcal{M}$ a five-dimensional polytope.

Another subset of particular physical interest is the set $\mathcal{L}$ of local behaviors, which contains all the behaviors admitting a local model

$$
\begin{equation*}
p(a b \mid x y)=\int_{\Lambda} d \lambda p(a \mid x, \lambda) p(b \mid y, \lambda) \tag{4}
\end{equation*}
$$

where $\lambda$ are arbitrary variables taking values in some set $\Lambda$ shared by both devices, usually referred to as hidden variables. This set is a polytope that is strictly smaller than the nonsignaling set, that is, $\mathcal{L} \subset \mathcal{N} \mathcal{S}$. Its vertices are known as
the local deterministic behaviors ( $L D$ behavior in the following), and correspond to those situations (16 in our scenario) where both devices work as deterministic functions of their inputs. The behaviors that do not belong to this set are called nonlocal.

The last physically relevant set is $\mathcal{Q}$, the quantum set. This is the set of behaviors allowed by quantum mechanics. A behavior belongs to $\mathcal{Q}$ if and only if there exist two Hilbert spaces $\mathcal{H}_{A}$ and $\mathcal{H}_{B}$ of arbitrary dimensions, and a density matrix $\rho$ acting on $\mathcal{H}_{A} \otimes \mathcal{H}_{B}$ such that

$$
\begin{equation*}
p(a b \mid x y)=\operatorname{tr}\left[\rho\left(M_{a \mid x} \otimes M_{b \mid y}\right)\right] \tag{5}
\end{equation*}
$$

where $\left\{M_{a \mid x}\right\}$ is a set of measurement operators (all $M_{a \mid x}$ are semi-definite-positive and $\sum_{a} M_{a \mid x}=\mathbb{I}_{A}$ ) and analogously $\left\{M_{b \mid y}\right\}$ for Bob's measurements. Note that, by means of purification, we can assume without loss of generality that the density matrix corresponds to a pure state and the measurements are orthogonal projectors, so any element of $\mathcal{Q}$ can also be written as

$$
\begin{equation*}
p(a b \mid x y)=\langle\psi| M_{a \mid x} \otimes M_{b \mid y}|\psi\rangle \tag{6}
\end{equation*}
$$

where now $|\psi\rangle$ is a pure quantum state in $\mathcal{H}_{A} \otimes \mathcal{H}_{B}$ and all the involved measurements are projective: $M_{a \mid x} M_{a^{\prime} \mid x}=\delta_{a a^{\prime}} M_{a \mid x}$, and similarly for Bob's measurements. The local and quantum sets have the same dimension as the nonsignaling set [11] and satisfy the following strict inclusions: $\mathcal{L} \subset \mathcal{Q} \subset \mathcal{N S}$ [9].

The distinction between the quantum behaviors and the postquantum ones (those behaviors that are nonsignaling but lie outside the quantum set) is clear from an operational point of view [a behavior is quantum if and only if it can be written as (6)]. But this distinction is not yet fully understood in terms of a physical point of view, and in this work we will present an informational approach to this problem. To do so, we will make use of two functionals that map behaviors into real numbers. Before doing so, a little digression about the geometry of the three sets [9] will come in handy. As we said, using the parametrization in terms of correlators, both normalization and nonsignaling constraints are automatically fulfilled. Therefore, the nonsignaling polytope is defined just by specifying its 16 facets, given by the positivity constraints. Local behaviors can also attain the bound imposed by the positivity conditions, so there are 16 facets of $\mathcal{L}$ that are contained in the facets of $\mathcal{N S}$. Given that $\mathcal{L} \subset \mathcal{Q} \subset \mathcal{N S}$, the last assertion must also hold for $\mathcal{Q}$ (which is convex but not a polytope so not all of its boundary will be given by hyperplanes). The inner facets of $\mathcal{L}$, that is, the facets that do not correspond to positivity constraints, establish the frontier between local and nonlocal behaviors. Being hyperplanes, they can be described by level surfaces of linear functionals, called Bell inequalities, acting over the set of behaviors. For instance, the well-known Clauser-Horne-Shimony-Holt (CHSH) functional [12]

$$
\begin{equation*}
S \equiv\left\langle A_{0} B_{0}\right\rangle+\left\langle A_{0} B_{1}\right\rangle+\left\langle A_{1} B_{0}\right\rangle-\left\langle A_{1} B_{1}\right\rangle, \tag{7}
\end{equation*}
$$

is such that local behaviors must satisfy $-2 \leqslant S \leqslant 2$, so the two hyperplanes $S= \pm 2$ are facets of $\mathcal{L}$. The quantum bound for $S$ can be easily obtained as $-2 \sqrt{2} \leqslant S \leqslant 2 \sqrt{2}$ and is known as the Tsirelson bound. In this case, $\mathcal{L}$ is defined by the eight inequalities obtained by relabeling inputs on $-2 \leqslant S \leqslant$ 2 , along with the positivity constraints. In the following, we refer to behaviors attaining Tsirelson bound as Bell behaviors.

