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# Electrical imaging for localizing historical tunnels at an urban environment

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# Abstract

We performed a geophysical study at a historical site in Buenos Aires, Argentina, corresponding to the location of a Jesuit Mission established during the 17<sup>th</sup> century, remaining there until the 18th century. The site consisted of a church, cloisters, a school, orchards and a procurator's office; also several tunnels were built, connecting the mission with different public buildings in the town. In the 19th century the Faculty of Sciences of the University of Buenos Aires was built in a sector of the site originally occupied by an orchard, functioning until its demolition in 1973. At present, this area is a cobbled square. With the aim of preserving and restoring the buried structures, work was carried out in this square looking for tunnels and remains of the basement of the old building.

Considering the conductive features of the subsoil, mainly formed by clays and silt, the complex characteristics of the buried structures, and the urban localization of the study area with its consequent high level of environmental electromagnetic noise, we performed prefeasibility studies to determine the usefulness of different geophysical methods. The best results were achieved from the geoelectrical method. Dipole–dipole profiles with electrode spacings of 1.5 and 3 m provided enough lateral and vertical resolution and the required penetration depth. Reliable data were obtained as long as the electrodes were buried at least 15 cm among the cobble stones. Nine 2D electrical resistivity tomographies were obtained by using a robust inversion procedure to reduce the effect of possible data outliers in the resulting models. The effect on these models of different error estimations was also analyzed. Then, we built up a pseudo-3D model by laterally interpolating the 2D inversion results. Finally, by correlating the resulting model with the original plans, the remains of the expected main structures embedded in the site were characterized. In addition, an anomaly was identified that indicates the presence of a tunnel not previously reported.

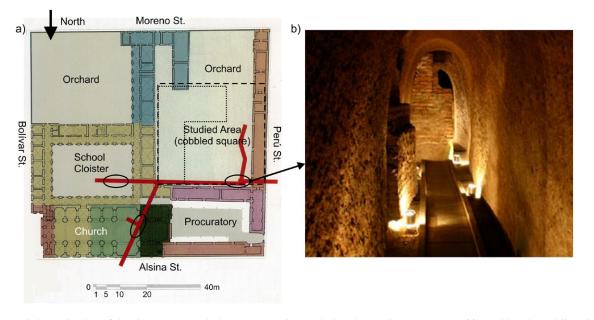
Keywords: urban geophysics, electrical resistivity tomography, tunnels

(Some figures may appear in colour only in the online journal)

# Introduction

The paper presented here is a case of a geophysical study at an urban site. This study was performed in the historical site named 'Manzana de las Luces', located in the old downtown of Buenos Aires, Argentina, which today is a highly populated area. This site is known as the birthplace of the intellectuality of the region. Its history began in 1661, with the settlement of Jesuits in the town (e.g. Furlong 1994). They planned and built up different buildings, including a church, a school,

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**Figure 1.** (a) Schematic plan of the site 'Manzana de las Luces', as it was during the Jesuit occupancy (1661–1730). The red lines indicate the location of the tunnels reported in historical records and the ellipses the sectors of these tunnels currently exposed. The dashed rectangle denotes the area studied in the present work (nowadays a cobbled square). The dotted lines show the limits of the basement of the old building of the Faculty of Sciences of the University of Buenos Aires, as described in a plan of 1895 (Mayochi *et al* 2008). (b) Photo of a tunnel restored and exposed.

cloisters and the procurator's offices. They also developed and maintained large orchards for the food supplies of the mission. During the 17th and 18th centuries tunnels were built in the downtown, forming a network linking churches and different public buildings with the Fort and the Customs of the town. According to historical records, at least three of them ran under the site of the mission (Mayochi et al 2008, Levinton 2012), one lying from east to west and two others approximately from north to south (figure 1(a)). Further historical investigations indicated that these tunnels could be longer and also that there could be others not officially reported. In the 19th century, the Faculty of Sciences of the University of Buenos Aires was built in a place previously occupied by an orchard, functioning until its demolition in 1973 (figure 1(a)). Then, this area became a cobbled square, which is now employed as a parking lot.

During the last years of the 20th century, a national project began to recover the cultural heritage of the site. Starting in 1983, tracts of the tunnels were located and conditioned for its reopening (figures 1(a) and (b)). A major objective in this project is to build up an interpretation center over the actual cobbled square, under the condition of preserving the historical remains, some of which will be later restored for exhibition. Within this context, we carried out a geophysical study with a primary goal of detecting and characterizing those buried structures.

Geophysical methods are increasingly being used to characterize archaeological remains and other subsurface structures in urban environments (e.g. Papadopoulos *et al* 2009, Batayneh 2011, Drahor 2011). These methods provide solutions to specific problems that arise with the advance of infrastructure modernization and urbanization and, due to its non-invasive character, are especially adequate for safeguarding cultural heritage.

Urban archaeogeophysics has its specific difficulties (Papadopoulos et al 2009, Batayneh 2011, Drahor 2011). The environmental noise in cities (electric, electromagnetic, vibrations, etc.) affects geophysical measurements. Besides, the access to the survey areas is often physically and/or timely limited by other uses, which generally restricts the amount of data that can be acquired. Regarding the archaeological structures, they are usually embedded in upper layers with intricate heterogeneities caused by later urban development. All these factors usually affect the quality of the data and the resolution of the obtained images, reducing the capability of identifying and characterizing these targets. Hence, at the beginning of each study, the available complimentary information (historical, geological, etc.) should be taken into account; then, different methods and/or methodologies should be explored to determine the most suitable based on the particular objectives and site conditions.

