

# WEIGHTED BEST LOCAL APPROXIMATION IN ORLICZ SPACES

SERGIO FAVIER AND CLAUDIA RIDOLFI

ABSTRACT. In this paper we prove the existence of best multipoint local  $\phi$ -approximation to a function  $f$  in an Orlicz space  $L^\phi$  from an  $N$ -dimensional space  $S_N$  for a suitable integer  $N$ . The concept of  $\phi$ -balanced integer is considered since we deal with different speed of approaching the data on each of the real points  $x_1, \dots, x_n$ .

## INTRODUCTION

The best multipoint local approximations of a given data has been studied by several authors. In [1] Beatson and Chui considered the uniform norm when  $n = 2$ . In [6] Marano studied this problem in  $L^p$ , where the same speed at each point was assumed. This problem was also considered by Chui et al. in [2], and in this case, they introduced the concept of balanced point in  $L^p$ , where a different speed of convergence is considered at each point and where this fact also depends on  $p$ . In [3] Favier studied the best local approximation by polynomials using the Luxemburg norm in an Orlicz space. In this article we study the best local approximations in Orlicz spaces with a generalized concept of balanced points which depends, also in this case, on the function  $\phi$ .

We now introduce some notation. Let  $X$  be a bounded open set in  $\mathbb{R}$  and  $f : X \rightarrow \mathbb{R}$  be a sufficiently smooth function. We consider a finite measure space  $(X, \mathcal{A}, m)$ , where  $m$  is the Lebesgue measure and denote  $\mathcal{M} = \mathcal{M}(X, \mathcal{A}, m)$  the system of all equivalence classes of Lebesgue measurable real valued functions.

For each convex function  $\phi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ , with  $\phi(x) = 0$  if and only if  $x = 0$ , define

$$L^\phi(X) = \{f \in \mathcal{M} : \int_X \phi(\alpha|f(x)|)dx < \infty, \text{ for some } \alpha > 0\}.$$

This function spaces  $L^\phi$  is called the Orlicz space determined by  $\phi$ . The spaces  $L^\phi$  can be endowed with the following norm

$$\|f\|_\phi := \inf\{\lambda > 0 : \int_X \phi\left(\frac{|f(x)|}{\lambda}\right)dx \leq 1\},$$

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2000 *Mathematics Subject Classification.* Primary: 41A10. Secondary: 41A30.  
*Key words and phrases.* best local approximation,  $\phi$ -approximations, balanced integers.

This work was supported by CONICET and Universidad Nacional de San Luis.

called the Luxemburg norm. The spaces  $(L^\phi, \|\cdot\|_\phi)$  are Banach spaces (see e.g. [4]).

In this article we will use the following conditions. We say that the function  $\phi$  satisfies the  $\Delta_2$  condition if there exists a constant  $M > 0$  such that  $\phi(2x) \leq M\phi(x)$  for  $x \geq 0$  and we say that  $\phi$  satisfies the  $\Delta'$  condition if there exists a constant  $C > 0$  such that  $\phi(xy) \leq C\phi(x)\phi(y)$  for  $x, y \geq 0$ . There is some property about these conditions, for example,  $\Delta'$  condition imply  $\Delta_2$  condition, furthermore it is well known that if  $\phi$  satisfies the  $\Delta_2$  condition then the  $L^\phi$  space can be defined as

$$L^\phi(X) = \{f : \int_X \phi(\alpha|f(x)|)dx < \infty, \text{ for any } \alpha > 0\}.$$

We assume in this article that the convex function  $\phi$  satisfies the  $\Delta'$  condition. For a detailed study of Orlicz spaces the reader is referred to [4].

Given  $n$  real points  $\{x_1, \dots, x_n\}$  we define for  $\delta > 0$  a net of measurable sets  $V_k = V_k(\delta)$ ,  $k = 1, \dots, n$ , where  $V_k(\delta) = x_k + \varepsilon_k(\delta) A_k(\delta)$  and  $A_k = A_k(\delta)$  is a measurable set with measure 1 and  $\varepsilon_k = \varepsilon_k(\delta) \searrow 0$  as  $\delta \rightarrow 0$ . We point out that the sets  $A_k$  are uniformly bounded for all  $\delta > 0$ .

For each  $\delta > 0$  the function  $f$  will be approximated on the set  $V = V(\delta) = \bigcup V_k$  by a function from a subspace  $S_N$  of  $L^\phi$ . Denote  $g_\delta \in S_N$  so that

$$\int_V \phi(|f(x) - g_\delta(x)|)dx \leq \int_V \phi(|f(x) - h(x)|)dx,$$

for all  $h \in S_N$ . Such a function  $g_\delta$  is called the best  $\phi$ -approximation of  $f$  from  $S_N$ .

