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Short Geodesics of Unitaries in the L^2 Metric

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Abstract. Let \mathcal{M} be a type II_1 von Neumann algebra, τ a trace in \mathcal{M} , and $L^2(\mathcal{M}, \tau)$ the GNS Hilbert space of τ . We regard the unitary group $U_{\mathcal{M}}$ as a subset of $L^2(\mathcal{M}, \tau)$ and characterize the shortest smooth curves joining two fixed unitaries in the L^2 metric. As a consequence of this we obtain that $U_{\mathcal{M}}$, though a complete (metric) topological group, is not an embedded riemannian submanifold of $L^2(\mathcal{M}, \tau)$

1 Introduction

Let \mathcal{M} be a type II_1 von Neumann algebra with a faithful and normal tracial state τ . Let $L^2(\mathcal{M}, \tau)$ be the Hilbert space obtained by completion of \mathcal{M} with the norm $\|x\|_2 = \tau(x^*x)^{1/2}$. Denote by $U_{\mathcal{M}}$ the group of unitaries of \mathcal{M} . Then $U_{\mathcal{M}}$, as a subset of $L^2(\mathcal{M}, \tau)$, is a complete metric space and a topological group. The Hilbert space norm induces on $U_{\mathcal{M}}$ the strong operator topology. These are well-known facts (see [10]). In a previous note [1], we showed that $U_{\mathcal{M}}$ cannot be embedded as a differentiable submanifold in a way which makes the product of unitaries a differentiable map. Here we show that the same question, dropping the requirement for the product, again has a negative answer: $U_{\mathcal{M}} \subset L^2(\mathcal{M}, \tau)$ is not an embedded riemannian submanifold.

Hence, it makes sense to study the following: are there curves of unitaries of \mathcal{M} which have minimal length measured in the L^2 metric? We measure the length of a curve of unitaries in the following way: let $\mu(t)$ be a curve in $U_{\mathcal{M}}$, with $\mu(0) = v$ and $\mu(1) = u$, which is piecewise C^1 as a curve in $L^2(\mathcal{M}, \tau)$, then the length of μ is

$$\ell(\mu) = \int_0^1 \|\dot{\mu}(t)\|_2 dt,$$

where, as is the usual notation, $\|x\|_2 = \tau(x^*x)^{1/2}$. The usual norm of \mathcal{M} is denoted by $\|\cdot\|$.

Suppose that we fix u and v . Is there a shortest curve joining u and v inside $U_{\mathcal{M}}$? We obtain the following answer (Theorem 3.4):

There exists $x = x^ \in \mathcal{M}$ with $\|x\| \leq \pi$ such that $v^*u = e^{ix}$. The curve*

$$\delta(t) = ve^{itx}$$

has minimal length among piecewise C^1 curves of unitaries joining u and v .

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1. If $\|x\| < \pi$, then such x is uniquely determined and the curve δ is unique among piecewise C^∞ minimizing curves.
2. Otherwise ($\|x\| = \pi$), δ is non unique. Other minimizing piecewise C^2 curves are of the form $\gamma(t) = ve^{it\xi}$, with $\xi = J\xi \in L^4(\mathcal{M}, \tau)$.

In both cases, the shortest (piecewise C^1) curve has length $\|x\|_2$.

The first condition defines a set of unitaries, namely:

$$\{u \in U_{\mathcal{M}} : v^*u = e^{ix} \text{ for } x^* = x \text{ with } \|x\| < \pi\},$$

which is an open neighbourhood of v in the norm topology, but not in the *strong operator* topology. In [7] Popa and Takesaki found what E. Michael [6] calls a geodesic structure for the unitary group of certain type II_1 factors. Such a structure has strong topological implications, leading for example to a complete elucidation of the homotopy type of the unitary group for such factors, in the strong operator topology. We wanted to know if the naive “geodesic” curves, of the form $\delta(t) = ve^{itx}$, could be used to obtain a geodesic structure for all type II_1 von Neumann algebras in the strong operator topology, as is the case in the norm topology for arbitrary C^* -algebras [2]. The result above proves that one cannot.

We call these curves δ geodesics, because they are the geodesics of a covariant derivative defined in $U_{\mathcal{M}}$ in a natural way. If $U_{\mathcal{M}}$ were an embedded submanifold of $L^2(\mathcal{M}, \tau)$, this covariant derivative would be the Levi–Civita derivative. Therefore the result above also shows that $U_{\mathcal{M}}$ is not a submanifold of $L^2(\mathcal{M}, \tau)$.

This study was inspired by the paper by Durán, Mata-Lorenzo and Recht [4] which studied minimal curves of projections for the p -norms.

2 Geodesics in $U_{\mathcal{M}}$

Let us first define the tangent spaces of $U_{\mathcal{M}}$ in the L^2 topology. Let $J: L^2(\mathcal{M}, \tau) \rightarrow L^2(\mathcal{M}, \tau)$ be the involution, *i.e.*, the extension to $L^2(\mathcal{M}, \tau)$ of the usual involution $*$ of \mathcal{M} . Clearly $J^2 = I$. Let $L^2(\mathcal{M}, \tau)_+ = \{\xi \in L^2(\mathcal{M}, \tau) : J\xi = \xi\}$ and $L^2(\mathcal{M}, \tau)_- = \{\xi \in L^2(\mathcal{M}, \tau) : J\xi = -\xi\}$, which are *real* Hilbert spaces. $L^2(\mathcal{M}, \tau)_-$ is the completion in the L^2 norm of the set of antihermitian elements of \mathcal{M} ($x^* = -x$), which is the tangent space of $U_{\mathcal{M}}$ at the identity 1 in the norm topology. Let us postulate $T(U_{\mathcal{M}})_1 := L^2(\mathcal{M}, \tau)_-$. For $u \in U_{\mathcal{M}}$, the map $L_u: L^2(\mathcal{M}, \tau) \rightarrow L^2(\mathcal{M}, \tau)$, defined on $\mathcal{M} \subset L^2(\mathcal{M}, \tau)$ as $L_u(x) = ux$ (*i.e.*, the GNS representation of u as an operator in $L^2(\mathcal{M}, \tau)$) is a unitary operator. Then we choose $T(U_{\mathcal{M}})_u = L_u(L^2(\mathcal{M}, \tau)_-)$. Also, right multiplication $R_u(x) = xu$ extends to a unitary operator in $L^2(\mathcal{M}, \tau)$. For brevity, we shall write $u\xi$ and $u(L^2(\mathcal{M}, \tau)_-)$ (resp. ξu and $(L^2(\mathcal{M}, \tau)_-)u$) instead of $L_u\xi$ and $L_u(L^2(\mathcal{M}, \tau)_-)$ (resp. $R_u(\xi)$ and $R_u(L^2(\mathcal{M}, \tau)_-)$).