The geophysical methods most frequently applied for urban archaeological studies are ground penetrating radar (GPR) (e.g. Leucci and Negri 2006, Bonomo et al 2012), magnetic (e.g. Eppelbaum 2011), and electrical resistivity tomography (ERT) with measurements performed on surface and/or in boreholes (e.g. Tsokas et al 2011). These studies comprise, for instance, the detection of walls and cavities and the imaging of foundations. In some of them different techniques are combined, which usually provides greater reliability in the analysis of these complex environments (e.g. Negri and Leucci (2006), combined 2D ERT to study walls and cavities buried under and ancient temple and 3D GPR imaging to detect modern man-made structures, Drahor et al (2011), used magnetic gradiometry, GPR and ERT to define subsurface characteristics and search for possible structural damage in the subfloor of a church). Other geophysical techniques such



**Figure 2.** Photo of the cobbled square, initially being an orchard of the Mission, and from the last decade of the 19th century until 1973, the site of the Faculty of Sciences of the University of Buenos Aires (imprints can be seen on the front wall). A deployment of electrodes is also shown.

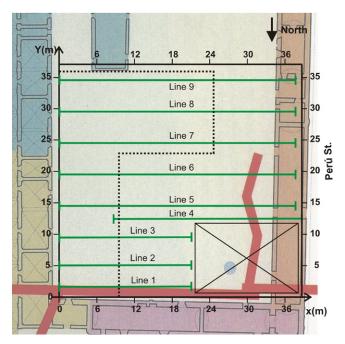
as seismic and microgravity are less used due to the difficulty to acquire this type of data in urban environments (Batayneh 2011, Drahor 2011).

Detecting tunnels is generally difficult, even more when they are placed in urban sites. GPR, gravity, ERT, electromagnetic induction (EMI) and seismic methods have been used for this task, alone or sometimes in combination, with varied effectiveness, depending on the characteristics of the soil and the contrast with the materials forming the tunnel, its depth and state of conservation, and the environmental conditions at the surface (e.g. Beetham and Hutchison 2009, De Franceschini and Marras 2010, Martinez-Lorenzo *et al* 2011, Orfanos and Apostolopoulos 2011, Tawfik *et al* 2011, Banks 2012).

Within this context, our main goals were to establish the actual trace and length of the N–S tunnel shown in figure 1(a) and to detect evidence of possible non-reported tunnels. An additional objective was to localize remains of the basement of the old building of the Faculty of Sciences (figure 1(a)). In the following, we describe the design of the geophysical survey, the data acquisition and processing procedures, and the obtained results. The anomalies detected in the ERT maps were interpreted in terms of possible buried archaeological features.

# Methodology for data acquisition and inversion

The characteristics of the study area were challenging. Previous data from boreholes and archaeological test pits showed the presence of a complex urban stratigraphy with relocated architectural remains, in a rich organic soil with large percentages of silt and clay (Weissel 2010). Due to its appreciable content of clay, the soil was expected to have high electrical conductivity. Within this conductive host medium,



**Figure 3.** Location of the dipole–dipole profiles deployed in the cobbled square (studied area in figure 1(a). The crossed rectangle indicates a provisional construction. Like in figure 1(a), the red lines indicate the location of the tunnels reported in historical records and the dotted lines the limits of the old basement.

we looked for remains of the basement from the previous building (mainly composed of concrete and other resistive construction materials) and for tunnels, also resistive structures if they were not collapsed. The basement of the old building was expected to be located approximately 2–4 m deep; the exposed tunnel showed an approximate width of 1 m and was located about 3–4 m deep. In addition, we had to deal

**Table 1.** Mean values of the percentage coefficients of variation of the measured apparent resistivities, for all the lines, electrode spacings and dipole separation factors.