The quantum set $\mathcal{Q}$ is convex but it is not a polytope, it is bounded by some nonflat regions and any set of inequalities describing it must necessarily be nonlinear. A closed set of expressions defining whether a behavior is quantum or not is not known in the general case, but there exist useful approximations to bound the quantum set. For example, in the present scenario, a necessary condition for a behavior to be quantum is $[8,13,14]$

$$
\begin{equation*}
\left|\sum_{x^{\prime} y^{\prime}} \arcsin \left\langle A_{x^{\prime}} B_{y^{\prime}}\right\rangle-2 \arcsin \left\langle A_{x} B_{y}\right\rangle\right| \leqslant \pi \quad \forall x, y \tag{8}
\end{equation*}
$$

which, notably, when considering behaviors in the correlation space becomes also a sufficient condition. That is, the set $\mathcal{Q} \cap$ $\mathcal{C}$ is completely described by the set of four inequalities (8). In the general case, the set satisfying (8), which we will call $\tilde{\mathcal{Q}}$ contains the quantum set $\mathcal{Q}$. A better approximation to the quantum set [15] is given by those behaviors where at least one $x$ (or $y$ ) such that $\left\langle A_{x}\right\rangle= \pm 1$ (or $\left\langle B_{y}\right\rangle= \pm 1$ ) or

$$
\begin{equation*}
\left|\sum_{x^{\prime} y^{\prime}} \arcsin \left(\mathcal{F}_{x^{\prime} y^{\prime}}\right)-2 \arcsin \left(\mathcal{F}_{x y}\right)\right| \leqslant \pi \tag{9}
\end{equation*}
$$

for all $x, y$, with

$$
\begin{equation*}
\mathcal{F}_{x y} \equiv \frac{\left\langle A_{x} B_{y}\right\rangle-\left\langle A_{x}\right\rangle\left\langle B_{y}\right\rangle}{\sqrt{\left(1-\left\langle A_{x}\right\rangle^{2}\right)\left(1-\left\langle B_{y}\right\rangle^{2}\right)}} \tag{10}
\end{equation*}
$$

A behavior satisfying these conditions is said to belong to the first level of the Navascués-Pironio-Acín (NPA) hierarchy [16], and we will refer to it as $\mathcal{Q}_{1}$. In general, then, we have $\mathcal{Q} \subset \mathcal{Q}_{1} \subset \tilde{\mathcal{Q}}$.

The algebraic bounds for $S$ are clearly $-4 \leqslant S \leqslant 4$ and, notably, can be attained by elements on $\mathcal{N S}$. This kind of behaviors are associated to devices called Popescu-Rohrlich (PR) boxes [2], and they correspond to the situations in which for instance: $\left\langle A_{0} B_{0}\right\rangle=\left\langle A_{0} B_{1}\right\rangle=\left\langle A_{1} B_{0}\right\rangle=1=-\left\langle A_{1} B_{1}\right\rangle$. We will refer to this kind of nonlocal behaviors as $P R$ behaviors. As a summary, Fig. 1 schematizes the geometric structure of the nonsignaling polytope we discussed in the last paragraphs.

## B. Functionals

Let us define the two main functionals over which our analysis will be based. The first one was already mentioned in a sense and is related to the CHSH functional: it is the maximum of such quantity over all possible relabelings of inputs and outputs.

Definition 1. Let $\mathbf{p} \in \mathcal{N S}$ de an arbitrary nonsignaling behavior. The functional $\mathcal{S}: \mathcal{N S} \rightarrow \mathbb{R}$ is defined as

$$
\begin{equation*}
\mathcal{S}[\mathbf{p}] \equiv \max _{x y}\left|\left(\sum_{x^{\prime} y^{\prime}}\left\langle A_{x^{\prime}} B_{y^{\prime}}\right\rangle\right)-2\left\langle A_{x} B_{y}\right\rangle\right| . \tag{11}
\end{equation*}
$$

Maximizing over all CHSH functionals is important because it gives us a quantity that does not depend upon particular relabelings of inputs and/or outputs, which have no physical relevance. This is so because, for any nonlocal behavior, there is always a relabeling for which the value of a particular CHSH functional does not violate the local bound. In other words, a behavior $\mathbf{p} \in \mathcal{N S}$ is nonlocal if and only


FIG. 1. Pictorial representation of the nonsignaling set. Dark red (outer) lines represent positivity constraints and orange (inner and straight) lines represent CHSH facets. The black segments are those portions of the positivity constraints that are also boundaries of $\mathcal{L}$ and $\mathcal{Q}$. The nonflat boundaries of $\mathcal{Q}$ are the inner and curved red lines.
if $\mathcal{S}[\mathbf{p}]>2$. Behaviors satisfying $\mathcal{S}[\mathbf{p}]=2$ lay at one of the nontrivial facets of the local set and any deviation from this value indicates how far it is from its closest nontrivial facet of $\mathcal{L}$. Notably, the amount of violation of the local bound has an interesting interpretation as it imposes a lower bound on the average communication needed to produce such correlations [17].

The second functional we will consider in this work is related to the correlations between the distribution of outputs of the devices. The mutual information between two random variables $W$ and $R$, conditioned to a third random variable $T$, can be computed as [18]

$$
\begin{equation*}
I(W ; R \mid T)=H(W \mid T)+H(R \mid T)-H(W R \mid T), \tag{12}
\end{equation*}
$$

where $H(\star \mid \star)$ is the conditional entropy. In our scenario, if we refer $X$ and $Y$ to the random variables associated with the inputs of both devices and $A$ and $B$ to the random variables associated with the outputs, the mutual information between Alice's and Bob's variables can be written as

$$
\begin{equation*}
I(A ; B \mid X Y)=H(A \mid X)+H(B \mid Y)-H(A B \mid X Y) \tag{13}
\end{equation*}
$$

