# Weighted operator least squares problems and the $J$-trace in Krein spaces 

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#### Abstract

Given $B, C$ and $W$ operators in the algebra $L(\mathcal{H})$ of bounded linear operators on the Krein space $\mathcal{H}$, the minimization problem min $(B X-C)^{\#} W(B X-C)$, for $X \in L(\mathcal{H})$, is studied when the weight $W$ is selfadjoint. The analogous maximization and min-max problems are also considered. Complete answers to these problems and to those naturally associated to trace clase operators on Krein spaces are given.


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## 1. Introduction

In estimation theory one would like to approximate the values of certain quantities that are not directly observable from the values of some sampled measurements. The solution to the problem of estimating the unobservable quantities given the observable ones depends on the model one uses to describe the relation between them and the optimality criterion one chooses to determine the desired estimates. The weighted least squares method is the standard approach in situations when it may not be feasible to assume that every observation should be treated equally. It works by incorporating a weight to each data point as a way to describe its influence over the estimates.

The Krein space estimation theory developed by Hassibi et al. 17] has brought into play indefinite weighted least squares problems. Some of those problems were studied in their "pointwise" form, for linear operators on infinite-dimensional spaces in [15] and, for matrices with complex entries in [18, 23]. Roughly speaking, if one is given an infinite or finite-dimensional linear space $\mathcal{H}$, a weight $W$, bounded linear operators or matrices $B, C$, and a vector $y \in \mathcal{H}$, then the problem is to find an "extremal" vector $x_{0} \in \mathcal{H}$ for the quadratic form $[W(B x-C y), B x-C y]$ with [ , ] a Krein space inner product on $\mathcal{H}$. If $R(B)$, the range of $B$, is closed and $W$-nonnegative, the vector $x_{0}$ one seeks minimizing the above quadratic form is called a weighted indefinite least squares solution of $B x=C y$.

In this work we look instead for a "global" solution of the problem, meaning a bounded linear operator $X_{0}$ acting as a $W$-inverse of $B$. Broadly speaking, we consider a Krein space ( $\left.\mathcal{H},[],\right)$, a selfadjoint operator $W$ on $\mathcal{H}$ and bounded linear operators $B, C$ on $\mathcal{H}$. We then determine whether there exists $X_{0}$ such that, for each $y \in \mathcal{H}, X_{0} y$ is a weighted indefinite least squares solution of $B x=C y$. For a positive weight $W$, the notion of $W$-inverse was introduced by Mitra and Rao in the case of matrices

[^0][21], and later on extended to Hilbert space operators in [10, 7]. Here we say that $X_{0}$ is an indefinite minimum solution of $B X-C=0$ with weight $W$ if $X_{0}$ realizes the minimum of $(B X-C)^{\#} W(B X-C)$ as $X$ runs over $L(\mathcal{H})$, the space of the bounded linear operators on $\mathcal{H}$, where the order is induced by the cone of [, ]-positive operators of $L(\mathcal{H})$. Necessary and sufficient conditions for the existence of such a solution are given and we show that the solution of $B X-I=0$, if it exists, is none other than the Schur complement of $W$ to $R(B)$; i.e.,
$$
W_{/[R(B)]}=\min _{X \in L(\mathcal{H})}(B X-I)^{\#} W(B X-I)
$$

Given the $W$-indefiniteness of the range of $B$, it is natural to consider min-max problems. In fact, any factorization of $B$ as the sum of two operators, one with $W$-nonnegative range and the other with $W$ nonpositive range, yields a min-max problem. As with the minimization problem, we give necessary and sufficient conditions for the solvability of the min-max problem and we obtain another characterization of the Schur complement. Furthermore, even though the decomposition of $B$ depends on the chosen signature operator $J$, the solutions to the min-max problem does not.

In the Hilbert space setting an associated minimizing problem can be considered in the context of unitarily invariant norms, particularly, in the $p$-Schatten class norms $\left\|\|_{p}\right.$, in which case - and under the assumption that $W$ is positive - it takes the form of the Procrustes problem $\min _{X \in L(\mathcal{H})}\left\|W^{1 / 2}(B X-C)\right\|_{p}$. Indeed, these two kinds of problems are closely related, as [14, 16, 7] have shown. Inspired by the work of Kintzel on an indefinite Procrustes problem expressed as a max-min problem on traces of matrices [19], we define a $J$-trace, $\operatorname{tr}_{J}$, and study the corresponding min-max problem. We find that, if the problem is solvable for every $C$, the solution is unique and equals $\operatorname{tr}_{J}\left(C^{\#} W_{/[R(B)]} C\right)$. In addition, if $\operatorname{tr}_{J}(T)<\infty$ for some signature operator $J$, then $\operatorname{tr}_{J^{\prime}}(T)<\infty$ for any other signature operator $J^{\prime}$, though it may happen that $\operatorname{tr}_{J}(T) \neq \operatorname{tr}_{J^{\prime}}(T)$. Consequently, the min-max value for the $\operatorname{tr}_{J}$ depends on $J$, but the set of solutions where this value is attained for each $J$, is independent of $J$.

The paper may be thought of as the second part of [8], for it contains the weighted versions of the operator least squares problems we studied there. There the fundamental tool for solving the least squares problems was given by the indefinite inverse. In this work the Schur complement, as defined and studied in (9], plays this role.

The paper has four additional sections. Section 2 fixes notation and recalls the basics of Krein spaces, Section 3 gives a brief account of the fundamental results on the Schur complement from [9]. In Section 4 we turn to weighted least squares problems. Subsection 4.1 is entirely devoted to the weighted min-max problems and contains the main results. Section 5 extends the notion of the trace of an operator to the Krein space setting, and applies the results obtained in the previous section to trace-type min and min-max problems for operators.

## 2. Preliminaries

We assume that all Hilbert spaces are complex and separable. If $\mathcal{H}$ is a Hilbert space, $L(\mathcal{H})$ stands for the algebra of bounded linear operators on $\mathcal{H}$ and $L(\mathcal{H})^{+}$for the cone of positive semidefinite operators in $L(\mathcal{H})$. We write $C R(\mathcal{H})$ to indicate the subset of $L(\mathcal{H})$ of operators with closed range.

The range and nullspace of any $A \in L(\mathcal{H})$ are denoted by $R(A)$ and $N(A)$, respectively. Given a subset $\mathcal{T} \subseteq \mathcal{H}$, the preimage of $\mathcal{T}$ under $A$ is denoted by $A^{-1}(\mathcal{T})$ so $A^{-1}(\mathcal{T})=\{h \in \mathcal{H}: A h \in \mathcal{T}\}$. Given two operators $S, T \in L(\mathcal{H})$, the notation $T \leq_{\mathcal{H}} S$ signifies that $S-T \in L(\mathcal{H})^{+}$. For any $T \in L(\mathcal{H})$, $|T|:=\left(T^{*} T\right)^{1 / 2}$ is the modulus of $T$ and $T=U|T|$ is the polar decomposition of $T$, with $U$ the partial isometry such that $N(U)=N(T)$.

The direct sum of two closed subspaces $\mathcal{M}$ and $\mathcal{N}$ of $\mathcal{H}$ is represented by $\mathcal{M} \dot{+} \mathcal{N}$. If $\mathcal{H}$ is decomposed as $\mathcal{H}=\mathcal{M} \dot{+} \mathcal{N}$, the projection onto $\mathcal{M}$ with nullspace $\mathcal{N}$ is denoted by $P_{\mathcal{M} / \mathcal{N}}$ and abbreviated $P_{\mathcal{M}}$ when $\mathcal{N}=\mathcal{M}^{\perp} . \mathcal{Q}$ indicates the subset of oblique projections in $L(\mathcal{H})$, namely, $\mathcal{Q}:=\left\{Q \in L(\mathcal{H}): Q^{2}=Q\right\}$.

## Krein Spaces

A linear space $\mathcal{H}$ endowed with an indefinite inner product (a Hermitian sesquilinear form) [, ] is a Krein space if $\mathcal{H}$ is the algebraic direct sum of two subspaces $\mathcal{H}_{+}$and $\mathcal{H}_{-}$such that: (1) $\left[x_{+}, x_{-}\right]=0$
for every $x_{ \pm} \in \mathcal{H}_{ \pm}$, and $(2)\left(\mathcal{H}_{+},[],\right)$and $\left(\mathcal{H}_{-},-[],\right)$are Hilbert spaces. We write

$$
\begin{equation*}
\mathcal{H}=\mathcal{H}_{+}[\dot{+}] \mathcal{H}_{-} \tag{2.1}
\end{equation*}
$$

to indicate that the Krein space $\mathcal{H}$ is the [, ]-orthogonal direct sum of $\mathcal{H}_{+}$and $\mathcal{H}_{-}$, and we say that (2.1) is a fundamental decomposition of $\mathcal{H}$.