Given  $f$ ,  $S_N$ ,  $\phi$  and the  $n$ -tuples  $\langle x_k \rangle := \langle x_1, \dots, x_n \rangle$  and  $\langle V_k \rangle := \langle V_1, \dots, V_n \rangle$ , if we consider a net of best  $\phi$ -approximation functions  $\{g_\delta\}$  and it has a limit in  $S_N$  as  $\delta \rightarrow 0$  then this limit is called *the best local  $\phi$ -approximation of  $f$  from  $S_N$* . Under certain conditions the best local  $\phi$ -approximation can be obtained by Hermite interpolation and it can be calculated explicitly without having to find the elements of the net  $\{g_\delta\}$ . This result will be presented in sections 3.

Now we make an assumption on the  $n$ -tuple  $\langle \varepsilon_k \rangle$  which will guarantee us that the terms of the form  $\phi(\varepsilon_k^\alpha)\varepsilon_k$  can be compared with each other as functions of  $\delta$  which is a weaker condition to those in [2] for the  $L^P$  case. However in our case it depends also on  $\phi$ . Namely, for any  $\alpha, \beta \geq 0$  and any  $j, k$  such that  $1 \leq j, k \leq n$ , we assume that either  $\phi(\varepsilon_j^\beta)\varepsilon_j = O(\phi(\varepsilon_k^\alpha)\varepsilon_k)$  or  $\phi(\varepsilon_k^\alpha)\varepsilon_k = O(\phi(\varepsilon_j^\beta)\varepsilon_j)$  or both. Given a  $n$ -tuple of functions  $\langle \phi(\varepsilon_k^{\alpha_k})\varepsilon_k \rangle$  where  $\alpha_k \geq 0$  is a positive real number,  $\phi(\varepsilon_j^{\alpha_j})\varepsilon_j$  is said to be maximal if for all  $k$ ,  $1 \leq k \leq n$ ,  $\phi(\varepsilon_k^{\alpha_k})\varepsilon_k = O(\phi(\varepsilon_j^{\alpha_j})\varepsilon_j)$ . We denote it by  $\max\{\phi(\varepsilon_k^{\alpha_k})\varepsilon_k\}$ .

*Remark 1.* The assumption over the  $n$ -tuple  $\langle \varepsilon_k \rangle$  imply the existence of  $\max\{\phi(\varepsilon_k^{\alpha_k})\varepsilon_k\}$  for any  $n$ -tuple  $\langle \alpha_k \rangle$  of positive real numbers.

We assume that  $f$  and  $S_N$  are in  $PC^m(X)$ , where  $PC^m(X)$  is the class of functions with  $m-1$  continuous derivatives and with piecewise continuous  $m^{\text{th}}$  derivative. The space  $S_N$  is assumed to be fully interpolating at the set  $\langle x_k \rangle$ , that is if  $S_N \in PC^m(X)$  and  $i_1, \dots, i_n$  are nonnegative integers with  $i_k \leq m$  and  $\sum_{k=1}^n i_k = N$  then there exists a unique  $g \in S_N$  such that  $g^{(j)}(x_k) = a_{j,k}$ ,  $0 \leq j \leq i_k - 1$ ,  $1 \leq k \leq n$ , where  $a_{j,k}$  are an arbitrary set of real numbers.

## 1. PRELIMINARY RESULTS

In this section we prove two Lemmas, which will be used to obtain the main results. This pattern follows the way used in [2] for the  $L^p$  case.

The following Lemma provides an order of the error  $\int_V \phi(|f-g|)dx$  when  $g \in S_N$  and satisfies  $f^{(j)}(x_k) = g^{(j)}(x_k)$ ,  $0 \leq j \leq i_k - 1$ ,  $1 \leq k \leq n$ .

**Lemma 1.1.** *Let  $i_1, \dots, i_n$  be nonnegative integers. Suppose  $h \in PC^m(X)$ , where  $m = \max\{i_k\}$ , and  $h^{(j)}(x_k) = 0$ ,  $0 \leq j \leq i_k - 1$ ,  $1 \leq k \leq n$ . Then*

$$\int_V \phi(|h|)dx = O(\max\{\phi(\varepsilon_k^{i_k})\varepsilon_k\}).$$

*Proof.* Approximating  $h$  by the Taylor polynomial about  $x_k$ , we have

$$h(x) = \sum_{j=0}^{i_k-1} \frac{h^{(j)}(x_k)}{j!} (x - x_k)^j + R_k(x),$$

where  $R_k(x) = \frac{h^{(i_k)}(\xi)}{i_k!} (x - x_k)^{i_k}$ , with  $\xi$  between  $x$  and  $x_k$ . It means  $R_k(x) = O((x - x_k)^{i_k})$ . Since  $h^{(j)}(x_k) = 0$ ,  $0 \leq j \leq i_k - 1$ , we have  $h(x) = O((x - x_k)^{i_k})$ ,  $x \in V_k$ . Thus, by the  $\Delta_2$  condition on  $\phi$  and setting