a	п	<i>z</i> *	Line 1	Line 2	Line 3	Line 4	Line 5	Line 6	Line 7	Line 8	Line 9	Mean
1.5	1	- 0.624	0.235	0.193	0.143	0.197	0.109	0.152	0.120	0.184	0.194	0.170
1.5	2	- 1.046	0.915	0.544	0.425	0.257	0.376	0.221	0.242	0.348	0.336	0.407
1.5	3	- 1.443	1.130	0.398	0.516	0.337	0.365	0.689	0.322	0.301	0.790	0.539
1.5	4	- 1.830	1.040	0.420	0.395	0.657	0.800	1.280	0.707	0.652	0.891	0.760
1.5	5	- 2.214	2.650	0.851	0.728	1.580	2.490	3.820	0.784	1.160	2.440	1.830
1.5	6	- 2.595	5.200	1.940	2.790	3.250	4.490	5.770	1.600	2.500	5.800	3.700
1.5	7	- 2.975	5.480	3.230	2.640	3.450	5.600	6.850	2.070	2.320	6.870	4.280
1.5	8	- 3.354	6.940	4.910	5.380	8.050	9.640	7.550	3.900	7.200	8.570	6.900
1.5	9	- 3.734				5.760	8.520	4.840	4.670	7.970	7.830	6.600
1.5	10	-4.110				4.280	7.070	6.390	8.090	7.790	12.20	7.640
3	1	- 1.248	0.339	0.252	0.371	0.195	0.258	0.322	0.255	0.329	0.193	0.279
3	2	- 2.091	0.352	0.462	0.547	0.362	0.629	0.392	0.287	0.392	0.279	0.411
3	3	- 2.886	1.580	3.020	4.140	1.320	2.400	2.530	0.843	0.917	1.790	2.060
3	4	- 3.660	5.480	5.900	7.830	3.300	3.140	6.170	1.590	1.480	2.630	4.170
3	5	- 4.428	4.580	3.190	9.600	6.940	4.730	8.600	5.560	2.310	9.700	6.130
3	6	- 5.190				6.980	5.690	9.560	10.50	4.370	11.10	8.030
3	7	- 5.949				10.50	10.60	9.740	14.00	9.010	13.60	11.20
Mean			2.760	1.950	2.730	3.380	3.940	4.400	3.270	2.900	5.010	3.450

Note: z\* denotes the median depth of investigation (following Edwards 1977).

with high environmental electromagnetic noise, and with the characteristics of the rough surface, covered by cobblestones (figure 2).

Considering this, we performed a pre-feasibility study to determine the usefulness of different geophysical methods. We made tests using three different methods: ERT, GPR and EMI.

For the electromagnetic induction measurements we used a small-loop, multifrequency EMI system GEM-2 (Geophex). This equipment works in a frequency range between 300 and 96000 Hz, and has an intercoil separation of 1.66 m; so it could provide the required penetration depth. Nevertheless, no useful information was obtained from these data because they were highly contaminated by environmental electromagnetic noise.

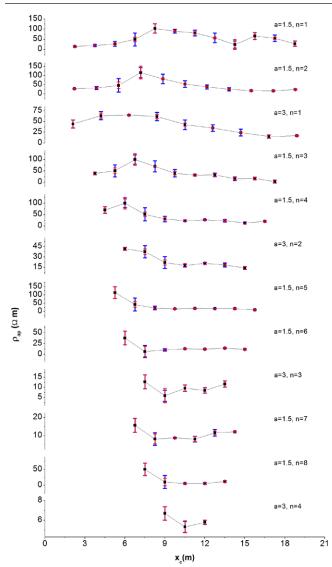
Then, we used a PulseEkko Pro GPR system (Sensors and Software Inc.), with shielded antennas of 250 and 500 MHz. Usually, GPR has good potential for providing high resolution images; however, the usefulness of GPR over most of the urban area of Buenos Aires has been very limited due to the high clay content in soil composition, and its large humidity. For this particular case, the obtained data showed strong attenuation. The soil strongly absorbed the signals in the used frequency range, and this reduced the penetration depth for both antennas, 500 MHz and 250 MHz, to about 0.60 m and 1.2 m, respectively. The use of 100 MHz antennas, as they were unshielded, produced noisy data without the required resolution.

Regarding the geoelectrical measurements, we had to determine the best way to make the electrode contact with the surface. There were different possibilities; the use of flat base electrodes that do not need to be nailed down (Tsokas *et al* 2008), the use of capacitive contacts (Dabas *et al* 2000, Bongiovanni and de la Vega 2006, Osella *et al* 2012) or the use of usual galvanic contact electrodes placed in holes making contact with the soil underneath the surface obstacle, or even

used for borehole measurements (e.g. Tsokas *et al* 2011). The first two were discarded due to the irregular shape of the cobblestone surface where the study was performed. The last possibility had to be disregarded due to its invasive nature and the historical status of the site. Therefore, the third technique was used taking advantage of the space between the cobblestones (about 1.5 cm) to place the electrodes.

For these measurements, data were acquired using Saris 500 equipment (Scintrex). The electrodes were placed inbetween the cobbles (see figure 2). We performed different tests and found that, in general, good electrode contact and a stable injection of current could be achieved by burying the electrodes at least 15 cm deep, to overcome the cobblestone cover. Due to the high conductivity of the material beneath the cobblestones in some zones of the studied area, we had to limit the current injection between a minimum of 10 mA and a maximum of 50 mA to prevent equipment malfunction. Hence, a high stacking (about 15) was used in order to reduce data noise.

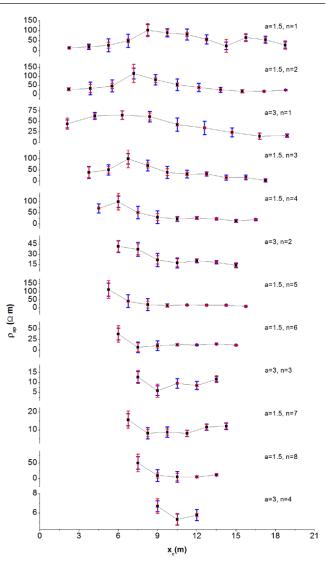
Several studies comparing the advantages and limitations of different electrode arrays (e.g. Dahlin and Zhou 2004, Martorana et al 2009, Szalai et al 2011) revealed that, in noisy environments, the dipole-dipole configuration can provide comparatively good penetration depth and one of the best imaging resolutions. In addition, our previous experience also indicated the usefulness of this configuration for archaeological prospecting (Martino et al 2005, Osella et al 2005, Bonomo *et al* 2012). On this basis, we decided to utilize the dipole-dipole configuration for this study. We deployed nine E-W profiles (figure 3), approximately perpendicular to the known N-S tunnel. Taking into account the expected characteristics of the targets, electrode spacings a = 1.5 and 3 m were selected, with dipole separation factors (n) up to n = 8 and 5, for Lines 1–3, and n = 10 and 7, for Lines 4–9, respectively. The separation between the profiles was approximately 5 m.