In general, all geometrical notions on a Krein space are to be understood with respect to the indefinite inner product. In particular, the orthogonal companion of a set $\mathcal{T}$ in $\mathcal{H}$, which we denote by $\mathcal{T}^{[\perp]}$, is the subspace of those $h \in \mathcal{H}$ such that $[h, x]=0$ for all $x \in \mathcal{T}$.

Every fundamental decomposition $\mathcal{H}=\mathcal{H}_{+}[\dot{+}] \mathcal{H}_{-}$of a given Krein space $(\mathcal{H},[]$,$) induces a Hilbert$ space inner product $\langle$,$\rangle on \mathcal{H}$. Namely, $\langle x, y\rangle:=\left[x_{+}, y_{+}\right]-\left[x_{-}, y_{-}\right]$, for $x, y \in \mathcal{H}, x=x_{+}+x_{-}$and $y=y_{+}+y_{-}$. In this situation the operator $J$ defined on $x=x_{+}+x_{-}$by $J x:=x_{+}-x_{-}$is called a signature operator of $\mathcal{H}$.

If $\mathcal{H}$ is a Krein space, $L(\mathcal{H})$ stands for the vector space of all the linear operators on $\mathcal{H}$ which are bounded in an associated Hilbert space $(\mathcal{H},\langle\rangle$,$) . Since the norms generated by different fundamental$ decompositions of a Krein space $\mathcal{H}$ are equivalent (see, for instance, [4, Theorem 7.19]), $L(\mathcal{H}$ ) does not depend on the chosen underlying Hilbert space.

The symbol $T^{\#}$ stands for the [, ]-adjoint of $T \in L(\mathcal{H})$. The set of the operators $T \in L(\mathcal{H})$ such that $T=T^{\#}$ is denoted $L(\mathcal{H})^{s}$. If $T \in L(\mathcal{H})^{s}$ and $[T x, x] \geq 0$ for every $x \in \mathcal{H}, T$ is said to be positive; the notation $S \leq T$ signifies that $T-S$ is positive.

Given $W \in L(\mathcal{H})^{s}$ and $\mathcal{S}$ a closed subspace of $\mathcal{H}$, we say that $\mathcal{S}$ is $W$-positive if [ $W s, s$ ] $>0$ for every $s \in \mathcal{S}, s \neq 0 . W$-nonnegative, $W$-neutral, $W$-negative and $W$-nonpositive subspaces are defined likewise. If $\mathcal{S}$ and $\mathcal{T}$ are two closed subspaces of $\mathcal{H}$, the notation $\mathcal{S}[\dot{+}]_{W} \mathcal{T}$ is used to indicate the direct sum of $\mathcal{S}$ and $\mathcal{T}$ when, additionally, $[W s, t]=0$ for every $s \in \mathcal{S}$ and $t \in \mathcal{T}$.

Standard references on Krein space theory are [2], [4] and [5]. We also refer to [12] and [13] as authoritative accounts of the subject.

## 3. Schur complement in Krein Spaces

In this section we include several results on the Schur complement in Krein spaces that will be useful along the paper. For the proofs the reader is referred to [9].

The notion of Schur complement (or shorted operator) of $A$ to $\mathcal{S}$ for a positive operator $A$ on a Hilbert space $\mathcal{H}$ and $\mathcal{S} \subseteq \mathcal{H}$ a closed subspace, was introduced by M.G. Krein [20]. He proved that the set $\left\{X \in L(\mathcal{H}): 0 \leq_{\mathcal{H}} X \leq_{\mathcal{H}} A\right.$ and $\left.R(X) \subseteq \mathcal{S}^{\perp}\right\}$ has a maximum element, which he defined as the Schur complement $A_{/ \mathcal{S}}$ of $A$ to $\mathcal{S}$. This notion was later rediscovered by Anderson and Trapp [1]. If $A$ is represented as the $2 \times 2$ block matrix $\left(\begin{array}{cc}a & b \\ b^{*} & c\end{array}\right)$ with respect to the decomposition of $\mathcal{H}=\mathcal{S} \oplus \mathcal{S}^{\perp}$, they established the formula

$$
A_{/ \mathcal{S}}=\left(\begin{array}{cc}
0 & 0 \\
0 & c-y^{*} y
\end{array}\right)
$$

where $y$ is the unique solution of the equation $b=a^{1 / 2} x$ such that the range inclusion $R(y) \subseteq \overline{R(a)}$ holds. The solution always exists because $A$ is positive: in this case, $a$ is also positive and the range inclusion $R(b) \subseteq R\left(a^{1 / 2}\right)$ holds.

In [3] Antezana et al., extended the notion of Schur complement to any bounded operator $A$ satisfying a weak complementability condition with respect to a given pair of closed subspaces $\mathcal{S}$ and $\mathcal{T}$, by giving an Anderson-Trapp type formula. In particular, if $A$ is a bounded selfadjoint operator, $\mathcal{S}=\mathcal{T}$ and $A=\left(\begin{array}{cc}a & b \\ b^{*} & c\end{array}\right)$, this condition reads $R(b) \subseteq R\left(|a|^{1 / 2}\right)$, which as noted, is automatic for positive operators. In this case, let $f$ be the unique solution of the equation $b=|a|^{1 / 2} x$ such that the range inclusion $R(f) \subseteq \overline{R(a)}$ holds and $a=u|a|$ the polar decomposition of $a$. Then, the Schur complement of $A$ to $\mathcal{S}$ is defined as

$$
A_{/ \mathcal{S}}=\left(\begin{array}{cc}
0 & 0 \\
0 & c-f^{*} u f
\end{array}\right)
$$

In [9], the notions of $\mathcal{S}$-complementability, $\mathcal{S}$-weak complementability and the Schur complement were extended to the Krein space setting in the following fashion.

Definition. Let $W \in L(\mathcal{H})^{s}$ and $\mathcal{S}$ be a closed subspace of $\mathcal{H}$. The operator $W$ is called $\mathcal{S}$-complementable if

$$
\mathcal{H}=\mathcal{S}+W^{-1}\left(\mathcal{S}^{[\perp]}\right)
$$

If $W$ is $\mathcal{S}$-complementable then, for any fundamental decomposition $\mathcal{H}=\mathcal{H}_{+}[\dot{+}] \mathcal{H}_{-}$with signature operator $J$, we get that $\mathcal{H}=\mathcal{S}+(J W)^{-1}\left(\mathcal{S}^{\perp}\right)$. Therefore, $W$ is $\mathcal{S}$-complementable if and only if the pair $(J W, \mathcal{S})$ is compatible in (the Hilbert space) $(\mathcal{H},\langle\rangle$,$) for any (and then for every) signature operator J$, meaning that there exists a projection $Q$ onto $\mathcal{S}$, such that $J W Q=Q^{*} J W$, see [6]. From this, it follows that $W$ is $\mathcal{S}$-complementable if and only if there exists a projection $Q$ onto $\mathcal{S}$ such that $W Q=Q^{\#} W$.

In a similar way the $\mathcal{S}$-weak complementability in Krein spaces, with respect to a fixed signature operator $J$, is defined.

Definition. Let $W \in L(\mathcal{H})^{s}$ and $\mathcal{S}$ be a closed subspace of $\mathcal{H}$. The operator $W$ is $\mathcal{S}$-weakly complementable with respect to a signature operator $J$ if $J W$ is $\mathcal{S}$-weakly complementable in $(\mathcal{H},\langle\rangle$,$) .$

In this case, if the matrix representation of $J W$ induced by $\mathcal{S}$ is

$$
J W=\left[\begin{array}{cc}
a & b  \tag{3.1}\\
b^{*} & c
\end{array}\right]
$$

the $\mathcal{S}$-weak complementability of $W$ is equivalent to $R(b) \subseteq R\left(|a|^{1 / 2}\right)$. The $\mathcal{S}$-weak complementability of $W$ does not depend on the signature operator, see [9, Theorem 4.4]. Then, we simply say that $W$ is $\mathcal{S}$-weakly complementable, whenever $W$ is $\mathcal{S}$-weakly complementable with respect to a signature operator $J$.

Let $W \in L(\mathcal{H})^{s}$ and $\mathcal{S}$ a closed subspace of $\mathcal{H}$. Then, by applying the spectral theorem for Hilbert space selfadjoint operators to $A=J W$, with $J$ any signature operator, $\mathcal{S}$ can be decomposed as

$$
\begin{equation*}
\mathcal{S}=\mathcal{S}_{+}[\dot{+}]_{W} \mathcal{S}_{-} \tag{3.2}
\end{equation*}
$$

where $\mathcal{S}_{+}$and $\mathcal{S}_{-}$are closed, $\mathcal{S}_{+}$is $W$-nonnegative, $\mathcal{S}_{-}$is $W$-nonpositive and $\mathcal{S}_{+} \perp \mathcal{S}_{-}$. Notice that the decomposition in (3.2) need not be unique.