$x - x_k = \varepsilon_k y$ , we obtain  $\int_{V_k} \phi(|h(x)|) dx \leq M \int_{V_k} \phi(|x - x_k|^{i_k}) dx \leq M \int_{A_k} \varepsilon_k \phi(\varepsilon_k^{i_k} |y|^{i_k}) dy \leq M' \varepsilon_k \phi(\varepsilon_k^{i_k})$ , since  $A_k$  are uniformly bounded for all  $\delta > 0$ . Finally there exist constant  $M$  and  $M'$  such that

$$\int_V \phi(|h|)dx \leq M \sum_{k=1}^n \phi(\varepsilon_k^{i_k})\varepsilon_k \leq M' \max\{\phi(\varepsilon_k^{i_k})\varepsilon_k\},$$

or

$$\int_V \phi(|h|)dx = O(\max\{\phi(\varepsilon_k^{i_k})\varepsilon_k\}),$$

as required.  $\square$

We now cite the Lemma 3 stated in [2] which will be used in the sequel.

**Lemma 1.2.** *Let  $\Lambda$  be a family of uniformly bounded measurable subsets of the real line with measure 1. Let  $P(x) = c_0 + c_1x + \dots + c_mx^m$  be an arbitrary polynomial of degree  $m$ . Then there exists a constant  $M$  (depending on  $m$ ) such that for all  $P(x)$  and all  $A \in \Lambda$ ,*

$$|c_k| \leq M \|P(x)\|_{L^p(A)},$$

$$1 \leq p \leq \infty, \quad 0 \leq k \leq m.$$

As a consequence of this Lemma we obtain a similar result in  $L^\phi$ .

**Corollary 1.3.** *Let  $\Lambda$  be a family of uniformly bounded measurable subsets of the real line with measure 1. Let  $P(x) = c_0 + c_1x + \dots + c_mx^m$  be an arbitrary polynomial of degree  $m$ . Then there exists a constant  $M$  (depending on  $m$  and  $\phi$ ) such that for all  $P(x)$  and all  $A \in \Lambda$ ,*

$$\phi(|c_k|) \leq M \int_A \phi(|P(x)|) dx,$$

$$0 \leq k \leq m.$$

*Proof.* In the following proof the constant  $M$  can be different in each occurrence. We know there is a constant  $M$  such that for all  $P(x)$  and all  $A \in \Lambda$ ,  $|c_k| \leq M \int_A |P(x)| dx$ ,  $0 \leq k \leq m$ , then

$$\phi(|c_k|) \leq M' \phi(M) \phi\left(\int_A |P(x)| dx\right),$$

since  $\phi$  is an increasing function which satisfies the  $\Delta'$  condition. Now, using the Jensen's Inequality we obtain

$$\phi(|c_k|) \leq M \int_A \phi(|P(x)|) dx, \quad 0 \leq k \leq m,$$

for all  $A \in \Lambda$ . This completes the proof.  $\square$

## 2. $\Phi$ -BALANCED NEIGHBORHOOD IN $L^\phi$

The following definition generalizes a concept given in [2] for the  $L^p$  space.

**Definition 2.1.** *Given the  $n$ -tuple  $\langle \varepsilon_k \rangle$ ; an  $n$ -tuple  $\langle i_k \rangle$  of nonnegative integers is said to be  $\phi$ -balanced if for each  $j$  such that  $i_j > 0$ ,*

$$\phi\left(\frac{1}{\varepsilon_j^{i_j-1}}\right) \max\left\{\frac{\phi(\varepsilon_k^{i_k})\varepsilon_k}{\varepsilon_j}\right\} = o(1).$$

If  $\langle i_k \rangle$  is  $\phi$ -balanced, then  $\sum_{k=1}^n i_k$  is said to be a  $\phi$ -balanced integer.

The  $n$ -tuple  $\langle V_k \rangle$  is said to be  $\phi$ -balanced neighborhoods if the dimension  $N$  of the space  $S_N$  is a  $\phi$ -balanced integer.

*Remark 2.* If  $\phi(x) = x^p$ ,  $1 \leq p < \infty$  the last definition of  $\phi$ -balanced is equivalent to those considered by Chui et al. in [2].

**Example 2.2.** Let  $\phi(x) = x^3(1 + |\ln x|)$  with  $\phi(0) = 0$ . This convex function satisfies the  $\Delta'$  condition and  $\langle \varepsilon_1, \varepsilon_2 \rangle = \langle \delta, e^{-1/\delta} \rangle$ . In this case any integer  $N$  is a  $\phi$ -balanced integer.