Here we used the nonsignaling conditions to simplify the first two terms as $H(A \mid X Y)=H(A \mid X)$ and $H(B \mid X Y)=H(B \mid Y)$. The conditional entropies appearing in (12) can be easily computed in terms of behaviors

$$
\begin{align*}
H(A \mid X) & =\sum_{x} p(x) H(A \mid X=x) \\
& =-\sum_{a x} p(x) p(a \mid x) \log _{2} p(a \mid x) \tag{14}
\end{align*}
$$



FIG. 2. $\mathcal{I}$ vs. $\mathcal{S}$ plot for a random sample of $5 \times 10^{6}$ quantum points for two-level systems on both sides. Some relevant behaviors are also plotted.
and similarly for $H(B \mid Y)$, and

$$
\begin{align*}
H(A B \mid X Y) & =\sum_{x y} p(x y) H(A B \mid X=x, Y=y) \\
& =-\sum_{a b x y} p(x y) p(a b \mid x y) \log _{2} p(a b \mid x y) \tag{15}
\end{align*}
$$

Naturally, as it is evident from the last two expressions, the mutual information depends on the probability distributions for the inputs. As we are interested in an intrinsic measure of the correlations contained in a given behavior, we will consider that both inputs are independent and uniformly distributed random variables.

Definition 2. Let $\mathbf{p} \in \mathcal{N S}$ be an arbitrary nonsignaling behavior. We define the functional $\mathcal{I}: \mathcal{N S} \rightarrow \mathbb{R}$ as

$$
\begin{align*}
\mathcal{I}[\mathbf{p}] \equiv & -\frac{1}{2} \sum_{a x} p(a \mid x) \log _{2} p(a \mid x) \\
& -\frac{1}{2} \sum_{b y} p(b \mid y) \log _{2} p(b \mid y) \\
& +\frac{1}{4} \sum_{a b x y} p(a b \mid x y) \log _{2} p(a b \mid x y) \tag{16}
\end{align*}
$$

We will measure entropy in bits, which means that we will use base 2 logarithms through this work. This implies that the functional $\mathcal{I}$ is a real number between 0 (no correlation) and 1 (maximum correlation between the parties).

Before presenting the results, it is instructive to look at a typical $\mathcal{I}$ versus $\mathcal{S}$ plot. Figure 2 shows the values of both functionals for a random sample of $5 \times 10^{6}$ quantum behaviors of the form (6) for two-dimensional Hilbert spaces. The plot also highlights some relevant points: the PR behavior, the Bell behavior, and a local deterministic behavior. In addition to those behaviors, we plot the one that maximizes $\mathcal{I}$ in the local set: $\left\langle A_{x} B_{y}\right\rangle=1$ and $\left\langle A_{x}\right\rangle=\left\langle B_{y}\right\rangle=0$ for all $x, y$; that is, both devices output a perfectly correlated random and uniformly distributed bit (we will refer to this behavior, or any of it relabelings, as the shared coin behavior or simply SC behavior). The other highlighted behavior is what we will call the noise, corresponding to $\left\langle A_{x} B_{y}\right\rangle=\left\langle A_{x}\right\rangle=\left\langle B_{y}\right\rangle=0$ for all $x, y[$ that is, $p(a b \mid x y)=1 / 4$ for all $a, b, x, y]$.


FIG. 3. Boundaries of $\mathcal{N S}$ in the $\mathcal{S}$ - $\mathcal{I}$ representation obtained by means of numerical optimization. The behaviors in $\mathcal{N S}$ fill the orange (inner) region on this representation.

Throughout this paper, we will work extensively with the boundaries between the different sets in this type of plots. These boundaries correspond to the points that maximize or minimize $\mathcal{I}$ for each value of $\mathcal{S}$. We will use the notation $I_{\max }^{\mathcal{A}}(\mathcal{S})$ to refer to the maximum value of mutual information over the set $\mathcal{A}$ when the CHSH functional is fixed to $\mathcal{S}$, and $I_{\min }^{\mathcal{A}}(\mathcal{S})$ for the minimum.

## III. RESULTS

Let us call $G: \mathcal{N S} \rightarrow \mathbb{R}^{2}$ the continuous function that maps behaviors to the $\mathcal{S}-\mathcal{I}$ plane: $G(\mathbf{p}) \equiv[\mathcal{S}(\mathbf{p}), \mathcal{I}(\mathbf{p})]$. It is well known that continuous functions map path-connected sets into path-connected sets, so we have that the $\mathcal{S}-\mathcal{I}$ representation of $\mathcal{N S}$ is a path-connected set. Moreover, the $\mathcal{N S}$ path-connected set is also simply connected (colloquially, it does not have empty regions inside of its outer boundaries). To see this, for each value of $s \in[0,4]$, we can take $\mathbf{p}_{\text {min }}$ and $\mathbf{p}_{\text {max }}$ to be two behaviors attaining the values of $I_{\text {min }}^{\mathcal{N} \mathcal{S}}(s)$ and $I_{\max }^{\mathcal{N} \mathcal{S}}(s)$, respectively, and, without loss of generality, we can assume that both behaviors attain the value of $\mathcal{S}=s$ for the same linear version of the CHSH functional. Thus, all convex combinations of those two behaviors have also the same value of the linear CHSH functional and, given that all other relabelled of it give smaller or equal values, the value of the nonlinear functional $\mathcal{S}$ is also $s$ for all such convex combinations. Then, all behaviors corresponding to convex combinations of $\mathbf{p}_{\min }$ and $\mathbf{p}_{\max }$ lay in the vertical line given by $\mathcal{S}=s$ in the $\mathcal{S}-\mathcal{I}$ representation, and, given that the mutual information is a continuous function, the vertical segment connecting $\mathbf{p}_{\text {min }}$ and $\mathbf{p}_{\text {max }}$ in the $\mathcal{S}-\mathcal{I}$ plane is filled by behaviors on $\mathcal{N S}$. Therefore, there are no empty regions inside of the outer boundaries of the $\mathcal{S}-\mathcal{I}$ representation of $\mathcal{N S}$ and to characterize the nonsignaling set, it is enough to find those outer boundaries.