The following is a characterization of the $\mathcal{S}$-weak complementability [9, Proposition 4.7].
Proposition 3.1. Let $W \in L(\mathcal{H})^{s}$ and $\mathcal{S}$ be a closed subspace of $\mathcal{H}$. Suppose that $\mathcal{S}=\mathcal{S}_{+}[\dot{+}]_{W} \mathcal{S}_{-}$is any decomposition as in (3.2) for some signature operator $J$. Then the following statements are equivalent:
i) $W$ is $\mathcal{S}$-weakly complementable,
ii) there exist $W_{1}, W_{2}, W_{3} \in L(\mathcal{H})^{s}, W_{2}, W_{3} \geq 0$ such that $W=W_{1}+W_{2}-W_{3}$ and $\mathcal{S} \subseteq N\left(W_{1}\right)$, $\mathcal{S}_{-} \subseteq N\left(W_{2}\right), \mathcal{S}_{+} \subseteq N\left(W_{3}\right)$,
iii) $W$ is $\mathcal{S}_{ \pm}$-weakly complementable.

Definition. Let $W \in L(\mathcal{H})^{s}, \mathcal{S}$ be a closed subspace of $\mathcal{H}$ and $J$ a signature operator. Suppose that $W$ is $\mathcal{S}$-weakly complementable. The $S$ chur complement of $W$ to $\mathcal{S}$ corresponding to $J$ is

$$
W_{/[\mathcal{S}]}^{J}=J(J W)_{/ \mathcal{S}}
$$

and the $\mathcal{S}$-compression of $W$ is $W_{[\mathcal{S}]}^{J}=W-W_{/[\mathcal{S}]}^{J}$.
In [9, Theorem 4.5] it was proved that the Schur complement does not depend on the fundamental decomposition of $\mathcal{H}$. Henceforth we write $W_{/[\mathcal{S}]}$ for this operator and $W_{[\mathcal{S}]}$ for the $\mathcal{S}$-compression. Also, suppose that $\mathcal{S}=\mathcal{S}_{+}[\dot{+}]_{W} \mathcal{S}_{-}$is any decomposition as in (3.2) for some signature operator $J$. If $W$ is $\mathcal{S}$-weakly complementable then

$$
\begin{equation*}
W_{/[\mathcal{S}]}=\left(W_{/\left[\mathcal{S}_{+}\right]}\right)_{/\left[\mathcal{S}_{-}\right]}=\left(W_{/\left[\mathcal{S}_{-}\right]}\right)_{/\left[\mathcal{S}_{+}\right]} \tag{3.3}
\end{equation*}
$$

Also, if $W=W_{1}+W_{2}-W_{3}$ as in Proposition 3.1 then

$$
\begin{equation*}
W_{/[\mathcal{S}]}=W_{1}+W_{2 /\left[\mathcal{S}_{+}\right]}-W_{3 /\left[\mathcal{S}_{-}\right]} \tag{3.4}
\end{equation*}
$$

Moreover, if $W$ is $\mathcal{S}$-complementable then

$$
\begin{equation*}
W_{/[\mathcal{S}]}=W(I-Q) \tag{3.5}
\end{equation*}
$$

for any projection $Q$ onto $\mathcal{S}$ such that $W Q=Q^{\#} W$.
The following result was proved in [9, Corollary 4.12].
Proposition 3.2. Let $W \in L(\mathcal{H})^{s}$ and $\mathcal{S}$ be a closed subspace of $\mathcal{H}$. Suppose that $\mathcal{S}$ is $W$-nonnegative. Then $W$ is $\mathcal{S}$-weakly complementable if and only if there exists $\inf \left\{E^{\#} W E: E=E^{2}, N(E)=\mathcal{S}\right\}$. In this case,

$$
W_{/[\mathcal{S}]}=\inf \left\{E^{\#} W E: E=E^{2}, \quad N(E)=\mathcal{S}\right\}
$$

## 4. Weighted least squares problems in Krein spaces

Consider the following problem: given the operators $W \in L(\mathcal{H})^{s}, B \in C R(\mathcal{H})$ and $C \in L(\mathcal{H})$, determine the existence of

$$
\begin{equation*}
\min _{X \in L(\mathcal{H})}(B X-C)^{\#} W(B X-C) \tag{4.1}
\end{equation*}
$$

Definition. Let $W \in L(\mathcal{H})^{s}, B \in C R(\mathcal{H})$ and $C \in L(\mathcal{H})$. An operator $X_{0} \in L(\mathcal{H})$ is an indefinite minimum solution of $B X-C=0$ with weight $W(W-\operatorname{ImS})$ if $X_{0}$ is a solution of Problem (4.1).

In a similar fashion, the analogous maximization problem can be considered. Along this section all the results are stated for problem (4.1) but similar results hold for the maximum problem.

Consider $W \in L(\mathcal{H})^{s}, B \in C R(\mathcal{H})$ and $C \in L(\mathcal{H})$ and define

$$
\begin{equation*}
F(X):=(B X-C)^{\#} W(B X-C) \tag{4.2}
\end{equation*}
$$

We begin by giving conditions for the existence of the infimum in $L(\mathcal{H})$ of the family $\{F(X): X \in L(\mathcal{H})\}$ when $C=I$.

Proposition 4.1. Let $W \in L(\mathcal{H})^{s}$ and $B \in C R(\mathcal{H})$ such that $R(B)$ is $W$-nonnegative. Then the following are equivalent:
i) There exists $\inf _{X \in L(\mathcal{H})}(B X-I)^{\#} W(B X-I)=: Z_{0} \in L(\mathcal{H})$ and $R(B)$ is $Z_{0}$-nonnegative,
ii) $W$ is $R(B)$-weakly complementable.

In this case, $Z_{0}=W_{/[R(B)]}$.
Proof. Suppose that $W$ is $R(B)$-weakly complementable. Let $F(X)$ be as in (4.2) for $C=I$. Then, for any $X \in L(\mathcal{H}), F(X)=W_{/[R(B)]}+(B X-I)^{\#} W_{[R(B)]}(B X-I) \geq W_{/[R(B)]}$, because $R(B) \subseteq N\left(W_{/[R(B)]}\right)$ and the fact that $R(B)$ is $W$-nonnegative yields $W_{[R(B)]} \geq 0$. Hence $W_{/[R(B)]}$ is a lower bound of $\{F(X)$ : $X \in L(\mathcal{H})\}$. Let $T \in L(\mathcal{H})$ be any other lower bound of $F(X)$.

In particular, given $E \in \mathcal{Q}$ such that $R(I-E)=R(B)$, by Douglas' Lemma [11], there exists $X_{0} \in L(\mathcal{H})$ satisfying $I-E=B X_{0}$; i.e., such that $-E=B X_{0}-I$. Then

$$
T \leq E^{\#} W E \text { for every } E \in \mathcal{Q} \text { such that } N(E)=R(B)
$$

By Proposition 3.2,

$$
T \leq \inf \left\{E^{\#} W E: E \in \mathcal{Q}, N(E)=R(B)\right\}=W_{/[R(B)]}
$$

Therefore, $W_{/[R(B)]}=\inf _{X \in L(\mathcal{H})} F(X)$ and, since $R(B) \subseteq N\left(W_{/[R(B)]}\right), R(B)$ is $W_{/[R(B)] \text {-nonnegative. }}$.
Conversely, if $Z_{0}$ exists and $R(B)$ is $Z_{0}$-nonnegative, then taking $X=0$, the inequality $Z_{0} \leq W$ shows that $Z_{0} \in L(\mathcal{H})^{s}$. As before,

$$
Z_{0} \leq E^{\#} W E \text { for every } E \in \mathcal{Q} \text { such that } N(E)=R(B)
$$

Fix a signature operator $J$ and let $(\mathcal{H},\langle\rangle$,$) be the corresponding Hilbert space; consider E=P_{R(B)^{\perp}}$. Since $Z_{0} \in L(\mathcal{H})^{s},\left(J Z_{0}\right)^{*}=J Z_{0}$ and

$$
\begin{equation*}
J Z_{0} \leq_{\mathcal{H}} P_{R(B)^{\perp}} J W P_{R(B)^{\perp}} \tag{4.3}
\end{equation*}
$$

Let $J W=\left[\begin{array}{cc}a & b \\ b^{*} & c\end{array}\right]$ and $J Z_{0}=\left[\begin{array}{cc}z_{11} & z_{12} \\ z_{12}^{*} & z_{22}\end{array}\right]$ be the matrix representation of $J W$ and $J Z_{0}$ induced by $R(B)$, respectively. By (4.3),

$$
P_{R(B)^{\perp}} J W P_{R(B)^{\perp}}-J Z_{0}=\left[\begin{array}{cc}
-z_{11} & -z_{12} \\
-z_{12}^{*} & c-z_{22}
\end{array}\right] \geq_{\mathcal{H}} 0 .
$$

Then, $z_{11} \leq_{\mathcal{H}} 0$ and $R\left(z_{12}\right) \subseteq R\left(\left(-z_{11}\right)^{1 / 2}\right)$. Since $R(B)$ is $Z_{0}$-nonnegative, $z_{11} \geq_{\mathcal{H}} 0$. So $z_{11}=z_{12}=$ $z_{12}^{*}=0$ and $R\left(J Z_{0}\right) \subseteq R(B)^{\perp}$ or equivalently, $R\left(Z_{0}\right) \subseteq R(B)^{[\perp]}$. Therefore, $W=\left(W-Z_{0}\right)+Z_{0}$, with $W-Z_{0} \geq 0$ and $R\left(Z_{0}\right) \subseteq R(B)^{[\perp]}$. Then, by Proposition 3.1, $W$ is $R(B)$-weakly complementable.