**Figure 4.** Apparent resistivity data ( $\rho_{ap}$ ) acquired along line 3, with electrode spacings a = 1.5 m and 3 m, and dipole separation factors up to n = 8 and 4, respectively.  $X_c$  denotes the *x* position of the center of the electrodes in each measurement. The error estimations  $\varepsilon_{\text{SD3}}$  and  $\varepsilon_{\text{DM3}}$ , obtained from equations (1) and (3), are indicated by blue and red error bars, respectively.

Their position was optimized considering parking lot operation. The time was very restrictive, since the area for each profile could be freed from cars only for short periods of time.

From the repeated measurements performed at each point, the standard deviation of each apparent resistivity data and its percentage coefficient of variation, were obtained. This provided an estimation of the random errors of this magnitude. Table 1 shows the mean values of these coefficients of variation, for all the lines, electrode spacings and n values. As can be observed, the values are acceptable considering the characteristics of the site. However, this did not guarantee data quality. As it is well known (e.g. Zhou and Dahlin 2003, Loke *et al* 2013), outlier data points (those arising from non-random sources of error such as bad electrode contact, electrode polarization, or equipment malfunction) can have low coefficients of variation.



**Figure 5.** The same as in figure 4, but considering the error estimations  $\varepsilon_{\text{SD5}}$  (blue error bars) and  $\varepsilon_{\text{DM5}}$  (red error bars) that were calculated using equations (2) and (4), respectively.

One manner to obtain more accurate error estimations, which include the described non-random effects, is to perform reciprocal measurements (Parasnis 1988, Park and Van 1991). We could not apply this method, because that would have required almost a duplication of the time required for data acquisition. Instead, four different error estimations,  $\varepsilon_{\text{SD3}}$ ,  $\varepsilon_{\text{SD5}}$ ,  $\varepsilon_{\text{DM3}}$  and  $\varepsilon_{\text{DM5}}$ , were calculated using the alternative methodology described next.

If  $\rho_{apijkl}$  is the apparent resistivity measured at the position of the center of the electrodes  $x_{ci}$ , along line *j*, with the electrode spacing  $a_k$  and the dipole separation factor  $n_l$ , then:

$$\varepsilon_{\text{SD3}}(\rho_{apijkl}) = \text{SD}(\rho_{ap(i-1)jkl}, \rho_{apijkl}, \rho_{ap(i+1)jkl})$$
(1)

(2)

 $\varepsilon_{ ext{SD5}}(
ho_{apijkl})$ 

$$= \text{SD}(\rho_{ap(i-2)jkl}, \rho_{ap(i-1)jkl}, \rho_{apijkl}, \rho_{ap(i+1)jkl}, \rho_{ap(i+2)jkl})$$

$$\varepsilon_{\text{DM3}}(\rho_{apijkl}) = \left| \rho_{apijkl} - \text{AVG}(\rho_{ap(i-1)jkl}, \rho_{apijkl}, \rho_{ap(i+1)jkl}) \right| (3)$$

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**Table 2.** Values of the main inversion parameters that provided thebest 2D ERTs.

Initial damping factor	0.3			
Minimum damping factor	0.03			
RMS convergence limit	2%			
Vertical to horizontal flatness filter ratio	1			
Number of nodes between adjacent electrodes	4			
Type of Jacobian matrix calculation	Gauss-Newton			
Data constrain	Robust			
Cutoff factor for robust data constrain	0.05			
Model constrain	Robust			
Cutoff factor for robust model constrain	0.005			
Extended model	No			
Reduce the effectof side blocks	Severe			
Forward modeling method	Finite Elements			
Type of mesh	Finest			
Width of blocks	Normal			
Blocks have the same width	Yes			
Logarithm of apparent resistivity	Yes			
Type of reference resistivity	Average			
Model refinement	Half-width cells			
Type of optimization method	Gauss-Newton			
Data errors present	No			