Let μ be a curve of unitaries which is C^1 as a curve in the Hilbert space $L^2(\mathcal{M}, \tau)$, and let X be a differentiable vector field in a neighbourhood of $\{\mu(t) : t \in [0, 1]\}$, which takes values in $TU_{\mathcal{M}}$ when restricted to $U_{\mathcal{M}}$, *i.e.*, $X_{\mu(t)} \in \mu(t)L^2(\mathcal{M}, \tau)_-$. For obvious reasons, such a field will be called a *tangent* vector field along μ . The covariant derivative of X along μ is given by:

$$\frac{DX}{dt} = \frac{1}{2}\{\dot{X} - \mu J(\dot{X})\mu\},$$

where \dot{X} denotes the usual derivative with respect to t in the Hilbert space $L^2(\mathcal{M}, \tau)$. This formula is obtained simply by projecting \dot{X} orthogonally (with respect to the inner product given by the real part of τ) onto $T(U_{\mathcal{M}})_\mu$. Note that if $\mu(t)$ is a C^2 curve in $U_{\mathcal{M}}$, then $\dot{\mu}$ is a tangent vector field along μ as usual. In particular, μ is a geodesic if

$$0 \equiv \frac{D\dot{\mu}}{dt}$$

or equivalently

$$(1) \quad \ddot{\mu} = \mu J(\dot{\mu})\mu.$$

It is straightforward to verify that if $x \in \mathcal{M}$ with $x^* = x$, and $v \in U_{\mathcal{M}}$, then $\mu(t) = ve^{itx}$ is a C^∞ curve with $\dot{\mu}(t) = ivxe^{itx}$.

There are other exponentials which give curves in $U_{\mathcal{M}}$. If $\xi \in L^2(\mathcal{M}, \tau)_+$, then ξ induces a possibly unbounded selfadjoint operator L_ξ on $L^2(\mathcal{M}, \tau)$, affiliated to \mathcal{M} (see [3, 9]). Namely, L_ξ is the closure of the linear map $L_\xi: \mathcal{M} \subset L^2(\mathcal{M}, \tau) \rightarrow L^2(\mathcal{M}, \tau)$ given by $L_\xi(m) = Jm^*J\xi$. Therefore $\mu(t) = e^{itL_\xi}$ is a continuous curve in the L^2 topology, which is differentiable in $L^2(\mathcal{M}, \tau)$. Indeed, the topological embedding $U_{\mathcal{M}} \subset L^2(\mathcal{M}, \tau)$ can be regarded as evaluation at the vector $1 \in L^2(\mathcal{M}, \tau)$. Strictly speaking, one should write $\mu(t) = e^{itL_\xi}1$. Since 1 lies in the domain of the operator L_ξ [9], by Stone's theorem $\mu(t)$ can be differentiated, and the derivative equals (see [8])

$$\dot{\mu}(t) = ie^{itL_\xi}\xi.$$

However, this curve $\dot{\mu}(t)$ cannot be differentiated again (in $L^2(\mathcal{M}, \tau)$) if ξ^2 does not belong to $L^2(\mathcal{M}, \tau)$. It could be differentiated in $L^1(\mathcal{M}, \tau)$. Clearly it is not in general a C^∞ curve of $L^2(\mathcal{M}, \tau)$.

Lemma 2.1 *Let $\xi \in L^2(\mathcal{M}, \tau)_+$, then the curve $\mu(t) = e^{itL_\xi}$ is C^∞ if and only if L_ξ is bounded, i.e., $\xi \in \mathcal{M}$.*

Proof The “if” part is clear. Suppose that μ has derivatives of any order. This implies that all the powers L_ξ^k , $k \geq 1$ lie in $L^2(\mathcal{M}, \tau)$. Denote by m the probability measure on \mathbb{R} given by the trace of the spectral measure of L_ξ . Then

$$\infty > \|L_\xi^k 1\|_2^2 = \int_{\mathbb{R}} \lambda^{2k} dm(\lambda), \quad \text{for all } k \geq 1.$$

The above statement means that the map $\mathbb{R} \rightarrow \mathbb{R}$, $\lambda \mapsto \lambda$ lies in $L^\infty(\mathbb{R}, m)$, i.e., m has support contained in a bounded interval $[-K, K]$. This implies that L_ξ is bounded by K , and therefore lies in \mathcal{M} . ■

Note that if ξ lies in $L^2(\mathcal{M}, \tau)$ but not in $L^4(\mathcal{M}, \tau)$, then $\mu(t) = ve^{itL_\xi}$ is C^1 but not C^2 , etc. Indeed, $\dot{\mu}(t) = iL_\xi e^{itL_\xi}$ is continuous in the L^2 norm: if $t \rightarrow t_0$, then

$$\|\dot{\mu}(t) - \dot{\mu}(t_0)\|_2 = \|e^{i(t-t_0)L_\xi}\xi - \xi\|_2 \rightarrow 0.$$

Let us call a C^2 curve a *geodesic* in $U_{\mathcal{M}}$ if it is a solution of the differential equation (1).

Proposition 2.2 *The C^∞ geodesics in $U_{\mathcal{M}}$ are of the form $\delta(t) = ve^{itx}$, for $x^* = x \in \mathcal{M}$.*

Proof First note that if $x^* = x$, then $\delta(t) = ve^{itx}$ satisfies (1). Let μ be a C^∞ curve in $L^2(\mathcal{M}, \tau)$ with values in $U_{\mathcal{M}}$, which is a solution of (1), parametrized in the interval $[0, 1]$, with $\mu(0) = v$. Let $i\xi = \dot{\mu}(0)$ and $\xi' = \ddot{\mu}(0)$, which lie in $L^2(\mathcal{M}, \tau)$ because μ is C^∞ .

If ν is a solution of (1), then $v^*\nu$ is another solution. Since $J(v^*\dot{\nu}) = J(\dot{\nu})v$,

$$v^*\nu J(v^*\dot{\nu})v^*\nu = v^*\nu J(\dot{\nu})\nu = v^*\dot{\nu} = v^*\nu.$$

Therefore we may suppose $v = 1$ without loss of generality.