Figure 3 shows the lower and upper bounds for $\mathcal{I}$ [that is, $I_{\max }^{\mathcal{N} \mathcal{S}}(\mathcal{S})$ and $I_{\min }^{\mathcal{N} \mathcal{S}}(\mathcal{S})$ ] obtained by means of numerical optimization, for 700 values of $\mathcal{S}$ in [0,4] for the maximums and 500 values of $\mathcal{S}$ in [2,4] for the minimums [we do not need to minimize $\mathcal{I}$ in the local region because it is straightforward to obtain analytically that $\left.I_{\text {min }}^{\mathcal{L}}(\mathcal{S}) \equiv 0\right]$.

The $\mathcal{S}-\mathcal{I}$ representation of $\mathcal{L}$, i.e., the $\mathcal{S} \in[0,2]$ region in Fig. 3, is pretty straightforward to analyze. For any fixed value
of $\mathcal{S} \leqslant 2$, it is easy to find a behavior that factorizes as a product of its marginals: $p(a b \mid x y)=p(a \mid x) p(b \mid y)$ giving $\mathcal{I}=0$ and hence the lower bound for the local region. The upper bound for this region shows that the maximum correlation that can be achieved is a monotonously increasing function of $\mathcal{S}$.

The situation in the nonlocal region becomes more interesting: the upper bound for $\mathcal{I}$ turns immediately into a decreasing function once we leave the local set, showing that there is a compromise between this quantity and the magnitude of a Bell violation. As it is well known, nonlocality does not necessarily mean stronger correlations. On the other hand, nonlocality cannot arise from product distributions and therefore the lower bound for $\mathcal{I}$ becomes a nonzero function of $\mathcal{S}$. This lower bound is a monotously increasing function of $\mathcal{S}$ over all the nonlocal region, and small values of $\mathcal{I}$ are less and less achievable as we move away from the corresponding CHSH facet of $\mathcal{L}$. A more detailed analysis of this curve leads to the most puzzling result of this work, but we will get into that later. In this respect, let us recall that no physical model was assumed when obtaining this plot, and the numerical optimization was done just imposing positivity, normalization, and nonsignaling constraints.

## A. $\mathcal{S Y} \mathcal{M}$ behaviors

Now we will see that, notably, the representation of $\mathcal{S Y} \mathcal{M}$ in the $\mathcal{S}$ - $\mathcal{I}$ plane is exactly the same as that of $\mathcal{N S}$. This is a useful result that will simplify part of our analysis, allowing us to obtain some analytic expressions for the boundaries of the nonsignaling set in this representation.

First, we will focus on the characterisation of $\mathcal{L}$. In this case, it is easy to check that a behavior maximizing $\mathcal{I}$ for $\mathcal{S}=$ 0 is given by $\mathbf{p}_{0} \in \mathcal{S Y} \mathcal{M}$ such that

$$
\begin{equation*}
\left\langle A_{0}\right\rangle=\left\langle B_{0}\right\rangle=-\frac{1}{2}, \quad\left\langle A_{1}\right\rangle=\left\langle B_{1}\right\rangle=\frac{1}{2}, \tag{17}
\end{equation*}
$$

and all the other correlators equal to zero. Another extremal point of this set, $(\mathcal{S}, \mathcal{I})=(2,1)$, is reached by the following relabelling of the shared coin behavior:

$$
\left\langle A_{x} B_{y}\right\rangle= \begin{cases}-1 & \text { if } x=y  \tag{18}\\ +1 & \text { otherwise }\end{cases}
$$

and local mean values equal to zero. We will call this behavior $\tilde{\mathbf{p}}_{S C} \in \mathcal{S Y} \mathcal{M}$. In this way, the local upper bound for $\mathcal{I}$ can be obtained by evaluating all convex combinations between $\mathbf{p}_{0}$ and $\tilde{\mathbf{p}}_{S C}$. Thus, the function

$$
\begin{equation*}
I_{\mathbf{p}_{0} \rightarrow \tilde{\mathbf{p}}_{S C}}(\mathcal{S}) \equiv \mathcal{I}\left(\frac{\mathcal{S} \tilde{\mathbf{p}}_{S C}+(2-\mathcal{S}) \mathbf{p}_{0}}{2}\right) \tag{19}
\end{equation*}
$$

gives the local upper bound $I_{\max }^{\mathcal{L}}(\mathcal{S})$. Figure 4 shows the agreement between this curve and the numerical results previously presented.