*Remark 3.* To each  $\phi$ -balanced integer there corresponds exactly one  $\phi$ -balanced  $\langle i_k \rangle$ . In fact, since  $\phi$  satisfies the  $\Delta'$  condition and we suppose  $\langle i_k \rangle \neq \langle i'_k \rangle$  with  $\sum_{k=1}^n i_k = \sum_{k=1}^n i'_k$  and  $\langle i_k \rangle$  is  $\phi$ -balanced, then there exist  $j, l$  with  $i_j < i'_j$  and  $i'_l < i_l$ , such that

$$\phi\left(\frac{1}{\varepsilon_j^{i'_j-1}}\right) \frac{\phi(\varepsilon_l^{i'_l})\varepsilon_l}{\varepsilon_j} \geq \phi\left(\frac{1}{\varepsilon_j^{i_j}}\right) \frac{\phi(\varepsilon_l^{i_l-1})\varepsilon_l}{\varepsilon_j} \geq M \frac{1}{\phi\left(\frac{1}{\varepsilon_l^{i_l-1}}\right) \frac{\phi(\varepsilon_j^{i_j})\varepsilon_j}{\varepsilon_l}},$$

and the last expression tends to infinite, so  $\langle i'_k \rangle$  is not  $\phi$ -balanced.

In [2] it was given an algorithm which generates all balanced integers in  $L^p$  spaces. Now, we will present an algorithm that inductively generates all the integers  $m$  which can be  $\phi$ -balanced in  $L^\phi$ , that is, it generates a  $n$ -tuple  $\langle i_k^{(m)} \rangle$  such that  $\sum_{k=1}^n i_k^{(m)} = m$ .

Beginning with the  $\phi$ -balanced  $n$ -tuple  $\langle i_k^{(0)} \rangle = \langle 0 \rangle$  corresponding to the  $\phi$ -balanced integer 0 and given  $\langle i_k^{(m)} \rangle$ , determine a maximal element of  $\langle \phi(\varepsilon_k^{i_k^{(m)}})\varepsilon_k \rangle$ , say  $\phi(\varepsilon_{k^*}^{i_{k^*}^{(m)}})\varepsilon_{k^*} = \max\{\phi(\varepsilon_k^{i_k^{(m)}})\varepsilon_k\}$  and define  $i_k^{(m+1)} = i_k^{(m)}$  for  $k \neq k^*$  and  $i_{k^*}^{(m+1)} = i_{k^*}^{(m)} + 1$  for  $k = k^*$ .

*Remark 4.* The algorithm reduces, at each step, the largest value of  $\phi(\varepsilon_k^{i_k})\varepsilon_k$  changing  $i_k$  by  $i_k + 1$ .

**Lemma 2.3.** a) The above algorithm generates all  $\phi$ -balanced  $\langle i_k \rangle$ .

b) If a  $n$ -tuple  $\langle i_k^{(m)} \rangle$  generated by the algorithm ( $m \geq 1$ ) is  $\phi$ -balanced, then there is a unique maximal element of  $\langle \phi(\varepsilon_k^{i_k^{(m-1)}})\varepsilon_k \rangle$ .

*Proof.* First we will prove a). Suppose that  $\langle i_k \rangle$  is  $\phi$ -balanced with  $\sum_{k=1}^n i_k = m$  and  $\langle i_k^{(m)} \rangle$  as obtained by the algorithm is not  $\phi$ -balanced. Then, there exist indices  $r, s$  with  $i_r^{(m)} > i_r$  and  $i_s > i_s^{(m)}$  such that, using the  $\phi$ -balanced integer definition,

$$\phi(\varepsilon_r^{i_r^{(m)}-1})\varepsilon_r = O(\phi(\varepsilon_r^{i_r})\varepsilon_r) = O(\max\{\phi(\varepsilon_k^{i_k})\varepsilon_k\}) = o\left(\frac{\varepsilon_s}{\phi\left(\frac{1}{\varepsilon_s^{i_s-1}}\right)}\right),$$

and from the  $\Delta'$  condition on  $\phi$ , the last expression is an  $o(\phi(\varepsilon_s^{i_s-1})\varepsilon_s)$ , so

$$\phi(\varepsilon_r^{i_r^{(m)}-1})\varepsilon_r = o(\phi(\varepsilon_s^{i_s^{(m)}})\varepsilon_s).$$

Since  $i_r^{(m)} > 0$  at some previous step  $\phi(\varepsilon_r^{i_r^{(m)}-1})\varepsilon_r$  was maximal of  $\langle \phi(\varepsilon_k^{i_k^{(m')}})\varepsilon_k \rangle$  with  $m' < m$ , so  $\phi(\varepsilon_r^{i_r^{(m)}-1})\varepsilon_r = \max\{\phi(\varepsilon_k^{i_k^{(m')}})\varepsilon_k\}$  because the exponents are non-decreasing at each step of the algorithm.

Thus for any  $k$

$$\phi(\varepsilon_k^{i_k^{(m)}})\varepsilon_k = O(\phi(\varepsilon_r^{i_r^{(m)}-1})\varepsilon_r),$$

which is a contradiction.