Corollary 4.2. Let $W \in L(\mathcal{H})^{s}$ and $B \in C R(\mathcal{H})$ such that $R(B)$ is $W$-nonnegative and $W$ is $R(B)$ weakly complementable. Then, for every $C \in L(\mathcal{H})$,

$$
\inf _{X \in L(\mathcal{H})}(B X-C)^{\#} W(B X-C)=C^{\#} W_{/[R(B)]} C
$$

Proof. If $W \geq 0$, by [7, Lemma 4.1],

$$
\inf \left\{C^{\#} E^{\#} W E C: E \in \mathcal{Q}, N(E)=R(B)\right\}=C^{\#} W_{/[R(B)]} C
$$

By Proposition 3.1, $W=W_{1}+W_{2}$, with $R(B) \subseteq N\left(W_{1}\right)$ and $W_{2} \geq 0$. Then, given $E \in \mathcal{Q}$ such that $N(E)=R(B)$,

$$
C^{\#} E^{\#} W E C=C^{\#} W_{1} C+C^{\#} E^{\#} W_{2} E C
$$

Hence

$$
\begin{aligned}
& \inf \left\{C^{\#} E^{\#} W E C: E \in \mathcal{Q}, N(E)=R(B)\right\}= \\
&=C^{\#} W_{1} C+\inf \left\{C^{\#} E^{\#} W_{2} E C: E \in \mathcal{Q}, N(E)=R(B)\right\} \\
&=C^{\#} W_{1} C+C^{\#} W_{2 /[R(B)]} C=C^{\#} W_{/[R(B)]} C
\end{aligned}
$$

Using this equality, the result follows in a similar way as in the first part of the proof of Proposition 4.1.

The next theorem establishes when the infimum in Proposition 4.1 is attained.
Theorem 4.3. Let $W \in L(\mathcal{H})^{s}$ and $B \in C R(\mathcal{H})$. Then the following are equivalent:
i) there exists a $W$-ImS of $B X-I=0$,
ii) $R(B)$ is $W$-nonnegative and $W$ is $R(B)$-complementable,
iii) $R(B)$ is $W$-nonnegative and the normal equation

$$
\begin{equation*}
B^{\#} W(B X-I)=0 \tag{4.4}
\end{equation*}
$$

admits a solution.
In this case,

$$
\min _{X \in L(\mathcal{H})}(B X-I)^{\#} W(B X-I)=W_{/[R(B)]}
$$

Proof. $\quad i) \Leftrightarrow i i i)$ : Suppose that $X_{0}$ is a $W-\operatorname{ImS}$ of $B X-I=0$. Then

$$
\left[W\left(B X_{0}-I\right) x,\left(B X_{0}-I\right) x\right] \leq[W(B X-I) x,(B X-I) x]
$$

for every $x \in \mathcal{H}$ and every $X \in L(\mathcal{H})$. Let $z \in \mathcal{H}$ be arbitrary. Then, for every $x \in \mathcal{H} \backslash\{0\}$, there exists $X \in L(\mathcal{H})$ such that $z=X x$. Therefore

$$
\left[W\left(B X_{0}-I\right) x,\left(B X_{0}-I\right) x\right] \leq[W(B z-x), B z-x]
$$

for every $x, z \in \mathcal{H}$. Thus, for every $x \in \mathcal{H}, X_{0} x$ is a weighted indefinite least squares solution of $B z=x$. So, by [15, Proposition 3.2] (see also [5, Chapter I, Theorem 8.4]), $R(B)$ is $W$-nonnegative and $X_{0} x$ is a solution of $B^{\#} W(B y-x)=0$ for every $x \in \mathcal{H}$, or equivalently, $X_{0}$ is a solution of (4.4).

The converse follows in a similar way, applying again [15, Proposition 3.2].
ii) $\Leftrightarrow$ iii) : Suppose that $\mathcal{H}=R(B)+W^{-1}\left(R(B)^{[\perp]}\right)$, then $R\left(B^{\#} W\right) \subseteq R\left(B^{\#} W B\right)$. Hence, by Douglas' Lemma, the equation $B^{\#} W(B X-I)=0$ admits a solution. The converse follows analogously.

In this case, by Proposition 4.1 .

$$
\min _{X \in L(\mathcal{H})}(B X-I)^{\#} W(B X-I)=W_{/[R(B)]}
$$

The next corollaries follow from Theorem 4.3.
Corollary 4.4. Let $W \in L(\mathcal{H})^{s}, B \in C R(\mathcal{H})$ and $C \in L(\mathcal{H})$. Then the following are equivalent:
i) there exists a $W$-ImS of $B X-C=0$,
ii) $R(B)$ is $W$-nonnegative and $R(C) \subseteq R(B)+W^{-1}\left(R(B)^{[\perp]}\right)$,
iii) $R(B)$ is $W$-nonnegative and the normal equation

$$
\begin{equation*}
B^{\#} W(B X-C)=0 \tag{4.5}
\end{equation*}
$$

admits a solution.
In this case, $X_{0}$ is a $W$ - $\operatorname{ImS}$ of $B X-C=0$ if and only $X_{0}$ is a solution of (4.5).
Proof. This follows in a similar way as in the proof of Theorem 4.3 using the fact that $u$ is a weighted indefinite least squares solution of the equation $B z=C x$ if and only if $R(B)$ is $W$-nonnegative and $u$ is a solution of $B^{\#} W(B y-C x)=0$, see [15, Proposition 3.2].

Corollary 4.5. Let $W \in L(\mathcal{H})^{s}$ and $B \in C R(\mathcal{H})$. Then there exists a $W$-ImS of $B X-C=0$ for every $C \in L(\mathcal{H})$ if and only if $R(B)$ is $W$-nonnegative and $W$ is $R(B)$-complementable. In this case,

$$
\min _{X \in L(\mathcal{H})}(B X-C)^{\#} W(B X-C)=C^{\#} W_{/[R(B)]} C
$$

Proof. Suppose that there exists a $W$ - $\operatorname{ImS}$ of $B X-C=0$ for every $C \in L(\mathcal{H})$. Then the conclusion follows by applying Theorem4.3 for $C=I$.

Conversely, if $W$ is $R(B)$-complementable and $R(B)$ is $W$-nonnegative, then $B^{\#} W(B X-I)=0$ admits a solution. Therefore $B^{\#} W(B X-C)=0$ admits a solution for every $C \in L(\mathcal{H})$ and, by Corollary 4.4, there exists a $W-\operatorname{ImS}$ of $B X-C=0$.

In this case, let $Q \in \mathcal{Q}$ be such that $R(Q)=R(B)$ and $W Q=Q^{\#} W$. Then, by Douglas' Lemma, there exists $X_{0} \in L(\mathcal{H})$ such that $B X_{0}=Q C$. Therefore $B^{\#} W\left(B X_{0}-C\right)=B^{\#} W(Q-I) C=0$, because $R(I-Q)=N(Q) \subseteq N\left(B^{\#} W\right)$ [6, Lemma 3.2]. Then, $X_{0}$ is a $W$ - $\operatorname{ImS}$ of $B X-C=0$. Hence, $\min _{X \in L(\mathcal{H})} F(X)=C^{\#} W_{/[R(B)]} C$, since $W_{/[R(B)]}=W(I-Q)$, by (3.5).

### 4.1. Weighted Min-Max problems

A necessary condition for the minimization (maximization) problem to be solvable is that the range of the operator $B$ is $W$-nonnegative ( $W$-nonpositive). In what follows, we are interested in posing (and solving) a problem similar to the one in (4.1), that does not require the range of $B$ to be $W$-definite in order to admit a solution. To do so, we begin by expressing the range of $B$ as the sum of suitable $W$-definite subspaces.