Differentiating the identity $\mu(t)\mu^*(t) = 1$, one obtains (we omit the parameter t)

$$\dot{\mu}\mu^* + \mu J(\dot{\mu}) = 0$$

($\dot{\mu}$ may lie outside \mathcal{M} , so we find more appropriate to write $J(\dot{\mu})$ instead of $\dot{\mu}^*$). Differentiating again,

$$\ddot{\mu}\mu^* + 2\dot{\mu}J(\dot{\mu}) + \mu J(\ddot{\mu}) = 0.$$

At $t = 0$ one obtains the relations

$$i\xi + J(i\xi) = 0, \quad \text{i.e. } \xi \in L^2(\mathcal{M}, \tau)_+$$

and

$$2\xi' + 2i\xi J(i\xi) = 0, \quad \text{i.e. } \xi' = -\xi J(\xi) = -\xi^2.$$

Consider the curve $\gamma(t) = e^{itL\xi}$. Then $\dot{\gamma}(t) = ie^{itL\xi}\xi$ and $\ddot{\gamma}(t) = e^{itL\xi}\xi'$. Therefore γ is C^2 ($\xi' \in L^2(\mathcal{M}, \tau)$), and the relations above show that it is a solution of (1), satisfying

$$\dot{\gamma}(0) = i\xi = \dot{\mu}(0) \text{ and } \ddot{\gamma}(0) = \xi' = \ddot{\mu}(0).$$

We claim that these facts imply that $\mu = \gamma$. To prove this claim, one needs a result on uniqueness of solutions of second order differential equations on Banach spaces. Let us first obtain a new form for equation (1). Consider again the identity $\dot{\mu}\mu^* + 2\dot{\mu}J(\dot{\mu}) + \mu J(\ddot{\mu}) = 0$ and multiply it on the right by μ

$$\ddot{\mu} + 2\dot{\mu}J(\dot{\mu})\mu + \mu J(\ddot{\mu})\mu = 0.$$

Then the identity (1) $\dot{\mu} = \mu J(\dot{\mu})\mu$, replaced above gives

$$(2) \quad \ddot{\mu} = -\dot{\mu}J(\dot{\mu})\mu,$$

which we shall adopt. We need a Banach space on which this equation will be considered. Our $L^2(\mathcal{M}, \tau)$ is not appropriate, since the right-hand side of the equation does not make sense for arbitrary $\mu(t)$ with derivatives in $L^2(\mathcal{M}, \tau)$, because $\dot{\mu}J(\dot{\mu})\mu$ may lie outside $L^2(\mathcal{M}, \tau)$. We are not worried about existence—we already know

Short Geodesics of Unitaries in the L^2 Metric

5

the solutions—we need a uniqueness result. Let us consider $L^4(\mathcal{M}, \tau)$. The map $L^4(\mathcal{M}, \tau) \rightarrow L^2(\mathcal{M}, \tau)$, $\xi \mapsto \xi J(\xi)$ is differentiable. It follows that the function

$$F(x, \xi) = -\xi J(\xi)x$$

with variables $x \in \mathcal{M}$ and $\xi \in L^4(\mathcal{M}, \tau)$ and values in $L^2(\mathcal{M}, \tau)$, satisfies a Lipschitz condition. Therefore the differential equation (2), $\dot{\mu} = F(\mu, \dot{\mu})$ has unique local solutions for any given set of initial conditions. Note that any solution μ of (2) should satisfy $\dot{\mu} \in L^4(\mathcal{M}, \tau)$ anyway.

Therefore $\mu(t) = e^{itL\xi}$. The fact that μ is C^∞ implies, by the lemma above, that $\xi = x$ is a selfadjoint element of \mathcal{M} . ■

Remark 2.3 The same argument can be used to prove that the C^2 geodesics are of the form $\delta(t) = ve^{itL\xi}$, with $\xi \in L^4(\mathcal{M}, \tau)$.

Our next result is borrowed and adapted from [4]. There it is stated for variations of geodesics of the grassmannian manifold (*i.e.*, manifold of selfadjoint projections) of a C^* -algebra with trace. Also, there the p -length functionals are considered (induced by the p -norms $\|x\|_p = \tau((x^*x)^{p/2})^{1/p}$, for $p = 2n$. We are interested only in the case $p = 2$. Our exposition in the rest of this section follows [4] with slight modifications. We want to compute the extremals of the functional

$$\ell(\mu) = \int_0^1 \|\dot{\mu}(t)\|_2 dt.$$

Let $U(t, s): [0, 1] \times (-\epsilon, \epsilon) \rightarrow U_{\mathcal{M}}$ be a variation of a curve $\mu: [0, 1] \rightarrow U_{\mathcal{M}}$, with fixed endpoints, *i.e.*,

$$U(t, 0) = \mu(t) \quad \text{for all } t \in [0, 1],$$

and

$$U(0, s) = \mu(0), \quad U(1, s) = \mu(1) \quad \text{for all } s \in [0, 1].$$

The variation is through piecewise C^2 curves, *i.e.*, for each fixed s , the curve $U(t, s)$ is piecewise C^2 in the parameter t , and vice versa. Denote by $\delta\ell(s)$ the *variation*

$$\delta\ell(s) = \frac{\partial}{\partial s} \int_0^1 \left\| \frac{\partial U}{\partial t} \right\|_2 dt.$$

The extremals of ℓ are the curves μ such that $\delta\ell(0) = 0$ for any $U(t, s)$ as above. Denote $V = \frac{\partial U}{\partial t}$ and $W = \frac{\partial U}{\partial s}$. Let us compute

$$\delta\ell(s) = \frac{\partial}{\partial s} \int_0^1 \left\| \frac{\partial U}{\partial t} \right\|_2 dt = \int_0^1 \frac{\partial}{\partial s} \tau \left(J \left(\frac{\partial U}{\partial t} \right) \frac{\partial U}{\partial t} \right)^{1/2} dt.$$

An easy computation shows that if $\xi(s) \neq 0$ is differentiable in $L^2(\mathcal{M}, \tau)$, then

$$\frac{d}{ds} \tau \left(J(\xi(s))\xi(s) \right)^{1/2} = \frac{1}{2\|\xi(s)\|_2} \tau \left(J \left(\frac{dx(s)}{ds} \right) x(s) + J(x(s)) \frac{dx(s)}{ds} \right).$$

In our case this gives

$$\delta\ell(s) = \int_0^1 \frac{1}{2\|V\|_2} \tau\left(\left[\frac{\partial}{\partial s} J(V)\right] V + J(V) \frac{\partial}{\partial s} V\right) dt.$$

We shall assume that the curve μ is parametrized by a multiple of arc length. In other words, $\|V\|_2$ is constant for $s = 0$. One should make the further assumption that V does not vanish for all s, t , in order that the above expression makes sense. Let us point out that at the final stages of this computation we put $s = 0$. Therefore it suffices to have that $V(t, s)$ does not vanish for all t and small s (which is attained if we suppose μ with constant speed).