For the nonlocal region, let us first note that when considering behaviors on the correlation space $\mathcal{C}$, mutual information takes a particularly simple form

$$
\begin{equation*}
\mathbf{p} \in \mathcal{C} \Rightarrow \mathcal{I}[\mathbf{p}]=\sum_{x y} g\left(\left\langle A_{x} B_{y}\right\rangle\right), \tag{20}
\end{equation*}
$$



FIG. 4. Boundaries of the $\mathcal{N S}$ set in the $\mathcal{S}$ - $\mathcal{I}$ representation when restricting to behaviors in the $\mathcal{S Y M}$ set. For comparison, in black we plot the points obtained by numerical optimization using the full set of $\mathcal{N S}$ behaviors.
where we defined $g:[-1,1] \rightarrow\left[0, \frac{1}{4}\right]$ as
$g(x) \equiv \frac{1}{2}\left[1+\frac{1+x}{4} \log _{2}\left(\frac{1+x}{4}\right)+\frac{1-x}{4} \log _{2}\left(\frac{1-x}{4}\right)\right]$,
which is an even function of its argument. It is clear that the suprema of $\mathcal{I}(\mathbf{p})$ with $\mathbf{p} \in \mathcal{C}$ is 1 and is achieved if and only if $\left|\left\langle A_{x} B_{y}\right\rangle\right|=1$ for all $x, y$; that is, for the shared coin behavior or the PR behavior, in agreement with the numerical optimization presented before. The condition $\left|\left\langle A_{x} B_{y}\right\rangle\right|=1$ for all $x, y$ imposes also that $\mathcal{S}$ is either 2 or 4 . Thus, crossing a CHSH facet comes at a price in terms of mutual information. As we will see later, this price is even bigger when we restrict ourselves to quantum behaviors.

To obtain the upper bound of $\mathcal{I}$ in the nonlocal part, one can consider behaviors on $\mathcal{C}$. Without loss of generality, we can stick to a particular labeling and set

$$
\begin{equation*}
\mathcal{S}(\mathbf{p})=\left\langle A_{0} B_{0}\right\rangle+\left\langle A_{0} B_{1}\right\rangle+\left\langle A_{1} B_{0}\right\rangle-\left\langle A_{1} B_{1}\right\rangle . \tag{21}
\end{equation*}
$$

Then, we want to maximize the $\mathcal{I}(\mathbf{p})$ given in Eq. (20) subject to the linear constraint $\mathcal{S}(\mathbf{p})=s$ for some $s \in[2,4]$. It is simple to show that the solution is attained when three of the correlators are equal to 1 , and the remaining one is such that the constraint $\mathcal{S}(\mathbf{p})=s$ is satisfied. That is, the behavior with

$$
\begin{equation*}
\left\langle A_{0} B_{0}\right\rangle=\left\langle A_{0} B_{1}\right\rangle=\left\langle A_{1} B_{0}\right\rangle=1, \quad\left\langle A_{1} B_{1}\right\rangle=3-s, \tag{22}
\end{equation*}
$$

maximizes $\mathcal{I}$ over $\mathcal{C}$. Notice that for each $s \in[2,4]$, the behavior (22) is not only an element of $\mathcal{C}$ but also of $\mathcal{S Y} \mathcal{M}$, and corresponds to a convex combination of the shared coin behavior and the PR behavior. Then, we have that the curve

$$
\begin{equation*}
I_{\max }^{\mathcal{C} \backslash \mathcal{L}}(\mathcal{S})=\mathcal{I}\left(\frac{(\mathcal{S}-2) \mathbf{p}_{P R}+(4-\mathcal{S}) \mathbf{p}_{S C}}{2}\right), \tag{23}
\end{equation*}
$$

gives the maximum value of $\mathcal{I}$ of the behaviors in $\mathcal{C}$ space for $\mathcal{S} \in[2,4]$. The corresponding plot is also shown in Fig. 4. This plot shows that there is a value of $\mathcal{S}$ from which the analytic curve (23) starts deviating from the numerical upper bound. Fortunately, this ramification can also be obtained as the mutual information of a mixture of two simple behaviors. In fact, if we call $\mathbf{p}_{L D}$ the local deterministic behavior with $\left\langle A_{x}\right\rangle=\left\langle B_{y}\right\rangle=\left\langle A_{x} B_{y}\right\rangle=1$ for all $x, y$, then the following
function:

$$
\begin{equation*}
I_{\mathbf{p}_{L D} \rightarrow \mathbf{p}_{P R}}(\mathcal{S})=\mathcal{I}\left(\frac{(\mathcal{S}-2) \mathbf{p}_{P R}+(4-\mathcal{S}) \mathbf{p}_{L D}}{2}\right) \tag{24}
\end{equation*}
$$

gives the upper bound for $\mathcal{I}$ in the nonlocal region after the intersection with (23) (see Fig. 4). Notice that this is also the mutual information for a set of elements in $\mathcal{S Y} \mathcal{M}$.

So far, we derived the upper bound for $\mathcal{I}$ as a function of $\mathcal{S}$ for the nonsignaling set. These bounds can be obtained by considering only symmetrical behaviors and can be summed up as

$$
I_{\max }^{\mathcal{N} \mathcal{S}}(\mathcal{S})= \begin{cases}I_{\max }^{\mathcal{L}}(\mathcal{S}) & \text { if } \mathcal{S} \leqslant 2  \tag{25}\\ \max \left\{I_{\mathbf{p}_{L D} \rightarrow \mathbf{p}_{P R}}(\mathcal{S}),\right. & \left.I_{\max }^{\mathcal{C} \mathcal{L}}(\mathcal{S})\right\} \\ \text { if } \mathcal{S}>2\end{cases}
$$