 $\varepsilon_{\text{DM5}}(\rho_{apijkl})$ 

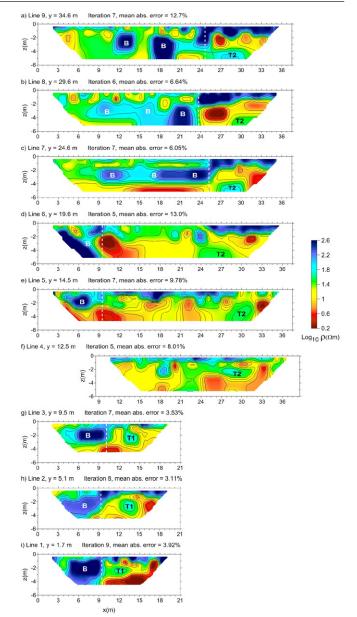
$$= \left| \rho_{apijkl} - \text{AVG}(\rho_{ap(i-2)jkl}, \rho_{ap(i-1)jkl}, \rho_{apijkl}, \rho_{ap(i+1)jkl}, \rho_{ap(i+2)jkl}) \right|$$
(4)

where SD and AVG refer to the standard deviation and the average of the indicated apparent resistivity data, respectively.  $\varepsilon_{\text{SD3}}$  and  $\varepsilon_{\text{SD5}}$  denote the error estimations of the datum  $\rho_{apijkl}$  obtained by calculating the standard deviation of the apparent resistivity considering 3 and 5 neighboring measurement points, respectively, while  $\varepsilon_{\text{DM3}}$  and  $\varepsilon_{\text{DM5}}$  name the error estimations of the datum  $\rho_{apijkl}$  obtained by calculating the absolute deviation of this datum from the mean apparent resistivity of 3 or 5 neighboring points, respectively.

These error estimations comprise measurements corresponding to different electrode positions, which could have, for instance, different contact resistances or electrode polarization values. Thus, when the resistivity of the subsurface material is nearly uniform, they may provide a good estimation of both the random and non-random errors. In other cases, because the effect caused by the variations in the subsurface resistivity (especially the lateral variations) is also included, values can be considered upper limits of the error estimations.

As an example, figure 4 shows the apparent resistivity data corresponding to line 3, with the error estimations  $\varepsilon_{\text{SD3}}$  and  $\varepsilon_{\text{DM3}}$  indicated. The same data, with the error estimations  $\varepsilon_{\text{SD5}}$  and  $\varepsilon_{\text{DM5}}$ , are shown in figure 5. On the whole, these errors were greater than the standard deviation of these data. According to their definition, for each electrode spacing  $a_k$  and dipole separation factor  $n_l$ ,  $\varepsilon_{\text{SD3}}$  and  $\varepsilon_{\text{DM3}}$ , or  $\varepsilon_{\text{SD5}}$  and  $\varepsilon_{\text{DM5}}$ , were similar when the apparent resistivity at point  $x_{ci}$  was a local maximum or minimum; otherwise,  $\varepsilon_{\text{SD3}}$  and  $\varepsilon_{\text{SD5}}$  were greater than  $\varepsilon_{\text{DM3}}$  and  $\varepsilon_{\text{SD5}}$ , respectively.

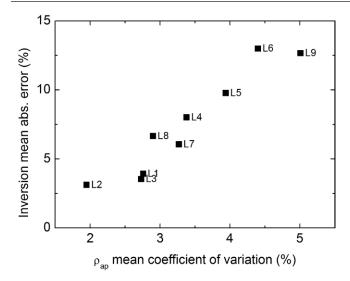
For the inversions, we used the codeRES2DINV, version 3.59.119 (Loke and Barker 1996). For each profile, the data



**Figure 6.** (a) to (i) Electrical resistivity tomographies obtained from the 2D inversion of the dipole–dipole profiles acquired along lines 1 to 9, respectively, as shown in figure 3. These inversions were performed with the code RES2DINV (Loke and Barker 1996), using robust data and model constrains, and without providing any error estimations (see table 2). The anomaly named B indicates zones with resistive materials that could correspond to remains of the basement of the old building. The limits of these zones are indicated by dashed white lines. The anomalies T1 and T2 probably correspond to stretches of tunnels.

acquired with both electrode spacings (a = 1.5 and 3 m) were inverted together to improve both the resolution and penetration depth of the models.

In addition to the usual least-squares (L2 norm) inversion, this program offers a robust inversion option in which the absolute values (L1 norm) of the data misfit are minimized (Loke *et al* 2003). We selected this robust data constrain option for all the inversions, because it allows reducing the effect of data outliers in the resulting models.



**Figure 7.** Mean absolute errors of the inversions shown in figure 6, plotted against the mean value of the coefficients of variation of the apparent resistivity along the corresponding line (which are listed in the last row of table 1). L1–L9 denote the lines 1–9, respectively.

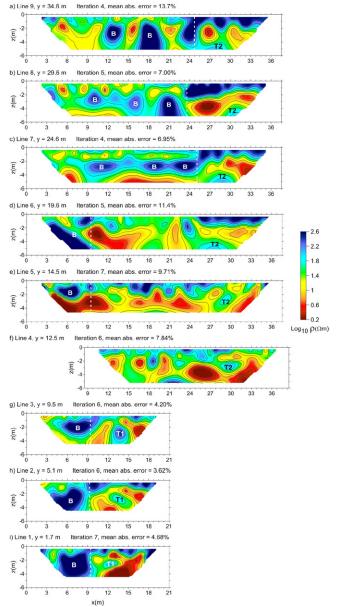
Regarding model constrains, the square (L2 norm) and the absolute (L1 norm) changes in the model resistivity values were alternatively minimized. As it is well known, the first procedure generates models with smooth resistivity variations. On the other hand, the robust model constrain tends to produce 'blocky' models, with sharp interfaces between regions with approximately constant resistivity. The best results were obtained with this last procedure, which is comprehensible, considering that the described blocky models were more consistent with the subsurface structure expected in the site. Table 2 lists the values of the main parameters used to obtain the final ERTs.