Now we will prove b). If  $\max\{\phi(\varepsilon_k^{i_k^{(m)}})\varepsilon_k\}$  is not unique then  $\langle i_k^{(m)} \rangle$  cannot be  $\phi$ -balanced because if the index  $j$  and  $s$  gives a maximal element of  $\langle \phi(\varepsilon_k^{i_k^{(m)}})\varepsilon_k \rangle$  then there exist two constant  $M, N$  such that

$$M \leq \frac{\phi(\varepsilon_j^{i_j^{(m-1)}})\varepsilon_j}{\phi(\varepsilon_s^{i_s^{(m-1)}})\varepsilon_s} \leq N.$$

Suppose that  $i_k^{(m)} = i_k^{(m-1)}$  for  $k \neq s$  and  $i_k^{(m)} = i_k^{(m-1)} + 1$  for  $k = s$ , so  $i_s^{(m)} > 0$  and then

$$\begin{aligned} \phi\left(\frac{1}{\varepsilon_s^{i_s^{(m)}-1}}\right) \max\left\{\frac{\phi(\varepsilon_k^{i_k^{(m)}})\varepsilon_k}{\varepsilon_s}\right\} &= \phi\left(\frac{1}{\varepsilon_s^{i_s^{(m-1)}}}\right) \frac{\phi(\varepsilon_j^{i_j^{(m-1)}})\varepsilon_j}{\varepsilon_s} \\ &\geq A \frac{\phi(\varepsilon_j^{i_j^{(m-1)}})\varepsilon_j}{\phi(\varepsilon_s^{i_s^{(m-1)}})\varepsilon_s} \geq AM, \end{aligned}$$

by the  $\Delta'$  condition. This show that  $\langle i_k^{(m)} \rangle$  cannot be  $\phi$ -balanced.  $\square$

*Remark 5.* The reverse hand of the Lemma 2.3 does not hold.

We take  $\phi(x) = x^3(|\ln x| + 1)$  with  $\phi(0) = 0$  and  $\langle \varepsilon_k \rangle = \langle \delta, \delta^4 \rangle$  then, in the first step, the algorithm generate  $\langle 1, 0 \rangle$  with a unique corresponding maximal element  $\max\{\phi(\varepsilon_k^{i_k})\varepsilon_k\} = \phi(\varepsilon_1^1)\varepsilon_1$ , however the bi-tuple  $\langle 2, 0 \rangle$  is not  $\phi$ -balanced.

We point out that the last Remark shows a difference with the  $L^p$  case. In [2] it is proved the reverse hand of this Lemma for the  $L^p$  case assuming a stronger condition on the  $n$ -tuple  $\langle \varepsilon_k \rangle$ .

### 3. BEST LOCAL $\phi$ -APPROXIMATION IN ORLICZ SPACES WITH $\phi$ -BALANCED NEIGHBORHOOD.

We now come to the main result concerning to the behavior of a net  $\{g_\delta\}$  of best  $\phi$ -approximations. For this purpose we set the following three Lemmas.

**Lemma 3.1.** *Given  $\langle \varepsilon_k \rangle$  and  $\langle i_k \rangle$ , define  $m = \max\{i_k\}$ . Let  $f \in PC^m(X)$  and  $S_N \subseteq PC^m(X)$ . If we consider a net  $\{g_\delta\}$  of best  $\phi$ -approximation such that*

$$(1) \quad \int_X \phi(|g_\delta|) dx \longrightarrow \infty, \text{ as } \delta \longrightarrow 0,$$

then the net of functions

$$h_\delta = \frac{g - g_\delta}{\int_X |g - g_\delta| dx},$$

where  $g \in S_N$  interpolate  $f^{(j)}(x_k)$ ,  $0 \leq j \leq i_k - 1$ ,  $1 \leq k \leq n$ , satisfies the following properties

i)  $\int_X \phi(|h_\delta|) dx \geq A > 0$ ,

ii)  $\int_V \phi(|h_\delta|) dx = o(\max\{\phi(\varepsilon_k^{i_k})\varepsilon_k\})$ .

*Proof.* Property i) follows using the Jensen's Inequality and property ii) is a consequence of the hypothesis. In fact, since  $\phi$  satisfies the  $\Delta_2$  condition

$$\int_X \phi(|g_\delta|) dx \leq M \left( \int_X \phi(|g_\delta - g|) dx + \int_X \phi(|g|) dx \right),$$

so, using (1) we obtain

$$(2) \quad \int_X \phi(|g - g_\delta|) dx \longrightarrow \infty,$$

as  $\delta \longrightarrow 0$ , or

$$\int_X |g - g_\delta| dx \longrightarrow \infty,$$

as  $\delta \longrightarrow 0$ , because if there were exist a sequence  $\{\delta_s\}$  such that  $\int_X |g - g_{\delta_s}| dx \leq M$  for all  $\delta_s$ , then  $\|g - g_{\delta_s}\|_\infty \leq M$  for all  $\delta_s$  since the norms are equivalent, and so  $\int_X \phi(|g - g_{\delta_s}|) dx \leq M'$ , which is a contradiction.