For a fix signature operator $J$, the spectral theorem for Hilbert space selfadjoint operators applied to $J W$ gives that $\mathcal{S}:=R(B)$ can be decomposed as $\mathcal{S}=\mathcal{S}_{+}[\dot{+}]_{W} \mathcal{S}_{-}$(compare with (3.2)). If $P_{ \pm}=P_{\mathcal{S}_{ \pm}}$ and $B_{ \pm}=P_{ \pm} B$ then $\mathcal{S}_{ \pm}=R\left(B_{ \pm}\right)$and the following result holds.

Lemma 4.6. Let $W \in L(\mathcal{H})^{s}$ and $B \in C R(\mathcal{H})$. Then, given a signature operator $J, B$ can be written as

$$
\begin{equation*}
B=B_{+}+B_{-} \tag{4.6}
\end{equation*}
$$

with $R\left(B_{+}\right)$closed and $W$-nonnegative, $R\left(B_{-}\right)$closed and $W$-nonpositive, $R\left(B_{+}\right) \perp R\left(B_{-}\right)$and $R(B)=$ $R\left(B_{+}\right)[\dot{+}]_{W} R\left(B_{-}\right)$.

Fix a descomposition of $R(B)$ as in (4.6) and define

$$
F_{J}(X, Y)=\left(B_{+} X+B_{-} Y-C\right)^{\#} W\left(B_{+} X+B_{-} Y-C\right)
$$

Notice that $F_{J}(X, X)=F(X)$.
Consider the following problem: determine the existence of

$$
\max _{Y \in L(\mathcal{H})}\left(\min _{X \in L(\mathcal{H})} F_{J}(X, Y)\right) .
$$

Proposition 4.7. Let $W \in L(\mathcal{H})^{s}$ and $B \in C R(\mathcal{H})$ such that $W$ is $R(B)$-weakly complementable and $B$ is represented as in (4.6) for some signature operator $J$. Then, for every $C \in L(\mathcal{H})$,

$$
\sup _{Y \in L(\mathcal{H})}\left(\inf _{X \in L(\mathcal{H})} F_{J}(X, Y)\right)=\inf _{X \in L(\mathcal{H})}\left(\sup _{Y \in L(\mathcal{H})} F_{J}(X, Y)\right)=C^{\#} W_{/[R(B)]} C .
$$

Proof. Write $W=W_{1}+W_{2}-W_{3}$, with $R(B) \subseteq N\left(W_{1}\right), R\left(B_{-}\right) \subseteq N\left(W_{2}\right), R\left(B_{+}\right) \subseteq N\left(W_{3}\right)$ and $W_{2}, W_{3} \geq 0$ (see Proposition 3.1). Then

$$
F_{J}(X, Y)=C^{\#} W_{1} C+\left(B_{+} X-C\right)^{\#} W_{2}\left(B_{+} X-C\right)-\left(B_{-} Y-C\right)^{\#} W_{3}\left(B_{-} Y-C\right)
$$

By Proposition 3.1, $W$ is $R\left(B_{ \pm}\right)$-weakly complementable. Also, $W$ is $R\left(B_{+}\right)$-weakly complementable and $R\left(B_{+}\right)$is $W$-nonnegative if and only if $W_{2}$ is $R\left(B_{+}\right)$-weakly complementable and $R\left(B_{+}\right)$is $W_{2^{-}}$ nonnegative. Applying Corollary 4.2,

$$
\inf _{X \in L(\mathcal{H})}\left(B_{+} X-C\right)^{\#} W_{2}\left(B_{+} X-C\right)=C^{\#} W_{2 /\left[R\left(B_{+}\right)\right]} C .
$$

Therefore, for each $Y \in L(\mathcal{H})$,

$$
\inf _{X \in L(\mathcal{H})} F_{J}(X, Y)=C^{\#} W_{1} C+C^{\#} W_{2 /\left[R\left(B_{+}\right)\right]} C-\left(B_{-} Y-C\right)^{\#} W_{3}\left(B_{-} Y-C\right)
$$

In the same way, by applying Corollary 4.2 and (3.4)

$$
\begin{aligned}
& \sup _{Y \in L(\mathcal{H})}\left(\inf _{X \in L(\mathcal{H})} F_{J}(X, Y)\right)=C^{\#} W_{1} C+C^{\#} W_{2 /\left[R\left(B_{+}\right)\right]} C-C^{\#} W_{3 /\left[R\left(B_{-}\right)\right]} C= \\
& =C^{\#} W_{/[R(B)]} C . \\
& \text { The second equality can be proved similarly. }
\end{aligned}
$$

Definition. Let $W \in L(\mathcal{H})^{s}, B \in C R(\mathcal{H})$ and $C \in L(\mathcal{H})$. Suppose that $B$ is represented as in (4.6) for some signature operator $J$. An operator $Z \in L(\mathcal{H})$ is an indefinite min-max solution of $B X-C=0$ with weight $W$ ( $W$-ImMS) (corresponding to the decomposition given by $J$ ) if

$$
\begin{equation*}
(B Z-C)^{\#} W(B Z-C)=\max _{Y \in L(\mathcal{H})}\left(\min _{X \in L(\mathcal{H})} F_{J}(X, Y)\right) \tag{4.7}
\end{equation*}
$$

When the weight is the identity, it was proved in [8, Theorem 5.1 and Corollary 5.2], that an operator $Z \in L(\mathcal{H})$ is an $I$-ImMS of $B X-C=0$, for some fundamental decomposition of $\mathcal{H}$, if and only if

$$
Z=Z_{1}+Z_{2}
$$

where $B^{\#}\left(B Z_{1}-C\right)=0$ and $\left(B Z_{2}\right)^{\#} B Z_{2}=0$. Therefore, an $I$-ImMS of $B X-C=0$ is independent of the selected fundamental decomposition of $\mathcal{H}$. Also, there exists an $I$-ImMS of $B X-C=0$ if and only if $R(C) \subseteq R(B)+R(B)^{[\perp]}$. A similar result holds for a general weight:

Theorem 4.8. Let $W \in L(\mathcal{H})^{s}, B \in C R(\mathcal{H})$ and $C \in L(\mathcal{H})$. An operator $Z$ is a $W$-ImMs of $B X-C=0$ for some (and, hence, any) fundamental decomposition of $\mathcal{H}$, if and only if

$$
Z=Z_{1}+Z_{2}
$$

where $B^{\#} W\left(B Z_{1}-C\right)=0$ and $\left(B Z_{2}\right)^{\#} W B Z_{2}=0$.
The proof follows from Corollary 4.4 using similar arguments to those found in the proof of [8, Theorem 5.1].

Remark. Let $W \in L(\mathcal{H})^{s}, B \in C R(\mathcal{H})$ and $C \in L(\mathcal{H})$. Suppose that $B$ is represented as in (4.6) for some signature operator $J$. Then

$$
\max _{Y \in L(\mathcal{H})}\left(\min _{X \in L(\mathcal{H})} F_{J}(X, Y)\right)=\min _{X \in L(\mathcal{H})}\left(\max _{Y \in L(\mathcal{H})} F_{J}(X, Y)\right)
$$

This follows from Theorem 4.8 and using similar arguments to those found in the proof of 8 , Remark after Theorem 5.1].

Corollary 4.9. Let $W \in L(\mathcal{H})^{s}, B \in C R(\mathcal{H})$ and $C \in L(\mathcal{H})$. Then, there exists a $W$-ImMS of $B X-C=$ 0 if and only if $R(C) \subseteq R(B)+W^{-1}\left(R(B)^{[\perp]}\right)$.

Proof. Suppose that $Z$ is a $W$-ImMs of $B X-C=0$. Then, by Theorem 4.8, $Z=Z_{1}+Z_{2}$ where $B^{\#} W\left(B Z_{1}-C\right)=0$ and $\left(B Z_{2}\right)^{\#} W B Z_{2}=0$. Therefore

$$
R(C) \subseteq R(B)+W^{-1}\left(R(B)^{[\perp]}\right)
$$

Conversely, if $R(C) \subseteq R(B)+W^{-1}\left(R(B)^{[\perp]}\right)$ then $R\left(B^{\#} W C\right) \subseteq R\left(B^{\#} W B\right)$. By Douglas's Lemma, there exists a solution of the normal equation $B^{\#} W(B X-C)=0$, say $Z_{1} \in L(\mathcal{H})$. Put $Z_{2}=0$ and apply Theorem4.8 to get that $Z_{1}$ is a $W$-ImMs of $B X-C=0$.

Corollary 4.10. Let $W \in L(\mathcal{H})^{s}$ and $B \in C R(\mathcal{H})$. Then, there exists a $W$-ImMS of $B X-C=0$ for every $C \in L(\mathcal{H})$ if and only if $W$ is $R(B)$-complementable. In this case, for every signature operator $J$,

$$
\max _{Y \in L(\mathcal{H})}\left(\min _{X \in L(\mathcal{H})} F_{J}(X, Y)\right)=C^{\#} W_{/[R(B)]} C=C^{\#} W(I-Q) C
$$

where $Q$ is any projection onto $R(B)$ such that $W Q=Q^{\#} W$.
Proof. If W is $R(B)$-complementable then, for every $C \in L(\mathcal{H}), R(C) \subseteq R(B)+W^{-1}\left(R(B)^{[\perp]}\right)$ and, by Corollary 4.4, there exists a $W$ - $\operatorname{ImMS}$ of $B X-C=0$.