Since U is (piecewise) C^2 we may interchange

$$\frac{\partial}{\partial s} V = \frac{\partial}{\partial s} \left(\frac{\partial U}{\partial t} \right) = \frac{\partial}{\partial t} \left(\frac{\partial U}{\partial s} \right) = \frac{\partial}{\partial t} W.$$

Therefore the variation formula equals

$$\frac{1}{2} \int_0^1 \tau\left(J\left(\frac{\partial}{\partial t} W\right) \frac{V}{\|V\|_2} + J\left(\frac{V}{\|V\|_2}\right) \frac{\partial}{\partial t} W\right) dt.$$

Fix s , and let $0 = t_0 < t_1 < \dots < t_n = 1$ be a partition of $[0, 1]$ such that $U(t, s)$ is C^2 in the interior of the smaller intervals. We may integrate the above formula by parts in each interval $[t_{i-1}, t_i]$ to obtain

$$\begin{aligned} \frac{1}{2} \int_{t_{i-1}}^{t_i} \tau\left(J\left(\frac{\partial}{\partial t} W\right) \frac{V}{\|V\|_2} + J\left(\frac{V}{\|V\|_2}\right) \frac{\partial}{\partial t} W\right) dt = \\ \frac{1}{2} \left\{ \tau\left(J(W) \frac{V}{\|V\|_2} + W J\left(\frac{V}{\|V\|_2}\right)\right) \right\} \Big|_{t_{i-1}}^{t_i} \\ - \frac{1}{2} \int_{t_{i-1}}^{t_i} \tau\left(J(W) \frac{\partial}{\partial t} \left(\frac{V}{\|V\|_2}\right) + W \frac{\partial}{\partial t} J\left(\frac{V}{\|V\|_2}\right)\right) dt. \end{aligned}$$

Recall from the beginning of this section the definition of the covariant derivative of a tangent vector field X along a curve μ of unitaries:

$$\frac{DX}{dt} = \frac{1}{2} \{ \dot{X} - \mu J(\dot{X}) \mu \}.$$

In our case, for each fixed s , the field $\frac{V}{\|V\|_2}$ is tangent along the curve $U(t, s)$, so we have

$$\frac{D}{dt} \frac{V}{\|V\|_2} = \frac{1}{2} \left\{ \frac{\partial}{\partial t} \frac{V}{\|V\|_2} - U J\left(\frac{\partial}{\partial t} \frac{V}{\|V\|_2}\right) U \right\}.$$

Now we differentiate the identity $U^*U = 1$ with respect to t . It was pointed out in the introduction that the product of unitaries is not a differentiable map of the arguments in the L^2 topology. However a product $u(t)v(t)$ of C^2 curves of unitaries

Short Geodesics of Unitaries in the L^2 Metric

7

$u(t)$ and $v(t)$ can be differentiated twice with respect to t . Indeed, the first derivative yields $\dot{u}v + u\dot{v}$. Since u and v are C^2 , the norms $\|\dot{v}(t)\|_2$ and $\|\dot{u}(t)\|_2$ are uniformly bounded, and the second derivative can be computed. In our case, the derivative of the identity $U^*U = 1$ gives

$$V = -UJ(V)U,$$

i.e.,

$$\frac{V}{\|V\|_2} = -UJ\left(\frac{V}{\|V\|_2}\right)U.$$

Before computing the second derivative we put $s = 0$

$$\frac{\dot{\mu}}{\|\dot{\mu}\|_2} = -\mu J\left(\frac{\dot{\mu}}{\|\dot{\mu}\|_2}\right)\mu.$$

Differentiating this expression with respect to t (recall that we assume that μ is parametrized proportionally to arc length, *i.e.*, $\|\dot{\mu}\|_2$ is constant)

$$\frac{\partial}{\partial t} \frac{\dot{\mu}}{\|\dot{\mu}\|_2} = -\dot{\mu} J\left(\frac{\dot{\mu}}{\|\dot{\mu}\|_2}\right)\mu - \mu J\left(\frac{\dot{\mu}}{\|\dot{\mu}\|_2}\right)\dot{\mu} - \mu J\left(\frac{\partial}{\partial t} \frac{\dot{\mu}}{\|\dot{\mu}\|_2}\right)\mu.$$

Combining these one obtains

$$2\frac{\partial}{\partial t} \frac{\dot{\mu}}{\|\dot{\mu}\|_2} = 2\frac{D}{dt} \frac{\dot{\mu}}{\|\dot{\mu}\|_2} - \frac{\dot{\mu}J(\dot{\mu})}{\|\dot{\mu}\|_2}\mu - \mu\frac{J(\dot{\mu})\dot{\mu}}{\|\dot{\mu}\|_2},$$

with an analogous expression for $2J\left(\frac{\partial}{\partial t} \frac{\dot{\mu}}{\|\dot{\mu}\|_2}\right)$. We add the integrals over the intervals $[t_{i-1}, t_i]$, and use these relations to obtain,

$$\begin{aligned} \delta\ell(s) &= \frac{1}{2} \sum_{i=1}^n \left\{ \tau\left(J(W)\frac{\dot{\mu}}{\|\dot{\mu}\|_2} + WJ\left(\frac{\dot{\mu}}{\|\dot{\mu}\|_2}\right)\right) \right\} \Big|_{t_{i-1}}^{t_i} \\ &\quad + \frac{1}{2} \int_0^1 \tau\left(J(W)(\mu\dot{\mu}J\left(\frac{\dot{\mu}}{\|\dot{\mu}\|_2}\right) - 2J(W)\frac{D}{dt} \frac{\dot{\mu}}{\|\dot{\mu}\|_2} \right. \\ &\quad \left. + W(\mu^*\dot{\mu}J\left(\frac{\dot{\mu}}{\|\dot{\mu}\|_2}\right) + J\left(\frac{\dot{\mu}}{\|\dot{\mu}\|_2}\dot{\mu}\mu^*\right) - 2J\left(\frac{D}{dt} \frac{\dot{\mu}}{\|\dot{\mu}\|_2}\right)) \right) dt. \end{aligned}$$