On the other hand, by the  $\Delta_2$  condition on  $\phi$  and Lemma 1.1

$$\begin{aligned} \int_V \phi(|g - g_\delta|) dx &\leq M \int_V \phi(|g - f|) dx + M \int_V \phi(|f - g_\delta|) dx \\ &= O(\max\{\phi(\varepsilon_k^{i_k})\varepsilon_k\}), \end{aligned}$$

then, since  $\phi$  is a convex function

$$\int_V \phi(|h_\delta|) dx \leq \frac{1}{\int_X |g - g_\delta| dx} \int_V \phi(|g - g_\delta|) dx = o(\max\{\phi(\varepsilon_k^{i_k})\varepsilon_k\}),$$

as required.  $\square$

**Lemma 3.2.** *Given  $\langle \varepsilon_k \rangle$  set a  $\phi$ -balanced  $n$ -tuple  $\langle i_k \rangle$  such that  $N = \sum_{k=1}^n i_k$  and define  $m = \max\{i_k\}$ . If  $f \in PC^m(X)$ ,  $S_N \subseteq PC^m(X)$  and given  $\delta > 0$  set  $\{g_\delta\}$  for a net of best  $\phi$ -approximation of  $f$ , then there exists  $M > 0$  such that*

$$\int_X \phi(|g_\delta|) dx \leq M,$$

for all  $\delta > 0$ .

*Proof.* Suppose  $\{\delta_r\}$  is a sequence such that

$$\int_X \phi(|g_{\delta_r}|) dx \longrightarrow \infty,$$

as  $\delta_r \longrightarrow 0$ . Let  $g$  be a fixed function in  $S_N$  interpolating the derivatives  $f^{(j)}(x_k)$ ,  $0 \leq j \leq i_k-1$ ,  $1 \leq k \leq n$  and define

$$h_{\delta_r} = \frac{g - g_{\delta_r}}{\int_X |g - g_{\delta_r}| dx},$$

then, using Lemma 3.1, we have

- i)  $\int_X \phi(|h_{\delta_r}|) dx \geq A > 0$ , for all  $\delta_r$ .
- ii)  $\int_V \phi(|h_{\delta_r}|) dx = o(\max\{\phi(\varepsilon_k^{i_k})\varepsilon_k\})$ .

Expanding  $h_{\delta_r}$  using Taylor polynomials we obtain for each  $k$

$$h_{\delta_r}(x) = \sum_{j=1}^{i_k-1} \frac{h_{\delta_r}^{(j)}(x_k)}{j!} (x - x_k)^j + R_{\delta_r}(x),$$

where  $R_{\delta_r}(x) = O((x-x_k)^{i_k})$  uniformly in  $\delta_r$ . In fact, since  $\|h_{\delta_r}\|_{L^1(X)} \leq 1$  for all  $\delta_r$  and using the fact that the norms are equivalent in  $S_N$ , we can choose the norm  $\|h_{\delta_r}\| := \sup_{x \in X} \{|h_{\delta_r}(x)| + \dots + |h_{\delta_r}^{(i_k)}(x)|\}$  to show the statement.

This uniform bound of  $R_{\delta_r}(x)$ , leads to

$$\int_{V_k} \phi(|R_{\delta_r}(x)|) dx = O(\varepsilon_k \phi(\varepsilon_k^{i_k})),$$

for all  $r$ , taking  $x - x_k = \varepsilon_k y$  and using that the sets  $A_k$  are uniformly bounded. Thus, using property *ii*) we obtain

$$\begin{aligned} & \int_{V_k} \phi \left( \left| \sum_{j=0}^{i_k-1} \frac{h_{\delta_r}^{(j)}(x_k)}{j!} (x - x_k)^j \right| \right) dx \\ & \leq M \int_{V_k} \phi \left( \left| \sum_{j=0}^{i_k-1} \frac{h_{\delta_r}^{(j)}(x_k)}{j!} (x - x_k)^j + R_{\delta_r}(x) \right| \right) dx + M \int_{V_k} \phi(|R_{\delta_r}(x)|) dx \\ & = M \int_{V_k} \phi(|h_{\delta_r}|) dx + O(\varepsilon_k \phi(\varepsilon_k^{i_k})) \leq M \int_V \phi(|h_{\delta_r}|) dx + O(\varepsilon_k \phi(\varepsilon_k^{i_k})) \\ & = o(\max\{\phi(\varepsilon_l^{i_l})\varepsilon_l\}) + O(\varepsilon_k \phi(\varepsilon_k^{i_k})), \end{aligned}$$

if we substitute  $x - x_k = \varepsilon_k y$  again we obtain

$$\int_{A_k} \phi \left( \left| \sum_{j=0}^{i_k-1} \frac{h_{\delta_r}^{(j)}(x_k)}{j!} (\varepsilon_k)^j y^j \right| \right) dy = O \left( \max \left\{ \frac{\phi(\varepsilon_l^{i_l})\varepsilon_l}{\varepsilon_k} \right\} \right),$$

for  $1 \leq k \leq n$ . From Corollary 1.3

$$\phi \left( \left| \frac{h_{\delta_r}^{(j)}(x_k)}{j!} (\varepsilon_k)^j \right| \right) = O \left( \max \left\{ \frac{\phi(\varepsilon_l^{i_l})\varepsilon_l}{\varepsilon_k} \right\} \right),$$