Conversely, assume that, for every $C \in L(\mathcal{H})$ there exists a $W$ - ImMS of $B X-C=0$. Set $C=I$ and apply the corollary once again to get that W is $R(B)$-complementable as $\mathcal{H}=R(I) \subseteq R(B)+$ $W^{-1}\left(R(B)^{[\perp]}\right)$.

In this case, like in the proof of Corollary 4.5 let $Q \in \mathcal{Q}$ be such that $R(Q)=R(B)$ and $W Q=Q^{\#} W$. Then, by Douglas' Lemma, there exists $Z_{1} \in L(\mathcal{H})$ such that $B Z_{1}=Q C$ and $B \# W\left(B Z_{1}-C\right)=0$. Then, by Theorem 4.8, $Z_{1}$ is a $W$ - ImMS of $B X-C=0$. Therefore,

$$
\max _{Y \in L(\mathcal{H})}\left(\min _{X \in L(\mathcal{H})} F_{J}(X, Y)\right)=F\left(Z_{1}\right)=C^{\#} W_{/[R(B)]} C=C^{\#} W(I-Q) C
$$

## 5. Minimization problems in the indefinite trace space

In the present section the notion of trace of an operator is extended to the Krein space setting with the aim of applying the results previously obtained to trace-type problems on operators.

We denote by $S_{p}$ the $p$-Schatten class for $1 \leq p<\infty$. The reader is referred to [22, 24] for further details on $S_{p}$-operators.

Let $(\mathcal{H},[]$,$) be a Krein space. If J$ is a signature operator for $\mathcal{H}$, fix the Hilbert space $(\mathcal{H},\langle\rangle$,$) ,$ where $\langle x, y\rangle=[J x, y]$ for all $x, y \in \mathcal{H}$. The operator $T$ belongs to the Schatten class $S_{p}(J)$ if $T \in S_{p}$ when viewed as acting on the associated Hilbert space $(\mathcal{H},\langle\rangle$,$) . The next lemma shows that if T \in S_{p}\left(J_{a}\right)$ for some fundamental decomposition of $\mathcal{H}$ with signature operator $J_{a}$ then $T \in S_{p}\left(J_{b}\right)$ for any other fundamental decomposition of $\mathcal{H}$ with signature operator $J_{b}$. To prove this assertion we will use the following result, see 22, Theorem 2.1.3].

Theorem 5.1. Let $\mathcal{H}$ be a Hilbert space, $T \in L(\mathcal{H})$ and $1 \leq p<\infty$. Then $T \in S_{p}$ if and only if there exists a sequence $\left\{F_{n}\right\}_{n \in \mathbb{N}}$ of operators on $\mathcal{H}$ such that $F_{n}$ has finite rank not greater than $n$ and

$$
\sum_{n \geq 1}\left\|T-F_{n}\right\|^{p}<\infty
$$

Lemma 5.2. Let $(\mathcal{H},[]$,$) be a Krein space with signature operators J_{a}$ and $J_{b}$. Fix the Hilbert spaces $\left(\mathcal{H},\langle,\rangle_{a}\right)$ and $\left(\mathcal{H},\langle,\rangle_{b}\right)$. Then $T \in S_{p}\left(J_{a}\right)$ if and only if $T \in S_{p}\left(J_{b}\right)$.

Proof. The result is readily obtained by applying Theorem 5.1 and from the fact that $\langle,\rangle_{a}$ and $\langle,\rangle_{b}$ are equivalent.

On account of the above lemma we just write $S_{p}$ instead of $S_{p}(J)$.
Definition. Let $(\mathcal{H},[]$,$) be a separable Krein space with signature operator J$ and fix the associated Hilbert space $(\mathcal{H},\langle\rangle$,$) . If T \in S_{1}$ and $\left\{e_{n}: n \in \mathbb{N}\right\}$ is an orthonormal basis of $(\mathcal{H},\langle\rangle$,$) , then the$ $J$-trace of $T$, denoted by $\operatorname{tr}_{J}(T)$, is defined as

$$
\operatorname{tr}_{J}(T)=\sum_{n=1}^{\infty}\left[T e_{n}, e_{n}\right]
$$

Notice that $\operatorname{tr}_{J}(T)$ equals $\operatorname{tr}(J T)$ in the inner product $\langle\rangle=,[J$,$] see [22, 24]. Whence the J$-trace of $T$ does not depend on the particular choice of the orthonormal basis (see [22, Lemma 2.2.1]).

The next lemma gathers the basic properties of the $J$-trace. By using the definition of $\operatorname{tr}_{J}$ and the properties of the trace of an operator in a Hilbert space the proof is straightforward.

Lemma 5.3. Let $(\mathcal{H},[]$,$) be a Krein space with signature operator J$ and fix the associated Hilbert space $(\mathcal{H},\langle\rangle$,$) . Let T, S \in S_{1}$ and $\alpha, \beta \in \mathbb{C}$, then
i) $\operatorname{tr}_{J}(\alpha T+\beta S)=\alpha \operatorname{tr}_{J}(T)+\beta \operatorname{tr}_{J}(S)$,
ii) $\operatorname{tr}_{J}\left(T^{\#}\right)=\overline{\operatorname{tr}_{J}(T)}$,
iii) $\operatorname{tr}_{J}(T)=\operatorname{tr}(J T)$, where the trace is calculated with respect to the inner product $\langle\rangle=,[J$,$] ,$
iv) $\operatorname{tr}_{J}(T S)=\operatorname{tr}_{J}(J S J T)=\operatorname{tr}_{J}(S J T J)$,
v) $\left|\operatorname{tr}_{J}(T)\right| \leq\|T\|_{1}$.

The next example shows that the $J$-trace depends on the signature operator $J$.
Example 1. Consider $\mathbb{C}^{2}$ with the indefinite metric $\left[\left(x_{1}, x_{2}\right),\left(y_{1}, y_{2}\right)\right]=x_{1} \overline{y_{1}}-x_{2} \overline{y_{2}}$.
Then $\left(\mathbb{C}^{2},[],\right)$ is a Krein space with fundamental decompositions: $\mathbb{C}^{2}=\operatorname{span}\{(1,0)\}[\dot{+}] \operatorname{span}\{(0,1)\}$ and $\mathbb{C}^{2}=\operatorname{span}\{(2,1)\}[\dot{+}] \operatorname{span}\{(1,2)\}$. Let $J_{a}$ and $J_{b}$ be the corresponding signature operators. Observe that $\{(1,0),(0,1)\}$ is an orthonormal basis in $\left(\mathbb{C}^{2},\left[J_{a},\right]\right)$ and $\left\{\frac{1}{\sqrt{3}}(2,1), \frac{1}{\sqrt{3}}(1,2)\right\}$ is an orthonormal basis in $\left(\mathbb{C}^{2},\left[J_{b},\right]\right)$. Set $T: \mathbb{C}^{2} \rightarrow \mathbb{C}^{2}, T\left(x_{1}, x_{2}\right):=\left(x_{1}+x_{2}, 0\right)$. A straightforward computation gives $\operatorname{tr}_{J_{a}}(T)=1 \neq 3=\operatorname{tr}_{J_{b}}(T)$.