We can deal better with this expression if we relate it to the second differential of the map $x \mapsto \tau(x^*x)$, which is the (real) bilinear form

$$H: L^2(\mathcal{M}, \tau) \times L^2(\mathcal{M}, \tau) \rightarrow \mathbb{R}, \quad H(\xi, \eta) = \tau(\xi J(\eta) + J(\xi)\eta).$$

Then the expression for the variation of ℓ becomes

$$\begin{aligned} \delta\ell(0) &= \frac{1}{2} \sum_{i=1}^n H\left(\frac{\dot{\mu}}{\|\dot{\mu}\|_2}, W\right) \Big|_{t_{i-1}}^{t_i} \\ &\quad + \int_0^1 H\left(\mu^*W, \frac{1}{2\|\dot{\mu}\|_2}(J(\dot{\mu})\dot{\mu} - \dot{\mu}J(\dot{\mu}))\right) - H\left(\frac{D}{dt} \frac{\dot{\mu}}{\|\dot{\mu}\|_2}, W\right) dt. \end{aligned}$$

A fact used here is that the field W satisfies relations analogous as V , i.e., $U^*W = -J(W)U$. A remark is in order. The element $\dot{\mu}J(\dot{\mu})$ (resp. $\dot{\mu}J(\dot{\mu})$) lies in $L^2(\mathcal{M}, \tau)$. This is a consequence of μ being (piecewise) C^2 , namely, its second derivatives, which involve such terms, lie in $L^2(\mathcal{M}, \tau)$.

Note that $\frac{1}{\|\dot{\mu}\|_2}(J(\dot{\mu})\dot{\mu} - \dot{\mu}J(\dot{\mu}))$ lies in $L^2(\mathcal{M}, \tau)_+$ (is “hermitian”) and μ^*W lies in $L^2(\mathcal{M}, \tau)_-$ (“antihermitian”). Indeed, the latter has just been remarked. The former holds because $\dot{\mu}$ can be approximated by elements x of \mathcal{M} , and therefore $J(\dot{\mu})\dot{\mu} - \dot{\mu}J(\dot{\mu})$ can be approximated by $x^*x - xx^*$. Now if $\xi \in L^2(\mathcal{M}, \tau)_-$ and $\eta \in L^2(\mathcal{M}, \tau)_+$, it is clear that $H(\xi, \eta) = 0$. Therefore we arrive at our final expression for the variation

$$(3) \quad \delta\ell(0) = -\frac{1}{2} \sum_{i=1}^n H\left(\frac{\dot{\mu}}{\|\dot{\mu}\|_2}, W\right) \Big|_{t_{i-1}}^{t_i} - \int_0^1 H\left(\frac{D}{dt} \frac{\dot{\mu}}{\|\dot{\mu}\|_2}, W\right) dt.$$

Let us transcribe Theorem 3.3 by Durán, Mata-Lorenzo and Recht [4], which applies to our situation, with minor adaptations, once we have (3) analogous to their expression for the variation.

If a piecewise C^2 curve μ has minimal length among all the piecewise C^2 curves of unitaries joining the same endpoints, then clearly $\delta\ell(0)$ vanishes for any variation U of μ . As is standard use, let us call a curve for which all variations make $\delta\ell(0)$ vanish, an extremal of ℓ .

Theorem 2.4 *The extremals of ℓ (among piecewise C^2 -curves) are precisely the geodesics of $U_{\mathcal{M}}$.*

Proof Clearly a geodesic is an extremal of ℓ . Suppose now that μ is a piecewise C^2 curve of unitaries. The converse is proven as in [4], by means of the following facts:

1. If μ is an extremal of ℓ , then for all $t \in [0, 1]$ and every vector field W along μ

$$H\left(W(t), \frac{D}{dt} \frac{\dot{\mu}(t)}{\|\dot{\mu}(t)\|_2}\right) = 0.$$

2. If μ is an extremal of ℓ , then μ is C^2 .
3. If μ is C^2 and satisfies that for any vector field W along μ

$$H\left(W(t), \frac{D}{dt} \frac{\dot{\mu}(t)}{\|\dot{\mu}(t)\|_2}\right) = 0$$

then μ is a geodesic.

For the first assertion, suppose that for some t_0 (a point where μ is C^2) one has

$$H\left(W(t_0), \frac{D}{dt} \frac{\dot{\mu}(t_0)}{\|\dot{\mu}(t_0)\|_2}\right) > 0$$

for some variation U . Let us consider another variation

$$\tilde{U}(t, s) = U(t, \varphi(t)s),$$

where φ is a scalar function satisfying

Short Geodesics of Unitaries in the L^2 Metric

9

1. $0 \leq \varphi(t) \leq 1$, with $\varphi(0) = 1$ and $\varphi(1) = 1$.
2. $\varphi(t_0) = 1$ and φ vanishes on small intervals around the points t_1, \dots, t_n where the derivative of μ is not continuous.

Note that $\tilde{U}(t, 0) = U(t, 0) = \mu(t)$. Also the first condition above implies that $\tilde{U}(0, s) = U(s, 0) = \mu(0)$ and $\tilde{U}(1, s) = U(1, s) = \mu(1)$. In other words, \tilde{U} is another variation of μ with fixed endpoints. Moreover

$$\tilde{W}(t, s) = \frac{\partial \tilde{U}}{\partial s} = \frac{\partial U}{\partial s}(t, \varphi(t)s) = \varphi(t)W(t, \varphi(t)s),$$

and therefore $\tilde{W}(t) = \tilde{W}(t, 0) = \varphi(t)W(t)$. Note that since $\varphi(t_0) = 1$,

$$H\left(\frac{D}{dt} \frac{\dot{\mu}(t_0)}{\|\dot{\mu}(t_0)\|_2}, \tilde{W}(t_0)\right) > 0.$$

We can further choose φ in order that

$$H\left(\frac{D}{dt} \frac{\dot{\mu}(t)}{\|\dot{\mu}(t)\|_2}, \tilde{W}(t)\right) = \varphi(t)H\left(\frac{D}{dt} \frac{\dot{\mu}(t)}{\|\dot{\mu}(t)\|_2}, W(t)\right) \geq 0.$$

Since $\tilde{W}(t) = \varphi(t)W(t)$ vanishes at the points t_1, \dots, t_n , it follows that for \tilde{U} the variation is

$$\delta\ell(0) = -\frac{1}{2} \int_0^1 H\left(\frac{D}{dt} \frac{\dot{\mu}(t)}{\|\dot{\mu}(t)\|_2}, \tilde{W}(t)\right) dt > 0,$$

and therefore μ is not an extremal.