$j = 0, \dots, i_k - 1$ ,  $1 \leq k \leq n$ , using that  $\phi$  satisfies the  $\Delta'$  condition, for each  $k$  we get

$$\phi(|h_{\delta_r}^{(j)}(x_k)|) \leq M\phi\left(\frac{1}{\varepsilon_k^{i_k-1}}\right)O\left(\max\left\{\frac{\phi(\varepsilon_l^{i_l})\varepsilon_l}{\varepsilon_k}\right\}\right),$$

for  $j = 0, \dots, i_k - 1$ . Finally, since  $N$  is a  $\phi$ -balanced integer and  $\phi$  a strictly increasing function, we obtain

$$h_{\delta_r}^{(j)}(x_k) = o(1),$$

$0 \leq j \leq i_k - 1$ ,  $1 \leq k \leq n$ , and when  $\delta_r \rightarrow 0$ . Now, since  $h_{\delta_r} \in S_N$  we get  $h_{\delta_r} = \sum_{i=1}^N a_{\delta_r, i} \tilde{h}_i$  where  $\{\tilde{h}_1, \dots, \tilde{h}_N\}$  is a basis of  $S_N$ . So  $h_{\delta_r}$  is uniquely determined by the  $N$  values  $h_{\delta_r}^{(j)}(x_k)$ ,  $0 \leq j \leq i_k - 1$ ,  $1 \leq k \leq n$ , using the fixed linear transformation

$$\begin{pmatrix} \tilde{h}_1(x_1) & \dots & \tilde{h}_N(x_1) \\ \vdots & \ddots & \vdots \\ \tilde{h}_1^{(i_n-1)}(x_n) & \dots & \tilde{h}_N^{(i_n-1)}(x_n) \end{pmatrix}.$$

Then  $h_{\delta_r} \rightarrow 0$  as  $\delta_r \rightarrow 0$ , thus

$$\lim_{\delta_r \rightarrow 0} \int_X \phi(|h_{\delta_r}|) dx = 0$$

which contradicts property *i*). Thus  $g_\delta$  must be bounded for all  $\delta$  and the proof of the Lemma is complete.  $\square$

**Lemma 3.3.** *Given  $\langle \varepsilon_k \rangle$  and a  $\phi$ -balanced  $n$ -tuple  $\langle i_k \rangle$  such that  $N = \sum_{k=1}^n i_k$ , define  $m = \max\{i_k\}$ . If  $f \in PC^m(X)$ ,  $S_N \subseteq PC^m(X)$  and  $\{g_\delta\}$  is a net of best  $\phi$ -approximation, then for each  $k$*

$$\phi(|(f - g_\delta)^{(j)}(x_k)| \varepsilon_k^j) = O\left(\max\left\{\frac{\phi(\varepsilon_l^{i_l})\varepsilon_l}{\varepsilon_k}\right\}\right),$$

$$0 \leq j \leq i_k - 1.$$

*Proof.* For each  $k$ , expanding  $f - g_\delta$  using Taylor polynomials, we obtain

$$(f - g_\delta)(x) = \sum_{j=1}^{i_k-1} \frac{(f - g_\delta)^{(j)}(x_k)}{j!} (x - x_k)^j + R_\delta(x).$$

We may use the above analysis to show that  $R_{\delta_r}(x) = O((x - x_k)^{i_k})$  uniformly in  $\delta$ . In fact, it follows from Lemma 3.2 that  $\int_X \phi(|g_\delta|) dx \leq M$  for all  $\delta$ , thus  $\|g_\delta\|_\phi \leq M$  for all  $\delta$  and using that the norms are equivalent in  $S_N$ , we can choose again the norm  $\|h_{\delta_r}\| = \sup_{x \in X} \{|h_{\delta_r}(x)| + \dots + |h_{\delta_r}^{(i_k)}(x)|\}$  to prove the statement.