To show that all the boundaries of $\mathcal{N} S$, in the $\mathcal{I}-\mathcal{S}$ representation, can be obtained by considering only the symmetric part of this set, we have to consider also lower bounds. For the local part, this is straightforward because the segment $\mathcal{I}=0$ for $\mathcal{S} \in[0,2]$ is constructed from product behaviors, and this can be done within the symmetry assumption. The lower bound of the nonlocal part is nontrivial, and we do not have an analytic expression for the full set (as we will see later, we do have an analytic expression for a fraction of it). Thus, here we will just mention that the numerical minimization, when subjected to the additional constraint of symmetry, gives the same lower bound, $I_{\text {min }}^{\mathcal{N} \mathcal{S}}(\mathcal{S})$, as for the full set (see Fig. 4). Finally, note that the fragment of $I_{\text {min }}^{\mathcal{N} \mathcal{S}}(\mathcal{S})$ lying on the postquantum region (that is, for $\mathcal{S} \in[2 \sqrt{2}, 4]$ ) can be also analytically described by

$$
\begin{equation*}
I_{\mathbf{p}_{\mathrm{Bell}} \rightarrow \mathbf{p}_{\mathrm{PR}}}(\mathcal{S}) \equiv \mathcal{I}\left(\frac{(\mathcal{S}-2 \sqrt{2}) \mathbf{p}_{\mathrm{PR}}+(4-\mathcal{S}) \mathbf{p}_{\mathrm{Bell}}}{4-2 \sqrt{2}}\right) \tag{26}
\end{equation*}
$$

that is, by all the convex combinations between the Bell behavior and the PR behavior.

## B. Quantum set

To characterize the quantum set we will consider the sets, $\tilde{\mathcal{Q}}$ and $\mathcal{Q}_{1}$, that contain the quantum set $\mathcal{Q}$. The analytic expressions defining those two sets in this scenario, can be used to find their boundaries in the $\mathcal{I}-\mathcal{S}$ representation. First, note that constraints (8) cannot be satisfied by any behavior with $\mathcal{S}>2 \sqrt{2}$, so $\tilde{\mathcal{Q}}$ is contained in $\mathcal{N} S$. Given that $\mathcal{L} \subset \tilde{\mathcal{Q}}$, the boundaries in the $0 \leqslant \mathcal{S} \leqslant 2$ region are those already obtained in the previous section. The last two observations imply that we only need to consider the boundaries of $\tilde{\mathcal{Q}}$ in the $\mathcal{S} \in[2,2 \sqrt{2}]$ region. In addition, given that $\mathcal{Q}_{1} \subset \tilde{\mathcal{Q}}$, this is also true for the set of behaviors belonging to the first level of the NPA hierarchy. Moreover, for $\mathcal{S} \in[2,2 \sqrt{2}]$ we can check that all behaviors obtained through numerical minimization of $\mathcal{I}$, pass the test defining the first level of the NPA hierarchy. Thus, the lower bound for $\mathcal{Q}_{1}$ matches what we called $I_{\text {min }}^{\mathcal{N} \mathcal{S}}(\mathcal{S})$, if $2 \leqslant \mathcal{S} \leqslant 2 \sqrt{2}$. As $\mathcal{Q}_{1} \subset \tilde{\mathcal{Q}} \subset \mathcal{N} \mathcal{S}$ this remains true for $\tilde{\mathcal{Q}}$.

As we mentioned before, for behaviors in $\mathcal{C}$ the set of relations (8) are not only necessary but also sufficient conditions to be in $\mathcal{Q}$. Thus, we will show that it is possible to find the upper bound analytically for behaviors in $\mathcal{C}$. We want to maximize $\mathcal{I}(\mathbf{p})$ in Eq. (20), but


FIG. 5. Boundaries for the $\mathcal{N} S$ set and the quantum sets. Upper bounds of $\mathcal{I}: I_{\text {max }}^{\mathcal{Q}}(\mathcal{S})$ in blue; $I_{\text {max }}^{\mathcal{Q}}(\mathcal{S})$ in green; and $I_{\text {max }}^{\mathcal{Q} \mathcal{C}}(\mathcal{S})$ in red. The lower bound for these sets is the same as the one for $\mathcal{N} S$, the orange point represents the Bell behavior.
in this case, subjected to the set of nonlinear inequalities (8). As before, we set $\mathcal{S}(\mathbf{p})=s[(21)]$ for $s \in[2,2 \sqrt{2}]$. Given that the maximum value of the CHSH is reached by that labeling, then the constraints in (8) reduce to just one inequality: $\arcsin \left\langle A_{0} B_{0}\right\rangle+\arcsin \left\langle A_{0} B_{1}\right\rangle+\arcsin \left\langle A_{1} B_{0}\right\rangle-$ $\arcsin \left\langle A_{1} B_{1}\right\rangle \leqslant \pi$. Therefore, the upper bound for $\mathcal{I}$ over the set $\mathcal{Q} \cap \mathcal{C}$ is given by

$$
\begin{equation*}
I_{\max }^{\mathcal{Q} \cap \mathcal{C}}(\mathcal{S})=3 g[w(\mathcal{S})]+g[3 w(\mathcal{S})-\mathcal{S}], \tag{27}
\end{equation*}
$$

where

$$
\begin{equation*}
w(\mathcal{S})=\sqrt{2} \cos \left[\frac{\pi}{6}+\frac{1}{3} \arctan \left(\frac{\mathcal{S}}{\sqrt{8-\mathcal{S}^{2}}}\right)\right] \tag{28}
\end{equation*}
$$