These inversions were first performed without providing to the program any information about data errors. This is a common approach, since in many cases accurate error estimations are not available. Then, in order to investigate the reliability of the anomalies detected in the final models, the inversions were repeated using the same parameters as in table 2, but considering the error estimations  $\varepsilon_{SD3}$ ,  $\varepsilon_{SD5}$ ,  $\varepsilon_{DM3}$ and  $\varepsilon_{DM5}$ , defined by equations (1)–(4).

The separation of the profiles (about 5 m) prevented the performance of a 3D inversion. As an alternative, we generated a pseudo-3D model of the subsurface by combining the 2D inversion results. Model resistivities obtained for all the lines at each zvalue were interpolated in the *x*-*y* plane, using a kriging method with a linear variogram. Then, those constant-depth slices were plotted, to better visualize the alignment of the anomalies.

# Results

The ERTs obtained from the 2D inversion of the nine dipole– dipole profiles are shown in figure 6. These inversions were performed applying robust data and model constrains, and without providing any estimation of data errors (see table 2). The achieved mean absolute errors are reasonable, taking into account the difficulties encountered for data acquisition and



**Figure 8.** (a) to (i) Electrical resistivity tomographies corresponding to lines 1 to 9, respectively, obtained using robust data constrains, but smooth model constrains. The rest of the inversion parameters had the same values as in the inversions shown in figure 6 (listed in table 2). Again, no error estimations were provided. The anomalies B, T1 and T2 are also clearly observable in these models. Their resistivities are somewhat different than in the former case, but their localization is similar.

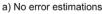
the complexity of the subsurface structure. Another indicator that the data were neither over nor under fitted is that, although no error estimations were provided for the inversions, the attained mean absolute errors exhibit a clear correlation with the mean value of the percentage coefficients of the variation of the apparent resistivity along each line (figure 7).

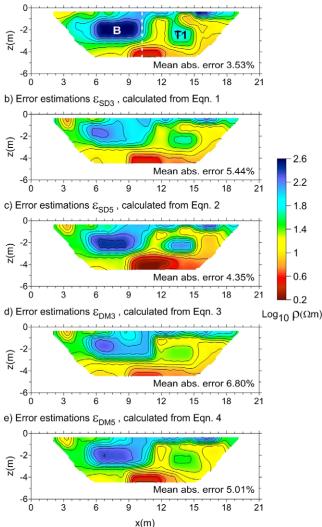
Different structures can be identified in the models shown in figure 6. The conductive matrix has resistivity values close to 10 ohm m. Zones containing highly resistive materials (resistivity about 100–300 ohm m) are found in most of the profiles (anomaly named B). These zones were associated to the remains of the basement of the old building of the Faculty of Sciences; the limits of these zones are indicated by dashed white lines in figure 6. In addition, there are other types of anomalies, named T1 and T2, which appear as localized structures more resistive than their surroundings. The centers of the anomaly T1, appearing in lines 1-3, are located at x between 12-14 m and z = 2.5-3 m, approximately. The anomaly T2 is centered at x = 27-30 m; its depth is similar to that of T1 in line 4, and increases towards the south. In lines 6-9, the top of this anomaly is located about 4m deep. Considering its characteristics and localization, T2 possibly corresponds to the N-S tunnel reported in the historical records, and shown in figures 1(a) and 3. In this case, this tunnel would continue towards the south throughout all the studied area. T1 could correspond to a stretch of a non-declared tunnel, which should be connected with the main E-W tunnel.

The ERTs obtained using smooth instead of robust model constrains are shown in figure 8, for comparison with the results displayed in figure 6. Once more, no error estimations were provided; the rest of the inversion parameters had the same values as in the previous inversions. The most relevant result is that the anomalies B, T1 and T2 are also clearly observable in these models. Their resistivity values are somewhat different, but their localization is almost the same. The attained mean absolute errors are also similar to the former case.

The ERTs shown in figures 6 and 8 were obtained without including the errors. To analyze the effects of the errors on the final models, we repeated the inversions including the error estimations calculated according equations (1)-(4), respectively. Figure 9 shows the models obtained for line 3 using these error estimations; the rest of the inversion parameters are those listed in table 2. Figure 6(g) is included at the top, for an easier comparison. Figures 10 and 11 show the analogous results, for lines 5 and 7, respectively. As the variations in the subsurface resistivity were appreciable along the three lines (figures 9(a), 10(a) and 11(a), or 6(g), (e) and (c), respectively), according to what was explained in the last section, the error estimations used,  $\varepsilon_{SD3}$ ,  $\varepsilon_{SD5}$ ,  $\varepsilon_{DM3}$  and  $\varepsilon_{DM5}$ , were probably significantly greater than actual data errors. Even so, the anomaly B is still clearly detectable in all the models obtained for the three lines, and T1 is detectable in all the models corresponding to line 3. With regards to T2, the loss of detectability is greater in line 7 than in line 5. Two probable reasons for this are that, on one side, T2 is deeper in line 7, and that, on the other side, the variability of the subsurface resistivity in the zone near T2 is greater in line 7 (figures 6(c) and (e), or 10(a)and 11(a), respectively), thus, the overestimation of the errors possibly was greater.