To prove the second assertion, suppose that μ is an extremal of ℓ , and that t_0 is a point where $\dot{\mu}$ is not continuous. Denote by V_0^+ and V_0^- the lateral limits of $\frac{D}{dt} \frac{\dot{\mu}(t)}{\|\dot{\mu}(t)\|_2}$ at $t = t_0$. Note that V_0^+ and V_0^- are unit vectors. Put

$$U(t, s) = e^{is\varphi(t)V_0^+},$$

where $\varphi(t)$ is a smooth scalar function, which satisfies that $0 \leq \varphi(t) \leq 1$, $\varphi(t_0) = 1$ and φ vanishes on the other points where $\dot{\mu}$ is not continuous. By the first assertion, the integral term in the expression of the variation of μ vanishes. Moreover, by the choice of φ , one has

$$\delta\ell(0) = H(W(t_0), V_0^+) - H(W(t_0), V_0^-) = H(V_0^+, V_0^+) - H(V_0^+, V_0^-).$$

Now

$$H(V_0^+, V_0^+) = \tau(V_0^+ J(V_0^+) + J(V_0^+) V_0^+) = 2\|V_0^+\|_2^2 = 2.$$

On the other hand, the fact that $\frac{\dot{\mu}(t)}{\|\dot{\mu}(t)\|_2}$ has a jump at $t = t_0$ implies that the unit vectors V_0^+ and V_0^- do not point in the same direction, *i.e.*, the Cauchy–Schwarz inequality is strict:

$$\tau(V_0^+ J(V_0^-)) < \|V_0^+\|_2 \|V_0^-\|_2 = 1,$$

and analogously $\tau(J(V_0^+)V_0^-) < 1$. It follows that

$$\delta\ell(0) > 0$$

for this U , and μ is not an extremal.

The third assertion is straightforward. Since in our case, the form H is nondegenerate, the identity

$$H\left(W(t), \frac{D}{dt} \frac{\dot{\mu}(t)}{\|\dot{\mu}(t)\|_2}\right) = 0$$

for any field W implies that

$$\frac{D}{dt} \frac{\dot{\mu}(t)}{\|\dot{\mu}(t)\|_2} = 0$$

i.e., μ is a geodesic. ■

3 Short Curves

The key to our main result is the following:

Lemma 3.1 *Let x be a selfadjoint element of \mathcal{M} with finite spectrum and $\|x\| < \pi$. Then $\delta(t) = e^{itx}$ has minimal length amongst piecewise C^1 curves joining 1 and e^{ix} , in the L^2 metric.*

Proof The element x is of the form $x = \sum_{i=1}^k \alpha_i p_i$, where p_1, \dots, p_k are pairwise orthogonal projections and $\alpha_1, \dots, \alpha_k$ are real numbers with $|\alpha_i| < \pi$. The length of the geodesic δ is $\|\delta\|_2 = (\sum_{i=1}^k \alpha_i^2 r_i)^{1/2}$, where $r_i = \tau(p_i)$. Suppose that μ is another piecewise C^1 curve of unitaries with $\mu(0) = 1$ and $\mu(1) = e^{ix}$. Then

$$\ell(\mu) = \int_0^1 (\tau(J(\dot{\mu})\dot{\mu}))^{1/2} dt = \int_0^1 \left(\sum_{i=1}^k \tau(p_i J(\dot{\mu})\dot{\mu} p_i) \right)^{1/2} dt.$$

For each $1 \leq i \leq k$ denote by $S_{r_i^{1/2}}$ the sphere of radius $r_i^{1/2}$ in $L^2(\mathcal{M}, \tau)$,

$$S_{r_i^{1/2}} = \{\xi \in L^2(\mathcal{M}, \tau) : \langle \xi, \xi \rangle = r_i\}.$$

Note that the curves $p_i\delta$ and $p_i\mu$ are curves in $S_{r_i^{1/2}}$. Indeed, for example

$$\langle p_i\mu, p_i\mu \rangle = \tau((p_i\mu)^* p_i\mu) = \tau(p_i) = r_i.$$

Moreover, $p_i\delta$ is a geodesic of $S_{r_i^{1/2}}$ with length strictly less than $\pi r_i^{1/2}$. An elementary spectral argument shows that

$$p_i\delta(t) = p_i e^{itx} = p_i e^{it\alpha_i},$$

which is clearly a geodesic of the sphere $S_{r_i^{1/2}}$. The length of $p_i\delta$ is

$$\ell(p_i\delta) = \|\alpha_i p_i\|_2 = |\alpha_i| r_i^{1/2} < r_i^{1/2} \pi.$$

In other words, $p_i\delta$ is the shortest curve in $S_{r_i^{1/2}}$ joining its endpoints.

Consider the riemannian submanifold of $L^2(\mathcal{M}, \tau)^k$

$$\mathcal{S} = S_{r_1^{1/2}} \times \cdots \times S_{r_k^{1/2}}$$

with its Levi–Civita connection. The curve $\Delta(t) = (p_1\delta(t), \dots, p_k\delta(t))$ is a geodesic of \mathcal{S} , since it is a k -tuple of geodesics of the coordinates. Moreover, it is the shortest curve of \mathcal{S} joining its endpoints. Indeed, none of its coordinates could be replaced by a shorter curve. Therefore it is shorter than the curve $M(t) = (p_1\mu(t), \dots, p_k\mu(t))$. Now the length of M in \mathcal{S} is measured as follows:

$$\int_0^1 \langle \dot{M}(t), \dot{M}(t) \rangle^{1/2} dt = \int_0^1 \left(\sum_{i=1}^k \tau(p_i J(\dot{\mu}(t)) \dot{\mu}(t)) \right)^{1/2} dt = \ell(\mu).$$

Analogously, the length of Δ coincides with $\ell(\delta)$. It follows that

$$\ell(\mu) \geq \ell(\delta). \quad \blacksquare$$

Lemma 3.2 *Let $x \in \mathcal{M}$ be a selfadjoint element with $\|x\| < \pi$, and $v \in U_{\mathcal{M}}$. Then the geodesic $\delta(t) = ve^{itx}$ has minimal length among piecewise C^1 curves of unitaries joining its endpoints. It is unique among piecewise C^∞ curves with this property.*

Proof There is no loss in generality if we suppose $v = 1$. Indeed, for any curve μ of unitaries, $\ell(\mu) = \ell(v^* \mu)$. Suppose that there exists a piecewise C^1 curve of unitaries μ which is strictly shorter than δ , $\ell(\mu) < \ell(\delta) - \epsilon = \|x\|_2 - \epsilon$. The element x can be approximated in the norm topology of \mathcal{M} by selfadjoint elements of \mathcal{M} , say z , with finite spectrum and the following conditions:

1. $\|z\| \leq \|x\| < \pi$.
2. $\|x\|_2 - \epsilon/2 < \|z\|_2 \leq \|x\|_2$.
3. $\|e^{ix} - e^{iz}\| < \epsilon/2$.
4. There exists a C^∞ curve of unitaries joining e^{ix} and e^{iz} of length less than $\epsilon/2$.