Lemma 5.4. Let $(\mathcal{H},[]$,$) be a separable Krein space with signature operators J_{a}$ and $J_{b}$. Fix the Hilbert spaces $\left(\mathcal{H},\langle,\rangle_{a}\right)$ and $\left(\mathcal{H},\langle,\rangle_{b}\right)$. If $T \in S_{1}$ then

$$
\operatorname{tr}_{J_{b}}(T)=\operatorname{tr}_{J_{a}}\left(J_{b} T J_{a}\right)
$$

Proof. We use the notation $\left.\operatorname{tr}_{\langle }{ }^{\text {, }}\right\rangle$ when we want to highlight the inner product on which the trace is calculated. Let $\alpha=J_{a} J_{b}$. Then $\alpha$ is an invertible operator on $\mathcal{H}$ such that, for every $x, y \in \mathcal{H}$,

$$
\langle\alpha x, y\rangle_{a}=\left\langle J_{a} J_{b} x, y\right\rangle_{a}=\left[J_{b} x, y\right]=\langle x, y\rangle_{b} .
$$

In particular, $\langle\alpha x, x\rangle_{a} \geq 0$ for every $x \in \mathcal{H}$.
Let $\left\{e_{n}: n \in \mathbb{N}\right\}$ be an orthonormal basis in $\left(\mathcal{H},\langle,\rangle_{b}\right)$. Then

$$
\delta_{i j}=\left\langle e_{i}, e_{j}\right\rangle_{b}=\left\langle\alpha e_{i}, e_{j}\right\rangle_{a}=\left\langle\alpha^{1 / 2} e_{i}, \alpha^{1 / 2} e_{j}\right\rangle_{a}
$$

Hence, $\left\{\alpha^{1 / 2} e_{n}: n \in \mathbb{N}\right\}$ is an orthonormal basis in $\left(\mathcal{H},\langle,\rangle_{a}\right)$.
So, if $T \in S_{1}$ then
$\operatorname{tr}_{J_{b}}(T)=\operatorname{tr}_{\langle,\rangle_{b}}\left(J_{b} T\right)=\operatorname{tr}_{\langle,\rangle_{b}}\left(T J_{b}\right)=\sum_{n \geq 1}\left\langle T J_{b} e_{n}, e_{n}\right\rangle_{b}=$
$=\sum_{n \geq 1}\left\langle\alpha T J_{a} \alpha e_{n}, e_{n}\right\rangle_{a}=\sum_{n \geq 1}\left\langle\left(\alpha^{1 / 2} T J_{a} \alpha^{1 / 2}\right) \alpha^{1 / 2} e_{n}, \alpha^{1 / 2} e_{n}\right\rangle_{a}=$
$\left.=\operatorname{tr}_{\langle,\rangle_{a}}\left(\alpha^{1 / 2} T J_{a} \alpha^{1 / 2}\right)=\operatorname{tr}_{\langle,\rangle_{a}}\left(\alpha T J_{a}\right)=\operatorname{tr}_{\langle },\right\rangle_{a}\left(J_{a} J_{b} T J_{a}\right)=$
$=\operatorname{tr}_{J_{a}}\left(J_{b} T J_{a}\right)$.

## Fréchet derivative of the J-trace

Let $(\mathcal{E},\|\cdot\|)$ be a Banach space and $\mathcal{U} \subseteq \mathcal{E}$ be an open set. We recall that a function $f: \mathcal{E} \rightarrow \mathbb{R}$ is said to be Fréchet differentiable at $X_{0} \in \mathcal{U}$ if there exists $D f\left(X_{0}\right): \mathcal{E} \rightarrow \mathbb{R}$ a bounded linear functional such that

$$
\lim _{Y \rightarrow 0} \frac{\left|f\left(X_{0}+Y\right)-f\left(X_{0}\right)-D f\left(X_{0}\right)(Y)\right|}{\|Y\|}=0
$$

If $f$ is Fréchet differentiable at every $X_{0} \in \mathcal{E}, f$ is called Fréchet differentiable on $\mathcal{E}$ and the function $D f$ which assigns to every point $X_{0} \in \mathcal{E}$ the derivative $D f\left(X_{0}\right)$, is called the Fréchet derivative of the function $f$. If, in addition, the derivative $D f$ is continuous, $f$ is said to be a class $\mathcal{C}^{1}$-function, in symbols, $f \in \mathcal{C}^{1}(\mathcal{E}, \mathbb{R})$.

Let $W \in L(\mathcal{H})^{s}, B \in C R(\mathcal{H})$ and $C \in L(\mathcal{H})$. Recall that $F(X)=(B X-C)^{\#} W(B X-C)$ and consider $f_{J}: L(\mathcal{H}) \rightarrow \mathbb{R}$ defined by

$$
f_{J}(X):=\operatorname{tr}_{J}(F(X))
$$

In the following lemma we give the formula for the Fréchet derivative of $f_{J}(X)$, see [16] for the finite-dimensional case.

Lemma 5.5. Let $(\mathcal{H},[]$,$) be a Krein space with signature operator J. Fix the associated Hilbert space$ $(\mathcal{H},\langle\rangle$,$) . Let W \in S_{1}, B \in C R(\mathcal{H})$ and $C \in L(\mathcal{H})$. Then $f_{J}$ is Fréchet differentiable on $L(\mathcal{H})$ and

$$
D f_{J}(X)(Y)=2 \operatorname{Re} \operatorname{tr}_{J}\left(Y^{\#} B^{\#} W(B X-C)\right)
$$

Moreover, $f_{J} \in \mathcal{C}^{1}(L(\mathcal{H}), \mathbb{R})$.
Proof. For all $X, Y \in L(\mathcal{H})$,

$$
f_{J}(X+Y)=f_{J}(X)+2 R e \operatorname{tr}_{J}\left((B Y)^{\#} W(B X-C)\right)+\operatorname{tr}_{J}\left((B Y)^{\#} W(B Y)\right)
$$

Then

$$
\begin{aligned}
& \frac{\left|f_{J}(X+Y)-f_{J}(X)-2 R e \operatorname{tr}_{J}\left((B Y)^{\#} W(B X-C)\right)\right|}{\|Y\|}= \\
= & \frac{\left|\operatorname{tr}_{J}\left((B Y)^{\#} W(B Y)\right)\right|}{\|Y\|} \leq \frac{\|B Y\|^{2}\|W\|_{1}}{\|Y\|} \leq\|B\|^{2}\|W\|_{1}\|Y\|
\end{aligned}
$$

(see Lemma 5.3). Hence $f_{J}$ is Fréchet differentiable on $L(\mathcal{H})$ and

$$
D f_{J}(X)(Y)=2 \operatorname{Re} \operatorname{tr}_{J}\left((B Y)^{\#} W(B X-C)\right)
$$

Finally, since

$$
\begin{aligned}
\left|D f_{J}\left(X_{1}\right)(Y)-D f_{J}\left(X_{2}\right)(Y)\right| & =2 \mid R e \operatorname{tr}_{J}\left((B Y)^{\#} W\left(B\left(X_{1}-X_{2}\right)\right) \mid\right. \\
& \leq 2\|B\|^{2}\|Y\|\|W\|_{1}\left\|X_{1}-X_{2}\right\|
\end{aligned}
$$

(once again by Lemma 5.3), it follows that $f_{J} \in \mathcal{C}^{1}(L(\mathcal{H}), \mathbb{R})$.
In this section we deal with the following problems: let $(\mathcal{H},[]$,$) be a Krein space with signature$ operator $J$. Fix the associated Hilbert space $(\mathcal{H},\langle\rangle$,$) . Given B \in C R(\mathcal{H}), C \in L(\mathcal{H})$ and $W \in S_{1} \cap$ $L(\mathcal{H})^{s}$, we analyze whether there exists the

$$
\begin{equation*}
\min _{X \in L(\mathcal{H})} \operatorname{tr}_{J}\left((B X-C)^{\#} W(B X-C)\right) \tag{5.1}
\end{equation*}
$$

and the corresponding maximum.
Finally, if $B$ is represented as in (4.6) and $F_{J}(X, Y)=\left(B_{+} X+B_{-} Y-C\right)^{\#} W\left(B_{+} X+B_{-} Y-C\right)$, we also analyze the existence of

$$
\begin{equation*}
\max _{Y \in L(\mathcal{H})}\left(\min _{X \in L(\mathcal{H})} \operatorname{tr}_{J}\left(F_{J}(X, Y)\right)\right) \tag{5.2}
\end{equation*}
$$

It follows from the last lemma that, if $f_{J}: L(\mathcal{H}) \times L(\mathcal{H}) \rightarrow \mathbb{R}$ is given by

$$
\begin{equation*}
f_{J}(X, Y):=\operatorname{tr}_{J}\left(F_{J}(X, Y)\right) \tag{5.3}
\end{equation*}
$$

then $f_{J} \in \mathcal{C}^{1}(L(\mathcal{H}) \times L(\mathcal{H}), \mathbb{R})$ and the partial derivatives of $f_{J}$ in every $\left(X_{0}, Y_{0}\right) \in L(\mathcal{H}) \times L(\mathcal{H})$ are

$$
\begin{aligned}
& D_{X} f_{J}\left(X_{0}, Y_{0}\right)(H)=2 R e \operatorname{tr}_{J}\left(\left(B_{+} H\right)^{\#} W\left(B_{+} X_{0}+B_{-} Y_{0}-C\right)\right) \\
& D_{Y} f_{J}\left(X_{0}, Y_{0}\right)(K)=2 R e \operatorname{tr}_{J}\left(\left(B_{-} K\right)^{\#} W\left(B_{+} X_{0}+B_{-} Y_{0}-C\right)\right)
\end{aligned}
$$

for all $H, K \in L(\mathcal{H})$.
Theorem 5.6. Let $W \in L(\mathcal{H})^{s}$ such that $W \in S_{1}, B \in C R(\mathcal{H})$ and $C \in L(\mathcal{H})$. The following assertions hold:

1. Assume that $R(B)$ is $W$-nonnegative. Then, $X_{0} \in L(\mathcal{H})$ realizes (5.1) for any signature operator $J$ if and only if $X_{0}$ is a $W$-ImS of the equation $B X-C=0$.
2. Let $B$ be represented as in (4.6) for some signature operator $J$. Then, the min-max in (5.2) exists for every $C \in L(\mathcal{H})$ if and only if $W$ is $R(B)$-complementable. In this case,

$$
\max _{Y \in L(\mathcal{H})}\left(\min _{X \in L(\mathcal{H})} \operatorname{tr}_{J}\left(F_{J}(X, Y)\right)\right)=\operatorname{tr}_{J}\left(C^{\#} W_{/[R(B)]} C\right)
$$

The operator $Z \in L(\mathcal{H})$ realizes (5.2) if and only if $Z$ is a $W$-ImMS of $B X-C=0$.
Proof. Let $J$ be a signature operator of $\mathcal{H}$ and fix the associated Hilbert space $(\mathcal{H},\langle\rangle$,$) . Suppose that$ $X_{0}$ is a solution of Problem (5.1). If $f_{J}$ is as in Lemma 5.5 then $X_{0}$ is a global minimum of $f_{J}$. Since $f_{J}$ is a $\mathcal{C}^{1}$-function, $X_{0}$ is a critical point of $f_{J}(X)$; i.e., for every $Y \in L(\mathcal{H}), D f_{J}\left(X_{0}\right)(Y)=0$ or equivalently,

$$
0=2 R e \operatorname{tr}_{J}\left((B Y)^{\#} W\left(B X_{0}-C\right)\right)=2 R e \operatorname{tr}\left(J(B Y)^{\#} W\left(B X_{0}-C\right)\right)
$$

Thus, considering a suitable $Y$, it follows that

$$
B^{\#} W\left(B X_{0}-C\right)=0
$$

So, by Corollary 4.4, $X_{0}$ is a $W-\operatorname{ImS}$ of $B X-C=0$.
As for the converse, suppose that $X_{0}$ is a $W$ - $\operatorname{ImS}$ of $B X-C=0$. Let $\left\{e_{n}: n \in \mathbb{N}\right\}$ be any orthonormal basis in $(\mathcal{H},\langle\rangle$,$) . Then$

$$
\left[W\left(B X_{0}-C\right) e_{n},\left(B X_{0}-C\right) e_{n}\right] \leq\left[W(B X-C) e_{n},(B X-C) e_{n}\right]
$$

for every $n \in \mathbb{N}$ and every $X \in L(\mathcal{H})$. Therefore

$$
\operatorname{tr}_{J}\left(F\left(X_{0}\right)\right) \leq \operatorname{tr}_{J}(F(X))
$$

for every $X \in L(\mathcal{H})$. Hence $X_{0}$ is a solution of Problem (5.1) and the proof of the item 1 is complete.
As for the item 2 , suppose that $W$ is $R(B)$-complementable and $Z^{\prime}$ is a solution of $B^{\#} W(B X-I)=0$. Then, for any $C \in L(\mathcal{H}), Z=Z^{\prime} C$ is a solution of $B^{\#} W(B X-C)=0$ and, by Theorem 4.8, $Z$ is a $W$-ImMS of $B X-C=0$, i.e.,

$$
(B Z-C)^{\#} W(B Z-C)=\max _{Y \in L(\mathcal{H})}\left(\min _{X \in L(\mathcal{H})} F_{J}(X, Y)\right)
$$

Let $\left\{e_{n}: n \in \mathbb{N}\right\}$ be any orthonormal basis in $(\mathcal{H},\langle\rangle$,$) . Then, for every n \in \mathbb{N}$ and any $X, Y \in L(\mathcal{H})$,

$$
\begin{aligned}
& {\left[\left(B_{+} Z+B_{-} Y-C\right)^{\#} W\left(B_{+} Z+B_{-} Y-C\right) e_{n}, e_{n}\right] \leq} \\
& \leq\left[\left(B_{+} Z+B_{-} Z-C\right)^{\#} W\left(B_{+} Z+B_{-} Z-C\right) e_{n}, e_{n}\right] \\
& \leq\left[\left(B_{+} X+B_{-} Z-C\right)^{\#} W\left(B_{+} X+B_{-} Z-C\right) e_{n}, e_{n}\right]
\end{aligned}
$$

Therefore

$$
\begin{aligned}
\operatorname{tr}_{J}\left(F_{J}(Z, Z)\right)=\operatorname{tr}_{J}(F(Z)) & =\max _{Y \in L(\mathcal{H})}\left(\min _{X \in L(\mathcal{H})} \operatorname{tr}_{J}\left(F_{J}(X, Y)\right)\right)= \\
& =\operatorname{tr}_{J}\left(C^{\#} W_{/[R(B)]} C\right)
\end{aligned}
$$

where we used Corollary 4.10. Hence $Z$ is a solution of Problem (5.2).
Conversely, if $Z \in L(\mathcal{H})$ is a solution of Problem (5.2) for any $C \in L(\mathcal{H})$, then

$$
f_{J}(Z, Y) \leq f_{J}(Z, Z) \leq f_{J}(X, Z) \text { for every } X, Y \in L(\mathcal{H})
$$

where $f_{J}$ is as in (5.3). Hence, $Z$ is a global minimum of $f_{J}(X, Z)$ and $Z$ is a global maximum of $f_{J}(Z, Y)$. Therefore, for every $H, K \in L(\mathcal{H})$,

$$
D_{X} f_{J}(Z, Z)(H)=D_{Y} f_{J}(Z, Z)(K)=0
$$

or equivalently,
$\operatorname{Re} \operatorname{tr}_{J}\left(\left(B_{+} H\right)^{\#} W\left(B_{+} Z+B_{-} Z-C\right)\right)=\operatorname{Re} \operatorname{tr}_{J}\left(\left(B_{-} K\right)^{\#} W\left(B_{+} Z+B_{-} Z-C\right)\right)=0$. Then, considering suitable $H, K$, it follows that

$$
B_{+}^{\#} W\left(B_{+} Z+B_{-} Z-C\right)=B_{-}^{\#} W\left(B_{+} Z+B_{-} Z-C\right)=0 .
$$

Thus

$$
B^{\#} W(B Z-C)=0
$$

and, by Theorem 4.8 once again, $Z$ is a $W$ - $\operatorname{ImMS}$ of $B X-C=0$.
The following theorem synthesizes the results of the last two sections.
Theorem 5.7. Let $W \in L(\mathcal{H})^{s}$ such that $W \in S_{1}$ and $B \in C R(\mathcal{H})$. Then the following statements are equivalent:
i) there exists a $W$-ImMS of $B X-C=0$ for every $C \in L(\mathcal{H})$,
ii) the $\max _{Y \in L(\mathcal{H})}\left(\min _{X \in L(\mathcal{H})} \operatorname{tr}_{J}\left(F_{J}(X, Y)\right)\right)$ is attained, for every $C \in L(\mathcal{H})$,
iii) $W$ is $R(B)$-complementable,
iv) the equation $B^{\#} W(B X-C)=0$ admits a solution for every $C \in L(\mathcal{H})$.

In this case,

$$
\max _{Y \in L(\mathcal{H})}\left(\min _{X \in L(\mathcal{H})} F_{J}(X, Y)\right)=C^{\#} W_{/[R(B)]} C
$$

and

$$
\max _{Y \in L(\mathcal{H})}\left(\min _{X \in L(\mathcal{H})} \operatorname{tr}_{J}\left(F_{J}(X, Y)\right)\right)=\operatorname{tr}_{J}\left(C^{\#} W_{/[R(B)]} C\right) .
$$

Moreover, $Z$ is a $W$-ImMS of $B X-C=0$ and the min-max in ii) is attained in $Z$ if and only $Z=Z_{1}+Z_{2}$, where $B^{\#} W\left(B Z_{1}-C\right)=0$ and $\left(B Z_{2}\right)^{\#} W B Z_{2}=0$.

## Final remark: the $\mathbf{J}-\mathbf{S}_{\mathbf{2}}$ space

Let $(\mathcal{H},[]$,$) be a Krein space with signature operator J$. Fix the associated Hilbert space $(\mathcal{H},\langle\rangle$, and set

$$
[S, T]_{J}:=\operatorname{tr}_{J}\left(T^{\#} S\right), \quad S, T \in S_{2} .
$$

It can be readily seen that $[,]_{J}$ is an indefinite inner product on $S_{2}$. Moreover, $\left(S_{2},[,]_{J}\right)$ is a Krein space and

$$
\operatorname{tr}_{J}\left(T^{\#} T\right)=\left\|P_{+} T\right\|_{2}^{2}-\left\|P_{-} T\right\|_{2}^{2}
$$

where $P_{ \pm}=\frac{I \pm J}{2}$.

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