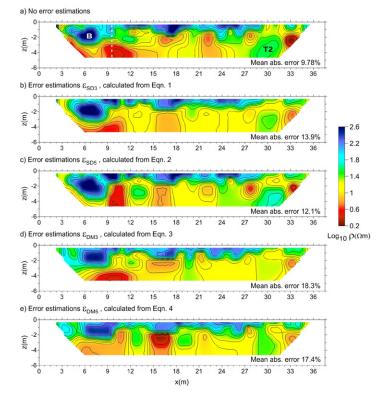
Having tested the reliability of the resulting models, we then analyzed the correlation of the anomalies along the different profiles. As explained in the last section, by combining the results of the 2D inversions shown in figure 6, we generated a pseudo-3D model of the subsurface. This procedure had provided very useful results in a previous work, where it contributed to the detection of linear anomalies associated to the remains of a Spanish fort from the 16th century (Bonomo *et al* 2012).



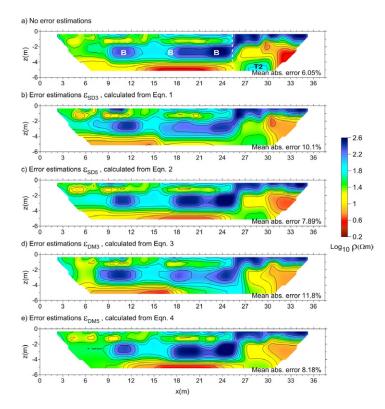


**Figure 9.** Models obtained for the Line 3, after 7 iterations, using the same inversion parameters as for the inversion shown in figure 6. The upper model (a) is the same as the one shown in figure 6(g). The rest of the models (b to e) were obtained considering different error estimations. All of them have lower resolutions than (a), but the anomalies B and T1 are still detectable in all the cases.

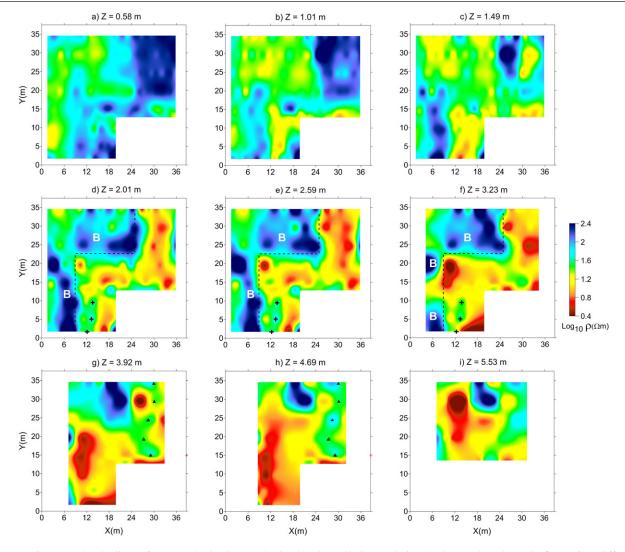
Constant-depth slices of this pseudo-3D model are shown in figure 12. The localization of the anomalies T1 and T2, according to the ERTs shown in figure 6, and the limits of the old basement according to the plan of 1895 (figures 1(a) and 3), are superimposed for comparison. The zone occupied by remains of the basement, associated with resistive anomaly B, appears clearly delineated, at depths ranging from about 2-3.5 m. The depth, approximate localization and general alignment of the resistive anomaly T2 are close to the ones expected for the N–S tunnel (figures 1(a) and 3), which, according to these results, would extend southwards beyond what was previously reported. Regarding the anomaly T1, observed at depths between 2-3.5 m, comparing its features with T2, we earlier proposed the existence of another tunnel, not previously known. The NNE-SSW orientation of this tunnel can be clearly appreciated in this figure. This structure is not detected for y > 10 m.



**Figure 10.** The same as in figure 9 for the line 5. In this case, the upper model (a) is the same as the one shown in figure 6(e). The anomaly T2 is detectable in all the models (b to e, respectively) the lowest resolution corresponds to the error estimations  $\varepsilon_{\text{DM3}}$  (d).



**Figure 11.** The same as in figures 9 and 10, for the line 7. In this case, the upper model (a) is the same as the one shown in figure 6(c). The anomaly B is still relatively well defined in all the models (b to e, respectively). Regarding T2, the loss of resolution is greater than in the previous case (see the text for a discussion of this result).