Figure 5 shows the boundaries obtained by means of numerical optimization for $\mathcal{Q}_{1}$ and $\tilde{\mathcal{Q}}$. Note that the strict inclusion $\mathcal{Q}_{1} \subset \tilde{\mathcal{Q}}$ is preserved in this representation and the same holds for $\mathcal{Q} \subset \mathcal{Q}_{1}$. This is so, given that the Bell behavior is the only quantum behavior with $\mathcal{S}=2 \sqrt{2}$ and, thus, the lower and upper bounds of this set have to intersect at this value of $\mathcal{S}$, which is not true for $\mathcal{Q}_{1}$. The figure also shows the analytic curve (27) for the upper bound of $\mathcal{Q} \cap \mathcal{C}$. It can be seen that, as expected, this curve intersects the lower bound exactly at the Bell behavior. All these boundaries show that the relation between mutual information and the magnitude of a Bell violation is indeed stronger for quantum behaviors than for arbitrary nonsignaling behaviors.

To perform another test of these bounds, in Fig. 6 we show the sampling of $5 \times 10^{6}$ random quantum behaviors (gray points) of the form (6) with Hilbert spaces of dimension 2. There it is also shown the analytic curve (27) upper bounding the set $\mathcal{Q} \cap \mathcal{C}$. Additionally, it is shown the sampling of $10^{4}$ random points in $\mathcal{C}$ obtained as a mixture between the shared coin, Bell, and PR behaviors: the orange (black) points do (do not) pass the test of (8). There we can see more explicitly how (27) is the proper bound for the quantum behaviors in the correlation space.

## C. Tsirelson bound

Perhaps the most puzzling result of this work is the natural appearance of the Tsirelson bound in this representation. If we look carefully to the lower bound of the mutual


FIG. 6. Random sample of behaviors. Gray points are $5 \times 10^{6}$ quantum behaviors sampled for Hilbert spaces of dimension two, it can be seen that all of them lie below the (red) curve representing the upper bound for the set $\mathcal{Q} \cap \mathcal{C}$. The other points are random convex combinations of $\mathbf{p}_{\mathrm{SC}}, \mathbf{p}_{\text {Bell }}$, and $\mathbf{p}_{\mathrm{PR}}$ : behaviors not passing the test for $\tilde{\mathcal{Q}}$ are shown in black (above the upper bound for $\mathcal{Q} \cap \mathcal{C}$ ), while for the rest are in orange (below the upper bound for $\mathcal{Q} \cap \mathcal{C}$ ).
information in the nonlocal region $I_{\text {min }}^{\mathcal{N} \mathcal{S}}(\mathcal{S})$, we can identify, in the neighborhood of the Bell behavior, a change in the concavity of the curve. Let us try to find out exactly where it happens. To avoid working with second derivatives, which can carry a lot of numerical noise, we can take advantage of the following trick: given an ordered set of three points in a two-dimensional plane, $\vec{A}=\left(x_{A}, y_{A}\right), \vec{B}=\left(x_{B}, y_{B}\right)$, and $\vec{C}=$ $\left(x_{C}, y_{C}\right)$; the orientation of the path $\vec{A} \rightarrow \vec{B} \rightarrow \vec{C}$ is related to the sign of the determinant of the following matrix [19]:

$$
\mathbf{O}=\left[\begin{array}{lll}
1 & x_{A} & y_{A}  \tag{29}\\
1 & x_{B} & y_{B} \\
1 & x_{C} & y_{C}
\end{array}\right]
$$

The points are orientated clockwise if $\operatorname{det}(\mathbf{O})<0$ and counterclockwise if $\operatorname{det}(\mathbf{O})>0$. Therefore, we can take the numerical values of $\mathcal{I}_{\text {min }}^{\mathcal{N} \mathcal{S}}(\mathcal{S})$ to evaluate the concavity of the curve at any value of $\mathcal{S}$ using the determinant of the matrix in (29).

To get a detailed inspection of the region where the concavity change occurs, we obtain again (through numerical optimization) $I_{\text {min }}^{\mathcal{N} \mathcal{S}}(\mathcal{S})$ for 5000 equispaced values of $\mathcal{S}$ in the interval $[2.5,3.1]$ (note that the Tsirelson bound lies in this interval, given that $2 \sqrt{2} \simeq 2.83$ ). For what comes next, it will be useful to give a name to the horizontal separation between the points in this curve $\delta \mathcal{S} \equiv \frac{3.1-2.5}{5000}$.

Figure 7 shows, for each value of $\mathcal{S}$, the determinant of $\mathbf{O}$ for the corresponding point and two other points to the right of it. To avoid excessive numerical noise, it is convenient not to take three consecutive points because in that case $\mathbf{O}$ is almost singular and computing its determinant becomes tricky from a numerical point of view. For that reason, the determinant computed for each value of $\mathcal{S}$ corresponds to the point with that value of $\mathcal{S}$, the point with $\mathcal{S}+100 \delta \mathcal{S}$ and the point with $\mathcal{S}+200 \delta \mathcal{S}$. Therefore, in this plot, we should expect to find a region of width $200 \delta \mathcal{S}$ where the sign of $\operatorname{det}(\mathbf{O})$ does not have a valid interpretation in terms of concavity because this region (highlighted in green) corresponds to values of $\mathcal{S}$ where


FIG. 7. Determinant of $\mathbf{O}$ for sets of three points in the curve $I_{\min }^{\mathcal{N} \mathcal{S}}(\mathcal{S})$. The horizontal axis gives the value of $\mathcal{S}$ for the first point of each set. The highlighted area shows those points where $\operatorname{det}(\mathbf{O})$ does not allow us to decide, numerically, whether the curve is concave or convex.
the curve is still concave but in the matrix $\mathbf{O}$ we are taking into account points where the curve is already convex. From the last observation, it follows the way in which we should interpret where the concavity change happens, and it is in the value of $\mathcal{S}$ from which the transition region ends and the plot of $\operatorname{det}(\mathbf{O})$ as a function of $\mathcal{S}$ stabilizes to the new curve of positive values.