The first three are clear. The fourth condition can be obtained as follows. By the third condition $e^{-ix}e^{iz} = e^{iy}$, with $y^* = y \in \mathcal{M}$. Moreover z can be adjusted so as to obtain y of arbitrarily small norm. Then the curve of unitaries $\gamma(t) = e^{ix}e^{ity}$ is C^∞ , joins e^{ix} and e^{iz} , with length $\|\gamma\|_2 \leq \|y\| < \epsilon/2$.

Consider now the curve μ' , which is the curve μ followed by the curve $e^{ix}e^{ity}$ above. Then clearly

$$\ell(\mu') \leq \ell(\mu) + \|\gamma\|_2 < \ell(\mu) + \epsilon/2.$$

Therefore $\ell(\mu') < \|x\|_2 - \epsilon/2$. On the other hand, since μ' joins 1 and e^{iz} , by the lemma above, it must have length greater than or equal to $\|z\|_2$. It follows that

$$\|z\|_2 \leq \|x\|_2 - \epsilon/2,$$

a contradiction.

Let us now show that δ is unique. Let δ' be another piecewise C^∞ curve joining the same endpoints, parametrized proportional to arc length, with $\ell(\delta) = \ell(\delta')$. The minimality of δ' implies, by Theorem 2.4, that it is a C^∞ geodesic. Then $\delta'(t) = e^{itx'}$ for some $x'^* = x' \in \mathcal{M}$. We claim that $x' = x$.

Since $\|x\| < \pi$, ix can be obtained as an analytic logarithm of $e^{ix} = e^{ix'}$. It follows that x and x' commute. Then $e^{i(x-x')} = 1$ and therefore $x - x'$ is a selfadjoint element with finite spectrum, contained in the discrete set $\{2n\pi : n \in \mathbb{Z}\}$. Then $x' = x + \sum_{i=1}^k 2n_i\pi p_i$ with $n_i \in \mathbb{Z}$ and p_i pairwise orthogonal projections in \mathcal{M} , $i = 1, \dots, k$. Note that $x p_i = 0$. Therefore

$$\|x'\|_2^2 = \|x\|_2^2 + \sum_{i=1}^k 4n_i^2 \pi^2 \tau(p_i).$$

Now, since $\|x\|_2 = \ell(\delta) = \ell(\delta') = \|x'\|_2$, it follows that $\tau(p_i) = 0$, for each $i = 1, \dots, k$, i.e., $x = x'$. ■

Lemma 3.3 *Let x be a selfadjoint element of \mathcal{M} with $\|x\| = \pi$. Then $\delta = ve^{ix}$ is the shortest curve joining its endpoints.*

Proof The proof is the same as the first part of the above lemma, approximating x with z of finite spectrum and $\|z\| < \pi$. Note that any unitary $u \in U_{\mathcal{M}}$ is of the form $u = e^{ix}$ with $x^* = x$ and $\|x\| \leq \pi$. This element x is non unique. ■

We may summarize these lemmas in our main result.

Theorem 3.4 *Let u, v be unitaries in \mathcal{M} , and $x = x^* \in \mathcal{M}$ with $\|x\| \leq \pi$, such that $v^*u = e^{ix}$.*

1. *If $\|x\| < \pi$, then there exists a geodesic joining u and v , which has minimal length among piecewise C^1 curves with these endpoints. It is unique with this property among piecewise C^∞ curves.*
2. *If $\|x\| = \pi$, there exist many minimal C^∞ geodesics joining u and v .*

Remark 3.5 In case 2, the multiple C^∞ geodesics are of the form $\delta(t) = ve^{itx}$ for diverse $x = x^* \in \mathcal{M}$ with $\|x\| = \pi$ such that $v^*u = e^{ix}$. If one only requires that the curves be C^2 , other minimizing curves appear. Namely, by Remark 2.3 they are of the form $\gamma(t) = ve^{itL\xi}$, where ξ lies in $L^4(\mathcal{M}, \tau)$, and satisfies $J\xi = \xi$ and $v^*u = e^{iL\xi}$.

The following corollary might be obtained in a more straightforward way.

Corollary 3.6 *Let $x, y \in \mathcal{M}$ be selfadjoint elements of norm less than or equal to π such that $e^{ix} = e^{iy}$. Then $\tau(x^2) = \tau(y^2)$.*

Proof Both $\delta(t) = e^{itx}$ and $\gamma(t) = e^{ity}$ are minimizing geodesics joining 1 and e^{ix} , therefore $\ell(\delta) = \ell(\gamma)$, i.e., $\tau(x^2) = \tau(y^2)$. ■

4 Non Embeddability of $U_{\mathcal{M}}$ in $L^2(\mathcal{M}, \tau)$

In this section we show that $U_{\mathcal{M}}$ is not a riemannian submanifold of $L^2(\mathcal{M}, \tau)$. By this we mean that $U_{\mathcal{M}}$ is not a riemannian manifold with the inner product of $L^2(\mathcal{M}, \tau)$ at each tangent space. We also consider other aspects of the local structure of $U_{\mathcal{M}}$.