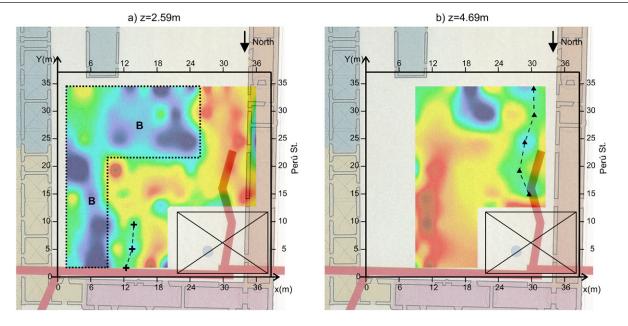


**Figure 12.** Constant-depth slices of the pseudo-3D image obtained by laterally interpolating the 2D models shown in figure 6, at different depths (a to i, respectively). The localization of the anomalies T1 and T2 in those ERTs is superimposed for comparison, as crosses (in d to f) and triangles (in g to h), respectively. The limits of the old basement (anomaly B) are indicated by a dashed line (d to f). The anomaly T2, associated to the N–S tunnel reported in historical records (figures 1(a) and 3), extends from North to South along the whole studied area; first it has a NNW–SSE direction, and for y < 20 m, a NNE–SSW orientation. The anomaly T1, associated to a tunnel non-previously reported, has a NNE–SSW direction.

In figures 12(d) and (e), a resistive zone can be observed between x = 17 m and x = 31 m, for y = 13-14 m, approximately. This zone is associated to the resistive anomaly appearing along the same x values, for 1 m < z < 3 m, approximately, in the ERT corresponding to line 4, shown in figure 6(f). Due to the presence of the temporary construction previously mentioned, we could not perform transversal profiles (in the y direction) to further investigate the characteristics of this anomaly; in particular, if it could eventually correspond to a continuity of T1 to the west, up to the location of T2.

To further clarify the final interpretation, in figures 13(a) and (b) we show the main electrical resistivity anomalies, superposed to the supposed localizations of the old basement and the known N–S tunnel, according to the historical information. The agreement between the results is rather good. In particular, performing the description from north to south: the localization and direction (NNW–SSE) of the northernmost part of the anomaly T2 are almost coincident with the

ones reported of the N-S tunnel (figure 13(b)), and after that, there is also a change in direction of T2 from NNW-SSE to NNE–SSW, though this change occurs at a value of y, 2 or 3 meters greater than expected. It has to be taken into account that the available maps are not very precise, since they were drawn from approximated data, obtained at different periods of construction; hence, differences may appear in the positioning and trace of this tunnel. The probable continuity of this tunnel towards the south beyond what was reported in the historical maps is a relevant finding of this study. Regarding the anomaly T1, which has a NNE-SSW alignment (figure 13(a)), its shape in the ERTs shown in figure 6 resembled the shapes of the anomaly T2 that was associated to the N-S tunnel. On this basis, we concluded that T1 could indicate a stretch of a tunnel not previously reported, which should be connected with the E-W tunnel. As previously explained, its continuity to the west up to the location of T2 remains an open question.



**Figure 13.** Summary of the main anomalies found at the studied area, together with the supposed location of the known N–S tunnel (red lines in (a) and (b)) and the remains of the old basement (dotted line in (a)), according to the historical information, for comparison. In figure 9, the anomaly that could correspond to a tunnel non-previously reported is indicated by crosses connected by a dashed line, while in (b), the obtained trace of the anomaly corresponding to the known tunnel is marked by triangles connected by a dashed line.

# Conclusions

This work is an example of the application of geophysical methods at urban historical sites. The main goal was to detect tunnels built during the presence of Jesuits in the city of Buenos Aires, Argentina, between the 17th and18th centuries. An additional goal was to localize the remains of the basement of the former building of the Faculty of Sciences of the University of Buenos Aires, built in the 19th century. In particular, the detection of the tunnels was the most challenging. They were expected to have a width of about 1 m, a height of 1.5–2 m, and could be located at depths ranging from 2 m to more than 4 m.

The main results can be summarized as follow:

Good lateral and vertical resolutions, as well as the required penetration depth were obtained carrying out dipole–dipole profiles, combining two different electrode spacings (1.5 and 3 m, respectively). The high stacking used for the measurements reduced the random data errors arising from the environmental electric and electromagnetic noise, to a minimum. In addition, inverting the data acquired along each profile using a robust procedure reduced the effect of outlier data points (where the error comes from non-random sources) in the resulting models. In this manner, different anomalies were detected that could correspond to the described targets.

Those inversions were performed without providing any information to the program about data errors, which is the usual approach since often appropriate error estimations are not available. Occasionally, reciprocal measurements are done to estimate the errors, but this methodology is difficult to apply in urban environments, mainly due to time limitations in the accessibility to the study sites.

As a means of determining the reliability of the anomalies that were associated to the targets, we investigated the effect of data errors on the inversion results. For this purpose, we implemented a fast numerical procedure that allows us to obtain error estimations from the lateral variability of data. Using this procedure, we obtained different error estimations; and then, we analyzed the changes produced in the models when these errors were considered for the inversions. Thereby, we could disregard (or at least strongly diminish) the possibility that these anomalies were mere inversion artifacts.

Finally, the generation of a pseudo-3D model by transversally interpolating the 2D inversion results was very useful for the final interpretation. Since the separation of the profiles prevented the performance of a 3D inversion, plotting constant-depth slices of the interpolated 3D model allowing a much more clear alignment of the anomalies.

In summary, notwithstanding the difficult conditions, the applied methodologies allowed for the delimitation of remains of the old basement, delineatation of the trace of a tunnel reported in historical records and the establishment of its continuation beyond what was previously known, and the detectiion of another anomaly possibly associated to the presence of a tunnel not previously reported.

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