These uniform bound of  $R_{\delta_r}(x)$  and since the sets  $A_k$  are uniformly bounded, substituting  $x - x_k = \varepsilon_k y$ , leads to

$$(3) \quad \int_{V_k} \phi(|R_{\delta}(x)|) dx = O(\phi(\varepsilon_k^{i_k}) \varepsilon_k).$$

On the other hand, using a fixed  $g \in S_N$  which interpolates the derivatives  $f^{(j)}(x_k)$ ,  $0 \leq j \leq i_k - 1$ ,  $1 \leq k \leq n$ , from Lemma 1.1 we obtain

$$\int_V \phi(|f - g_{\delta}|) dx = O(\max\{\phi(\varepsilon_k^{i_k}) \varepsilon_k\}),$$

thus, using (3) and the  $\Delta_2$  condition, we obtain for each  $k$

$$\begin{aligned} & \int_{V_k} \phi \left( \left| \sum_{j=0}^{i_k-1} \frac{(f - g_{\delta})^{(j)}(x_k)}{j!} (x - x_k)^j \right| \right) dx \leq M \int_{V_k} \phi(|f - g_{\delta}|) dx \\ & + M \int_{V_k} \phi(|R_{\delta}(x)|) dx = O(\max\{\phi(\varepsilon_l^{i_l}) \varepsilon_l\}) + O(\varepsilon_k \phi(\varepsilon_k^{i_k})) \\ & = O(\max\{\phi(\varepsilon_l^{i_l}) \varepsilon_l\}), \end{aligned}$$

and finally if we substitute  $x - x_k = \varepsilon_k y$  then for each  $k$

$$\int_{A_k} \phi \left( \left| \sum_{j=0}^{i_k-1} \frac{(f - g_{\delta})^{(j)}(x_k)}{j!} \varepsilon_k^j y^j \right| \right) dy = O \left( \max \left\{ \frac{\phi(\varepsilon_l^{i_l}) \varepsilon_l}{\varepsilon_k} \right\} \right).$$

Now we conclude from Corollary 1.3 that

$$\phi(|(f - g_{\delta})^{(j)}(x_k) \varepsilon_k^j|) = O \left( \max \left\{ \frac{\phi(\varepsilon_l^{i_l}) \varepsilon_l}{\varepsilon_k} \right\} \right),$$

$0 \leq j \leq i_k - 1$ , for each  $k$ . □

Now we present the following result.

**Theorem 3.4.** *If  $N$  is a  $\phi$ -balanced integer with  $\phi$ -balanced  $\langle i_k \rangle$  and  $f \in PC^m(X)$ ,  $S_N \subset PC^m(X)$ , ( $m = \max\{i_k\}$ ), then the best local  $\phi$ -approximation of  $f$  from  $S_N$  is the unique  $g \in S_N$  defined by the  $N$  interpolation conditions*

$$f^{(j)}(x_k) = g^{(j)}(x_k),$$

$0 \leq j \leq i_k - 1$ ,  $1 \leq k \leq n$ .

*Proof.* From Lemma 3.3

$$\phi(|(f - g_{\delta})^{(j)}(x_k) \varepsilon_k^j|) = O \left( \max \left\{ \frac{\phi(\varepsilon_l^{i_l}) \varepsilon_l}{\varepsilon_k} \right\} \right),$$

$0 \leq j \leq i_k - 1$ ,  $1 \leq k \leq n$ . Using the  $\Delta'$  condition and the  $\phi$ -balanced integer definition we have for each  $k$

$$\phi(|(f - g_{\delta})^{(j)}(x_k)|) = \phi \left( \frac{1}{\varepsilon_k^{i_k-1}} \right) O \left( \max \left\{ \frac{\phi(\varepsilon_l^{i_l}) \varepsilon_l}{\varepsilon_k} \right\} \right) = o(1),$$

$0 \leq j \leq i_k - 1$ , thus, since  $\phi$  is a strictly increasing function with  $\phi(x) = 0$  if and only if  $x = 0$

$$\lim_{\delta \rightarrow 0} g_\delta^{(j)}(x_k) = f^{(j)}(x_k),$$

$0 \leq j \leq i_k - 1$ ,  $1 \leq k \leq n$ . Now we will do a similar analysis as above. As  $g_\delta$  is uniquely determined via a fixed linear transformation with rank  $N$  from the  $N$  values  $g_\delta^{(j)}(x_k)$ ,  $0 \leq j \leq i_k - 1$ ,  $1 \leq k \leq n$ , then  $g_\delta$  must converge to the unique  $g$  satisfying

$$g^{(j)}(x_k) = f^{(j)}(x_k),$$

$0 \leq j \leq i_k - 1$ ,  $1 \leq k \leq n$ . This  $g$  is by definition the best local  $\phi$ -approximation of  $f$  from  $S_N$ . □

**Acknowledgment.** The authors wish to thank Professor H. Cuenya for his helpful comments about this paper.

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INSTITUTO DE MATEMÁTICA APLICADA SAN LUIS. CONICET AND UNIV. NAC.  
DE SAN LUIS. AVDA. JÉRCITO DE LOS ANDES 950. 5700 SAN LUIS, ARGENTINA.  
*E-mail address:* sfavier@unsl.edu.ar; ridolfi@unsl.edu.ar