Lemma 4.1 *There exists a sequence of selfadjoint elements $a_n \in \mathcal{M}$ such that $\|a_n\|_2 = \epsilon$ for a given $\epsilon > 0$ and $\|e^{ia_n} - 1\|_2$ tends to zero.*

Proof For each $n \geq 1$ pick a projection p_n in \mathcal{M} such that $\tau(p_n) = \frac{\epsilon^2}{n^2}$. Put $a_n = np_n$. Note that $\|a_n\|_2 = n\tau(p_n)^{1/2} = \epsilon$. On the other hand

$$\|e^{ia_n} - 1\|_2^2 = 2 - \tau(e^{ia_n}) - \tau(e^{-ia_n}).$$

Clearly

$$\tau(e^{ia_n}) = 1 + \frac{\epsilon^2}{n^2}(e^{in} - 1),$$

which tends to 1. Analogously for $\tau(e^{-ia_n})$. ■

Corollary 4.2 *$U_{\mathcal{M}}$ is not a riemannian submanifold of $L^2(\mathcal{M}, \tau)$.*

Proof Consider $u_n = e^{ia_n} \in U_{\mathcal{M}}$ as above. Then the sequence u_n tends to 1 in the L^2 metric. If $U_{\mathcal{M}}$ were a riemannian submanifold, then $\delta_n(t) = e^{ita_n}$ would be a geodesic. If one adjusts ϵ smaller than the radius of a normal neighbourhood around $1 \in U_{\mathcal{M}}$, then δ_n would be a minimizing geodesic. It follows that the geodesic distance between 1 and e^{ia_n} equals ϵ for all n . This leads to contradiction: in a riemannian manifold the topology given by the geodesic distance and the underlying topology are equivalent. ■

Note that δ_n above is in fact not a minimizing geodesic, according to our discussion of the previous section. Indeed, $\|a_n\| = n$. If one tries to compute minimizing geodesics joining 1 and e^{ia_n} , one must replace the exponent $a_n = np_n$ by $x_n = (n - 2k_n\pi)p_n$, where k_n is an integer such that $|n - 2k_n\pi| \leq \pi$ (in this case it will be strictly smaller than π). Such x_n satisfy

$$\|x_n\|_2^2 = (n - 2k_n\pi)^2 \frac{\epsilon^2}{n^2} \rightarrow 0 \text{ as } n \rightarrow \infty.$$

In other words, these minimizing geodesics have lengths which tend to 0.

Let us denote by d_g the geodesic distance in $U_{\mathcal{M}}$, *i.e.*,

$$d_g(u, v) = \inf\{\ell(\mu) : \mu \text{ piecewise } C^1 \text{ curve of unitaries with } \mu(0) = u, \mu(1) = v\}.$$

Since $U_{\mathcal{M}}$ is not a riemannian manifold, we must prove the following:

Proposition 4.3 d_g is a metric in $U_{\mathcal{M}}$.

Proof Clearly $d_g(u, v) \geq 0$ and $d_g(u, v) = 0$ imply $u = v$. Also it is clear that $d_g(u, v) = d_g(v, u)$. Let us verify that the triangle inequality holds. Let $u, v, w \in U_{\mathcal{M}}$. We need to show that

$$d_g(u, v) \leq d_g(u, w) + d_g(w, v).$$

By Theorem 3.4, u and w are joined by a minimizing geodesic δ and w and v are joined by a minimizing geodesic δ' , with both curves realizing the geodesic distance. The curve δ followed by the curve δ' is a piecewise C^1 curve of unitaries joining u and v , with length $d_g(u, w) + d_g(w, v)$. Therefore $d_g(u, v) \leq d_g(u, w) + d_g(w, v)$. ■

Proposition 4.4 The metrics d_g and $\|\cdot\|_2$ are equivalent in $U_{\mathcal{M}}$.

Proof Both metrics are invariant by left translation with elements of $U_{\mathcal{M}}$, *i.e.*, $d_g(u, v) = d_g(v^*u, 1)$ and $\|u - v\|_2 = \|v^*u - 1\|_2$. Therefore it suffices to compare $d_g(u, 1)$ and $\|u - 1\|_2$, for $u \in U_{\mathcal{M}}$. Let $x = x^* \in \mathcal{M}$ with $\|x\| \leq \pi$ and $u = e^{ix}$. Then by Theorem 3.4

$$d_g(u, 1) = \|x\|_2 = \tau(x^2)^{1/2}.$$

On the other hand

$$\|u - 1\|_2^2 = 2 - \tau(e^{ix} + e^{-ix}) = 2 \left[\frac{\tau(x^2)}{2} - \frac{\tau(x^4)}{4!} + \frac{\tau(x^6)}{6!} - \dots \right].$$

Note that for all $n \geq 1$,

$$\frac{\tau(x^{2n})}{(2n)!} - \frac{\tau(x^{2n+2})}{(2n+2)!} \geq 0.$$

Indeed, it is apparent that this inequality is equivalent to $(2n+2)(2n+1) \geq \frac{\tau(x^{2n+2})}{\tau(x^{2n})}$.

Since $x^2 \leq \pi^2$,

$$\frac{\tau(x^{2n+2})}{\tau(x^{2n})} = \frac{\tau(x^n x^2 x^n)}{\tau(x^{2n})} \leq \frac{\tau(x^n \pi^2 x^n)}{\tau(x^{2n})} = \pi^2,$$

and the above claim holds. First, note that with this inequality one has

$$\|u - 1\|_2^2 = 2 \left[\frac{1}{2} \tau(x^2) - \left(\frac{\tau(x^4)}{4!} - \frac{\tau(x^6)}{6!} \right) - \dots \right] \leq \tau(x^2),$$

i.e., $\|u - 1\|_2 \leq d_g(u, 1)$.

On the other hand, the same inequality proves that

$$\|u - 1\|_2^2 = 2 \left[\frac{1}{2} \tau(x^2) - \frac{1}{4!} \tau(x^4) + \left(\frac{\tau(x^6)}{6!} - \frac{\tau(x^8)}{8!} \right) + \dots \right] \geq 2 \left[\frac{1}{2} \tau(x^2) - \frac{1}{4!} \tau(x^4) \right].$$

Short Geodesics of Unitaries in the L^2 Metric

15

Since $1 - \frac{x^2}{12} \geq 1 - \frac{\pi^2}{12} > 0$, it follows that

$$\frac{1}{2}\tau(x^2) - \frac{1}{4!}\tau(x^4) = \frac{1}{2}\tau(x^2(1 - \frac{1}{12}x^2)) \geq \frac{1}{2}\left(1 - \frac{\pi^2}{12}\right)\tau(x^2).$$

In other words,

$$\|u - 1\|_2 \geq Cd_g(u, 1),$$

for $C = \sqrt{1 - \frac{\pi^2}{12}}$. ■

Further properties of this metric d_g will be studied elsewhere.

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