Figure 8 shows the detail of the mentioned transition region. The vertical green line indicated the value of the Tsierlson bound and the orange region is a symmetrical neighborhood of size $10^{-2}$ around it. We see that the end of the transition region (and hence the value of $\mathcal{S}$ where the concavity flips) is located in the range $\mathcal{S}=2 \sqrt{2} \pm 0.005$. The error in the last expression can be made smaller by taking an increasing amount of points when obtaining the lower bound for the mutual information around the Bell behavior, so this result gives robust numerical evidence that the inflection point is, indeed, located at the Tsirelson bound.

This change in the convexity can be interpreted as follows. If we consider the mutual information as a shared resource, then increasing nonlocality by having a larger value for the


FIG. 8. Determinant of $\mathbf{O}$ as a function of $\mathcal{S}$ in the neighborhood of the concavity flip. The vertical green line gives the value of the Tsirelson bound. The change on the concavity of $I_{\text {min }}^{\mathcal{N} \mathcal{S}}(\mathcal{S})$ occurs inside of the orange (highlighted) region.


FIG. 9. Values of the five relevant mean values for symmetrical behaviors along the curve $I_{\text {max }}^{\mathcal{N S}}(\mathcal{S})$ in the $\mathcal{S} \in[2,4]$ region. For grayscale versions, the order in which the curves emerge from $\mathcal{S}=2$, from top to bottom, is the same as in the legend. The vertical line is located at $\mathcal{S}=2 \sqrt{2}$.

Bell functional requires more of such a resource. However, upon exceeding the Tsirelson bound there is a change in behavior in which each increase of the Bell functional costs more of that resource than the previous one. This strongly suggests that mutual information plays an important role in Nature's correlations.

At the Tsirelson bound we can also find a singularity when looking at the behaviors that give place to the curve $I_{\min }^{\mathcal{N} \mathcal{S}}(\mathcal{S})$. As we have shown, there is no loss of generality in describing this curve by taking into account only symmetrical behaviors, so five parameters are enough to describe any of its points. Figure 9 shows the values of the five correlators that correspond to the behaviors along $I_{\max }^{\mathcal{N} \mathcal{S}}(\mathcal{S})$ when going from $\mathcal{S}=2$ to $\mathcal{S}=4$. Once the Bell behavior is reached, both local mean values stay fixed to zero and the correlators vary lineally from the values corresponding to the Bell behavior to those corresponding to the PR behavior, in agreement with (26). As we can see, the parametrizations of the mean values in terms $\mathcal{S}$ show discontinuous changes in their first derivatives when going through the Bell behavior. It is important to mention that, when the symmetry hypothesis is relaxed, the optimization gives place to the same behaviors, that is, the extremal behaviors giving place to the curve of minimal mutual information are unique (except for relabeling of inputs and
outputs) and the discontinuity at $\mathcal{S}=2 \sqrt{2}$ is not an artifact of the symmetry hypothesis.

In this section we showed robust numerical evidence that the curve $I_{\text {min }}^{\mathcal{N} \mathcal{S}}(\mathcal{S})$ changes its concavity at $\mathcal{S}=2 \sqrt{2}$ and, furthermore, the associated curve of behaviors is not smooth because it exhibits singularities in its first derivatives at the Bell behavior. Those two facts are rather intriguing, given that the curve $I_{\text {min }}^{\mathcal{N} \mathcal{S}}(\mathcal{S})$ is found without making use of quantum mechanics at all. Therefore, this result might suggest that the Tsirelson bound can be obtained in a device-independent manner.

## IV. SUMMARY

In this work we presented an alternative approach to describe the set of nonsignaling correlations that is based on a two-dimensional representation of the nonsignaling polytope, combining a geometrical quantity (the maximum value of a Bell functional) with an informational one (mutual information). Bell functionals provide us with a kind of measure of the nonlocal content of each behavior, while the mutual information is a measure of the total correlations between the parties. We showed that there exists a trade-off between mutual information and the magnitude of the maximum Bell violation once the nonlocal region is reached, and this tradeoff is more restrictive for quantum behaviors. Our analysis also suggests that the Tsirelson bound can be obtained from a device-independent argument, as we showed that in this scenario it appears as an inflection point in the curve for the lower bound of the mutual information. An interesting question that we leave for future analysis is whether this approach of finding quantum bounds from the study of informational related quantities can provide further insights in more general Bell scenarios. Note that this generalization has, in principle, two difficulties of a different nature: on one side, there is a practical difficulty when trying to increase the number of inputs or outputs of the scenario (because the sampling needs to be done in higher dimensions). On the other hand, a more fundamental problem appears if one wants to increase the number of parties because the mutual information between three or more variables is not trivial to define, so the functional used to quantify correlations should be chosen carefully.

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